1. Basic setup:

4 Training set

where 
$$\underline{x}_n \in \mathbb{R}^d$$
,  $\underline{x}_n = (x_{n1}, x_{n2}, --- x_{nd})$ 

→ <u>Task:</u>

Given any  $x \in \mathbb{R}^d$ , output  $y \in [-1, +1]$ 

4. (Hypothesis H) Decision Rule:

Weighted vector 
$$\underline{W} = (W_1, W_2, ..., W_d) \in \mathbb{R}^d$$

Threshold b & IR

Given data point 
$$\underline{x} = (x_1, x_2 - x_d)$$

if 
$$\sum_{i=1}^{d} W_i \chi_i > b$$
, then  $y = +1$ 

if 
$$\sum_{i=1}^{\alpha} W_i \chi_i < b$$
, then  $y = -1$ 

if 
$$i = 1$$
 Wi Xi = b, output either +1 or -1 (unimportant)

4. Training phase:

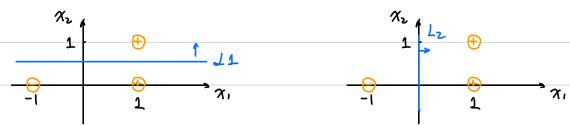
- 'Compare decision rule with training data, to choose the "best" parameter values for decision rule "best" hypothesis.
- Given  $\mathcal{D}$ , find  $(\underline{w}, b)$  to minimize the training errors  $E_{in}(\underline{w}, b) = \frac{1}{N} \sum_{n=1}^{N} 1(y_n \neq \hat{y_n}(\underline{w}, b))$

avg error on take Average oneput of decision rule on example  $\underline{x}_n$  training set for  $\underline{x}_n$  true label for  $\underline{x}_n$ 

 $\omega$  Goal: find  $(\underline{W}, b)$  to minimize Ein  $(\underline{W}, b)$ 

## 2. <u>Example:</u>

d=1 (i.e. two attributes  $x_1$ ,  $x_2$ )



Lo consider  $L1: \chi_2 = \frac{1}{2}$ 

. This correspond to: (0) 
$$x_1 + (1) x_2 = \frac{1}{2}$$

$$\therefore \ \underline{W} = (0, 1) , \ b = \frac{1}{2}$$

· Find Ein 
$$(W, b)$$

$$1' \quad \underline{x} = (1,0) \quad y_1 = +1$$

$$W^T x_1 = 0 < b \Rightarrow y_1' = 1$$
 // Make one error

$$2' \frac{\alpha}{2} = (1,1), \quad q_2 = +1$$

$$W^{\mathsf{T}} \mathcal{A}_{2} = 1 > b \Rightarrow \hat{\mathcal{J}}_{2} = +1$$

$$3' \quad \underline{x}_3 = (-1, 0), \quad \underline{y}_3 = -1$$

$$W^{T} \pi_{3} = 0 < b \Rightarrow \hat{y}_{3} = -1$$

$$\pm E_{M}(\underline{W}, b) = \frac{1}{3}(1+0+0) = \frac{1}{3}$$

$$Ein(\underline{W},b)=0$$

13. Minimize Ein(W,b) is an NP-hard problem in general.

Lec 3.2 Perception Learning Algo (PLA) 1. efficiently finds a perfect classifer for linearly seportable data. 1. change of notation: 4. Decision Rule: W1 x, + W2 x2 + --- + Wd xd y=-1 b y=+1 → -b + W, x, + W, x, + --- + W, x, x ≥ 0 · let Wo = -b, xo = 1 Then we have an <u>Augmented</u> vectors: <u>w</u> = ( wo, w, ... wd) E IR  $\underline{\alpha} = (\chi_0 = 1, \chi_1, \ldots, \chi_d) \in IR^{d+1}$ · Then the new decision rule becomes:  $\underline{\omega}^{\mathsf{T}} \underline{\chi} \overset{\mathsf{J-tl}}{\geq} 0$ and  $y = h\omega(\frac{\pi}{2}) \stackrel{\triangle}{=} sign(\frac{\omega^T \pi}{2}) \stackrel{\leftarrow}{\leftarrow} "perceptron learning"$ // sign (+) = s + 1 , t < 02. PLA, is suppose training set  $\mathcal{D}$  is linearly separable, find  $\underline{w} \in \mathbb{R}^{d+1}$  s.t.  $Ein \left( \frac{\omega}{n} \right) = \frac{1}{N} \sum_{n=1}^{\infty} 1 \left( y_n \neq h_w \left( \frac{x_n}{n} \right) \right) = 0$ 10 Input: Training set D that is linearly seperable Dutput:  $\underline{W} \in \mathbb{R}^{d+1}$  that achieves  $E_{in}(\underline{W}) = 0$ Initialization: arbitary e.g. w = 0 // d-dimentional zero vector

b. Step 1:	check whether $Ein(\underline{W}) = 0$	
	If yes, stop and output w.	
Step 2:	Let $(x_n, y_n)$ be a miss-classified example	
·	(including points on boundary)	
	If $y_n = +1$ , then replace $w$ with $w + \pi + \pi$ same as saying	
	If $y_n = -1$ , then replace $\underline{w}$ with $\underline{w} - \chi_n$ $\underline{w} \leftarrow \underline{w} + y_n \chi_n$	_
Then go	to step 1.	
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