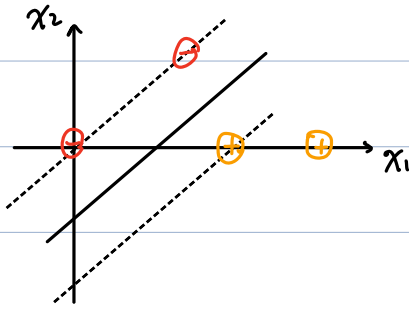


# Lec 28 Lagrange Dual Formulation of SVM

## Recap: SVM



### ↳ Fact (optional)

$$E_{\text{out}} \approx E_{\text{cross validation}} \leq \frac{\# \text{ support vectors}}{N}$$

### ↳ Original formulation:

$$\min_{\underline{w}, b} \frac{1}{2} \underline{w}^T \underline{w} \quad \text{s.t.} \quad y_n (\underline{w}^T \underline{x}_n + b) \geq 1, \quad n=1, \dots, N$$

"primal problem"

## 1. Lagrange Dual Formulation of SVM (ch 8.2)

### ↳ Lagrange function:

$$\mathcal{L}(\underline{w}, b, \underline{\alpha}) = \frac{1}{2} \underline{w}^T \underline{w} - \underbrace{\sum_{n=1}^N \alpha_n (y_n (\underline{w}^T \underline{x}_n + b) - 1)}_{\text{penalty for constraints violation}},$$

for  $\underline{\alpha}_1, \dots, \underline{\alpha}_N \geq 0$

"dual variables" / "Lagrange Multiplier"

↳ Fact: Primal problem is convex

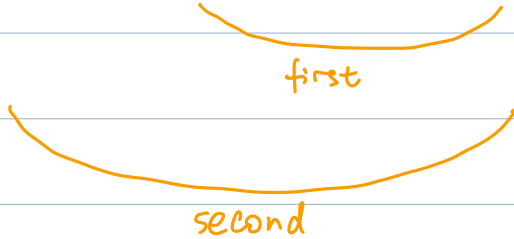
Mild cond.

⇒ "strong duality" property

i.e. optimal solution to primal problem



$$\max_{\{\alpha_n \geq 0\}} \min_{\underline{w}, b} \mathcal{L}(\underline{w}, b, \underline{\alpha})$$



unconstrained  
optimization

↳ steps:

$$\textcircled{1} \nabla_{\underline{w}} \mathcal{L}(\underline{w}, b, \underline{\alpha}) = 0$$

$$\Rightarrow \underline{w} - \sum_{n=1}^N \alpha_n y_n \underline{x}_n = 0$$

$$\Rightarrow \underline{w} = \sum_{n=1}^N \alpha_n y_n \underline{x}_n$$

$$\frac{\partial \mathcal{L}(\underline{w}, b, \underline{\alpha})}{\partial b} = 0 \Rightarrow \sum_{n=1}^N \alpha_n y_n = 0$$

$$\begin{aligned} \Rightarrow \mathcal{L}(\underline{w}, b, \underline{\alpha}) &= \frac{1}{2} \underline{w}^T \underline{w} - \underline{w}^T \underline{w} + \sum_{n=1}^N \alpha_n \\ &= -\frac{1}{2} \underline{w}^T \underline{w} + \sum_{n=1}^N \alpha_n \end{aligned}$$

$$\therefore \mathcal{L}(\underline{\alpha}) = -\frac{1}{2} \sum_{n=1}^N \sum_{m=1}^N \alpha_n \alpha_m y_n y_m \underline{x}_n^T \underline{x}_m + \sum_{n=1}^N \alpha_n$$

↑  
remove dependency of  $\underline{w}, b$

$$\textcircled{2} \max \mathcal{L}(\underline{\alpha}) \quad \text{s.t.} \quad \alpha_n \geq 0, \quad n=1, 2, \dots, N \quad \text{"Dual problem"}$$

$$\sum_{n=1}^N \alpha_n y_n = 0 \quad \text{"Another inner constraints"}$$

This is also a QP problem

$$J(\underline{\alpha}) = \frac{1}{2} \underline{\alpha}^T Q \underline{\alpha} + \underline{p}^T \underline{\alpha}$$

$$Q = \begin{bmatrix} y_1 y_1 \underline{x}_1^T \underline{x}_1 & y_1 y_2 \underline{x}_1^T \underline{x}_2 & \dots & y_1 y_N \underline{x}_1^T \underline{x}_N \\ \vdots & & & \\ \vdots & & & \\ y_N y_1 \underline{x}_N^T \underline{x}_1 & \dots & & y_N y_N \underline{x}_N^T \underline{x}_N \end{bmatrix}, \in \mathbb{R}^{N \times N}$$

$$\underline{p} = \begin{bmatrix} -1 \\ \vdots \\ -1 \end{bmatrix}$$

constraints: linear

↳ if  $\underline{\alpha}^*$  is an optimal solution to the dual problem, then

$$\underline{w}^* = \sum_{n=1}^N \alpha_n^* y_n \underline{x}_n$$

↳ How to find b?

• One the KKT conditions

• At optimum, we must have:

$$\alpha_n (y_n (\underline{w}^T \underline{x}_n + b) - 1) = 0, \forall n$$

(penalty = 0)

$$\therefore \text{either } \alpha_n = 0 \text{ or } y_n (\underline{w}^T \underline{x}_n + b) - 1 = 0$$

• If  $\alpha_n \neq 0$ , then  $\underline{x}_n$  is a point on the margin

i.e. is a support vector

• If  $\alpha_n = 0$ , then  $\underline{x}_n$  does not affect  $\underline{w}$ .

and  $(\underline{x}_n, y_n)$  can be removed from  $\mathcal{D}$  w/out changing the sol.

• To find  $b^*$ , pick any support vector  $(\underline{x}_s, y_s)$  s.t

$$y_s (\underline{w}^T \underline{x}_s + b) = 1$$

$$\because y_s \in \{+1, -1\} \quad \therefore \frac{1}{y_s} = y_s$$

$$\therefore b = y_s - \underline{w}^T \underline{x}_s = y_s - \sum_{n=1}^N y_n \alpha_n \underline{x}_n^T \underline{x}_s$$