

CSC 261/461

Query Processing

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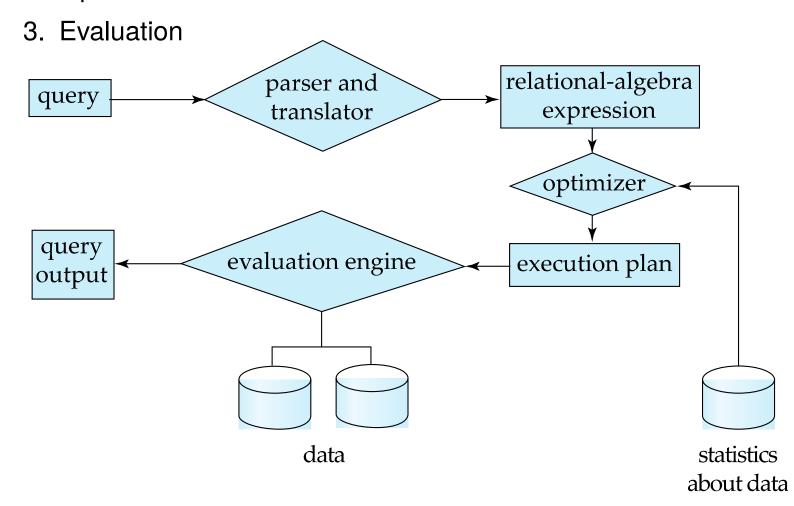
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Basic Steps in Query Processing

- 1. Parsing and translation
- 2. Optimization





Basic Steps in Query Processing (Cont.)

- Parsing and translation
 - translate the query into its internal form. This is then translated into relational algebra.
 - Parser checks syntax, verifies relations
- Evaluation
 - The query-execution engine takes a query-evaluation plan, executes that plan, and returns the answers to the query.



Basic Steps in Query Processing: Optimization

- A relational algebra expression may have many equivalent expressions
 - E.g., $\sigma_{salary < 75000}(\Pi_{salary}(instructor))$ is equivalent to $\Pi_{salary}(\sigma_{salary < 75000}(instructor))$
- Each relational algebra operation can be evaluated using one of several different algorithms
- An RA operation annotated with instructions on how to evaluate it is called an evaluation primitive.
- Annotated expression specifying detailed evaluation strategy is called an evaluation-plan.
 - E.g., can use an index on salary to find instructors with salary < 75000,
 - or can perform complete relation scan and discard instructors with salary ≥ 75000



Figure 12.02

```
\pi_{salary}
    \sigma salary < 75000; use index 1
instructor
```



Measures of Query Cost

- Cost is generally measured as total elapsed time for answering query
 - Many factors contribute to time cost
 - disk accesses, CPU, or even network communication
- Typically disk access is the predominant cost, and is also relatively easy to estimate. Measured by taking into account
 - Number of seeks

- * average-seek-cost
- Number of blocks read * average-block-read-cost
- Number of blocks written * average-block-write-cost
 - Cost to write a block is greater than cost to read a block
 - data is read back after being written to ensure that the write was successful



Measures of Query Cost (Cont.)

- For simplicity we just use the **number of block transfers** from disk and the **number of seeks** as the cost measures
 - t_T time to transfer one block
 - t_s time for one seek
 - Cost for b block transfers plus S seeks
 b * t_T + S * t_S
- We ignore CPU costs for simplicity
 - Real systems do take CPU cost into account
- We do not include cost to writing output to disk in our cost formulae



Selection Operation

- **■** File scan
- Algorithm A1 (linear search). Scan each file block and test all records to see whether they satisfy the selection condition.
 - Cost estimate = b_r block transfers + 1 seek
 - b_r denotes number of blocks containing records from relation r
 - If selection is on a key attribute, can stop on finding record
 - ightharpoonup cost = $(b_r/2)$ block transfers + 1 seek
 - Linear search can be applied regardless of
 - selection condition or
 - ordering of records in the file, or
 - availability of indices



Selections Using Indices

- Index scan search algorithms that use an index
 - selection condition must be on search-key of index.
- A2 (primary index, equality on key). Retrieve a single record that satisfies the corresponding equality condition
 - $Cost = (h_i + 1) * (t_T + t_S)$
- A3 (primary index, equality on nonkey) Retrieve multiple records.
 - Records will be on consecutive blocks.
 - Let b = number of blocks containing matching records
 - $Cost = h_i * (t_T + t_S) + t_T * b$



Selections Using Indices

- A4 (secondary index, equality on nonkey).
 - Retrieve a single record if the search-key is a candidate key
 - $Cost = (h_i + 1) * (t_T + t_S)$
 - Retrieve multiple records if search-key is not a candidate key
 - each of n matching records may be on a different block
 - Cost = $(h_i + n) * (t_T + t_S)$
 - Can be very expensive!



Selections Involving Comparisons

- Can implement selections of the form $\sigma_{A \leq V}(r)$ or $\sigma_{A \geq V}(r)$ by using
 - a linear file scan,
 - or by using indices in the following ways:
- A5 (primary index, comparison). (Relation is sorted on A)
 - For $\sigma_{A \ge V}(r)$ use index to find first tuple $\ge V$ and scan relation sequentially from there
 - For $\sigma_{A \leq V}(r)$ just scan relation sequentially till first tuple > V; do not use index
- A6 (secondary index, comparison).
 - For $\sigma_{A \ge V}(r)$ use index to find first index entry $\ge v$ and scan index sequentially from there, to find pointers to records.
 - For $\sigma_{A \leq V}(r)$ just scan leaf pages of index finding pointers to records, till first entry > V
 - In either case, retrieve records that are pointed to
 - requires an I/O for each record



Sorting

- We may build an index on the relation, and then use the index to read the relation in sorted order. May lead to one disk block access for each tuple.
- For relations that fit in memory, techniques like quicksort can be used. For relations that don't fit in memory, **external sort-merge** is a good choice.



External Sort-Merge

Let *M* denote memory size (in pages).

1. Create sorted runs. Let *i* be 0 initially.

Repeatedly do the following till the end of the relation:

- (a) Read *M* blocks of relation into memory
- (b) Sort the in-memory blocks
- (c) Write sorted data to run R_i ; increment i.

Let the final value of *i* be *N*

2. Merge the runs (next slide).....



External Sort-Merge (Cont.)

- **2.** Merge the runs (N-way merge). We assume (for now) that N < M.
 - Use N blocks of memory to buffer input runs, and 1 block to buffer output. Read the first block of each run into its buffer page

2. repeat

- Select the first record (in sort order) among all buffer pages
- 2. Write the record to the output buffer. If the output buffer is full write it to disk.
- Delete the record from its input buffer page.If the buffer page becomes empty then read the next block (if any) of the run into the buffer.
- 2. until all input buffer pages are empty:

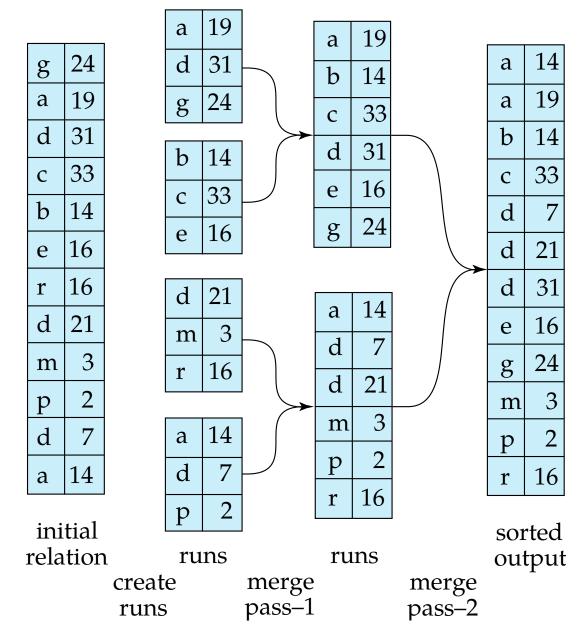


External Sort-Merge (Cont.)

- If $N \ge M$, several merge *passes* are required.
 - In each pass, contiguous groups of M 1 runs are merged.
 - A pass reduces the number of runs by a factor of M -1, and creates runs longer by the same factor.
 - ▶ E.g. If M=11, and there are 90 runs, one pass reduces the number of runs to 9, each 10 times the size of the initial runs
 - Repeated passes are performed till all runs have been merged into one.



Example: External Sorting Using Sort-Merge





Join Operation

- Several different algorithms to implement joins
 - Nested-loop join
 - Block nested-loop join
 - Indexed nested-loop join
 - Merge-join
 - Etc.
- Choice based on cost estimate
- Examples use the following information
 - Number of records of student: 5,000 takes: 10,000
 - Number of blocks of student: 100 takes: 400



Nested-Loop Join

- To compute the theta join $r \bowtie_{\theta} s$ for each tuple t_r in r do begin for each tuple t_s in s do begin test pair (t_r, t_s) to see if they satisfy the join condition θ if they do, add $t_r \cdot t_s$ to the result. end end
- \blacksquare r is called the **outer relation** and s the **inner relation** of the join.
- Requires no indices and can be used with any kind of join condition.
- Expensive since it examines every pair of tuples in the two relations.



Nested-Loop Join (Cont.)

In the worst case, if there is enough memory only to hold one block of each relation, the estimated cost is

$$n_r * b_s + b_r$$
 block transfers, plus $n_r + b_r$ seeks

- If the smaller relation fits entirely in memory, use that as the inner relation.
 - Reduces cost to $b_r + b_s$ block transfers and 2 seeks
- Assuming worst case memory availability cost estimate is
 - with student as outer relation:
 - \blacktriangleright 5000 * 400 + 100 = 2,000,100 block transfers,
 - ▶ 5000 + 100 = 5100 seeks
 - with takes as the outer relation
 - 10000 * 100 + 400 = 1,000,400 block transfers and 10,400 seeks
- If smaller relation (*student*) fits entirely in memory, the cost estimate will be 500 block transfers.
- Block nested-loops algorithm (next slide) is preferable.



Block Nested-Loop Join

Variant of nested-loop join in which every block of inner relation is paired with every block of outer relation.

```
for each block B_r of r do begin

for each block B_s of s do begin

for each tuple t_r in B_r do begin

for each tuple t_s in B_s do begin

Check if (t_r, t_s) satisfy the join condition

if they do, add t_r \cdot t_s to the result.

end

end

end
```



Block Nested-Loop Join (Cont.)

- Worst case estimate: $b_r * b_s + b_r$ block transfers + 2 * b_r seeks
 - Each block in the inner relation s is read once for each block in the outer relation
- Best case: $b_r + b_s$ block transfers + 2 seeks.



Indexed Nested-Loop Join

- Index lookups can replace file scans if
 - join is an equi-join or natural join and
 - an index is available on the inner relation's join attribute
 - Can construct an index just to compute a join.
- For each tuple t_r in the outer relation r, use the index to look up tuples in s that satisfy the join condition with tuple t_r .
- Worst case: buffer has space for only one page of r, and, for each tuple in r, we perform an index lookup on s.
- Cost of the join: $b_r(t_T + t_S) + n_r * c$
 - Where c is the cost of traversing index and fetching all matching s tuples for one tuple or r
 - c can be estimated as cost of a single selection on s using the join condition.
- If indices are available on join attributes of both r and s, use the relation with fewer tuples as the outer relation.



Example of Nested-Loop Join Costs

- \blacksquare Compute student \bowtie takes, with student as the outer relation.
- Let *takes* have a primary B+-tree index on the attribute *ID*, which contains 20 entries in each index node.
- Since takes has 10,000 tuples, the height of the tree is 4, and one more access is needed to find the actual data
- student has 5000 tuples
- Cost of block nested loops join
 - 400*100 + 100 = 40,100 block transfers + 2 * 100 = 200 seeks
 - assuming worst case memory
 - may be significantly less with more memory
- Cost of indexed nested loops join
 - 100 + 5000 * 5 = 25,100 block transfers and seeks.
 - CPU cost likely to be less than that for block nested loops join



Questions?

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