

Machine learning for HOMO-LUMO-gap Prediction and Inverse Molecular Design

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Abstract

In the abstract of your paper, briefly summarize your research in about 150 to 250 words. Briefly explain the problem statement, the techniques you used, and your general results. You can't go into deep detail here, of course, but you don't have to. Think of this as a kind of written "elevator pitch": explain your research to someone who has 1-2 minutes time to listen.

1 Introduction

Within the spectrum of discrete energy levels (molecular orbitals) in a molecule that can be filled with electrons, the HOMO-LUMO gap is the energy difference between the highest occupied molecular orbital (HOMO) and lowest unoccupied molecular orbital (LUMO). This is a fundamental descriptor of the electronic structure of a molecule and is strongly influenced by the specific molecular structure and its functional groups. The HOMO-LUMO gap governs key properties such as reactivity, optical absorption and charge transport characteristics and is directly related to the band-gap in conductivity, determining whether a material behaves as a conductor, insulator or semi-conductor (Dwivedi et al., 2025). The HOMO-LUMO gap also influences the efficiency of organic photovoltaics (solar cells based on organic molecules) and organic light-emitting devices (OLED-technology) (Liu et al., 2015). As a consequence, accurate determination of the HOMO-LUMO gap and design of molecular materials with a specified HOMO-LUMO gap is essential for both materials science and molecular engineering.

Determining the HOMO-LUMO gap, by approximation, is typically done in an experimental setting through optical spectroscopy or voltammetry (Costa et al., 2016; Sworakowski, 2018). However, experimental measurements require synthesized, purified materials making large-scale exploration of hypothetical chemical structures cost expensive and time consuming. As an alternative, methods in computational quantum chemistry, such as Hartree-Fock and Density functional theory (DFT) are used to simulate approximations. Despite their accuracy, these quantum chemical methods are computationally expensive and scale poorly with molecular size and dataset volume, also restricting the capacity of HOMO-LUMO gap exploration and molecular design.

Machine learning (ML) provides a strategy to overcome these computational limitations (Hasan et al., 2025). After training, ML models can predict electronic properties with negligible computational cost compared to traditional quantum chemistry. Crucially, large-scale quantum-chemical datasets like QM9, contain extensive information about molecular structures and properties of organic molecules, enabling the development and benchmarking of ML models with the data volume required for robust learning. Beyond property prediction, ML also enables generative molecular

design, making it possible to explore hypothetical chemical structures, optimize properties in silico, and drastically reduce the number of costly experiments. This accelerates molecular discovery pipelines, supports safer design exploration, and opens chemical regions that would be impractical to investigate experimentally.

In this study, we pursue a two-fold objective. First, we build predictive models for HOMO-LUMO gap estimation using both Light Gradient Boosting Model (LightGBM), a high-performance gradient boosting framework and a graph convolutional network (GCN) that learns molecular representations directly from graph topology. Second, we integrate the predictive GCN into a conditional variational autoencoder (cVAE) to generate novel molecular structures with user-specified target HOMO-LUMO gaps. This combined framework enables both accurate property prediction and inverse molecular design, supporting accelerated discovery workflows in molecular design and thereby potentially facilitating a more directed control of specific chemical reactions and increasing the relevance of organic based technology (like OPVs and OLED).

NEED TO ADD A PART ABOUT OUR RESULTS

2 Related work

In recent years, significant progress has been made in predicting HOMO-LUMO gaps using various ML techniques, such as deep learning, ensemble methods, and graph-based models. Early descriptor-based regression models achieved MAEs in the range of about 0.10-0.25 eV using methods such as Random Forests or LightGBM on connectivity/descriptor features [references?](#).

why use LightGBM

Graph neural networks (GNNs) have emerged as a powerful tool to predict molecular properties from graph representations of molecular structures. As there is still a lack of 3D graph-based and 3D grid-based methods for molecular property prediction (Li et al., 2022), we will focus on a 2D graph-based model. One such model that is common for molecular property prediction, but also specifically for HOMO-LUMO prediction, is the graph convolutional network (GCN) (Choi et al., 2022; Therrien et al., 2025; Xia et al., 2023).

Xia et al. (2023) demonstrated that deep-learning models generally are unable to outperform non-deep ones for molecular property prediction. However, Xia et al. (2023) also report MAEs of the predicted HOMO-LUMO gap (using the QM9 dataset) that indicate graph-based deep-learning models as more accurate than traditional models. To more clearly assess whether graph-based deep-learning models outperform traditional models for HOMO-LUMO gap prediction, we chose to compare the performance of a LightGBM model with that of a graph convolutional network (GCN).

In the context of generative models, variational autoencoders (VAEs) have emerged as a standard framework for de novo molecular design (Walters & Barzilay, 2021). One of the more recent influential works is done by Gómez-Bombarelli et al. (2018), which adopted a variational autoencoder to optimize the molecular properties in a latent space and uses a Gaussian process to optimize a chemical structure with the desired properties. Lim et al. (2018) later demonstrated a conditional VAE framework that enables property-controlled molecular generation and serves as a foundational inspiration for our work. Both studies highlight limitations arising from SMILES-based representations and suggest that graph-based encoders and decoders could better capture molecular structure and improve validity, motivating the graph-based generative approach adopted in our research.

TO BE CHANGED

3 Methodology

3.1 Dataset

For all models in this study, we used the QM9 dataset (Team, 2024), a widely adopted quantum chemistry dataset comprising 130,831 small organic molecules with associated properties, including the HOMO–LUMO gap. Only molecules with valid SMILES representations were retained, leaving 129,012 molecules, can be seen in Figure 1. SMILES (Simplified Molecular Input Line Entry System) is a text-based notation that encodes chemical structures as ASCII strings, enabling efficient computational processing; for example, benzene is represented as C1=CC=CC=C1. While SMILES strings can be interpreted by computers, they are not directly suitable as input for most machine learning models, which require numerical representations. Consequently, preprocessing is necessary to transform molecular structures into informative, fixed-length numerical features suitable for model training.

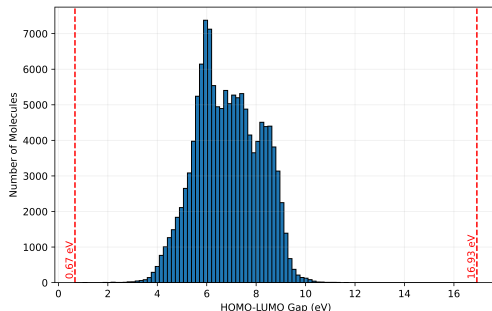


Figure 1: Illustration of the bandgap distribution in the QM9 dataset where only the valid molecules are kept. The vertical dashed lines indicate the minimum and maximum bandgap values in the dataset.

3.2 Molecular Representations and Preprocessing

In this study, we focus on two different models for HOMO-LUMO gap prediction: LightGBM, a classical machine learning model and GCN, a deep learning model, which require different types of molecular representations. Therefore, two types of molecular representations were generated from the SMILES strings.

3.2.1 DESCRIPTOR-BASED FEATURES FOR LIGHTGBM

Using RDKit, a set of 217 molecular descriptors was generated for each molecule from the SMILES representation (RDKit: Open-Source Cheminformatics, 2025). These descriptors capture various aspects of molecular structure and properties, including molecular size, shape, electronic characteristics, surface area, and the presence of functional groups. Together, they provide a fixed-length numerical representation of each molecule suitable for machine learning models such as LightGBM.

3.2.2 GRAPH-BASED REPRESENTATION FOR GCN:

For graph neural networks, molecules are represented as graphs where atoms are nodes and bonds are edges. As the QM9 dataset represents molecules as SMILES, all molecule SMILES were translated to a node and edge matrix using the *Chem* package of RDKit (RDKit Developers, 2025). Node features include atomic number, formal charge, hybridization, aromaticity, and whether the atom is in a ring

structure. The edge matrix was defined as an adjacency matrix where the diagonal elements were set to 1, indicating a self-connection, which makes the matrix amenable to convolutions (Deshmukh, 2023). The distance of each bond was included in the edge matrix as 1 over the bond distance. The representation of a molecule as a node and edge matrix allows the GCN to learn structural features directly from molecular graphs without relying on precomputed descriptors.

3.3 Data Splitting

To ensure unbiased evaluation, the dataset was split into training, validation, and test sets. For all models, nested cross-validation was used:

- **Outer loop:** 5-fold cross-validation to estimate generalization performance
- **Inner loop:** 10-fold cross-validation for hyperparameter tuning

The splits were stratified based on the distribution of the HOMO-LUMO gap values into 10 quantile bins to preserve this distribution across the different folds.

3.4 Evaluation metrics

Since both the LightGBM and GCN models are used to predict HOMO-LUMO gaps and are directly compared, the same evaluation metrics are applied to both. Commonly used metrics for HOMO-LUMO gap prediction include the mean absolute error (MAE), root mean squared error (RMSE), and the coefficient of determination (R^2) between the predicted and true HOMO-LUMO gaps.

The cVAE model performance is evaluated using the average character-level reconstruction accuracy (\overline{CRA}), the chemical validity of newly generated SMILES strings using RDKit, and the agreement between the target HOMO-LUMO gap and the GCN-predicted gap of the generated molecules, quantified using MAE. Each metric is calculated as

$$MAE = \frac{1}{N} \sum^N |y_{pred} - y_{true}| \quad (1)$$

$$RMSE = \sqrt{\frac{1}{N} \sum^N (y_{pred} - y_{true})^2} \quad (2)$$

$$R^2 = 1 - \frac{\sum^N (y_{true} - y_{pred})^2}{\sum^N (y_{true} - \bar{y})^2} \quad (3)$$

$$\overline{CRA} = \frac{1}{N} \sum_{n=1}^N \frac{1}{T_n} \sum_{t=1}^{T_n} \mathbf{1}(\hat{x}_{n,t} = x_{m,t}) \quad (4)$$

with N the total number of test molecules and T_n the number of characters per SMILES string.

3.5 LightGBM

LightGBM is a gradient-boosted decision tree algorithm optimized for speed and high-dimensional data. It grows trees in a leaf-wise rather than level-wise manner, allowing it to capture complex, non-linear relationships more efficiently than many traditional boosting methods. This makes it well-suited for tabular molecular descriptor data, as it is robust to feature scaling, multicollinearity, and missing values.

Hyperparameter optimization for the LightGBM model was carried out using Optuna. The search space included parameters controlling model complexity and regularization: the number of leaves (num_leaves, 16–256), the learning rate (learning_rate, 1×10^{-3} –0.1, log-scaled), feature subsampling (feature_fraction, 0.7–1.0), sample bagging (bagging_fraction, 0.7–1.0; bagging_freq, 1–5), and the minimum number of samples per leaf (min_data_in_leaf, 10–100). Other LightGBM settings, such as the boosting type (gbdt) and objective function (regression_l1), were kept fixed throughout. Optuna selected the optimal hyperparameter configuration by minimizing the mean absolute error (MAE) obtained from the inner loop of the nested cross-validation, using a total of 50 trials.

After nested cross-validation, the best-performing hyperparameters were selected (either by averaging over outer folds or by majority vote). The final LightGBM model was then trained on the entire dataset to produce predictions for comparison with the GCN model.

3.6 GCN

The implementation of the GCN model was based on a tutorial about creating a simple Pytorch-based GCN (Deshmukh, 2023). Some edits to the tutorial code were made, for example the addition of node features, the addition of an R^2 metric, and correcting a mistake with the standardization of the loss.

Starting from the node and edge matrix representations of a graph, the GCN model first applied a graph convolution using multiple convolution layers. Each convolution layer gives a node information about its neighbors using the matrix multiplication shown in Figure 2. After the convolution layers *pooling* is applied, which turns the 2-dimensional matrix into a 1-dimensional vector that contains the means of every column of the node matrix. This vector can then be passed to the neural network, which is a simple multilayer perceptron (MLP), a fully connected feedforward neural network. For more details on the implementation, see the GitHub repository (ThiboVE, 2025).

	H	H	H	C	C	O	N	H	H										
H	1	0	0	1	0	0	0	0	0	H	0	1	0	0	0	0	0	0	0
H	0	1	0	1	0	0	0	0	0	H	0	1	0	0	0	0	0	0	0
H	0	0	1	1	0	0	0	0	0	H	0	1	0	0	0	0	0	0	0
C	1	1	1	1	1	0	0	0	0	C	0	0	0	0	0	0	1	0	0
C	0	0	0	1	1	1	1	0	0	C	0	0	0	0	0	0	1	0	0
O	0	0	0	0	1	1	0	0	0	O	0	0	0	0	0	0	0	0	1
N	0	0	0	0	1	0	1	1	1	N	0	0	0	0	0	0	0	1	0
H	0	0	0	0	0	0	1	1	0	H	0	1	0	0	0	0	0	0	0
H	0	0	0	0	0	0	1	0	1	H	0	1	0	0	0	0	0	0	0

Equation legend
 $\eta_k = k^{\text{th}} \text{node vector}$
 $\bar{\eta}_k = \text{convoluted } k^{\text{th}} \text{node vector}$
 $N_G(\eta_k) = \text{neighbors of } k^{\text{th}} \text{node}$
 $d_k = \text{degree of } k^{\text{th}} \text{node}$

$$\sigma \left(\begin{matrix} D_{n \times n}^{-1} & A_{n \times n} & N_{n \times m} & W_{m \times m'} \\ \text{Inverse diagonal} & \text{Adjacency} & \text{Node} & \text{Weight} \\ \text{degree matrix} & \text{matrix} & \text{matrix} & \text{matrix} \\ d_i^{-1} = \sum_j \frac{1}{a_{ij}} & & & \\ \text{From a nodal perspective, this product is equivalent to} & & & \end{matrix} \right) = N'_{n \times m'}$$

$$\bar{\eta}_i = \frac{\eta_i + \sum_{j \in N_G(\eta_i)} \eta_j}{d_i}$$

Figure 2: Graph convolution for an acetamide molecule (Deshmukh, 2023).

Hyperparameter optimization for the GCN model was performed using a simple grid search, as this allowed easy parallelization of hyperparameter tuning. The parameters and their possible values included in the grid search are: `batch_size` (64, 128, 256, 384), `hidden_nodes` (64, 96, 128), `n_conv_layers` (1-5), `n_hidden_layers` (1-3), `learning_rate` (0.001, 0.003, 0.005, 0.007, 0.01). Other parameters such as the maximum dimensions of the node and edge matrix, and the number of epochs were kept constant. After nested cross-validation, the same best-performing hyperparameters were obtained for each outer fold: `batch_size` = 256, `hidden_nodes` = 128, `n_conv_layers` = 4, `n_hidden_layers` = 2, `learning_rate` = 0.003, the number of epochs was kept constant at 50.

3.7 cVAE

The conditional variational autoencoder (cVAE) is chosen for its probabilistic nature, which enables sampling of new molecules with higher validity than a standard autoencoder (Kingma & Welling, 2019). Our implementation is partially inspired by (Gómez-Bombarelli et al., 2018; Lim et al., 2018), except for the encoder. The model consists of a graph-based GCN encoder, a continuous conditioned latent space, and a GRU sequence decoder (Cho et al., 2014; Yuan et al., 2020), combining the richer information from graph representations with the simplicity of SMILES decoding.

Training maximizes the conditional ELBO (equivalently, minimizes the negative ELBO), composed of a categorical cross-entropy reconstruction loss and a Kullback-Leibler divergence regularizing the latent space (Beckham, 2023):

$$\mathcal{L}_{cVAE} = -\mathbb{E}[\log p(x|z, y)] + \beta D_{KL}(q(z|x, y) \parallel \mathcal{N}(0, I)) \quad (5)$$

where $q(z|x, y)$ is the encoder’s approximate posterior, mapping a molecule and its HOMO-LUMO gap to a latent distribution, and $p(x|z, y)$ is the decoder’s likelihood, giving the probability of reconstructing a SMILES sequence from a latent vector and conditioning value.

Hyperparameters are optimized using Bayesian optimization with a TPE sampler (Watanabe, 2023), although only a limited search is feasible, consisting of only 15 trials, due to the large parameter space and time constraints. For the same reason, five inner folds are used for cross-validation instead of ten, but given the large size of the QM9 dataset, this reduction is not expected to significantly affect the results. An overview of the selected optimal hyperparameters is provided in Table 5.

The optimal set of hyperparameters is used to generate new molecules using two approaches: random sampling of latent vectors from the latent space and perturbation of latent vectors corresponding to molecules in the dataset by adding noise drawn from a normal distribution scaled by a factor of 0.5. In both cases, the latent vectors are decoded while conditioning on target HOMO-LUMO gaps.

For each experimental pathway, ten molecules with distinct target HOMO-LUMO gaps are selected. For each molecule, 1,000 generations are performed, and the average chemical validity is computed, as described in Section 3.4. For the valid generations of each molecule, the mean absolute error (MAE) is calculated by comparing the HOMO-LUMO gap predicted by the GCN model with the corresponding target gap, yielding a per-molecule MAE.

4 Results

4.1 LightGBM

For the performance of the model we first looked to the mean absolute error (MAE), root mean square error (RMSE), and R^2 between the predicted and true HOMO-LUMO gap which are calculated for each outer cross-validation fold. These results are shown in Table 1 and Figure 3. We see that the values for the different metrics does not change much with each fold which is in line with the chosen stratified splits. The mean MAE of 0.1418 eV is in line with the 0.1-0.2 eV that can be found in literature [references](#).

maybe drop this paragraph as it states the obvious? Closer inspection of the plot suggests that the largest deviations occur for a molecule with the highest HOMO-LUMO gaps. This trend is expected given that extreme values are less frequently represented in the dataset, and gradient-boosted models may underperform slightly on sparse regions of the target distribution. Nonetheless, the scatter remains tightly clustered around the parity line for the bulk of the molecules, confirming robust generalization across the typical gap range.

Table 1: LightGBM : mean absolute error (MAE), root mean square error (RMSE), and R^2 between predicted and target HOMO-LUMO gaps per outer fold. Mean values across all five folds are also reported.

	MAE (eV)	RMSE (eV)	R^2
Outer Fold 1	0.1417	0.2160	0.9715
Outer Fold 2	0.1408	0.2122	0.9727
Outer Fold 3	0.1411	0.2200	0.9705
Outer Fold 4	0.1430	0.2183	0.9709
Outer Fold 5	0.1423	0.2227	0.9696
Mean	0.14	0.22	0.97

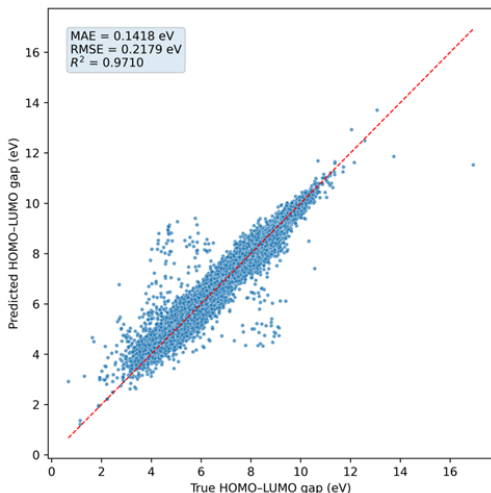


Figure 3: Predicted vs true HOMO-LUMO gap for all 5 outer folds together of the LightGBM model.

The feature importance stability plot (Figure 4) summarizes the mean and standard deviation of LightGBM feature importances across the five outer cross-validation folds for the top 20 descriptors.

Points indicate the average importance of each descriptor, while error bars reflect variability across folds, providing insight into both feature relevance and robustness. Several descriptors consistently dominate the model, most notably MinAbsEStateIndex, BCUT2D_{MWLOW}, and BCUT2D_{MRHI}, which exhibit high mean importance with low variability. This indicates that these features are both highly informative and stable predictors of the HOMO–LUMO gap.

Overall, feature importance shows a gradual decay, with approximately the top ten descriptors accounting for most of the predictive power. The low standard deviations observed for the most important features suggest that the model relies on a robust core of chemically meaningful descriptors that remain consistent across different training subsets. These results highlight the relevance of descriptors capturing electronic and topological properties, such as BCUT metrics and EState indices, for accurate HOMO-LUMO gap prediction, while lower-importance features appear to contribute only marginally to overall performance.

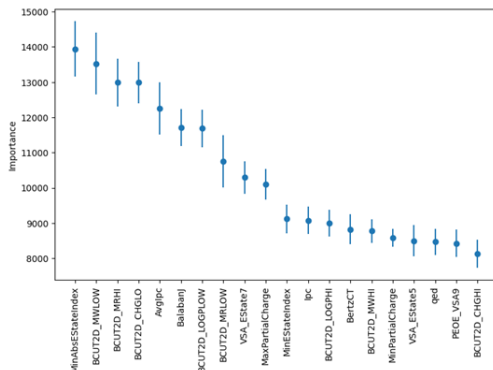


Figure 4: The top 20 most important features across the 5 outer folds where the error bar reflect variability across folds.

4.2 GCN

Just as for the LightGBM model, the mean absolute error (MAE), root mean square error (RMSE), and R^2 between the predicted and true HOMO-LUMO gap were determined for the GCN model. All evaluation metrics of the GCN model (Table 2) have slightly higher values than those of the LightGBM model (Table 1). The consistent appearance of the same group of outliers across all outer folds (upper left half of each R^2 plot in Figure 5) indicates that the stratified outer cross-validation split was balanced.

Table 2: GCN: Mean absolute error (MAE), root mean square error (RMSE), and R^2 between predicted and target HOMO-LUMO gaps per outer fold. Mean values across all five folds are also reported.

	MAE (eV)	RMSE (eV)	R^2
Outer Fold 1	0.1677	0.2403	0.9646
Outer Fold 2	0.1585	0.2280	0.9682
Outer Fold 3	0.1567	0.2255	0.9690
Outer Fold 4	0.1586	0.2231	0.9697
Outer Fold 5	0.1587	0.2299	0.9679
Mean	0.16	0.23	0.97

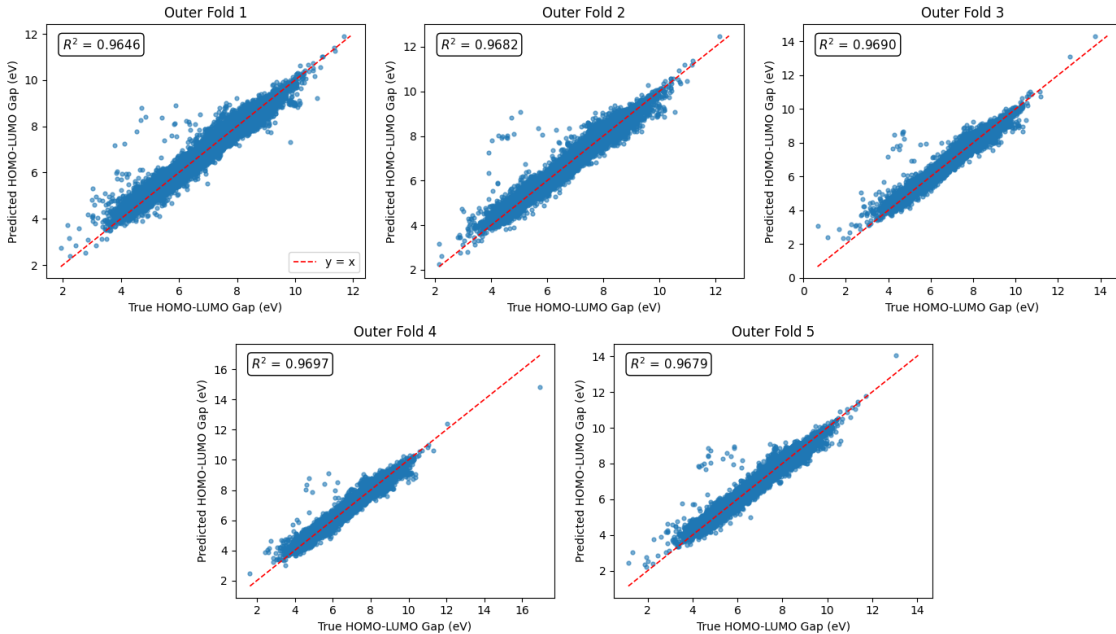


Figure 5: Predicted vs true HOMO-LUMO gap for all 5 outer folds of the GCN model.

4.3 cVAE

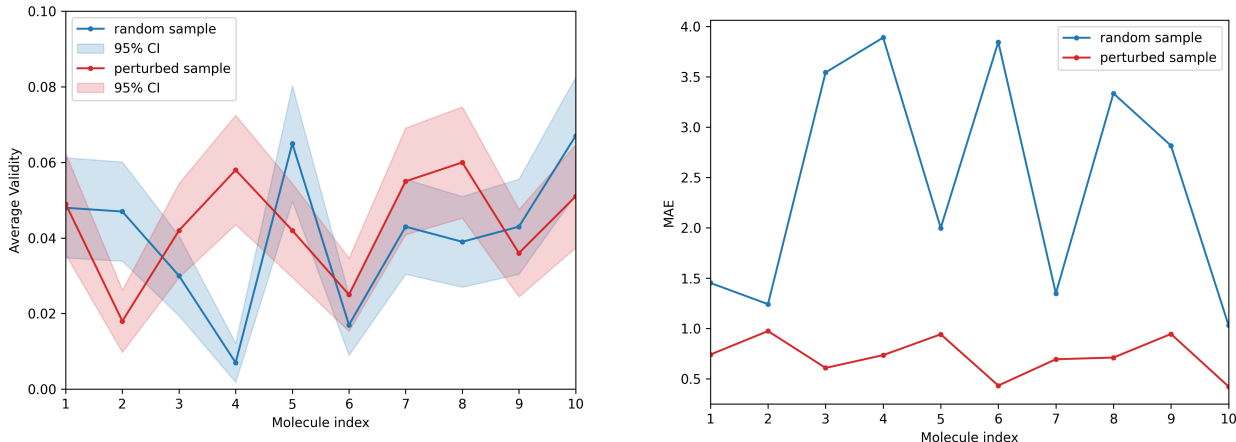
The reconstruction performance of the cVAE model, quantified by the average character-wise reconstruction accuracy \overline{CRA} , across the five outer cross-validation folds is reported in Table 3. The model achieves an overall mean reconstruction accuracy of 0.852, indicating that it is generally capable of accurately reconstructing individual molecules. Notably, outer folds three and five exhibit substantially higher reconstruction accuracies than the remaining folds. This improvement can be attributed to more favorable hyperparameter configurations identified during their respective tuning procedures (Table 5), in particular a higher learning rate, a larger GRU hidden dimension, and a lower β parameter.

Table 3: The average character-wise reconstruction accuracy, as calculated by Equation (4), of the test set per outer fold of the cross-validation.

	\overline{CRA}
Outer fold 1	0.842
Outer fold 2	0.840
Outer fold 3	0.871
Outer fold 4	0.846
Outer fold 5	0.863
Mean	0.852

Beyond reconstruction performance, the primary metric of interest is the generative capability of the cVAE. Using the best-performing trained model (outer fold 3), the chemical validity of molecules generated from both randomly sampled latent vectors and perturbed latent vectors is evaluated (Figure 6a and Table 4). Across the ten sampled target molecules in each experimental pathway, the average validity is low and comparable between the two sampling strategies, with no clear advantage observed for either method.

For each target molecule, the mean absolute error (MAE) between the HOMO-LUMO gaps predicted by the GCN model and the corresponding target gaps used to condition the cVAE (Section 3.7) is computed and reported in Table 4. It is important to note that this MAE is calculated per molecule and depends on the number of valid generations, as only valid molecules contribute to the error calculation. Consequently, the validity indirectly influences the MAE. Despite similar validity levels for both sampling methods, the perturbed latent sampling consistently yields substantially lower MAE values than random latent sampling. Nevertheless, for both approaches, the MAE remains considerably larger than the errors reported for the standalone GCN regression model.



(a) The average validity for both 10 randomly sampled latent vectors and 10 perturbed latent vectors with their respective 95% confidence intervals.

(b) The MAEs of the valid generated molecules for each of the 10 random and 10 perturbed samples.

Figure 6: A visual representation of the data from Table 4.

Table 4: The validity and MAE of the random samples and perturbed samples, obtained as described in Section 3.7.

	Random samples		Perturbed samples	
	Validity	gap MAE	Validity	gap MAE
1	0.048	1.453	0.049	0.742
2	0.047	1.242	0.018	0.975
3	0.030	3.543	0.042	0.609
4	0.007	3.889	0.058	0.736
5	0.065	1.999	0.042	0.943
6	0.017	3.845	0.025	0.434
7	0.043	1.349	0.055	0.695
8	0.039	3.335	0.060	0.712
9	0.043	2.816	0.036	0.946
10	0.067	1.032	0.051	0.424

Continuing with the perturbed latent space vectors, it is interesting to visualize some chemical structures to assess how well the cVAE can construct molecules with the same HOMO-LUMO gap

and slightly different chemical structures. From assessing molecules 1, 5 and 10 from Table 4, ... dont add too much as the section is already long enough, save the insights for the discussion section

5 Discussion

5.1 LightGBM and GCN have similar performances

Interpretation of LightGBM results and how it relates to literature

The GCN model achieves a mean MAE of approximately 0.16 eV for HOMO–LUMO gap prediction, with a consistently high R^2 of about 0.97 across all cross-validation folds (Table 2), indicating a balanced split. This performance improves upon a very recent GCN result reported for the PCQM4Mv2 dataset, where a MAE of around 0.20 eV was observed (Hu et al., 2021), and is competitive with other GCN based approaches reporting MAEs of 0.14 eV (Choi et al., 2022) and 0.12 eV (Therrien et al., 2025). Although the present model does not surpass the best-performing architectures in the literature, the relatively small performance gap suggests that a standard 2D GCN can capture most of the relevant structure–property relationships governing the HOMO–LUMO gap. Overall, these results reinforce the effectiveness of graph convolutional networks for molecular electronic property prediction while highlighting that further gains likely require more expressive models or additional structural information.

Although prior work has shown that deep-learning models do not consistently outperform non-deep models for molecular property prediction (Xia et al., 2023), our results show that the GCN attains comparable accuracy to that of the LightGBM model. While the GCN model learns chemically meaningful structural relationships through a graph, the LightGBM model uses descriptors of the molecule to learn mappings between these features and the target property. Rather than clearly favoring one approach over the other, our findings suggest that deep-learning and traditional models address the the prediction of HOMO-LUMO gap from complementary perspectives while achieving similar overall performance. A more comprehensive comparison across a wider range of models and datasets, similar to the analysis in Xia et al. (2023) but focused specifically on HOMO–LUMO gap prediction, would help clarify the relative advantages of traditional versus deep-learning approaches for this specific task.

5.2 cVAE

Results of cVAE related to literature and why we get the observed results

6 Conclusion

7 Disclaimers

Appendix A. Hyperparameters

Table 5: The optimized cVAE hyperparameters for each outer fold achieved after running 15 trials in a Bayesian optimization algorithm using a TPE sampler. The number of epochs and batch size were fixed to narrow the searching space of the Bayesian algorithm.

	fold 1	fold 2	fold 3	fold 4	fold 5
learning rate	0.00133	0.00133	0.00548	0.00133	0.00548
latent dimension	62	62	50	62	50
#hidden nodes	79	79	66	79	66
GRU dimension	42	42	64	42	64
#convolution layers	1	1	1	1	1
#hidden layers	1	1	2	1	2
#GRU layers	1	1	1	1	1
#FC layers	3	3	2	3	2
embedding dimension	18	18	14	18	14
teacher forcing ratio	0.876	0.876	0.888	0.876	0.888
β	4.62	4.62	1.88	4.62	1.88
batch size	1000	1000	1000	1000	1000
#epochs	15	15	15	15	15

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