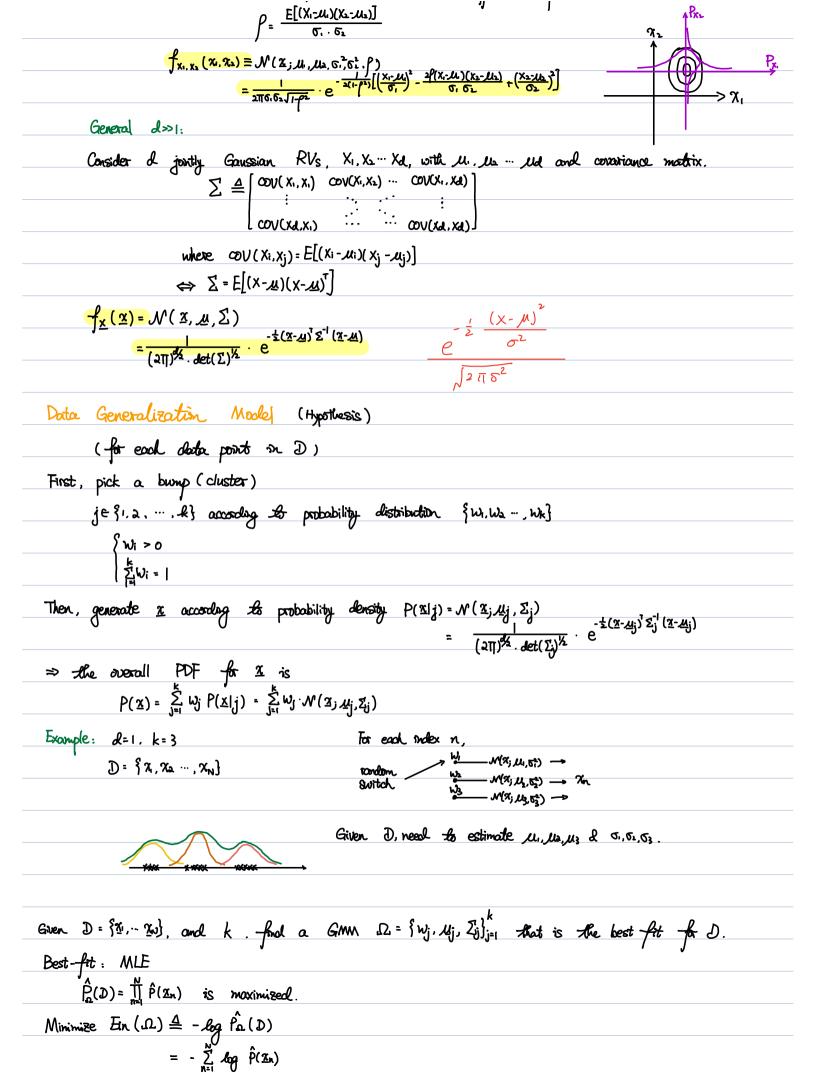
2 4.5 Observation: larger K. sworther ordputs. Gaussian Kernels 3) Porson Window Estimation with → Each sample has a Gaussiam Distribution. -> Add all the probability -> Scale to Name CDF=1 Details: Standard normal distribution (PDF)  $\phi(s) = \frac{2\pi}{1} 6 \frac{s}{s}$  $\hat{b}(x) = \frac{k}{l} \sum_{n=1}^{l=1} \phi\left(\frac{x}{\|x - \overline{x}_i\|}\right)$ 8: ternel width, width of each sample affected neighbor. k: Normalizza constant larger 8 smaller & overfit underfit Note: If more points -> complex computation. Sec 22. 4) Gaussian Mixture Model Each duster with its own Gaussian distribution It suffices to use only I Gaussian distributions one for each cluster. - meoun. M., Ma, ..., Mk ∈ Rd conditionce:  $\Sigma_1, \Sigma_2, \dots, \Sigma_k \in \mathbb{R}^d \times \mathbb{R}^d$ Review: PDF of Gaussian R.V. X with mean u, and variance of  $f_{X}(x) = \mathcal{N}(x; \mu, \sigma^{2}) = \frac{1}{\sqrt{\pi}\sigma} \cdot e^{-\left(\frac{x \cdot \mu}{2\sigma^{2}}\right)^{2}}$ PDF of jointed Gaussian R.V. X, and X2, with mean 11, & 112,  $\sigma_1^2$  &  $\sigma_2^2$ , and correlation coefficient f.



Given  $\Omega = \{W_j, U_j, \Sigma_j\}_{j=1}^K$ , estimate bump membership ie. for each  $\Sigma_n$ , find bump j that is most likely to produce In.  $\underline{x}_n \in B_{j^*}$  if  $j^* = \underset{j \in \S_1.a - k_j}{\text{argmax}} P_i(j|\underline{x}_n)$ Bayes' Thin  $= \frac{\mathcal{N}(\underline{x}_{i}; \underline{\mathcal{U}}_{i}, \underline{x}_{i}) \cdot \omega_{i}}{\underbrace{\underbrace{k}_{i}}_{i=1} \mathcal{N}(\underline{x}_{i}; \underline{\mathcal{U}}_{i}, \underline{x}_{i}) \cdot \omega_{i}}$ ⇒ j\* = Orgmax N(Mn; Ms, Zj)·Ws EM algo. Summary: (Hord decisions) 1. Initialization: Start with arbitary tump membership for each In. a. Estimate  $\Omega = \frac{9}{10} \text{ Wj. Mj. Zj}_{j=1}^{k}$  given bump membership  $\frac{9}{10} \text{Bi.} \dots \text{Bk}$  (Subproblem 1) 3. Estimate bump membership  ${}^{9}$ B1, ... Bk} given  $\Omega$  (subproblem 2) Repeat step 2 & 3 until convergence. Note: O Convergence is guaranteed. (a) B1, ..., Bk are auxiliary ("hidden" variables).