CSC 261/461
Database Systems

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Hashing Indexes

Hashes

- a *hash* function $h : K \rightarrow \{0, \ldots, B-1\}$ taking the key as argument, where B is the number of buckets.
- A *bucket* array indexed from 0 to $B-1$, holds the headers of B linked lists, one for each bucket of the array.
- If a record has search key K, store the record by linking it to the bucket list for the bucket numbered $h(K)$.

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Secondary-Storage Hashes

- A very large number of records must be kept *mainly* in secondary storage
- the bucket array consists of blocks, rather than pointers to the headers of lists.
- Records that hash to a certain bucket are put in the block for that bucket.
- If a bucket has too many records, a chain of overflow blocks can be added.
- a main-memory array of pointers to blocks indexed by the bucket number may be stored in main memory.

[1]

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Dynamic Hashing

- Most databases grow larger over time. If we are to use static hashing for such a database, we have three classes of options:
  1. Choose a hash function based on the current file size.
  2. Choose a hash function based on the anticipated size of the file at some point in the future.
  3. Periodically reorganize the hash structure in response to file growth.

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Extensible Hash Tables

- There is a level of indirection for the buckets, array of pointers.
- The array of pointers can grow, but always a power of 2.
- certain buckets can share a block if the total number of records in those buckets can fit.
- The hash function computes for each key a sequence of k bits for some large k.
- the bucket numbers use some smaller number of bits, say i bits

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Extensible Hash Tables Example