if we assure G^1

$t \in \forall R : [0,1]$

Still Bounded

G^4

G^2

G^3

End

$t=.5$ present

$t=1$ target

Decision Space

escaping from local minima

$ present

$past

But free will that out puts a

Gradient Field π

G^4 G^3 G^2 G^1 ← function

$\Delta+$

next iteration of function is $present.

4d Space Time Area

Traversal is Automatically Least energy. Ie Entropy. State

$Future

Can "Decide" to Traverse to different decision state objectively. Gradient descent algorithms in ND space