# CSC449, HW#2, Kefu Zhu

#### 1. Use of dev dataset

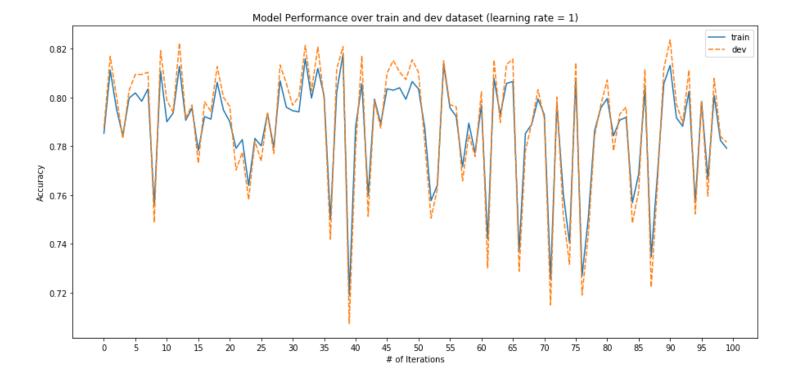
Since the I did not tune the learning rate in this assignment and I am using the SGD method to find the optimal weight vector, some updates during the interation can potentially overshoot the local minima of the cost function.

Therefore, I treat the weight vector (model) from each iteration as separate models and created a variable best\_weights to keep track the best weight vector that has been computed so far based on the test performance on dev dataset.

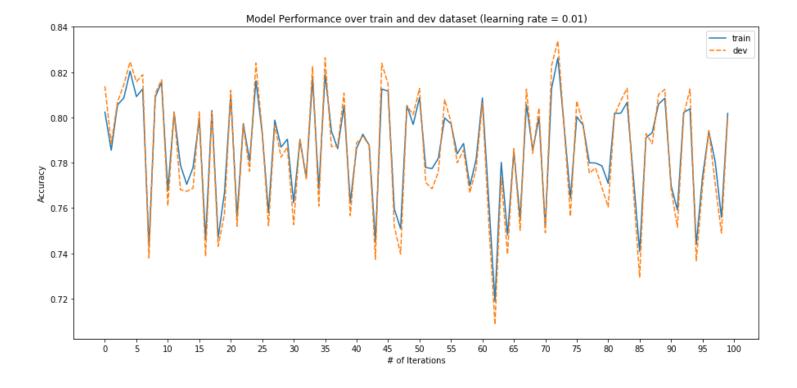
Rather than outputing the weight vector that results from the last iteration, I will return the best weight vector among all iterations when -nodev is not provided.

## 2. Model Training

As shown in the graph below, we can clearly see the model accuracy on both the train dataset and the dev dataset flunctuate a lot through the iterations, which also proves that the update is clearly overshooting a lot during the interation



After changing the learning rate from 1 to 0.01, the problem of overshooting is still significant. However, if we pay attention to the y-axis, we are able to reach higher accuracy than before.



### 3. Appendix

#### model performance: Function used to produce the model performance grpah

```
import pandas as pd
2
    import seaborn as sns
    import matplotlib.pyplot as plt
    def model_performance(learning_rate,train_xs,train_ys,dev_xs,dev_ys):
        # Initialize weight vector to be all zeros
        weights = np.zeros(NUM_FEATURES)
        # Initialize a dataframe to record model performance on train and dev dataset
        df = pd.DataFrame(columns=['iter_num', 'train_accuracy', 'dev_accuracy'], dtype=
10
11
        # Track the number of iterations
12
13
        num_iter = 0
        # Record the current number of iteration and model performance
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15
        df.loc[num_iter,'iter_num'] = num_iter
        df.loc[num_iter,'train_accuracy'] = test_accuracy(weights, train_ys, train_xs)
16
17
        df.loc[num_iter,'dev_accuracy'] = test_accuracy(weights, dev_ys, dev_xs)
        # While the number of iteractions does not go beyond the maximum
        while num_iter < 100:</pre>
            # # Make a deep copy of weight vector before next iteration
20
```

```
# old_weights = np.array([w for w in weights])
21
            # Loop through each pair of (x,y) in the training dataset
23
            for x,y in zip(train_xs,train_ys):
                # Classify current data point based on current weights
24
                y_hat = np.sign(np.dot(np.transpose(weights),x))
25
26
                # If we classify incorrectly
                if y_hat!=y:
28
                    # Update the weight vector
29
                    weights = np.add(weights,np.array(learning_rate*y*x))
30
            # Record the current number of iteration and model performance
32
            df.loc[num_iter,'iter_num'] = num_iter
            df.loc[num_iter,'train_accuracy'] = test_accuracy(weights, train_ys, train
34
            df.loc[num_iter,'dev_accuracy'] = test_accuracy(weights, dev_ys, dev_xs)
35
36
            # Increment the number of iteraction
            num iter += 1
            # Print the progress
            if 100 <= 10: #
39
40
                print('# of iterations: {}'.format(num_iter))
            else:
42
                if num_iter % round(100/10) == 0:
                    print('# of iterations: {}'.format(num_iter))
44
        return df
```