Classification

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Content

- Classification Problem
- 2 The Perceptron
- Newton's Method

Suppose we want to build an email spam classification software:

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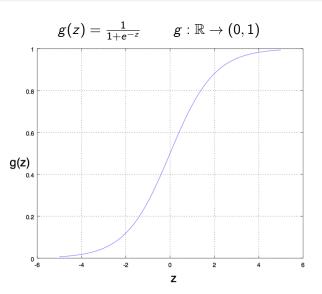
Hello

I want to know about different topics that relate to qualitative reinforcement learning and make abstraction&aggregation... to solve problem compactly . I have read some survey to know exactly but sometimes I doubt about some topics are related to or not. for example Qualitative Spatial Representation and Reasoning. can anyone tell me different categorized topics? I need to know the general classification of them.

...

- Classification is the same as regression, the only difference is that the output variable *y* can take only a small number of discrete values.
- The most simple classification problem is the binary classification, in which $y = \{0, 1\}$.
- In a binary classification problem we have positive examples y=1 (spam) and negative examples y=0 (no spam).
- The x may be some features of some piece of email.

- We could approach the classification problem ignoring the fact that y is a discrete value, and use linear regression to try to predict y given x.
- However, it is easy to construct examples showing this method to perform very badly.
- Intuitively, it does not make sense for $h_{\theta} = (\mathbf{x})$ to take values larger than 1 or smaller than 0, when we know that $y \in \{0,1\}$
- To fix this we will make $h_{\theta}(\mathbf{x}) = g(\theta^{\top}\mathbf{x}) = \frac{1}{1+e^{-\theta^{\top}\mathbf{x}}}$
- where $g(z) = \frac{1}{1 + e^{-z}}$



Derivative of the Sigmoid Function

$$g'(z) = \frac{d}{dz} \frac{1}{1+e^{-z}}$$

$$= -\frac{1}{(1+e^{-z})^2} \cdot (-e^{-z})$$

$$= \frac{1}{(1+e^{-z})^2} \cdot e^{-z}$$

$$= \frac{1}{(1+e^{-z})} \cdot \frac{e^{-z}}{(1+e^{-z})}$$

$$= \frac{1}{(1+e^{-z})} \cdot \frac{e^{-z}+1-1}{(1+e^{-z})}$$

$$= \frac{1}{(1+e^{-z})} \cdot \left(\frac{(1+e^{-z})}{(1+e^{-z})} - \frac{1}{(1+e^{-z})}\right)$$

$$= g(z)(1-g(z)).$$

A Probabilistic Approach

Lets assume that:

$$P(y = 1|x; \theta) = h_{\theta}(x)$$

$$P(y = 0|x; \theta) = 1 - h_{\theta}(x)$$

Note that this can be written more compactly as:

$$p(y|x;\theta) = (h_{\theta}(x))^{y}(1 - h_{\theta}(x))^{1-y}$$



Likelihood of the Training Data's Labels

Assuming that the m training examples were generated independently, we can then write:

$$L(\theta) = p(\mathbf{y}|\mathbf{X}; \theta)$$

$$= \prod_{i=1}^{m} p(y_i|\mathbf{x}_i; \theta)$$

$$= \prod_{i=1}^{m} (h_{\theta}(x_i))^{y_i} (1 - h_{\theta}(x_i))^{1-y_i}$$

Log Likelihood

$$L(\theta) = \prod_{i=1}^{m} (h_{\theta}(x_i))^{y_i} (1 - h_{\theta}(x_i))^{1 - y_i}$$

Working instead with the log likelihood:

$$\ell(\theta) = \log L(\theta)$$

$$= \sum_{i=1}^{m} y_i \log h(x_i) + (1 - y_i) \log(1 - h(x_i))$$

Using gradient ascent we get an update rule like this:

$$\theta := \theta + \alpha \nabla_{\theta} \ell(\theta)$$

Maximizing the Likelihood

Working with one example, the derivatives are as follows:

$$\frac{\partial}{\partial \theta_{j}} \ell(\theta) = \frac{\partial}{\partial \theta_{j}} \left[y \log h(\mathbf{x}) + (1 - y) \log(1 - h(\mathbf{x})) \right] \\
= \frac{\partial}{\partial \theta_{j}} \left[y \log g(\theta^{\top} \mathbf{x}) + (1 - y) \log(1 - g(\theta^{\top} \mathbf{x})) \right] \\
= \left(y \frac{1}{g(\theta^{\top} \mathbf{x})} - (1 - y) \frac{1}{1 - g(\theta^{\top} \mathbf{x})} \right) \frac{\partial}{\partial \theta_{j}} g(\theta^{\top} \mathbf{x}) \\
= \left(y \frac{1}{g(\theta^{\top} \mathbf{x})} - (1 - y) \frac{1}{1 - g(\theta^{\top} \mathbf{x})} \right) g(\theta^{\top} \mathbf{x}) \left(1 - g(\theta^{\top} \mathbf{x}) \right) \frac{\partial}{\partial \theta_{j}} \theta^{\top} \mathbf{x} \\
= \left(y (1 - g(\theta^{\top} \mathbf{x})) - (1 - y) g(\theta^{\top} \mathbf{x}) \right) x_{j} \\
= (y - h_{\theta}(\mathbf{x})) x_{j}$$

The LMS Update Rule for Classification

Given that:

$$\frac{\partial}{\partial \theta_i} \ell(\theta) = (y - h_{\theta}(\mathbf{x})) x_j,$$

our LMS update rule for classification can be written as:

$$\theta_j := \theta_j + \alpha(y_i - h_\theta(\mathbf{x}_i))(x_i)_j$$

where $h_{\theta}(\mathbf{x}_i) = g(\theta^{\top}\mathbf{x}_i) = \frac{1}{1+e^{(-\theta^{\top}\mathbf{x}_i)}}$ is now defined as a non-linear function of $\theta^{\top}\mathbf{x}_i$.

So, we end up with the same update rule for a different algorithm and learning problem.

12/22

LMS Algorithms for Classification

Batch Gradient Descent

```
Repeat until convergence { \theta_j := \theta_j + \alpha \sum_{i=1}^m \left[ y_i - g(\theta^\top x_i) \right] (x_i)_j \qquad \text{(for every } j\text{)}. }
```

Stochastic Gradient Descent

```
Loop \{ for i=1 to m \{ \theta_j:=\theta_j+lphaig[y_i-g(	heta^	op x_i)ig](x_i)_j (for every j). \}
```

LMS Algorithms for Classification

Mini-Batch Gradient Descent

```
Repeat until convergence { \theta_j := \theta_j + \alpha \sum_{i=1}^k \left[ y_i - h_\theta(x_i) \right] (x_i)_j \qquad \text{(for every $j$)}. }
```

Here we use mini-batches containing 10 to 1000 examples. This is $k \in [10, 1000]$.

Dr. Víctor Uc Cetina Classification Universität Hamburg 14 / 22

Error of a Binary Classifier (1/2)

True Positive = A positive example correctly identified as positive.

False Positive = A negative example incorrectly identified as positive.

True Negative = A negative example correctly identified as negative.

False Negative = A positive example incorrectly identified as negative.

Dr. Víctor Uc Cetina Universität Hamburg 15 / 22

Error of a Binary Classifier (2/2)

Precision

It answers the question: How many of the examples identified as positives are indeed positives?

Precision =
$$\frac{TP}{TP+FP}$$
.

Recall (Sensitivity)

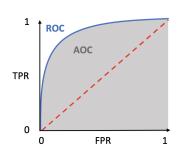
It answers the question: How many of the positive examples were correctly identified as positive?

Recall
$$= \frac{TP}{P} = \frac{TP}{TP + FN}$$
.

Receiver Operating Characteristic (ROC) curve

The Receiver Operating Characteristic curve is a graph showing the performance of a binary classifier with all the classification thresholds.

It shows two parameters: the true positive rate (TPR) and the false positive rate (FPR).



$$TPR = Recall = Sensitivity = \frac{TP}{TP + FN}$$

$$Specificity = \frac{TN}{FP+TN}$$

$$\mathit{FPR} = \frac{\mathit{FP}}{\mathit{FP} + \mathit{TN}} = 1$$
 - specificity

AOC = Area under the ROC curve.

17/22

The Perceptron Learning Algorithm

Consider modifying the logistic regression to output either 1 or 0:

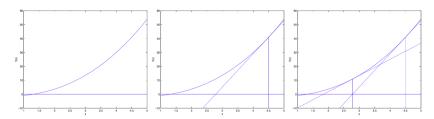
$$g(\mathbf{z}) = \begin{cases} 1 & \text{if } \mathbf{z} \ge 0 \\ 0 & \text{if } \mathbf{z} < 0 \end{cases}$$

By making $h_{\theta}(x) = g(\theta^{\top} \mathbf{x})$, then we have the update rule:

$$\theta_j := \theta_j + \alpha(y_i - h_\theta(x_i))(x_i)_j.$$

Newton's Method for Finding a Zero of a function

Suppose we have a function $f : \mathbb{R} \to \mathbb{R}$ and we want to find a value of θ such that $f(\theta) = 0$, with $\theta \in \mathbb{R}$.



Newton's method performs the following update rule:

$$\theta := \theta - \frac{f(\theta)}{f'(\theta)}.$$

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Newton's Method for Finding a Zero of a function

Now, suppose we want to maximize a function ℓ . The maxima of ℓ correspond to points where its first derivative $\ell'(\theta)$ is zero.

So, by letting $f(\theta) = \ell'(\theta)$, we can use the same algorithm to maximize ℓ :

$$\theta := \theta - \frac{\ell'(\theta)}{\ell''(\theta)}.$$

20 / 22

Newton-Raphson Method

In our regression setting θ is vector-valued. The generalization of Newton's method to this multidimensional setting is given by

$$\theta := \theta - H^{-1} \nabla_{\theta} \ell(\theta),$$

where H is the Hessian matrix

$$H_{ij} = \frac{\partial^2 \ell(\theta)}{\partial \theta_i \partial \theta_j}.$$

Thank you!

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