

THÉOPHILE SAUTORY

+1 (510) 502 52-09 | theophile.sautory@gmail.com | theosau.github.io | github.com/theosau

Education

University of California, Berkeley

May 2023

MS in Mechanical Engineering, *GPA:3.93/4.00*.

Physics-Informed Machine Learning, Geometry and Learning for 3D Vision, Advanced Fluid Mechanics

Imperial College London

MS in Computer Science, Artificial Intelligence & Machine Learning, *GPA:4.00/4.00*.

Sep. 2020

Thesis: Neuro-symbolic video question answering with spatio-temporal properties.

BSc in Mechanical Engineering, *GPA:4.00/4.00*.

Jun. 2019

Embedded C for Microcontrollers, Mechatronics, Design Make and Test, Heat Transfer, Thermodynamics.

Work Experience

Ansys

May. 2022 – Aug. 2022

Machine Learning Research Intern, CTO Office

San Jose, CA

- Designed autoencoders and training mechanisms for multi-objective optimization in physics-informed machine learning.
- Led the research on merging Ansys Fluent with deep learning for novel PDE solvers with the help of senior researchers.

UK National Crime Agency

Apr. 2021 – Jul. 2021

Research Assistant, Artificial Intelligence

London, UK

- Built data analysis and visualization programs with Python, and PyTorch including logistic regressions, PCA, siamese autoencoders, hypothesis testing, resulting in a 5x reduction in the number of cases to compare.
- Collaborated with Psychology Professors and crime analysts to consider human well-being and bias in the data.

Scortex

Sep. 2020 – Apr. 2021

Deep Learning and Computer Vision Researcher

Paris, France

- Tested various deep learning models on our hardware prototype to evaluate performance and latency.
- Improved the ROC-AUC performance in anomaly detection on images for the MVTec dataset by 5%, using generative modeling, TensorFlow, transfer learning and data augmentation.

L'Oréal Paris

Jul. 2017 – Aug. 2017

Mechanical Engineering Intern

Paris, France

- Implemented an eyelash classification algorithm to study personalized effects of applying mascara on eyelash health.
- Built a hand wheel machine to measure mascaras effect on eyelash volume and fall out for different eyelash classes.

Engineering Projects

Super-resolution of PC-MRI blood flow images | *Software development, health data analysis*

May. 2022 – current

- Combining deep learning with the Navier-Stokes equations to super-resolve PC-MRI blood flow images.
- Building an associated web app using Python, Plotly and Dash, to enhance clinical practitioners' decision-making.

Google Waymo 2D Object Detection | *Computer Vision Engineer*

Apr. 2020 – May 2020

- Designed an EfficientDetv4 model on 700k-1080p images using GCP, NVIDIA Tesla V100 GPU, PyTorch and OpenCV.
- Implemented test time augmentation, mixed precision training and k-means clustering for anchor priors.

Bionic hand for digital interface use | *Product Design Engineer, health data analysis*

Sep. 2018 – Jun. 2019

- Designed and manufactured a bionic hand with motor control, using CAD (SolidWorks), 3D printing and Abaqus.
- Analyzed electromyogram signals from a below-elbow amputee to drive motor actuation and collect user feedback.

Technical Skills

Design: CAD (Solidworks), Prototyping (3D printing, machining), FEM / CFD (Abaqus, Fluent, Star-CCM+), Arduino.

Coding: *Experienced:* Python, Julia, MATLAB, Linux, Git, LaTeX. *Familiar:* C/C++ (CUDA/MPI/OpenMP), SQL.

Selected Publications

- [1] Theophile Sautory, Nuri Cingillioglu, Alessandra Russo (2021): HySTER: A Hybrid Spatio-Temporal Event Reasoner, Thirty-Fifth AAAI Conference on Artificial Intelligence Workshop on Hybrid Artificial Intelligence.
- [2] Alvaro Prat, Theophile Sautory & S. Navarro-Martinez (2020): A Priori Sub-grid Modelling Using Artificial Neural Networks, International Journal of Computational Fluid Dynamics, DOI: 10.1080/ 10618562.2020.1789116.

Extracurricular

Leadership: Vice-president of the Imperial College Basketball Society, and team captain, leading the 120 members to win Imperial Sports Club of the Year (2018-2019).

Hobbies: Poetry, Hiking, Road biking, Tennis, Basketball.