

Working with valuations

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Séminaire Calcul Formel, Limoges

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Part 1: Signature Gröbner bases over Tate algebras

joint work with Xavier Caruso¹ and Tristan Vaccon²

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- Question: in $\mathbb{R}[X]$, reduce $f = X^2$ modulo $g = 0.01X - 1$

Precision and Gröbner bases

- ▶ **Question:** in $\mathbb{R}[X]$, reduce $f = X^2$ modulo $g = 0.01X - 1$
 $\text{LT}(g)$

- ▶ The usual way:

$$\begin{array}{l} f = X^2 \\ \left(\begin{array}{l} -100Xg \\ \downarrow \\ 100X \end{array} \right. \\ \left(\begin{array}{l} -10\,000g \\ \downarrow \\ 10\,000 \end{array} \right. \end{array}$$

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- ▶ $g \simeq 1$, but $f \bmod g \not\simeq 0$

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- ▶ Another way?

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- ▶ It does not terminate, but...
- ▶ The sequence of reductions tends to 0
- ▶ **This work:** make sense of this process for convergent power series in $\mathbb{Z}_p[[X]]$

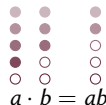
Valued fields and rings: basic definitions

Valuation: function $\text{val} : k \rightarrow \mathbb{Z} \cup \{\infty\}$ with:

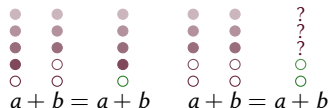
► $\text{val}(a) = \infty \iff a = 0$



► $\text{val}(ab) = \text{val}(a) + \text{val}(b)$



► $\text{val}(a + b) \geq \min(\text{val}(a), \text{val}(b))$



Examples: 1

π

$a = a_3\pi^3 + a_4\pi^4 + \dots$

$\text{val}(a) = 3$

$b = b_{-3}\pi^{-3} + b_{-2}\pi^{-2} + \dots$

$\text{val}(b) = -3$

Examples of valued fields and rings

$$\begin{array}{cccc} \text{Ring } K^\circ & \xrightleftharpoons[\text{val} \geq 0]{\text{Frac}} & \text{Field } K & \begin{array}{cc} \text{Uniformizer } \pi & \text{Residue field } K^\circ/\pi \end{array} \end{array}$$

$$\mathbb{Z}_{(p)}$$

$$\mathbb{Q}$$

$$p \text{ prime}$$

$$\mathbb{F}_p$$

$$\mathbb{Z}_p$$

$$\mathbb{Q}_p$$

$$p \text{ prime}$$

$$\mathbb{F}_p$$

$$\mathbb{C}[x]_{(x-\alpha)}$$

$$\mathbb{C}(x)$$

$$x - \alpha$$

$$\mathbb{C}$$

$$\mathbb{C}[[x - \alpha]]$$

$$\mathbb{C}((x - \alpha))$$

$$x - \alpha$$

$$\mathbb{C}$$

Examples of valued fields and rings

Ring K°	$\xrightleftharpoons[\text{val} \geq 0]{\text{Frac}}$	Field K	Uniformizer π	Residue field K°/π	Complete
$\mathbb{Z}_{(p)}$		\mathbb{Q}	p prime	\mathbb{F}_p	✗
\mathbb{Z}_p		\mathbb{Q}_p	p prime	\mathbb{F}_p	✓
$\mathbb{C}[x]_{(x-\alpha)}$		$\mathbb{C}(x)$	$x - \alpha$	\mathbb{C}	✗
$\mathbb{C}[[x - \alpha]]$		$\mathbb{C}((x - \alpha))$	$x - \alpha$	\mathbb{C}	✓

- ▶ Metric and topology defined by “ a is small” \iff “ $\text{val}(a)$ is large”
- ▶ In a **complete** valuation ring, a series is convergent iff its general term goes to 0:

$$\sum_{n=0}^{\infty} a_n = a_0$$

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The diagram shows the equation $\sum_{n=0}^{\infty} a_n = a_0 + a_1 + a_2 + a_3 + \cdots$. Above the terms, there are four columns of colored circles. The first column has four green circles. The second column has three purple circles and one white circle at the bottom. The third column has three purple circles and one dark red circle at the bottom. The fourth column has three purple circles, one dark red circle, and two white circles at the bottom. To the right of the fourth column, there are three horizontal green lines, indicating that the sequence continues infinitely.

Examples of valued fields and rings

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 \mathbb{Q}
 p prime

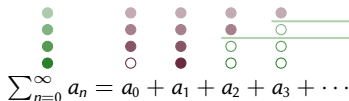
 \mathbb{F}_p
 \times
 \mathbb{Z}_p
 \mathbb{Q}_p

Now

 p prime

 \mathbb{F}_p
 \checkmark
 $\mathbb{C}[x]_{(x-\alpha)}$
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In part 2

- ▶ Metric and topology defined by “ a is small” \iff “ $\text{val}(a)$ is large”
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$$\sum_{n=0}^{\infty} a_n = a_0 + a_1 + a_2 + a_3 + \dots$$

Tate Series

$$\mathbf{X} = X_1, \dots, X_n$$

Definition

- ▶ $K\{\mathbf{X}\}^\circ$ = ring of series in \mathbf{X} with coefficients in K° converging for all $\mathbf{x} \in K^\circ$
= ring of power series whose general coefficients tend to 0


Motivation

- ▶ Introduced by Tate in 1971 for rigid geometry
(p -adic equivalent of the bridge between algebraic and analytic geometry over \mathbb{C})


Examples

- ▶ Polynomials (finite sums are convergent)

▶
$$\sum_{i,j=0}^{\infty} \pi^{i+j} X^i Y^j = 1 + \pi X + \pi Y + \pi^2 X^2 + \pi^2 XY + \pi^2 Y^2 + \dots$$



▶ Not a Tate series:
$$\sum_{i=0}^{\infty} X^i = 1 + 1X + 1X^2 + 1X^3 + \dots$$

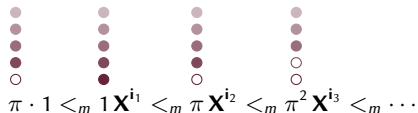


Term ordering for Tate algebras

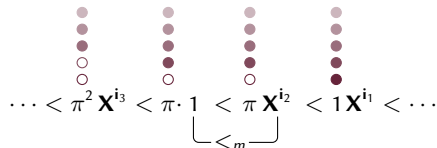
$$\mathbf{X}^{\mathbf{i}} = X_1^{i_1} \cdots X_n^{i_n}$$

- ▶ Starting from a usual monomial ordering $1 <_m \mathbf{X}^{i_1} <_m \mathbf{X}^{i_2} <_m \dots$
- ▶ We define a **term** ordering putting more weight on large coefficients

Usual term ordering:



Term ordering for Tate series:

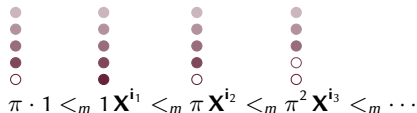


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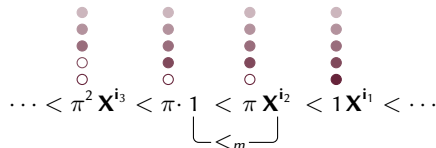
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Term ordering for Tate series:



- ▶ It has infinite descending chains, but **they converge to zero**
- ▶ Tate series always have a leading term

$LT(f)$

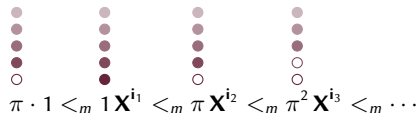
$f = a_2XY + a_1X + a_0 \cdot 1 + a_3X^2Y^2 + \dots$

Term ordering for Tate algebras

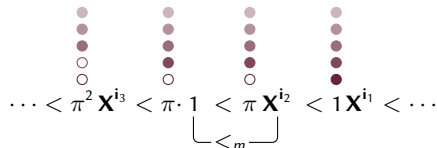
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▶ Isomorphism $K\{\mathbf{X}\}^\circ / \langle \pi \rangle \simeq \mathbb{F}[\mathbf{X}]$

$$f \mapsto \bar{f}$$

compatible with the term order

$LT(f)$

$f = a_2XY + a_1X + a_0 \cdot 1 + a_3X^2Y^2 + \dots$

$\bar{f} = \bar{a}_2XY + \bar{a}_1X$

Gröbner bases

- ▶ Standard definition once the term order is defined:

G is a Gröbner basis of $I \iff$ for all $f \in I$, there is $g \in G$ s.t. $\text{LT}(g)$ divides $\text{LT}(f)$

- ▶ Standard equivalent characterizations:

1. G is a Gröbner basis of I
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If I is saturated:

$$\pi f \in I \implies f \in I$$

4. \overline{G} is a Gröbner basis of \overline{I} in the sense of $\mathbb{F}[\mathbf{x}]$

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- ▶ Every Tate ideal has a finite Gröbner basis
- ▶ It can be computed using the usual algorithms (reduction, Buchberger, F_4)
- ▶ In practice, the algorithms run with finite precision and without loss of precision

No division by π

Buchberger's algorithm

1. $G \leftarrow \{f_1, \dots, f_m\}$
2. $B \leftarrow \{\text{S-pol of } g_1 \text{ and } g_2 \text{ for } g_1, g_2 \in G\}$
3. While $B \neq \emptyset$:
 4. Pop v from B
 5. $w \leftarrow$ reduction of v modulo G
 6. If $w = 0$:
 7. Pass
 8. Else:
 9. $B \leftarrow B \cup \{\text{S-pol of } w \text{ and } g \text{ for } g \in G\}$
 10. $G \leftarrow G \cup \{w\}$
11. Return G

Why signatures?

Problem: useless and redundant computations, **infinite** reductions to 0

Example with a S-polynomial

$$p = p_1f_1 + p_2f_2 + \cdots + p_kf_k + \cdots + p_mf_m$$

$$q = q_1f_1 + q_2f_2 + \cdots + q_lf_l + \cdots + q_mf_m$$

$$S\text{-Pol}(p, q) = \mu p - \nu q$$

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- ▶ **1st idea:** keep track of the representation of the ideal elements

[Möller, Mora, Traverso 1992]

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$$p = p_1f_1 + p_2f_2 + \cdots + p_kf_k + \cdots + p_mf_m$$

$$\mathbf{p} = p_1\mathbf{e}_1 + p_2\mathbf{e}_2 + \cdots + p_k\mathbf{e}_k + \cdots + p_m\mathbf{e}_m$$

$$q = q_1f_1 + q_2f_2 + \cdots + q_lf_l + \cdots + q_mf_m$$

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$$\text{S-Pol}(\mathbf{p}, \mathbf{q}) = \mu (p_1\mathbf{e}_1 + \cdots + p_k\mathbf{e}_k + \cdots + p_m\mathbf{e}_m) - \nu (q_1\mathbf{e}_1 + \cdots + q_l\mathbf{e}_l + \cdots + q_m\mathbf{e}_m)$$

Why signatures?

Problem: useless and redundant computations, **infinite** reductions to 0

- ▶ **1st idea:** keep track of the representation of the ideal elements
[Möller, Mora, Traverso 1992]
- ▶ **2nd idea:** the largest term of the representation is enough
[Faugère 2002 ; Gao, Volny, Wang 2010 ; Arri, Perry 2011... Eder, Faugère 2017]

Example with a S-polynomial

$$p = p_1 f_1 + p_2 f_2 + \cdots + p_k f_k + \cdots + 0 f_m$$

$$\mathbf{p} = p_1 \mathbf{e}_1 + p_2 \mathbf{e}_2 + \cdots + p_k \mathbf{e}_k + \cdots + 0 \mathbf{e}_m$$

$$= \text{LT}(p_k) \mathbf{e}_k + \text{smaller terms}$$

$$q = q_1 f_1 + q_2 f_2 + \cdots + q_l f_l + \cdots + 0 f_m$$

$$\mathbf{q} = q_1 \mathbf{e}_1 + q_2 \mathbf{e}_2 + \cdots + q_l \mathbf{e}_l + \cdots + 0 \mathbf{e}_m$$

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$$\mathbf{p} = p_1 \mathbf{e}_1 + p_2 \mathbf{e}_2 + \cdots + p_k \mathbf{e}_k + \cdots + 0 \mathbf{e}_m$$

$$= \text{LT}(p_k) \mathbf{e}_k + \text{smaller terms}$$

$$q = q_1 f_1 + q_2 f_2 + \cdots + q_l f_l + \cdots + 0 f_m$$

$$\mathbf{q} = q_1 \mathbf{e}_1 + q_2 \mathbf{e}_2 + \cdots + q_l \mathbf{e}_l + \cdots + 0 \mathbf{e}_m$$

$$= \text{LT}(q_l) \mathbf{e}_l + \text{smaller terms}$$

$$S\text{-Pol}(p, q) = \mu p - \nu q$$

$$S\text{-Pol}(\mathbf{p}, \mathbf{q}) = \mu (p_1 \mathbf{e}_1 + \cdots + p_k \mathbf{e}_k + \cdots + 0 \mathbf{e}_m) - \nu (q_1 \mathbf{e}_1 + \cdots + q_l \mathbf{e}_l + \cdots + 0 \mathbf{e}_m)$$

$$= \mu \text{LT}(p_k) \mathbf{e}_k - \nu \text{LT}(q_l) \mathbf{e}_l + \text{smaller terms}$$

$$= \mu \text{LT}(p_k) \mathbf{e}_k + \text{smaller terms} \quad \text{if } \mu \text{LT}(p_k) \mathbf{e}_k \succeq \nu \text{LT}(q_l) \mathbf{e}_l$$

Why signatures?

Problem: useless and redundant computations, **infinite** reductions to 0

- ▶ **1st idea:** keep track of the representation of the ideal elements
[Möller, Mora, Traverso 1992]
- ▶ **2nd idea:** the largest term of the representation is enough
[Faugère 2002 ; Gao, Volny, Wang 2010 ; Arri, Perry 2011... Eder, Faugère 2017]

Example with a S-polynomial

$$p = p_1 f_1 + p_2 f_2 + \cdots + p_k f_k + \cdots + 0 f_m$$

$$\mathbf{p} = p_1 \mathbf{e}_1 + p_2 \mathbf{e}_2 + \cdots + p_k \mathbf{e}_k + \cdots + 0 \mathbf{e}_m$$

$$= \text{LT}(p_k) \mathbf{e}_k + \text{smaller terms}$$

$$q = q_1 f_1 + q_2 f_2 + \cdots + q_l f_l + \cdots + 0 f_m$$

$$\mathbf{q} = q_1 \mathbf{e}_1 + q_2 \mathbf{e}_2 + \cdots + q_l \mathbf{e}_l + \cdots + 0 \mathbf{e}_m$$

$$= \text{LT}(q_l) \mathbf{e}_l + \text{smaller terms}$$

$$\mathfrak{s}(p) = \text{signature of } p$$

$$\text{S-Pol}(p, q) = \mu p - \nu q$$

$$\text{S-Pol}(\mathbf{p}, \mathbf{q}) = \mu (p_1 \mathbf{e}_1 + \cdots + p_k \mathbf{e}_k + \cdots + 0 \mathbf{e}_m) - \nu (q_1 \mathbf{e}_1 + \cdots + q_l \mathbf{e}_l + \cdots + 0 \mathbf{e}_m)$$

$$= \mu \text{LT}(p_k) \mathbf{e}_k - \nu \text{LT}(q_l) \mathbf{e}_l + \text{smaller terms}$$

$$= \mu \text{LT}(p_k) \mathbf{e}_k + \text{smaller terms} \quad \text{if } \mu \text{LT}(p_k) \mathbf{e}_k \succeq \nu \text{LT}(q_l) \mathbf{e}_l \quad \text{Regular S-polynomial}$$

Buchberger's algorithm, with signatures

1. $G \leftarrow \{(\mathbf{e}_1, f_1), \dots, (\mathbf{e}_m, f_m)\}$
2. $B \leftarrow \{\text{S-pol of } p_1 \text{ and } p_2 \text{ for } p_1, p_2 \in G\}$
3. While $B \neq \emptyset$:
 4. Pop (\mathbf{u}, v) from B with smallest \mathbf{u}
 5. $w \leftarrow$ regular reduction of (\mathbf{u}, v) modulo G
 6. If $w = 0$:
 7. Pass
 8. Else:
 9. $B \leftarrow B \cup \{\text{regular S-pol of } (\mathbf{u}, w) \text{ and } p \text{ for } p \in G\}$
 10. $G \leftarrow G \cup \{(\mathbf{u}, w)\}$
11. Return G

Buchberger's algorithm, with signatures

1. $G \leftarrow \{(\mathbf{e}_1, f_1), \dots, (\mathbf{e}_m, f_m)\}$
2. $B \leftarrow \{\text{S-pol of } p_1 \text{ and } p_2 \text{ for } p_1, p_2 \in G\}$
3. While $B \neq \emptyset$:
 4. Pop (\mathbf{u}, v) from B with smallest \mathbf{u} Need to order the signatures!
 5. $w \leftarrow$ regular reduction of (\mathbf{u}, v) modulo G
 6. If $w = 0$:
 7. Pass
 8. Else:
 9. $B \leftarrow B \cup \{\text{regular S-pol of } (\mathbf{u}, w) \text{ and } p \text{ for } p \in G\}$
 10. $G \leftarrow G \cup \{(\mathbf{u}, w)\}$
11. Return G

Signature orderings

Signature orderings:

- ▶ Necessary for correctness and termination of the algorithms
- ▶ Different choices lead to different performances

Examples (polynomial case):

- ▶ $\mu \mathbf{e}_i <_{\text{pot}} \nu \mathbf{e}_j \iff i < j, \text{ or if equal, } \mu < \nu$
Position over Term
- ▶ $\mu \mathbf{e}_i <_{\text{top}} \nu \mathbf{e}_j \iff \mu < \nu, \text{ or if equal, } i < j$
Term over Position
- ▶ $\mu \mathbf{e}_i <_{\text{dopot}} \nu \mathbf{e}_j \iff \deg(p) < \deg(q), \text{ or if equal, } i < j, \text{ or if equal, } \mu < \nu$
Degree over Position over Term

Signature orderings

Signature orderings:

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Examples (polynomial case):

- ▶ $\mu \mathbf{e}_i <_{\text{pot}} \nu \mathbf{e}_j \iff i < j, \text{ or if equal, } \mu < \nu$

Position over Term

- ▶ Theoretically convenient
- ▶ Incremental
- ▶ Rarely the most efficient

- ▶ $\mu \mathbf{e}_i <_{\text{top}} \nu \mathbf{e}_j \iff \mu < \nu, \text{ or if equal, } i < j$

Term over Position

- ▶ Better in practice
- ▶ Theoretically complicated

- ▶ $\mu \mathbf{e}_i <_{\text{dopot}} \nu \mathbf{e}_j \iff \deg(p) < \deg(q), \text{ or if equal, } i < j, \text{ or if equal, } \mu < \nu$

Degree over Position over Term

- ▶ “F5-ordering” for homogeneous systems and degree order
- ▶ Avoid going too high in degree, still incremental
- ▶ Best of both worlds

Buchberger's algorithm, incremental variant

1. $Q \leftarrow (f_1, \dots, f_m)$
2. $G \leftarrow \emptyset$
3. For $f \in Q$
4. $G \leftarrow G \cup \{f\}$
5. $B \leftarrow \{\text{S-pol of } f \text{ and } g \text{ for } g \in G\}$
6. While $B \neq \emptyset$:
7. Pop v from B
8. $w \leftarrow \text{reduction of } v \text{ modulo } G$
9. If $w = 0$:
10. Pass
11. Else:
12. $B \leftarrow B \cup \{\text{S-pol of } w \text{ and } g \text{ for } g \in G\}$
13. $G \leftarrow G \cup \{w\}$
14. Return G

Signature orderings for Tate series

Signature orderings:

- ▶ Necessary for correctness and termination of the algorithms
- ▶ Different choices lead to different performances
- ▶ **Difficulty with Tate series: multiplying by π should decrease the signature**

Orders for Tate series:

- ▶ $\mu \mathbf{e}_i <_{\text{pot}} \nu \mathbf{e}_j \iff i < j, \text{ or if equal, } \mu < \nu$

Position over Term

- ▶ Theoretically convenient
- ▶ Incremental
- ▶ Rarely the most efficient

- ▶ $\mu \mathbf{e}_i <_{\text{top}} \nu \mathbf{e}_j \iff \mu < \nu, \text{ or if equal, } i < j$

Term over Position

- ▶ Better in practice
- ▶ Theoretically complicated

Signature-based algorithm, PoT ordering

1. $Q \leftarrow (f_1, \dots, f_m)$
2. $G \leftarrow \emptyset$
3. For $f \in Q$
4. $G_S \leftarrow \{(0, g) : g \in G_S\} \cup \{(1, f)\}$
5. $B \leftarrow \{\text{S-pol of } (1, f) \text{ and } p \text{ for } p \in G_S\}$
6. While $B \neq \emptyset$:
7. Pop (u, v) from B with smallest u
8. $w \leftarrow$ regular reduction of (u, v) modulo G_S
9. If $w = 0$:
10. Pass
11. Else:
12. $B \leftarrow B \cup \{\text{regular S-pol of } (u, w) \text{ and } p \text{ for } p \in G_S\}$
13. $G_S \leftarrow G_S \cup \{(u, w)\}$
14. $G \leftarrow \{v : (u, v) \in G_S\}$
15. Return G

Signature orderings for Tate series

Signature orderings:

- ▶ Necessary for correctness and termination of the algorithms
- ▶ Different choices lead to different performances
- ▶ **Difficulty with Tate series: multiplying by π should decrease the signature**

Orders for Tate series:

- ▶ $\mu \mathbf{e}_i <_{\text{pot}} \nu \mathbf{e}_j \iff i < j, \text{ or if equal, } \mu < \nu$

Position over Term

- ▶ Theoretically convenient

- ▶ Incremental

- ▶ Rarely the most efficient

- ▶ $\mu \mathbf{e}_i <_{\text{top}} \nu \mathbf{e}_j \iff \mu < \nu, \text{ or if equal, } i < j$

Term over Position

- ▶ Better in practice

- ▶ Theoretically complicated

- ▶ $\mu \mathbf{e}_i <_{\text{vopot}} \nu \mathbf{e}_j \iff \text{val}(p) < \text{val}(q), \text{ or if equal, } i < j, \text{ or if equal, } \mu < \nu$

Valuation over Position over Term

- ▶ Analogue of the F5 ordering for the valuation
- ▶ Allows to delay (or avoid) high valuation computations

Signature-based algorithm, VoPoT ordering

1. $Q \leftarrow (f_1, \dots, f_m)$
2. $G \leftarrow \emptyset$
3. While $\exists f \in Q$ with smallest valuation:
 4. $G_S \leftarrow \{(0, g) : g \in G_S\} \cup \{(1, f)\}$
 5. $B \leftarrow \{\text{S-pol of } (1, f) \text{ and } p \text{ for } p \in G_S\}$
 6. While $B \neq \emptyset$:
 7. Pop (u, v) from B with smallest u
 8. $w \leftarrow$ regular reduction of (u, v) modulo G_S
 9. If $\text{val}(w) > \text{val}(f)$:
 10. $Q \leftarrow Q \cup w$
 11. Else:
 12. $B \leftarrow B \cup \{\text{regular S-pol of } (u, w) \text{ and } p \text{ for } p \in G_S\}$
 13. $G_S \leftarrow G_S \cup \{(u, w)\}$
 14. $G \leftarrow \{v : (u, v) \in G_S\}$
15. Return G

Conclusion and perspectives

Results:

- ▶ Possible to design signature-based algorithms for Tate algebras
- ▶ Two algorithms with two orders
- ▶ Implemented in Sage, working towards including them in the distribution

Future work:

- ▶ Reduction of Tate series is very different from reduction of polynomials
- ▶ Design algorithms to perform those reductions more efficiently
- ▶ **Goal:** being able to take advantage of e.g. delaying reductions in VoPoT

References:

- ▶ Caruso, Vaccon and Verron, 'Gröbner bases over Tate algebras' (2019)
- ▶ Caruso, Vaccon and Verron, 'Signature-based algorithms for Gröbner bases over Tate algebras' (2020) [preprint]

Part 2: Integral bases of P-recursive sequences

joint work with Shaoshi Chen¹, Lixin Du^{1,2} and Manuel Kauers²

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Séminaire Calcul Formel, Limoges

27 février 2020

What does it mean to be integral?

Ring K°	$\xrightleftharpoons[\text{val} \geq 0]{\text{Frac}}$	Field K	Valuation at	
\mathbb{Z}_p		\mathbb{Q}_p	p prime	} Local integrality
$\mathbb{C}[[x - \alpha]]$		$\mathbb{C}((x - \alpha))$	$x - \alpha$	

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$\mathbb{C}[[x - \alpha]]$	$\mathbb{C}((x - \alpha))$	$x - \alpha$	
\mathbb{Z} Denom. $\in \{\pm 1\}$	\mathbb{Q}	All primes	} Global integrality
$\mathbb{C}[x]$ Denom. $\in \mathbb{C}$	$\mathbb{C}(x)$	All $x - \alpha$	

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$\mathbb{C}[x]$ Denom. $\in \mathbb{C}$		$\mathbb{C}(x)$	All $x - \alpha$	
$\mathcal{O}_{\mathbb{C}[x]}$ Denom. of minpoly $\in \mathbb{C}$		$\overline{\mathbb{C}(x)}$	All $x - \alpha$	

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		$\left\{ \begin{array}{l} \text{Sol. of diffeq} \\ \text{with poly. coefs.} \end{array} \right\}$		

What does it mean to be integral?

Ring K°	$\xrightleftharpoons[\text{val} \geq 0 \iff \text{"no pole"}]{\text{Frac}}$	Field K	Valuation at	
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\mathbb{Z} Denom. $\in \{\pm 1\}$		\mathbb{Q}	All primes	Global integrality
$\mathbb{C}[x]$ Denom. $\in \mathbb{C}$		$\mathbb{C}(x)$	All $x - \alpha$	
$\mathcal{O}_{\mathbb{C}[x]}$ Denom. of minpoly $\in \mathbb{C}$ \iff "no pole"		$\overline{\mathbb{C}(x)}$	All $x - \alpha$	
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"No pole" [Kauers Koutschan 2015]		$\left\{ \begin{array}{l} \text{Sol. of diffeq} \\ \text{with poly. coefs.} \end{array} \right\}$	All $x - \alpha$	

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"No pole" [Kauers Koutschan 2015]		$\left\{ \begin{array}{l} \text{Sol. of diffeq} \\ \text{with poly. coeffs.} \end{array} \right\}$	All $x - \alpha$	
This work : "val ≥ 0 "		$\left\{ \begin{array}{l} \text{Sol. of rec.} \\ \text{with poly. coeffs.} \end{array} \right\}$		

Better framework: integral operators

Polynomial algebras:

- ▶ “Algebraic equations”: $C(x)[y]$, commutative: $xy = yx$

Algebraic case (finite extension):

- ▶ Given $\alpha(x) \in \overline{C(x)}$ or equivalently given $P \in C[x][y]$
- ▶ **Question:** What are integral elements of $C(x)(\alpha) = C(x)[y]/\langle P \rangle$?
- ▶ **Answer:** Q is integral iff for all $\alpha(x)$ sol of P , $(Q(\alpha))(x)$ does not have any pole
- ▶ Integral elements form a $C[x]$ -algebra in $C(x)[y]$

Can we compute a basis of that set as a $C[x]$ -module?

- ▶ **Yes:** Trager’s algorithm, van Hoeij’s algorithm
- ▶ **Application:** computation of integrals [Trager 1984]

Better framework: integral operators

Polynomial and Ore algebras:

- ▶ “Algebraic equations”: $C(x)[y]$, commutative: $xy = yx$
- ▶ “Differential equations”: $C(x)\langle D \rangle$, non-commutative: $Dx = xD + 1$

Differential case:

- ▶ Given $L \in C[x]\langle D \rangle$
- ▶ **Question:** What are integral elements of $C(x)\langle D \rangle / \langle L \rangle$?
- ▶ **Answer:** B is integral iff for all $\alpha(x)$ sol of L , $(B \cdot \alpha)(x)$ does not have any pole
- ▶ Integral elements form a $C[x]$ -module in $C(x)\langle D \rangle$

Can we compute a basis of that $C[x]$ -module?

- ▶ **Yes:** adaptation of van Hoeij’s algorithm [Kauers, Koutschan 2015]
- ▶ **Application:** computation of integrals [Chen, van Hoeij, Kauers, Koutschan 2018]

Better framework: integral operators

Polynomial and Ore algebras:

- ▶ “Algebraic equations”: $C(x)[y]$, commutative: $xy = yx$
- ▶ “Differential equations”: $C(x)\langle D \rangle$, non-commutative: $Dx = xD + 1$
- ▶ “Recurrence equations”: $C(n)\langle S \rangle$, non-commutative: $Sn = (n + 1)S$

Recurrence case:

- ▶ Given $L \in C[x]\langle S \rangle$
- ▶ Question: What are integral elements of $C(x)\langle S \rangle / \langle L \rangle$?
- ▶ Answer: B is integral iff for all $\alpha(x)$ sol of L , $(B \cdot \alpha)(x) \dots ???$

Better framework: integral operators

Polynomial and Ore algebras:

- ▶ “Algebraic equations”: $C(x)[y]$, commutative: $xy = yx$
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Recurrence case:

- ▶ Given $L \in C[x]\langle S \rangle$
- ▶ Question: What are integral elements of $C(x)\langle S \rangle / \langle L \rangle$?
- ▶ Answer: B is integral iff for all $\alpha(x)$ sol of L , $(B \cdot \alpha)(x)$ has “valuation” ≥ 0 everywhere
- ▶ Integral elements form a $C[x]$ -module in $C(x)\langle D \rangle$

Can we compute a basis of that $C[x]$ -module?

- ▶ Yes: adaptation of van Hoeij’s algorithm [Chen, Du, Kauers, V. 2020]
- ▶ Application: computation of sums?

Van Hoeij's algorithm for finding integral bases (differential case)

Local algorithm:

Input. $L \in C[x]\langle D \rangle$ with order r , $\alpha \in C$

Output. B_1, \dots, B_r basis of $C(x)\langle D \rangle / \langle L \rangle$ integral at α

1. $B_1, \dots, B_r \leftarrow$ basis of $C(x)\langle D \rangle / \langle L \rangle$
2. For $d \in \{1, \dots, r\}$:
 3. While B_i is not integral at α
 4. $B_i \leftarrow (x - \alpha)B_i$
 5. While there exists $a_1, \dots, a_{d-1} \in C$
such that $A := \frac{1}{x - \alpha} (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d)$ is integral at α
 6. $B_d \leftarrow A$
7. Return B_1, \dots, B_r

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1. $B_1, \dots, B_r \leftarrow$ basis of $C(x)\langle D \rangle / \langle L \rangle$ $B_1, \dots, B_r \leftarrow 1, \dots, D^{r-1}$
2. For $d \in \{1, \dots, r\}$:
 3. While B_i is not integral at α
 4. $B_i \leftarrow (x - \alpha)B_i$
 5. While there exists $a_1, \dots, a_{d-1} \in C$
such that $A := \frac{1}{x - \alpha} (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d)$ is integral at α
 6. $B_d \leftarrow A$
7. Return B_1, \dots, B_r

Van Hoeij's algorithm for finding integral bases (differential case)

Local algorithm:

$f_1, \dots, f_r \in C((x-\alpha))$
basis of solutions of L

Input. $L \in C[x]\langle D \rangle$ with order r , $\alpha \in C$

Output. B_1, \dots, B_r basis of $C(x)\langle D \rangle / \langle L \rangle$ integral at α

1. $B_1, \dots, B_r \leftarrow$ basis of $C(x)\langle D \rangle / \langle L \rangle$ $B_1, \dots, B_r \leftarrow 1, \dots, D^{r-1}$
2. For $d \in \{1, \dots, r\}$:
3. While B_i is not integral at α $B_i \cdot f_j$ has a pole at α for some j
4. $B_i \leftarrow (x - \alpha)B_i$
5. While there exists $a_1, \dots, a_{d-1} \in C$
 such that $A := \frac{1}{x-\alpha} (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d)$ is integral at α
6. $B_d \leftarrow A$
7. Return B_1, \dots, B_r

Van Hoeij's algorithm for finding integral bases (differential case)

Local algorithm:

$f_1, \dots, f_r \in C((x-\alpha))$
basis of solutions of L

Input. $L \in C[x]\langle D \rangle$ with order r , $\alpha \in C$

Output. B_1, \dots, B_r basis of $C(x)\langle D \rangle / \langle L \rangle$ integral at α

1. $B_1, \dots, B_r \leftarrow$ basis of $C(x)\langle D \rangle / \langle L \rangle$

$B_1, \dots, B_r \leftarrow 1, \dots, D^{r-1}$

2. For $d \in \{1, \dots, r\}$:

3. While B_i is not integral at α

$B_i \cdot f_j$ has a pole at α for some j

4. $B_i \leftarrow (x - \alpha)B_i$

5. While there exists $a_1, \dots, a_{d-1} \in C$

such that $A := \frac{1}{x-\alpha} (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d)$ is integral at α

6. $B_d \leftarrow A$

7. Return B_1, \dots, B_r

$$\iff \forall j, (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d) \cdot f_j(\alpha) = 0$$

$$\iff \forall j, a_1 B_1 \cdot f_j(\alpha) + \dots + a_{d-1} B_{d-1} \cdot f_j(\alpha) = B_d \cdot f_j(\alpha)$$

Linear system of equations

Van Hoeij's algorithm for finding integral bases (differential case)

Local algorithm:

$f_1, \dots, f_r \in C((x-\alpha))$
basis of solutions of L

Input. $L \in C[x]\langle D \rangle$ with order r , $\alpha \in C$

Output. B_1, \dots, B_r basis of $C(x)\langle D \rangle / \langle L \rangle$ integral at α

1. $B_1, \dots, B_r \leftarrow$ basis of $C(x)\langle D \rangle / \langle L \rangle$

$B_1, \dots, B_r \leftarrow 1, \dots, D^{r-1}$

2. For $d \in \{1, \dots, r\}$:

3. While B_i is not integral at α

$B_i \cdot f_j$ has a pole at α for some j

4. $B_i \leftarrow (x - \alpha)B_i$

5. While there exists $a_1, \dots, a_{d-1} \in C$

such that $A := \frac{1}{x-\alpha} (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d)$ is integral at α

6. $B_d \leftarrow A$

7. Return B_1, \dots, B_r

$$\iff \forall j, (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d) \cdot f_j(\alpha) = 0$$

$$\iff \forall j, a_1 B_1 \cdot f_j(\alpha) + \dots + a_{d-1} B_{d-1} \cdot f_j(\alpha) = B_d \cdot f_j(\alpha)$$

Linear system of equations

Global algorithm: loop over all $\alpha \in C$

Van Hoeij's algorithm for finding integral bases (differential case)

Local algorithm:

$f_1, \dots, f_r \in C((x-\alpha))$
basis of solutions of L

Input. $L \in C[x]\langle D \rangle$ with order r , $\alpha \in C$

Output. B_1, \dots, B_r basis of $C(x)\langle D \rangle / \langle L \rangle$ integral at α

1. $B_1, \dots, B_r \leftarrow$ basis of $C(x)\langle D \rangle / \langle L \rangle$

$B_1, \dots, B_r \leftarrow 1, \dots, D^{r-1}$

2. For $d \in \{1, \dots, r\}$:

3. While B_i is not integral at α

$B_i \cdot f_j$ has a pole at α for some j

4. $B_i \leftarrow (x - \alpha)B_i$

5. While there exists $a_1, \dots, a_{d-1} \in C$

such that $A := \frac{1}{x-\alpha} (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d)$ is integral at α

6. $B_d \leftarrow A$

$\iff \forall j, (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d) \cdot f_j(\alpha) = 0$

7. Return B_1, \dots, B_r

$\iff \forall j, a_1 B_1 \cdot f_j(\alpha) + \dots + a_{d-1} B_{d-1} \cdot f_j(\alpha) = B_d \cdot f_j(\alpha)$

Linear system of equations

Global algorithm: loop over all $\alpha \in C$

Nothing happens at all but finitely many of them
(roots of the leading coefficient of L)

Finding solutions of P-recursive sequences

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3 \in \mathbb{C}[n]\langle S \rangle$ with $Sn = (n+1)S$

► **Natural action:** L acts on $\mathbb{C}^{\mathbb{Z}}$ via $(n \cdot u)_k = ku_k$, $(S \cdot u)_k = u_{k+1}$

If $(u_n)_{n \in \mathbb{Z}} \in \mathbb{C}^{\mathbb{Z}}$ is a solution, then for all $n \in \mathbb{Z}$:

► $(n-1)u_{n+3} = -(n-3)u_{n+1} - (n-1)(n+1)u_n$

...	-1	0	1	2	3	4	...
		1	0	0			
		0	1	0			
		0	0	1			

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		1	0	0	-1		
		0	1	0	0		
		0	0	1	-3		

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...	-1	0	1	2	3	4	...
		1	0	0	-1	×	$0 = -2$
		0	1	0	0	0	$0 = 0$
		0	0	1	-3	×	$0 = -6$

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		0	1	0	0	0	$0 = 0$
		0	0	1	-3	×	$0 = -6$
		0	0	0	0	1	

Finding solutions of P-recursive sequences


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...	-1	0	1	2	3	4	...
		1	0	0	-1	×	$0 = -2$
		0	1	0	0	0	$0 = 0$
		0	0	1	-3	×	$0 = -6$
		0	0	0	0	1	
		0	3	-1	0	0	$0 = 0$



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...	-1	0	1	2	3	4	...
		1	0	0	-1	×	$0 = -2$
		0	1	0	0	0	...
		0	0	1	-3	×	$0 = -6$
		0	0	0	0	1	...
		0	3	-1	0	0	...

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...	-1	0	1	2	3	4	...
		1	0	0	-1	×	$0 = -2$
$0 = 4$	×	0	1	0	0	0	...
		0	0	1	-3	×	$0 = -6$
	0	0	0	0	0	1	...
$0 = 10$	×	0	3	-1	0	0	...

Finding solutions of P-recursive sequences

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- $(n-1)(n+1)u_n = -(n-3)u_{n+1} - (n-1)u_{n+3}$

	...	-1	0	1	2	3	4	...
			1	0	0	-1	×	$0 = -2$
	$0 = 4$	×	0	1	0	0	0	...
			0	0	1	-3	×	$0 = -6$
		0	0	0	0	0	1	...
	$0 = 10$	×	0	3	-1	0	0	...
		1	0	0	0	0	0	...
	$0 = 0$	0	5	-6	2	0	0	...

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...	-1	0	1	2	3	4	...
		1	0	0	-1	×	$0 = -2$
$0 = 4$	×	0	1	0	0	0	...
		0	0	1	-3	×	$0 = -6$
...	0	0	0	0	0	1	...
$0 = 10$	×	0	3	-1	0	0	...
...	1	0	0	0	0	0	...
...	0	5	-6	2	0	0	...

Finding robust solutions of P-recursive sequences

$$L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3 \in \mathbb{C}[n]\langle S \rangle \text{ with } Sn = (n+1)S$$

- ▶ **Deformed action:** L acts on $\mathbb{C}(q)^{\mathbb{Z}}$ or $\mathbb{C}((q))^{\mathbb{Z}}$ via $(n \cdot u)_k = (k+q)u_k$
- ▶ **Recover usual solutions by setting $q = 0$**

0	1	2	3	4	5	...
1	0	0				
0	1	0				
0	0	1				

Finding robust solutions of P-recursive sequences

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0	1	2	3	4	5	...
1	0	0	$-q-1$			
0	1	0	0			
0	0	1	$\frac{3-q}{q-1}$			

Finding robust solutions of P-recursive sequences

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0	1	2	3	4	5	...
1	0	0	$-q-1$	$\frac{(q+1)(q-2)}{q}$		
0	1	0	0	$-q-2$		
0	0	1	$\frac{3-q}{q-1}$	$\frac{(q-3)(q-2)}{q(q-1)}$		

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0	1	2	3	4	5	...
1	0	0	$-q-1$	$\frac{(q+1)(q-2)}{q}$	$\frac{(q-2)(1-q)}{q}$	
0	1	0	0	$-q-2$	$\frac{(q-1)(q+2)}{q+1}$	
0	0	1	$\frac{3-q}{q-1}$	$\frac{(q-3)(q-2)}{q(q-1)}$	$\frac{6+\dots}{q(q+1)}$	

Finding robust solutions of P-recursive sequences

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0	1	2	3	4	5	...
1	0	0	$-q-1$	$\frac{(q+1)(q-2)}{q}$	$\frac{(q-2)(1-q)}{q}$...
0	1	0	0	$-q-2$	$\frac{(q-1)(q+2)}{q+1}$...
0	0	1	$\frac{3-q}{q-1}$	$\frac{(q-3)(q-2)}{q(q-1)}$	$\frac{6+\dots}{q(q+1)}$...

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0	1	2	3	4	5	...
1	0	0	$-q-1$	$\frac{(q+1)(q-2)}{q}$	$\frac{(q-2)(1-q)}{q}$...
0	1	0	0	$-q-2$	$\frac{(q-1)(q+2)}{q+1}$...
0	0	1	$\frac{3-q}{q-1}$	$\frac{(q-3)(q-2)}{q(q-1)}$	$\frac{6+\dots}{q(q+1)}$...
q	0	0	$-q(q+1)$	$(q+1)(q-2)$	$(q-2)(1-q)$...
0	0	q	$\frac{q(3-q)}{q-1}$	$\frac{(q-3)(q-2)}{q-1}$	$\frac{6+\dots}{q+1}$...

Finding robust solutions of P-recursive sequences

$$L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3 \in \mathbb{C}[n]\langle S \rangle \text{ with } Sn = (n+1)S$$

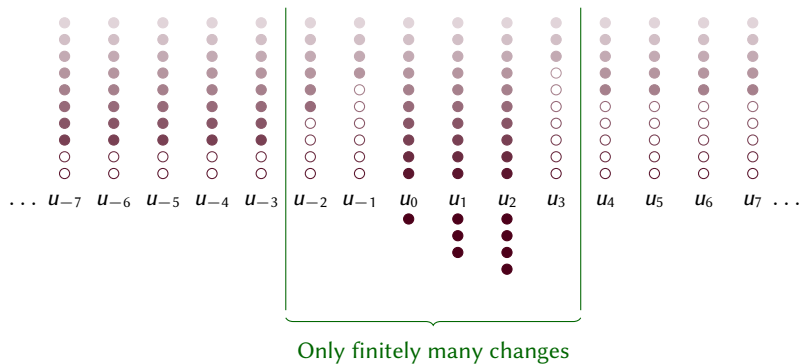
► **Deformed action:** L acts on $\mathbb{C}(q)^{\mathbb{Z}}$ or $\mathbb{C}((q))^{\mathbb{Z}}$ via $(n \cdot u)_k = (k+q)u_k$

► **Recover usual solutions by setting $q = 0$**

0	1	2	3	4	5	...
1	0	0	$-q-1$	$\frac{(q+1)(q-2)}{q}$	$\frac{(q-2)(1-q)}{q}$...
0	1	0	0	$-q-2$	$\frac{(q-1)(q+2)}{q+1}$...
0	0	1	$\frac{3-q}{q-1}$	$\frac{(q-3)(q-2)}{q(q-1)}$	$\frac{6+\dots}{q(q+1)}$...
q	0	0	$-q(q+1)$	$(q+1)(q-2)$	$(q-2)(1-q)$...
0	0	q	$\frac{q(3-q)}{q-1}$	$\frac{(q-3)(q-2)}{q-1}$	$\frac{6+\dots}{q+1}$...
$\frac{q-3}{q-1}$	0	$-q-1$	0	0	$(q+1)(q+3)$...

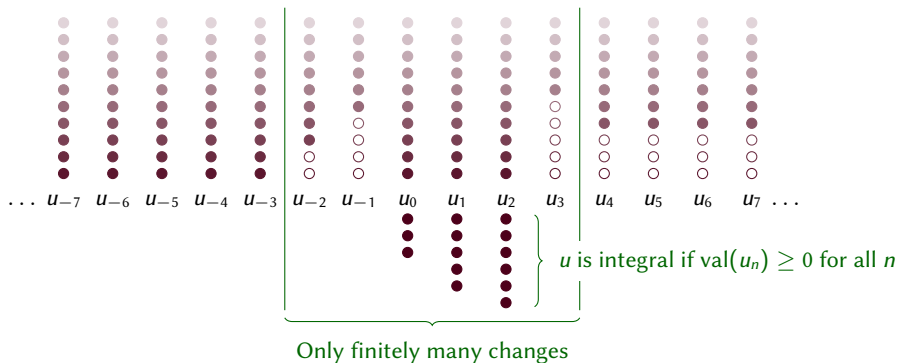
P-recursive sequences: what are poles?

In practice, robust solutions of an operator look like this:



P-recursive sequences: what are poles?

In practice, normalized robust solutions of an operator look like this:



- ▶ Given $L \in C[n]\langle S \rangle$ with order r , it has r independent normalized solutions $u^{(1)}, \dots, u^{(r)}$ in $C((q))^{\mathbb{Z}}$
- ▶ $B \in C(n)\langle S \rangle / \langle L \rangle$ acts on those solutions
- ▶ **Valuation** of B at $\alpha \in \mathbb{Z}$: min of the valuations of $B \cdot u^{(i)}$ at α
- ▶ B is **integral** iff it has non-negative valuation everywhere

Van Hoeij's algorithm for finding integral bases (recurrence case)

Local algorithm: **exactly the same!**

$u^{(1)}, \dots, u^{(r)} \in C((q))^{\mathbb{Z}}$
basis of solutions of L

Input. $L \in C[n]\langle S \rangle$ with order r , $\alpha \in \mathbb{Z}$

Output. B_1, \dots, B_r basis of $C(n)\langle S \rangle / \langle L \rangle$ integral at α

1. $B_1, \dots, B_r \leftarrow$ basis of $C(n)\langle S \rangle / \langle L \rangle$

$B_1, \dots, B_r \leftarrow 1, \dots, S^{r-1}$

2. For $d \in \{1, \dots, r\}$:

3. While B_i is not integral at α

$B_i \cdot u^{(j)}$ has **val** < 0 at α for some j

4. $B_i \leftarrow (x - \alpha)B_i$

5. While there exists $a_1, \dots, a_{d-1} \in C$

such that $A := \frac{1}{x-\alpha} (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d)$ is integral at α

6. $B_d \leftarrow A$

$\iff \forall j, (a_1 B_1 + \dots + a_{d-1} B_{d-1} - B_d) \cdot u^{(j)}$ has **val** > 0 at α

7. Return B_1, \dots, B_r

Linear system of equations



















Global algorithm: loop over all $\alpha \in \mathbb{Z}$

Nothing happens at all but finitely many of them
(roots of the leading and trailing coefficients of L)

Van Hoeij's algorithm for recurrences on an example (1)




Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$

Basis of solutions in $C((q))^{\mathbb{N}}$:

	0	1	2	3	4	5	...
u	 1	 0	 0	 $-1+O(q)$	 $-2q^{-1}+O(1)$	 $-2q^{-1}+O(1)$...
v	 0	 1	 0	 0	 $-2+O(q)$	 $-2+O(q)$...
w	 0	 0	 1	 $-3+O(q)$	 $-6q^{-1}+O(1)$	 $-6q^{-1}+O(1)$...







Van Hoeij's algorithm for recurrences on an example (2)

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$, $\alpha = 3$

B	1	
$(B \cdot u)_3$	 $-1 + O(q)$	
$(B \cdot v)_3$	 0	
$(B \cdot w)_3$	 $-3 + O(q)$	










Van Hoeij's algorithm for recurrences on an example (2)

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$, $\alpha = 3$

B	1	S
$(B \cdot u)_3$	 $-1 + O(q)$	 $-2q^{-1} + O(1)$
$(B \cdot v)_3$	 0	 $-2 + O(q)$
$(B \cdot w)_3$	 $-3 + O(q)$	 $-6q^{-1} + O(1)$










Van Hoeij's algorithm for recurrences on an example (2)

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$, $\alpha = 3$

B	1	S	$(n-3)S$
$(B \cdot u)_3$	 $-1 + O(q)$	 $-2q^{-1} + O(1)$	 $-2 + O(q)$
$(B \cdot v)_3$	 0	 $-2 + O(q)$	 $-2q + O(q^2)$
$(B \cdot w)_3$	 $-3 + O(q)$	 $-6q^{-1} + O(1)$	 $-6 + O(q)$













Van Hoeij's algorithm for recurrences on an example (2)

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$, $\alpha = 3$

B	1	S	$(n-3)S$
$(B \cdot u)_3$	 $-1 + O(q)$	 $-2q^{-1} + O(1)$	 $-2 + O(q)$
$(B \cdot v)_3$	 0	 $-2 + O(q)$	 $-2q + O(q^2)$
$(B \cdot w)_3$	 $-3 + O(q)$	 $-6q^{-1} + O(1)$	 $-6 + O(q)$
















Van Hoeij's algorithm for recurrences on an example (2)

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$, $\alpha = 3$

B	1	S	$(n-3)S$	$(n-3)S - 2$
$(B \cdot u)_3$	 $-1 + O(q)$	 $-2q^{-1} + O(1)$	 $-2 + O(q)$	 $q + O(q^2)$
$(B \cdot v)_3$	 0	 $-2 + O(q)$	 $-2q + O(q^2)$	 $-2q + O(q^2)$
$(B \cdot w)_3$	 $-3 + O(q)$	 $-6q^{-1} + O(1)$	 $-6 + O(q)$	 $3q + O(q^2)$
















Van Hoeij's algorithm for recurrences on an example (2)

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$, $\alpha = 3$

B	1	S	$(n-3)S$	$(n-3)S - 2$	$S - \frac{2}{n-3}$
$(B \cdot u)_3$	 $-1 + O(q)$	 $-2q^{-1} + O(1)$	 $-2 + O(q)$	 $q + O(q^2)$	 $1 + O(q)$
$(B \cdot v)_3$	 0	 $-2 + O(q)$	 $-2q + O(q^2)$	 $-2q + O(q^2)$	 $-2 + O(q)$
$(B \cdot w)_3$	 $-3 + O(q)$	 $-6q^{-1} + O(1)$	 $-6 + O(q)$	 $3q + O(q^2)$	 $3 + O(q)$
















Van Hoeij's algorithm for recurrences on an example (2)

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B	1	S	$(n-3)S$	$(n-3)S - 2$	$S - \frac{2}{n-3}$
$(B \cdot u)_3$	 $-1 + O(q)$	 $-2q^{-1} + O(1)$	 $-2 + O(q)$	 $q + O(q^2)$	 $1 + O(q)$
$(B \cdot v)_3$	 0	 $-2 + O(q)$	 $-2q + O(q^2)$	 $-2q + O(q^2)$	 $-2 + O(q)$
$(B \cdot w)_3$	 $-3 + O(q)$	 $-6q^{-1} + O(1)$	 $-6 + O(q)$	 $3q + O(q^2)$	 $3 + O(q)$

Van Hoeij's algorithm for recurrences on an example (2)

Example: $L = (n-1)(n+1) + (n-3)S^2 + (n-1)S^3$, $\alpha = 3$

B	1	S	$(n-3)S$	$(n-3)S - 2$	$S - \frac{2}{n-3}$	S^2
$(B \cdot u)_3$	 $-1 + O(q)$	 $-2q^{-1} + O(1)$	 $-2 + O(q)$	 $q + O(q^2)$	 $1 + O(q)$	\dots
$(B \cdot v)_3$	 0	 $-2 + O(q)$	 $-2q + O(q^2)$	 $-2q + O(q^2)$	 $-2 + O(q)$	\dots
$(B \cdot w)_3$	 $-3 + O(q)$	 $-6q^{-1} + O(1)$	 $-6 + O(q)$	 $3q + O(q^2)$	 $3 + O(q)$	\dots

Application and perspectives

Why do we care?

- ▶ In the differential case, integral bases can be used to compute integrals
- ▶ We hope that in the recurrence case, they can be used to compute sums
- ▶ **Future work:** /s/hope/prove/

What if it is the wrong definition for that?

- ▶ The definitions and the algorithm generalize to **valued vector spaces**
- ▶ No particularly restricting hypothesis
- ▶ So if the definition is wrong, we only have to find the correct one!

References

- ▶ Kauers and Koutschan, ‘Integral D-finite Functions’ (2015)
- ▶ Chen, van Hoeij, Kauers and Koutschan, ‘Reduction-based Creative Telescoping for Fuchsian D-finite Functions’ (2018)
- ▶ Chen, Du, Kauers and Verron, ‘Integral P-Recursive Sequences’ (2020) [preprint]

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Why do we care?

- ▶ In the differential case, integral bases can be used to compute integrals
- ▶ We hope that in the recurrence case, they can be used to compute sums
- ▶ **Future work:** /s/hope/prove/

What if it is the wrong definition for that?

- ▶ The definitions and the algorithm generalize to **valued vector spaces**
- ▶ No particularly restricting hypothesis
- ▶ So if the definition is wrong, we only have to find the correct one!

References

- ▶ Kauers and Koutschan, ‘Integral D-finite Functions’ (2015)
- ▶ Chen, van Hoeij, Kauers and Koutschan, ‘Reduction-based Creative Telescoping for Fuchsian D-finite Functions’ (2018)
- ▶ Chen, Du, Kauers and Verron, ‘Integral P-Recursive Sequences’ (2020) [preprint]

Thank you for your attention