

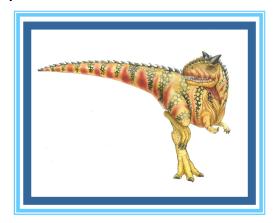


# Teoría de Sistemas Operativos

ELO 321 - Clase 01

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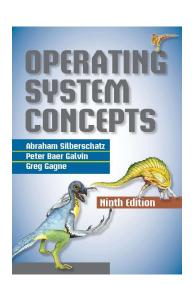
08 de septiembre, 2020, Valparaíso, Chile



#### **Course Information**

- Evaluation
  - □ 2 Certamenes (75%) y 2 tareas (homework) (25%)...
- Course book: A. Silberschatz, P. Galvin, y G. Gagne (2012). *Operating System Concepts*, Wiley, 9th Ed. (<a href="http://www.os-book.com">http://www.os-book.com</a>)









#### **Course Objectives**

- ☐ Explain what operating systems are, what they do, and how they are designed and constructed.
- Contents are organized as follows:
  - Process management. Describe the process concept and concurrency as the heart of modern operating systems. A process is the unit of work in a system. Cover methods for process scheduling, inter-process communication, process synchronization, etc.
  - Memory management. Management of main memory during the execution of a process. There are many different memory-management schemes, reflecting various approaches to memory management
  - Storage management. Describe how the *file system and I/O* are handled in a modern computer system. We describe the classic internal algorithms and structures of storage management and provide a firm practical understanding of the *algorithms* used—their *properties*, *advantages*, and *disadvantages*.
  - Protection and security...





#### **Chapter 1: Introduction**

- What Operating Systems Do
- Computer-System Organization
- Computer-System Architecture
- Operating-System Structure
- Operating-System Operations
- Process Management
- Memory Management
- Storage Management
- Protection and Security
- Kernel Data Structures

#### **Objectives**

- ☐ To describe the *basic organization of computer systems*
- To provide a grand tour of the major components of operating systems





## What is an Operating System?

- □ An operating system is a program that manages a computer's hardware.
  - It provides a basis for application programs
  - It acts as an intermediary between the user and the hardware.
- □ Some operating systems are designed to be convenient, others to be efficient, and others to be some combination of the two.
- Next we provide a general overview of the major components of a contemporary computer system as well as the functions provided by the operating system.





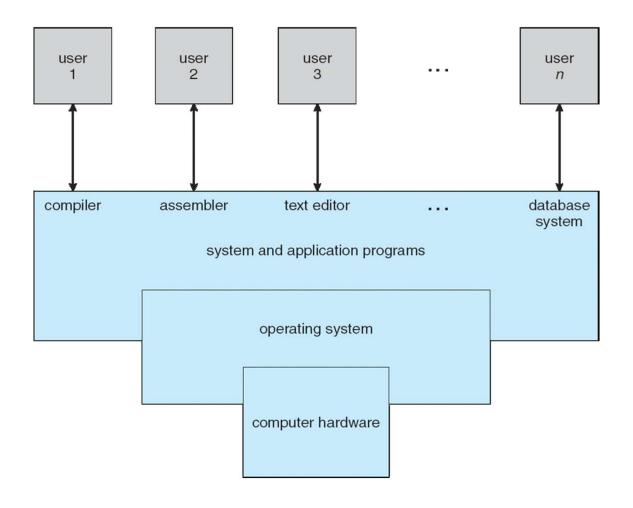
#### **Computer System Structure**

- □ **Computer** system can be divided into *four components*:
  - Hardware provides basic computing resources
    - ▶ CPU, memory, I/O devices
  - Operating system
    - Controls and coordinates use of hardware among various applications and users
  - Application programs define the ways in which the system resources are used to solve the computing problems of the users
    - Word processors, compilers, web browsers,...
  - п Users
    - People, machines, other computers





## Four Components of a Computer System







### **What Operating Systems Do**

#### **User View**

In system designed for one user, the operating system is designed mostly for ease of use

#### **System View**

- ☐ The operating system is a **resource allocator**.
  - CPU time, memory space, file-storage space, I/O devices, etc
  - Facing numerous (possibly conflicting), it must decide how to allocate resources to specific programs and users to operate the computer system efficiently and fairly.
- A slightly different view of an operating system emphasizes the need to control the various I/O devices and user programs.
  - It manages the execution of user programs to prevent errors and improper use of the computer.



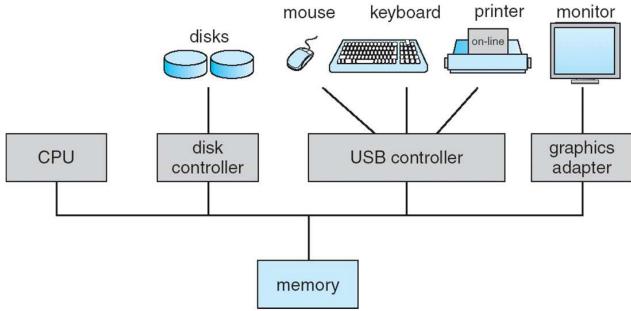
### **Operating System Definition**

- □ The term operating system covers many roles and functions. → How, then, can we define what an operating system is?
  - In general, we have no completely adequate definition of an operating system.
  - Operating systems exist because they offer a reasonable way to create a usable computing system.
- Since bare hardware alone is not particularly easy to use, application programs are developed.
  - These programs require certain common operations, such as those controlling the I/O devices.
  - The common functions of controlling and allocating resources are then brought together into one piece of software: the operating system.
- A more common definition is that the operating system is the program running at all times on the computer—usually called the kernel.



# **Computer System Organization**

- Computer-system operation
  - One or more CPUs, device controllers connect through common bus providing access to shared memory
  - Concurrent execution of CPUs and devices competing for memory cycles

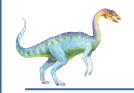




# **Computer System Organization**

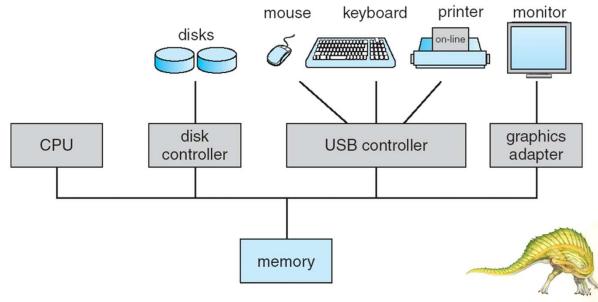
- □ For a computer to start running—when it is powered up or rebooted—it needs to have an initial program to run.
  - □ This initial program, or **bootstrap program**, is stored within the computer hardware in read-only memory (**ROM**) or electrically erasable programmable read-only memory (**EEPROM**)
  - It initializes CPU registers, device controllers and memory contents.
    - The bootstrap program must locate the operating-system kernel and load it into memory.
- System programs that are loaded into memory at boot time to become system processes.





#### **Computer-System Operation**

- □ I/O devices and the CPU can execute concurrently
- Each device controller is in charge of a particular device type
- Each device controller has a local buffer
- □ CPU moves data from/to main memory to/from local buffers
- □ I/O is from the device to local buffer of controller
- Device controller informs CPU that it has finished its operation by causing an interrupt



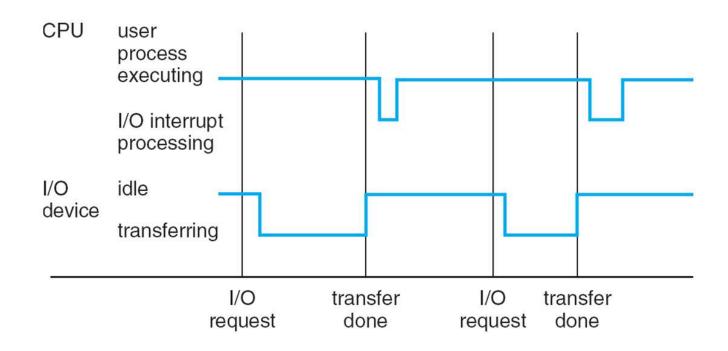


# **Common Functions of Interrupts**

- An operating system is interrupt driven
- ☐ The occurrence of an event is usually signaled by an interrupt from either the hardware or the software.
  - Software may trigger an interrupt (trap or exception) by executing a special operation called a system call
- □ When the CPU is interrupted, it stops what it is doing and immediately transfers execution to a fixed location.
  - The fixed location usually contains the starting address where the service routine for the interrupt is located.
  - The interrupt service routine executes; on completion, the CPU resumes the interrupted computation.
- □ Interrupts must be handled quickly.
  - Since only a predefined number of interrupts is possible, a table of pointers to interrupt service routines can be used
  - the table of pointers is stored in low memory (the first hundred or so locations), which is called interrupt vector.



## **Interrupt Timeline**







#### **Storage Structure**

- ☐ The CPU can load instructions only from main memory (also called random-access memory, or RAM), so any programs to run must be stored there.
  - Computers use other forms of memory as well (cache memory, CD-ROM, etc).
- All forms of memory provide an array of bytes. Each byte has its own address.
- The load instruction moves a byte or word from main memory to a register within the CPU, whereas the store instruction moves the content of a register to main memory.
- □ **Ideally**, we want the programs and data to reside in main memory permanently. This arrangement usually is not possible:
  - 1. Main memory is **usually too small** to store all needed programs and data permanently.
  - Main memory is a volatile storage device that loses its contents when power is turned off



#### **Storage Structure**

- ☐ Thus, most computer systems provide **secondary storage** as an extension of main memory.
- ☐ The main requirement for secondary storage is that it be able to *hold* large quantities of data permanently.
- ☐ The most common secondary-storage device is a **magnetic disk**
- ☐ The main differences among the various storage systems lie in *speed*, *cost*, *size*, *and volatility*.
- □ The wide variety of storage systems can be organized in a hierarchy according to speed and cost. The higher levels are expensive, but they are fast.

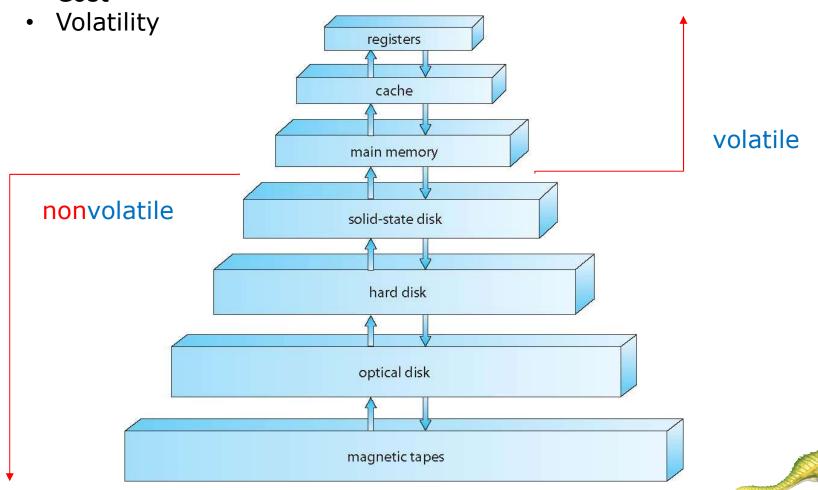




#### **Storage-Device Hierarchy**

Storage systems organized in hierarchy

- Speed
- Cost





#### I/O Structure

- A large portion of operating system code is dedicated to managing I/O, because of its importance to the reliability and performance of a system.
- □ A general-purpose computer system consists of CPUs and **multiple device controllers** that are connected through a common bus.
  - Each device controller is in charge of a specific type of device.
  - It is responsible for moving the data between the peripheral devices that it controls and its local buffer storage.
- Typically, operating systems have a device driver for each device controller.
  - This device driver provides the operating system with a uniform interface to the device.



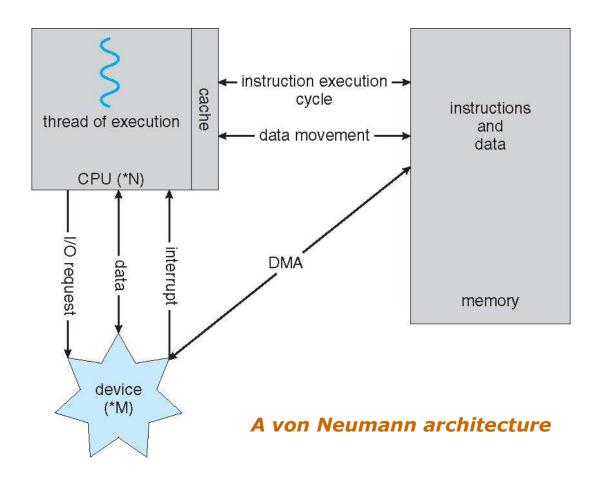


#### **I/O Structure**

- ☐ To **start an I/O operation**, the device driver loads the appropriate registers within the device controller.
- ☐ The device controller examines the contents of these registers to determine what action to take
  - The controller starts the transfer of data from the device to its local buffer.
  - Once the transfer of data is complete, the device controller informs the device driver via an interrupt
- ☐ This form of interrupt-driven I/O is fine for moving small amounts of data but can produce high overhead when used for bulk data movement.
- □ To solve this problem, **direct memory access (DMA)** is used.
  - the device controller transfers an entire block of data directly to or from its own buffer storage to memory, with no intervention by the CPU.
  - While the device controller is performing these operations, the CPU is available to accomplish other work.



### **How a Modern Computer Works**







#### **Storage Definitions and Notation Review**

The basic unit of computer storage is the **bit**. A bit can contain one of two values, 0 and 1. All other storage in a computer is based on collections of bits. Given enough bits, it is amazing how many things a computer can represent: numbers, letters, images, movies, sounds, documents, and programs, to name a few. A **byte** is 8 bits, and on most computers it is the smallest convenient chunk of storage. For example, most computers don't have an instruction to move a bit but do have one to move a byte. A less common term is **word**, which is a given computer architecture's native unit of data. A word is made up of one or more bytes. For example, a computer that has 64-bit registers and 64-bit memory addressing typically has 64-bit (8-byte) words. A computer executes many operations in its native word size rather than a byte at a time.

Computer storage, along with most computer throughput, is generally measured and manipulated in bytes and collections of bytes.

A **kilobyte**, or **KB**, is 1,024 bytes

- a **megabyte**, or **MB**, is 1,024<sup>2</sup> bytes
- a **gigabyte**, or **GB**, is 1,024<sup>3</sup> bytes
- a **terabyte**, or **TB**, is 1,024<sup>4</sup> bytes
- a **petabyte**, or **PB**, is 1,024<sup>5</sup> bytes

Computer manufacturers often round off these numbers and say that a megabyte is 1 million bytes and a gigabyte is 1 billion bytes. Networking measurements are an exception to this general rule; they are given in bits (because networks move data a bit at a time).



# **Computer-System Architecture**

#### □ Single-Processor Systems

One main CPU capable of executing a general-purpose instruction set

#### Multi-processor (multicore) Systems

- Such systems have two or more processors in close communication, sharing the computer bus and sometimes the clock, memory, and peripheral devices.
- Multiprocessor systems have three main advantages:
  - 1. **Increased throughput**. More work done in less time. The speed-up ratio with N processors is not N, however; rather, it is less than N.
  - 2. **Economy of scale**. Multiprocessor systems can cost less than equivalent multiple single-processor systems
  - 3. Increased reliability. Failure of one processor will not halt the system, only slow it down.



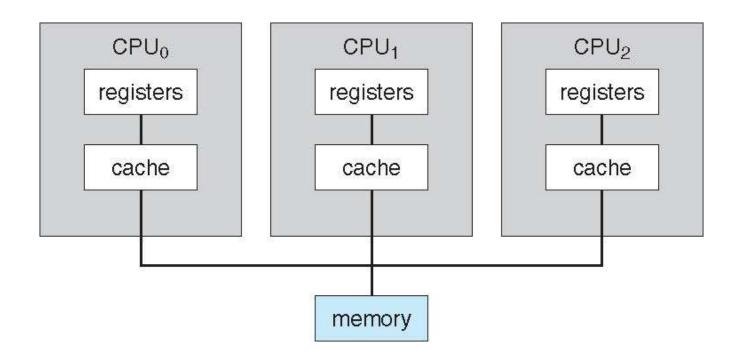
#### **Computer-System Architecture**

- ☐ The multiple-processor systems are of two types:
  - Asymmetric Multiprocessing each processor is assigned a specific task.
    - This scheme defines a boss—worker relationship. The boss processor schedules and allocates work to the worker processors.
  - 2. Symmetric Multiprocessing each processor performs all tasks
    - All processors are peers; Each processor has its own set of registers, as well as a private—or local —cache. However, all processors share physical memory
    - The benefit of this model is that many processes can run simultaneously—
      N processes can run if there are N CPUs—





#### **Symmetric Multiprocessing Architecture**

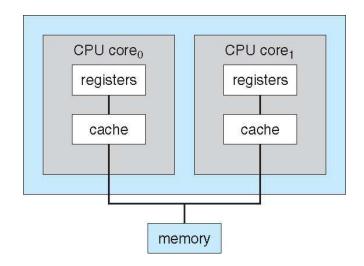






#### A Dual-Core Design

- Multi-chip and multicore
- A recent trend in CPU design is to include multiple computing cores on a single chip.
- Such multiprocessor systems are termed multicore. They can be more efficient than multiple chips with single cores because on-chip communication is faster than between-chip communication.
- In addition, one chip with multiple cores uses significantly less power than multiple single-core chips.



- In this design, each core has its own register set as well as its own local cache. Other designs might use a shared cache or a combination of local and shared caches.
- These multicore CPUs appear to the operating system as N standard processors.

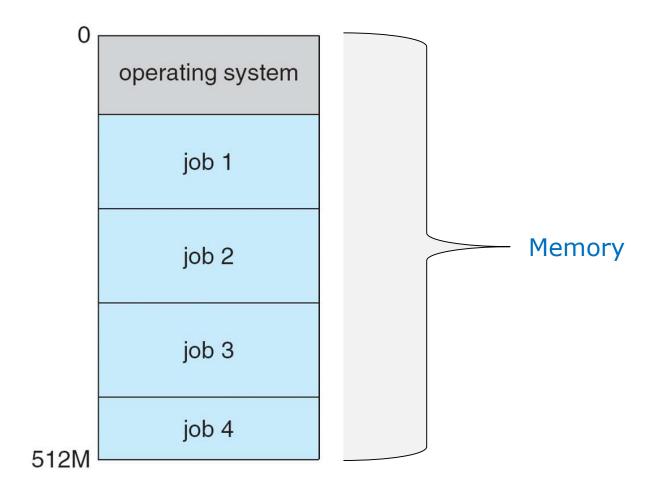


### **Operating System Structure**

- One of the most important aspects of operating systems is the ability to multi-program.
  - Multiprogramming increases CPU utilization by organizing jobs (code and data) so that the CPU always has one to execute.
- The idea is as follows:
  - The operating system keeps several jobs in memory simultaneously
  - □ Since main *memory is too small to accommodate all jobs*, the jobs are kept initially on the disk in the **job pool**.
  - This pool consists of all processes residing on disk awaiting allocation of main memory.
  - The operating system picks and begins to execute one of the jobs in memory.
  - Eventually, the job may have to wait for some task, such as an I/O operation, to complete. In a multi-programmed system, the operating system simply switches to, and executes, another job.
- As long as at least one job needs to execute, the CPU is never idle.



# **Memory Layout for Multiprogrammed System**





### **Operating System Structure**

- ☐ **Time sharing** (or multitasking) is a logical extension of multiprogramming.
  - The CPU executes multiple jobs by switching among them, but the switches occur so frequently that the users can interact with each program while it is running.
  - A time-shared operating system allows many users to share the computer simultaneously.
    - It provides each user with a small portion of a time-shared computer → each user is given the impression that the entire computer system is dedicated to his use
  - A program loaded into memory and executing is called a process. When a process executes, it typically executes for only a short time before it either finishes or needs to perform I/O.
  - Time sharing and multiprogramming require that several jobs be kept simultaneously in memory.
    - If several jobs are ready to be brought into memory, and if there is not enough room for all of them, then the system must choose among them. This involves job scheduling!



### **Operating System Structure**

- Having several programs in memory at the same time requires some form of memory management.
- If several jobs are ready to run at the same time, the system must choose which job will run first. Making this decision is CPU scheduling.

#### Virtual memory

- A technique that allows the execution of a process that is not completely in memory.
- It enables users to run programs that are larger than actual physical memory.
- Further, it abstracts main memory into a large, uniform array of storage
- A time-sharing system must also provide a file system. The file system resides on a collection of disks; hence, disk management must be provided
- To ensure orderly execution, the system must provide mechanisms for job synchronization and communication, and it may ensure that jobs do not get stuck in a deadlock, forever waiting for one another



### **Operating-System Operations**

- As mentioned earlier, modern operating systems are interrupt driven (both from hardware and software).
  - If there are no processes to execute, no I/O devices to service, and no users to whom to respond, an operating system will sit quietly, waiting for something to happen.
- Dual-Mode and Multi-mode Operation
  - In order to ensure the proper execution of the operating system, we must be able to *distinguish between the execution of operating-system code and user-defined code*.
  - Hardware support that allows us to differentiate among various modes of execution.





#### **Operating-System Operations**

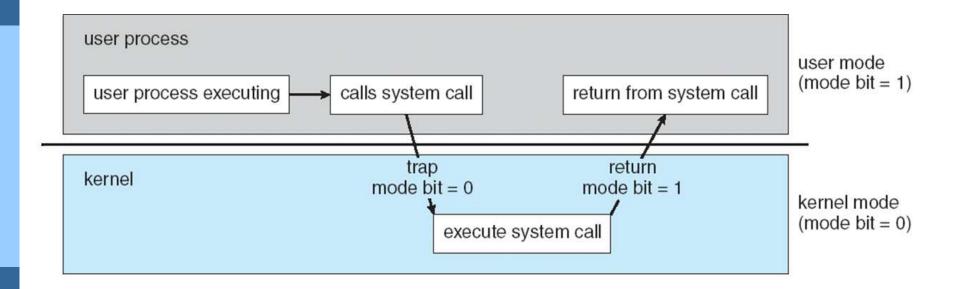
#### Hardware support

- At the very least, we need two separate modes of operation: user mode and kernel mode (also called privileged mode).
- A bit, called the mode bit, is added to the hardware of the computer to indicate the current mode: kernel (0) or user (1).
- At system boot time, the hardware starts in kernel mode. The operating system is then loaded and starts user applications in user mode.
- □ When a user application requests a service from the operating system (via a system call), the system must transition from user to kernel mode
- Some instructions designated as privileged, only executable in kernel mode





# **Transition from User to Kernel Mode**







### **Operating-System Operations**

- Dual-Mode and Multi-mode Operation
- ☐ The lack of a hardware-supported dual mode can cause serious shortcomings in an operating system.
- System calls provide the means for a user program to ask the operating system to perform tasks reserved for the operating system on the user program's behalf.
- We must ensure that the operating system maintains control over the CPU.
  - We cannot allow a user program to get stuck in an infinite loop or to fail to call system services and never return control to the operating system.
  - To accomplish this goal, we can use a timer (a counter that is decremented by the physical clock)
- □ A timer can be set to *interrupt the computer after a specified period*.
  - If the timer interrupts, control transfers automatically to the operating system



## Fin de la Clase

Gracias por su asistencia y atención

¿ Preguntas ?

