ECE421 Lab3 Report

1.K-means

1.1 Learning K-means

1)

distance_func

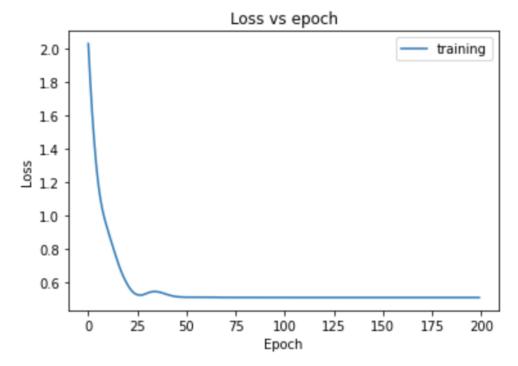
Implement K-means

```
def buildGraph(K, D):
    X = tf.placeholder(tf.float64, shape=(None, D))
    mu = tf.Variable(tf.truncated_normal((K, D), mean=0, stddev=1, dtype=tf.float64), trainable=True)
    loss = tf.reduce_sum(tf.reduce_min(distance_func(X, mu), axis=1))
    optimizer = tf.train.AdamOptimizer(learning_rate=0.1, beta1=0.9, beta2=0.99, epsilon=1e-5).minimize(loss)
    return X, mu, loss, optimizer
```

```
def Train_K_means(dataset, K, epochs, valid_data):
   D = dataset.shape[1]
   X, mu, loss, optimizer = buildGraph(K, D)
   loss\_List = []
   best_mu = None
   cluster = None
   valid_loss = None
   with tf. Session() as sess:
           sess.run(tf.global_variables_initializer())
           for i in range (epochs):
                   best_mu, opt = sess.run([mu, optimizer], feed_dict={X: dataset})
                   Loss = sess.run(loss, feed_dict={X: dataset})
                   loss_List.append(Loss/dataset.shape[0])
           # end of traning find cluster
           # Returns the index with the smallest value across axes of a tensor
           cluster = sess.run(tf.argmin(distance_func(X, best_mu), 1),feed_dict={X:dataset})
           # end of training find validation loss
           valid_loss = sess.run(loss, feed_dict={X: valid_data})
           valid_loss = valid_loss/valid_data.shape[0]
   return loss_List, best_mu, cluster, valid_loss
```

```
def plot_loss(train, valid = None):
    iterations = range(len(train))
   print("train_loss is ", train[-1])
   plt.plot(iterations, train, label = "training")
   if(valid):
        print("valid_loss is ", valid[-1])
       plt.plot(iterations, valid, label = "validation")
   plt. xlabel ("Epoch")
   plt.ylabel("Loss")
   plt.legend()
   plt.title('Loss vs epoch')
   plt.show()
   return
def Q1():
   data = load_dataset(True)
    loss_List, best_mu, cluster, valid_loss = Train_K_means(data, 3, 200, data)
   plot_loss(loss_List)
   return
```

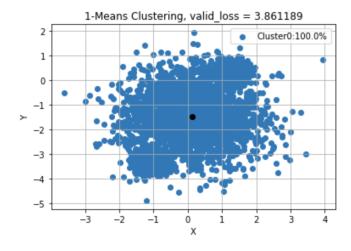
train_loss is 0.511094537291807

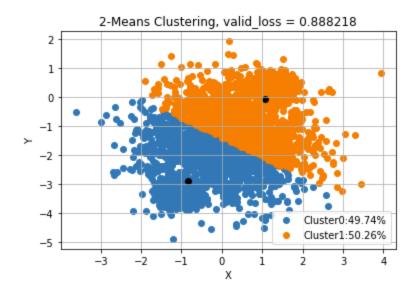


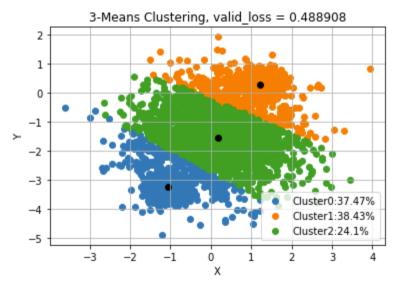
```
def plot_cluster(K, dataset, cluster, mu, valid_loss):
    legend = []
    for i in range(K):
       class i=[]
       for j in range(len(cluster)):
           if (cluster[j]==i):
               class i.append(dataset[j,:])
       class_i = np.array(class_i)
       plt.scatter(class_i[:, 0], class_i[:, 1], cmap='Pastel')
       #calculate number of data belongs to cluster
       percentage = str(round(100*np.sum(i==cluster)/len(cluster), 2))
       legend. append("Cluster"+str(i)+":"+percentage+"%")
    plt. legend (legend)
    plt.scatter(mu[:, 0], mu[:, 1], c='black')
    plt.title("%d-Means Clustering, valid_loss = %f" %(K, valid_loss))
    plt.xlabel('X')
   plt.ylabel('Y')
    plt.grid()
    plt.show()
    return
```

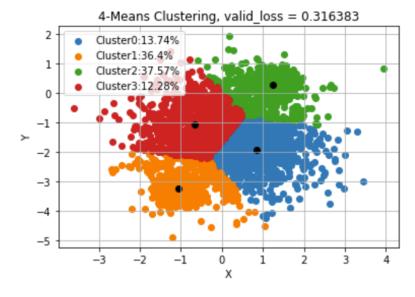
```
def Q2():
    K_list = [1,2,3,4,5]
    for K in K_list:
        data, val_data = load_dataset(True, True)
        loss_List, best_mu, cluster, valid_loss = Train_K_means(data, K, 100, val_data)
        plot_cluster(K, data, cluster, best_mu, valid_loss)
    return
```

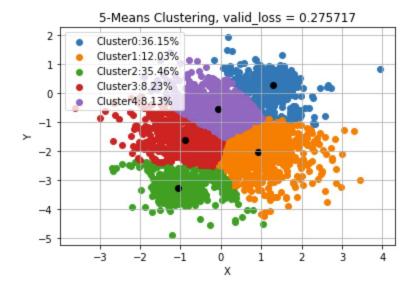
Plot











From the figures above,

Number of Cluster - K	Validation Loss
1	3.861
2	0.888
3	0.488
4	0.316
5	0.275

The minimum validation loss achieved here is when K=5, validation loss = 0.275

The validation loss decreases as K increase.

However, it doesn't make sense to divide the dataset into too many clusters.

The validation loss decreases drastically as K increase from 1 to 3, the validation loss drops 3.4.

The validation loss decreases much slower when increase K from 3 to 5, the validation loss drops 2.1.

Thus, I think K = 3 is the optimal number of clusters.

2. Mixtures of Gaussians

2.1 Gaussian cluster mode

1)

$$N(x, \mu k, \delta k) = \frac{1}{\delta k \sqrt{2\pi}} \exp\left(-\frac{1}{2} \left(\frac{x - \mu k}{\delta k}\right)^{2}\right)$$
$$\log(N(x, \mu k, \delta k)) = -\log(\delta k \sqrt{2\pi}) - \frac{1}{2} \left(\frac{x - \mu k}{\delta k}\right)^{2}$$
$$= -\frac{1}{2} \log(2\pi \delta k^{2}) - \frac{1}{2} \left(\frac{x - \mu k}{\delta k}\right)^{2}$$

2)

$$P(z|x) = \frac{P(x|z)P(z)}{\sum_{i}^{k} P(x|i)P(i)}$$

$$log P(z|x) = log (P(x|z)P(z)) - log (\sum_{i}^{k} P(x|i)P(i))$$

$$= log P(x|z) + P(z) - log (\sum_{i}^{k} P(x|i)P(i))$$

$$= log P(x|z) + P(z) - log (\sum_{i}^{k} exp(log P(x|i) + log P(i)))$$

```
def log_posterior(log_PDF, log_pi):
    """ Inputs:
        log_PDF: log Gaussian PDF N X K
        log_pi: K X 1

    Outputs
        log_post: N X K

"""

log_numerator = log_PDF + tf.squeeze(log_pi)
    log_denominator = reduce_logsumexp(log_numerator, keep_dims=True)
    answer = log_numerator - log_denominator
    return answer
```

The reason to use reduce logsumexp since we need to compute

$$\log \left(\sum_{i}^{k} \exp(\log P(x|i) + \log P(i)\right)\right)$$

while tf. reduce sum only compute the sum

2.2 Learning the MoG

1)

```
def buildGraph(K,D):
    #define variables
    X = tf.placeholder(tf.float32, shape=(None,D))
    mu = tf.Variable(tf.random_normal([K, D], stddev = 1))
    # theta is unconstrained parameter, sigma = exp(phi) with [0 - inf]
    theta = tf.Variable(tf.random_normal([K, 1], stddev = 1))
    sigma = tf.exp(theta)

# phi is unconstrained parameter, acheive constraint for pi
    phi = tf.Variable(tf.random_normal([K, 1], stddev = 1))
    log_pi = logsoftmax(phi)

log_pdf = log_gauss_pdf(X, mu, sigma)

#defien loss & optimizer
    loss= - tf.reduce_sum(reduce_logsumexp(log_pdf + tf.squeeze(log_pi), keep_dims=True))
    optimizer = tf.train.AdamOptimizer(learning_rate=0.1, beta1=0.9, beta2=0.99, epsilon=1e-5).minimize(loss)
    return X, mu, sigma, optimizer, loss, log_pdf, log_pi
```

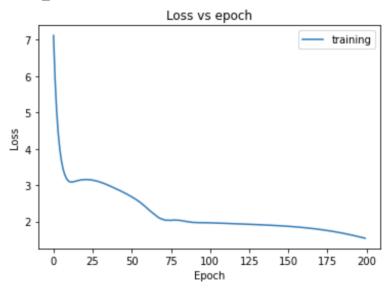
```
def Train GMM means (dataset, K, epochs, valid data):
   D = dataset.shape[1]
   X, mu, sigma, optimizer, loss, log_pdf, log_pi = buildGraph(K, D)
   loss_List = []
   best_mu = None
   best_sigma = None
   cluster = None
   valid_loss = None
   with tf. Session() as sess:
           sess.run(tf.global variables initializer())
           for i in range (epochs):
                  best_mu, best_sigma, opt = sess.run([mu, sigma, optimizer], feed_dict={X: dataset})
                  Loss = sess.run(loss, feed_dict={X: dataset})
                  loss_List.append(Loss/dataset.shape[0])
           # end of traning find cluster
           # Returns the index with the smallest value across axes of a tensor
           cluster = sess.run(tf.argmax(log_posterior(log_pdf,log_pi),1),feed_dict={X:dataset})
           # end of training find validation loss
           valid_loss = sess.run(loss, feed_dict={X: valid_data})
           valid_loss = valid_loss/valid_data.shape[0]
```

return loss_List, best_mu, best_sigma, cluster, valid_loss

```
def Q1():
    data = load_dataset(True)
    loss_List, best_mu, best_sigma, cluster, valid_loss = Train_GMM_means(data, 3, 200, data)
    plot_loss(loss_List)
    print("best_mu:", best_mu)
    print("best_sigma", best_sigma)
    return
```

Plot Loss:

train_loss is 1.53743203125

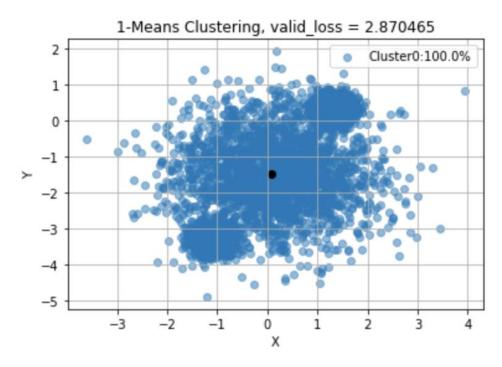


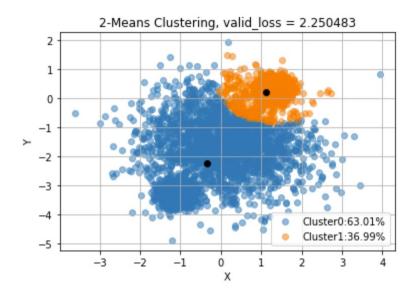
Model Parameter:

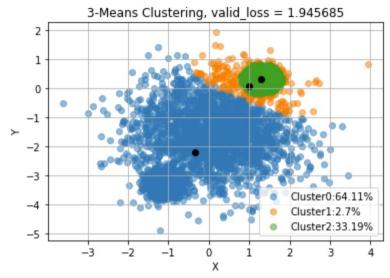
Cluster K	Log pi	mu	Sigma
1	-1.0067024	[0.05538136 -1.6027924]	2.9715424
2	-1.1738701	[-1.1191827 -3.316661]	0.07645379
3	-1.1226696	[1.3025047 0.31507367]	0.09755903

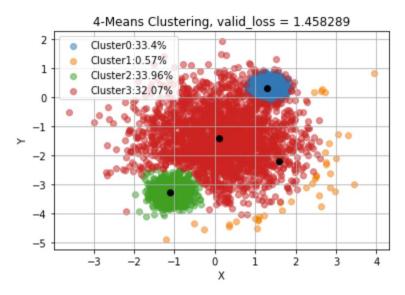
2)

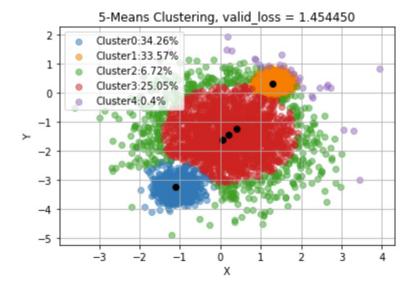
```
def Q2():
    K_list = [1,2,3,4,5]
    for K in K_list:
        data, val_data = load_dataset(True, True)
        loss_List, best_mu, best_sigma, best_pi, cluster, valid_loss = Train_GMM_means(data, K, 100, val_data)
        plot_cluster(K, data, cluster, best_mu, valid_loss)
    return
```











From the figures above,

Number of Cluster - K	Validation Loss
1	2.87
2	2.25
3	1.945
4	1.458
5	1.454

The minimum validation loss achieved here is when K=5, validation loss = 1.454

The validation loss decreases as K increase.

However, it doesn't make sense to divide the dataset into too many clusters.

The validation loss decreases drastically as K increase from 1 to 3, the validation loss drops 0.93.

The validation loss decreases much slower when increase K from 3 to 5, the validation loss drops 0.39.

Thus, I think K = 3 is the optimal number of clusters.

3) Compare K-means and MoG

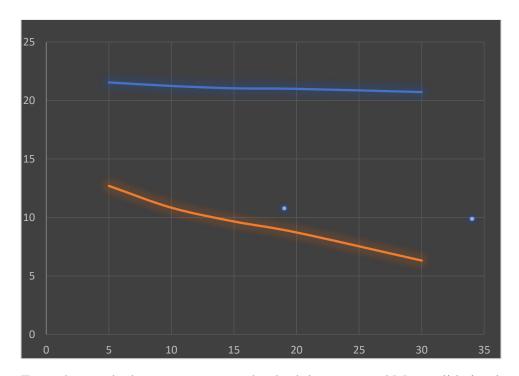
K	k-means Validation Loss	MoG Validation Loss
5	21.54334444037717	12.697508813381338
10	21.24050911505024	10.834202951545155
15	21.042035154237134	9.654315040879087
20	20.992872165406673	8.715772553817882
30	20.71745446427862	6.316014218609361

The minimum validation loss for both k-means and MoG achieved here is when K=30.

k-means validation loss = 20.717 MoG validation loss = 6.316

The validation loss for both k-means and MoG decreases as K increase.

However, increase in K post more effect on MoG algorithm, since its validation loss decrease more rapidly comparing to the validation loss for k-means as K increase.



From the graph above , we can see that both k-means and Mog validation loss decrease with a steady rate as K increase thus, I think K=30 is the optimal number of clusters.