

CSC249/449 HW3, Kefu Zhu

3.1 Optimization of DCF:

Prove Equation (3) is the optimal solution for Equation (2)

Equation (2)

$$\epsilon = \frac{1}{MN} (\|\sum_{l=1}^D \Phi_l(x) \odot W_l^* - Y\|^2 + \lambda \sum_{l=1}^D \|W_l\|^2)$$

Equation (3)

$$W_l = \frac{\Phi_l(x) \odot Y^*}{\sum_{k=1}^D \Phi_k(x) \odot \Phi_k^*(x) + \lambda}$$

Answer:

From Equation (2), we can get

$$MN \cdot \epsilon = \text{tr} [(\sum_{l=1}^D \Phi_l(x) \odot W_l^* - Y)^H \cdot (\sum_{l=1}^D \Phi_l(x) \odot W_l^* - Y)] + \lambda \sum_{l=1}^D \text{tr}(W_l^H W_l)$$

Since MN is a constant, so the original loss function ϵ is proportional to $MN \cdot \epsilon$. We can then write

$$\begin{aligned} \epsilon &\propto \text{tr} [(\sum_{l=1}^D \Phi_l(x) \odot W_l^* - Y)^H \cdot (\sum_{l=1}^D \Phi_l(x) \odot W_l^* - Y)] + \lambda \sum_{l=1}^D \text{tr}(W_l^H W_l) \\ &\propto \text{tr} [(\sum_{l=1}^D \Phi_l(x)^H \odot W_l^T) \cdot (\sum_{l=1}^D \Phi_l(x) \odot W_l^*)] - \text{tr}[Y(\sum_{l=1}^D \Phi_l(x)^H \odot W_l^T)] - \text{tr}[Y^H(\sum_{l=1}^D \Phi_l(x) \odot W_l^*)] + \text{tr}(Y^H Y) + \lambda \sum_{l=1}^D \text{tr}(W_l^H W_l) \end{aligned}$$

To obtain the optimal value of W_l^* , we calculate the derivative of loss function with respect to W_l^* and set it to zero

$$\frac{\partial \epsilon}{\partial W_l^*} = 0 = [\sum_{l=1}^D \Phi_l(x)^H \odot W_l^T \cdot \Phi_l(x)] - Y^* \Phi_l(x) + \lambda W_l = [\sum_{l=1}^D \Phi_l(x)^H \odot \Phi_l(x) \cdot W_l] + \lambda W_l - \Phi_l(x) Y^*$$

By rearranging the equation, we can get Equation (3)

$$W_l = \frac{\Phi_l(x) \odot Y^*}{\sum_{k=1}^D \Phi_k(x) \odot \Phi_k^*(x) + \lambda}$$

3.2 Proving Parseval's theorem for 2-d DFT

First, we will try to prove Equation (24)

Equation (24)

$$(D_N \otimes D_M)^H (D_N \otimes D_M) = MNI$$

\therefore

$$D_N \otimes D_M = \begin{bmatrix} D_M^{11} D_N & \dots & D_M^{m1} D_N \\ \vdots & \ddots & \vdots \\ D_M^{1m} D_N & \dots & D_M^{mm} D_N \end{bmatrix}, \quad D_N^H \otimes D_M^H = \begin{bmatrix} (D_M^{11})^H D_N^H & \dots & (D_M^{m1})^H D_N^H \\ \vdots & \ddots & \vdots \\ (D_M^{1m})^H D_N^H & \dots & (D_M^{mm})^H D_N^H \end{bmatrix}$$

\therefore

$$(D_N \otimes D_M)^H (D_N \otimes D_M) = (D_N^H \otimes D_M^H) (D_N \otimes D_M)$$

$$\begin{aligned}
&= \begin{bmatrix} (D_M^{11})^H D_N^H & \dots & (D_M^{m1})^H D_N^H \\ \vdots & \ddots & \vdots \\ (D_M^{1m})^H D_N^H & \dots & (D_M^{mm})^H D_N^H \end{bmatrix} \begin{bmatrix} D_M^{11} D_N & \dots & D_M^{m1} D_N \\ \vdots & \ddots & \vdots \\ D_M^{1m} D_N & \dots & D_M^{mm} D_N \end{bmatrix} \\
&= \begin{bmatrix} ((D_M^{11})^H D_M^{11} + \dots) D_N^H D_N & \dots & ((D_M^{m1})^H D_M^{1m} + \dots) D_N^H D_N \\ \vdots & \ddots & \vdots \\ ((D_M^{1m})^H D_M^{m1} + \dots) D_N^H D_N & \dots & ((D_M^{mm})^H D_M^{mm} + \dots) D_N^H D_N \end{bmatrix} \\
&= (D_M^H D_M) \otimes (D_N^H D_N) = (MI) \otimes (NI) = MNI
\end{aligned}$$

Hence, we can use $\text{vec}(X) = (D_N \otimes D_M) \text{vec}(x)$ to write $\text{vec}(x)$ as

$$\text{vec}(x) = \mathcal{F}^{-1}(\text{vec}(X)) = (D_N \otimes D_M)^{-1} \text{vec}(X) = \frac{(D_N^H \otimes D_M^H) \text{vec}(X)}{MN}$$

We can then expand $\sum_{m=0}^{M-1} \sum_{n=0}^{N-1} |x[m, n]|^2$ as the following

$$\begin{aligned}
&\sum_{m=0}^{M-1} \sum_{n=0}^{N-1} |x[m, n]|^2 = \text{vec}(x)^T \text{vec}(x) \\
&= \left(\frac{(D_N^H \otimes D_M^H) \text{vec}(X)}{MN} \right)^T \left(\frac{(D_N^H \otimes D_M^H) \text{vec}(X)}{MN} \right) \\
&= \frac{1}{M^2 N^2} \cdot (\text{vec}(X)^T \text{vec}(X)) \cdot [(D_N^H \otimes D_M^H)(D_N \otimes D_M)] \\
&= \frac{1}{M^2 N^2} \cdot (\text{vec}(X)^T \text{vec}(X)) \cdot MN \\
&= \frac{1}{MN} \cdot (\text{vec}(X)^T \text{vec}(X)) \\
&\because \frac{1}{MN} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} |X[m, n]|^2 = \frac{1}{MN} \cdot (\text{vec}(X)^T \text{vec}(X)) \\
&\therefore \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} |x[m, n]|^2 = \frac{1}{MN} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} |X[m, n]|^2
\end{aligned}$$