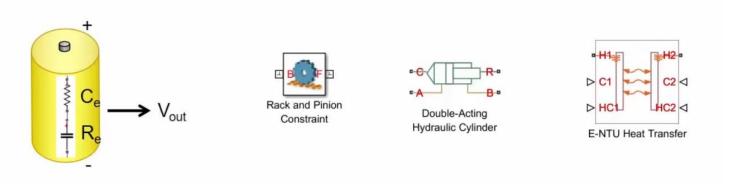
Physical Modeling Tutorial

Part1: Introduction to Simscape

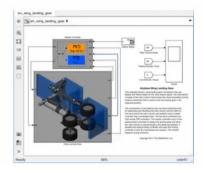
Outline

- Introduction to Simscape
- Modeling differences between Simulink and Simscape
- Building and simulating a model in Simscape
- Guidelines for Simscape modeling

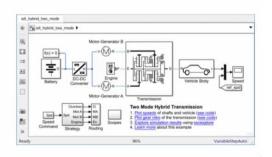


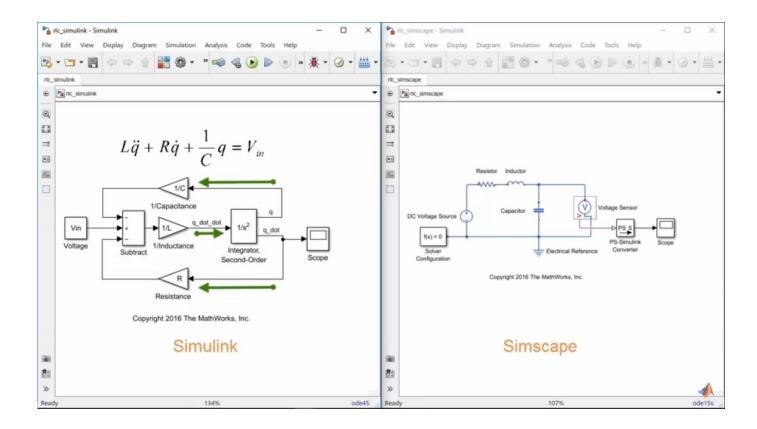
What is Simscape?

- Extends Simulink with libraries for modeling and simulating multidomain physical systems
- Contains models of foundation elements for various physical domains
- Contains other capabilities useful when modeling physical systems (unit manager, data logging, etc.)







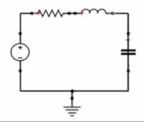


Modeling Differences Between Simulink and Simscape

Represented using equations

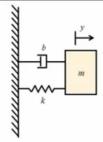
Represented using diagram

$$L\ddot{q} + R\dot{q} + \frac{1}{C}q = V_{in}$$



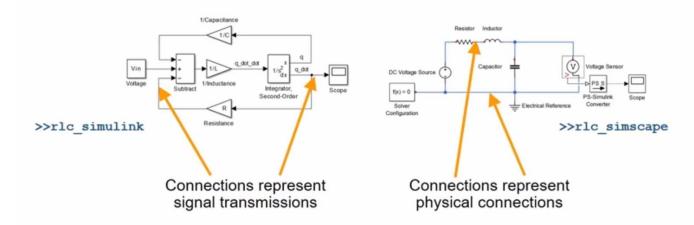
Mass-spring-damper

$$m\ddot{y} + b\dot{y} + ky = 0$$



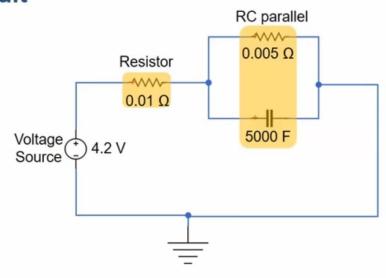


Modeling Differences Between Simulink and Simscape (Electrical System)



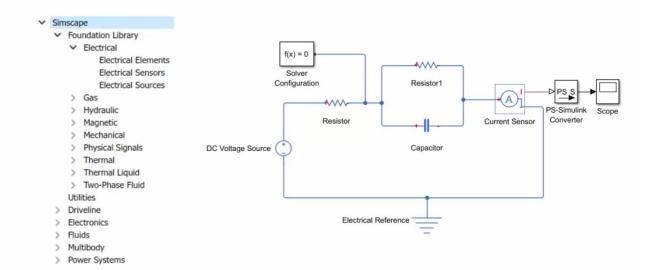


RC Circuit



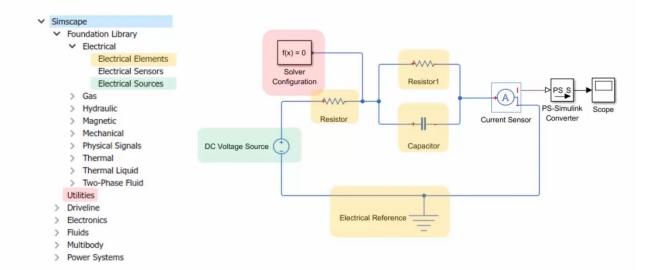


Building the Simscape Model



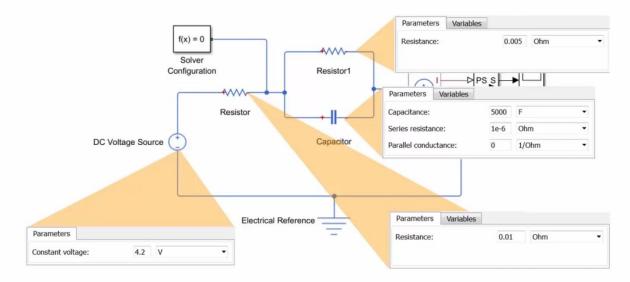


Building the Simscape Model



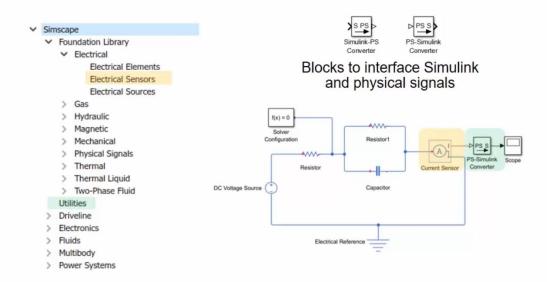


Setting Block Parameters



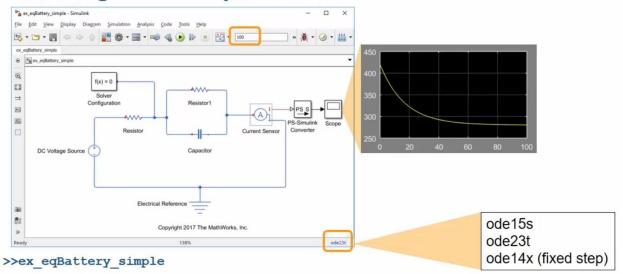


Measuring the Current





Simulating a Simscape Model



Use a recommended solver with Simscape models.

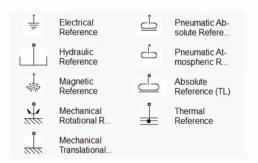


Important Blocks

Solver Configuration block



Domain specific reference block





Connection Guidelines

You can only connect two physical connection ports of the same physical domain.

