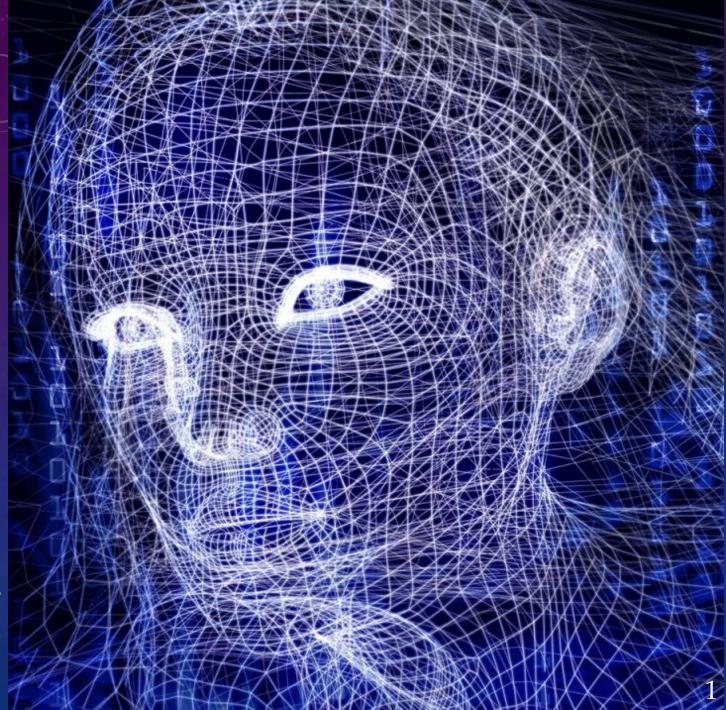
DIGITAL SURVEILLANCE
SYSTEMS AND APPLICATION

CH 2_EXERCISE

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Digital Surveillance Systems and Application

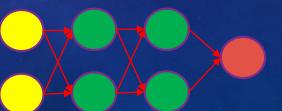
Please download 2-1_log_regression_visualize.zip and unzip it.

- Given an architecture with input size=2, hidden layer=2 and output size=1.
- Each layer is followed by ReLU activation function.
- In this case, we can know how to use "Autograd" to use the loss to compute the gradient; and how to establish a neural network in Pytorch.

Step:

- Autograd
- Build A Neural Network

```
Feedforward(
  (input): Linear(in_features=2, out_features=2, bias=True)
  (relu1): ReLU()
  (fc1): Linear(in_features=2, out_features=2, bias=True)
  (relu2): ReLU()
  (fc2): Linear(in_features=2, out_features=2, bias=True)
  (relu3): ReLU()
  (output): Linear(in_features=2, out_features=1, bias=True)
)
```



Yellow: Input layer

Green: Hidden layer

Orange: Output layer

- Autograd, which is an automatic differentiation package provided by PyTorch.
- The gradient can only be calculated if your variable is a function of the variable you want to differentiate.

```
import torch
x = torch.ones(1, requires_grad=True)
print(x.grad) # returns None
```

Example:

import torch $x = \text{torch.ones}(1, \text{requires_grad=True})$ y = x + 2 z = y * y * 2z.backward() # automatically calculates the gradient print(x.grad) # $\partial z/\partial x = 12$

.backward() : performs the
backpropagation automatically

$$\frac{\partial z}{\partial x} = \frac{\partial 2y^2}{\partial x}$$

$$= 4y \frac{\partial y}{\partial x}$$

$$= 4(x+2) \frac{\partial (x+2)}{\partial x}$$

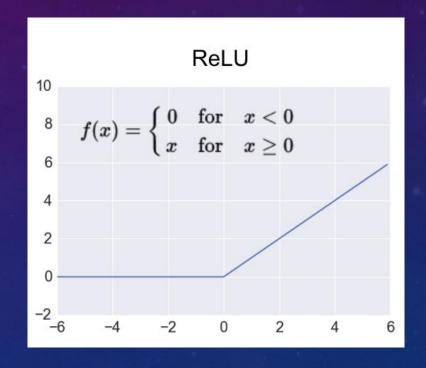
$$= 4(x+2)$$

$$\to x = 1$$

$$\to \frac{\partial z}{\partial x} = 12$$

Example:

```
class Perceptron(torch.nn.Module):
    def __init__(self):
        super(Perceptron, self).__init__()
        self.fc = nn.Linear(1,1)
        self.relu = torch.nn.ReLU()
    def forward(self, x):
        output = self.fc(x)
        output = self.relu(x)
        return output
```

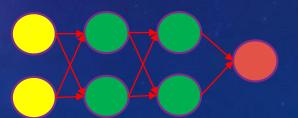


self.fc = outputs linear information self.relu = makes it non-linear

```
class Fedforward(torch.nn.Module):
    def init (self):
      super(Feedforward, self).__init__()
      self.input_size = 2
      self.hidden_size = 2
                               --- Parameters
      self.output size = 1
      self.input = torch.nn.Linear(self.input_size,
self.hidden_size)
      self.fc1 = torch.nn.Linear(self. hidden_size,
self.hidden size)
      self.relu = torch.nn.ReLU() → Relu function
      self.fc2 = torch.nn.Linear(self.hidden size, self.
hidden size)
      self.output = torch.nn.Linear(self.hidden_size,
self.output_size)
    def forward(self, x):
      input = self.input(x)
      relu1 = self.relu(input)
      hidden1 = self.fc1(relu1)
      relu2 = self.relu(hidden1)
      hidden2 = self.fc2(relu2)
      output = self.relu(hidden2)
      output = self.output(output)
```

When you have more than two hidden layers, the model is also called the deep/multilayer feedforward model or MultiLayer Perceptron (MLP).

```
Feedforward(
   (input): Linear(in_features=2, out_features=2, bias=True)
   (relu1): ReLU()
   (fc1): Linear(in_features=2, out_features=2, bias=True)
   (relu2): ReLU()
   (fc2): Linear(in_features=2, out_features=2, bias=True)
   (relu3): ReLU()
   (output): Linear(in_features=2, out_features=1, bias=True)
)
```



Yellow: Input layer

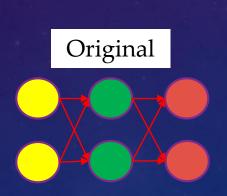
Green: Hidden layer

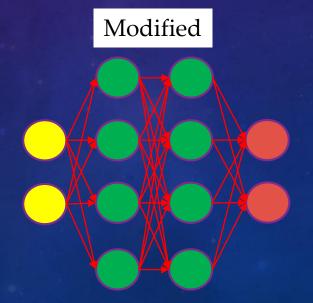
Orange: Output layer

Exercise 2.1 Build A Neural Network

Please download 2-1_log_regression_visualize.zip and unzip it.

- Please modify the settings in the file so that it can be structured as the "Modified".
- See the configurations below for both networks.
- You need to add the activation function "ReLU" behind each hidden layers
- Please write down the results, codes and your observations in the Word and upload to Moodle.





Yellow: Input layer

Green: Hidden layer

Orange: Output layer

Example 2.2 Activation Function

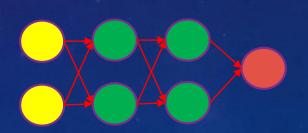
Please download 2-2_Activation_Function.zip and unzip it.

- Given an architecture with input size=2, hidden layer=2 and output size=1.
- Each layer is followed by the Leaky ReLU activation function.
- For more activation functions, please refer to the following link:

https://pytorch.org/docs/stable/nn.html#non-linear-activations-weighted-sum-nonlinearity

• In this case, we can know how to establish a neural network in Pytorch; and how to use the activation function.

```
Feedforward(
   (input): Linear(in_features=2, out_features=2, bias=True)
   (Leakyrelu1): LeakyReLU(negative_slope=0.01)
   (fc1): Linear(in_features=2, out_features=2, bias=True)
   (Leakyrelu2): LeakyReLU(negative_slope=0.01)
   (fc2): Linear(in_features=2, out_features=2, bias=True)
   (Leakyrelu3): LeakyReLU(negative_slope=0.01)
   (output): Linear(in_features=2, out_features=1, bias=True)
```



Example 2.2 Activation Function

```
class Feedforward(torch.nn.Module):
    def __init__(self):
        super(Feedforward, self).__init__()
        self.input_size = 2
        self.hidden_size = 2
        self.output_size = 1
        self.fc1 = torch.nn.Linear(self.input_size, self.hidden_size)
        self.leakyrelu1 = torch.nn.LeakyReLU()
        self.fc2 = torch.nn.Linear(self.hidden_size, self.hidden_size)
        self.leakyrelu2 = torch.nn.LeakyReLU()
        self.fc3 = torch.nn.Linear(self.hidden_size, self.output_size)
```

Change here as Leaky ReLU activation function

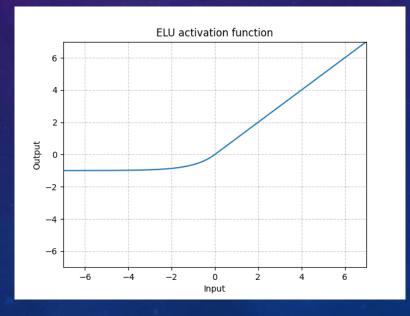
Exercise 2.2 Activation Function

Please download 2-2_Activation_Function.zip and unzip it.

- Given an architecture with input size=2, hidden layer=2 and output size=1.
- Each layer is followed by the ELU activation function.
- Compare the results made by the ReLU and the ELU.

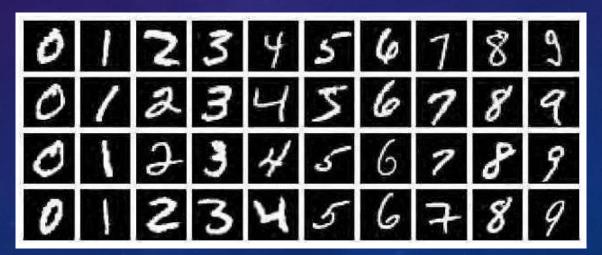
Please write down the results, codes and your observations in the Word and

upload to Moodle.



Please download 2-3_MLP_MNIST.zip and unzip it.

- Given an architecture with input size=28x28, hidden layer=3 and output size=10.
- The 1st hidden layer includes 500 neurons, the 2nd layer includes 250 neurons and the 3rd layer includes 125 neurons.
- Each layer is followed by the ReLU activation function.
- Use MNIST dataset as the input data: 90% for training and 10% for testing.
- Please follow the instructure to train a MLP base handwritten digits classifier.



```
def data_transform(x):
    x = np.array(x, dtype = 'float32') / 255
    x = (x - 0.5) /0.5
    x = x.reshape((-1, ))
    x = torch.from_numpy(x)
    return x
```

Normalize the image

Download the MNIST dataset for training and testing

```
trainset = mnist.MNIST('./dataset/mnist', train=True, transform=data_transform, download=True)
testset = mnist.MNIST('./dataset/mnist', train = False, transform=data_transform, download=True)
train_data = DataLoader(trainset, batch_size=64, shuffle=Irue)
test_data = DataLoader(testset, batch_size=128, shuffle=False)
```

```
class MLP(nn.Module):
    def __init__(self):
         super(MLP, self).__init__()
         self.fc1 = nn.Linear(28*28, 500)
         self.fc2 = nn.Linear(500, 250)
         self.fc3 = nn.Linear(250, 125)
         self.fc4 = nn.Linear(125, 10)
     def forward(self, x):
        x = F.relu(self.fc1(x))
         x = F.relu(self.fc2(x))
        x = F.relu(self.fc3(x))
         x = self.fc4(x)
         return x
mlp = MLP()
```

Define the MLP network

Use the relu activation function

```
Epoch: 15, Steps: 400, Losses: 0.5459817051887512
Epoch: 16, Steps: 0, Losses: 0.5937685966491699
Epoch: 16, Steps: 100, Losses: 0.652214527130127
Epoch:16, Steps:200, Losses:0.5800161361694336
Epoch: 16, Steps: 300, Losses: 0.5280714631080627
Epoch: 16, Steps: 400, Losses: 0.5458921790122986
Epoch: 17, Steps: 0, Losses: 0.5698919892311096
Epoch: 17, Steps: 100, Losses: 0.5695023536682129
Epoch:17, Steps:200, Losses:0.550654947757721
Epoch: 17, Steps: 300, Losses: 0.47420263290405273
Epoch: 17, Steps: 400, Losses: 0.4731411635875702
Epoch: 18, Steps: 0, Losses: 0.607618510723114
Epoch: 18, Steps: 100, Losses: 0.5122652053833008
Epoch:18, Steps:200, Losses:0.4506227970123291
Epoch:18, Steps:300, Losses:0.6634547710418701
Epoch: 18, Steps: 400, Losses: 0.4861069619655609
Epoch: 19, Steps: 0, Losses: 0.48043543100357056
Epoch:19, Steps:100, Losses:0.5214550495147705
Epoch: 19, Steps: 200, Losses: 0.45085906982421875
Epoch: 19, Steps: 300, Losses: 0.39653658866882324
Epoch: 19, Steps: 400, Losses: 0.47536396980285645
Performance=86.86%
```

We can see the losses in each epoch, and the performance tested on the test set.

Exercise 2.3 Train A MLP Model

Please download 2-3_MLP_MNIST.zip and unzip it.

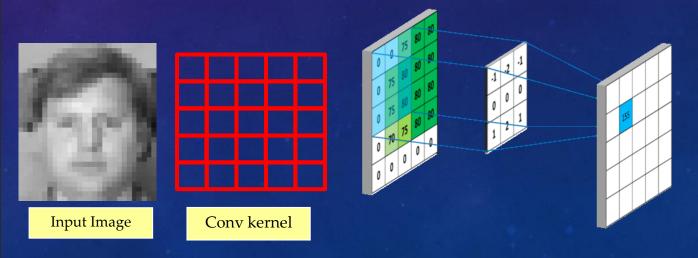
- Adjust the network architecture such as the number of hidden layer or the activation function.
- Use MNIST dataset as the input data: 90% for training and 10% for testing.
- Compare the result from example 2.3 to yours.
- Please write down the results, codes and your observations in the Word and upload to Moodle.

Example 2.4 Convolution Filter

- Please download 2-4_Convolution_Example.zip and unzip it.
- Given a face image I_{img} , please generate F_{conv} , a 5x5 convolution filter with random coefficients in uniform distribution
- Use "same zeros padding" with unit stride.
- Compute the output by convolving I_{img} with F_{conv} and calculate the information loss between original image and the one after convolving.

```
KERNAL_SIZE = 5
STRIDE = 1
PADDING = (KERNAL_SIZE - STRIDE)/2
PADDING = int(PADDING)
img = cv2.imread('./006_01_01_051_08.png')
img = cv2.resize(img,(28,32))

img = cv2.cvtColor(img,cv2.COLOR_RGB2GRAY)
Conv_Filter = np.random.rand(KERNAL_SIZE,KERNAL_SIZE)
#Conv_Filter =
np.random.normal(mean,std,(KERNAL_SIZE,KERNAL_SIZE))
#Normal distribution
Conv_Filter = Conv_Filter/np.sum(Conv_Filter)
img_F = img
```



Example 2.4 Convolution Filter

```
for h in range(int((H-KERNAL SIZE)/STRIDE)+1):
  for w in range(int((W-KERNAL_SIZE)/STRIDE)+1):
   aa = img_F[h*STRIDE:h*STRIDE + (KERNAL_SIZE), w*STRIDE:w*STRIDE +
(KERNAL SIZE)]*Conv Filter
   new feature[h,w] = np.sum(aa)
   img_S = img_F.astype(np.uint8)
    img_new = new_feature.astype(np.uint8)
    cv2.rectangle(img_S, (int(w*STRIDE), int(h*STRIDE)), (int((w*STRIDE +
KERNAL SIZE)), int((h*STRIDE + KERNAL SIZE))), (255, 0, 0), 1)
    cv2.namedWindow('Conv_process', cv2.WINDOW_NORMAL)
    cv2.resizeWindow("Conv process", 300, 300)
    cv2.imshow('Conv_process',img_S)
    cv2.namedWindow('Conv_result', cv2.WINDOW_NORMAL)
    cv2.resizeWindow("Conv_result", 300, 300)
    cv2.imshow('Conv result',img new)
   cv2.waitKey(100)
```







Example 2.4 Convolution Filter

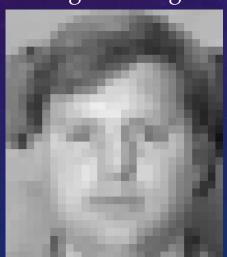
%% Percentage of information loss

imgd = reshape(double(img), numel(img),1);
convimgd = reshape(double(Conv_Img), numel(Conv_Img),1);

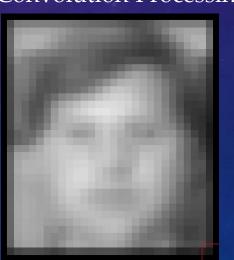
Diff = sum(sum(abs(double(imgd)./norm(double(imgd)) - double(convimgd)./norm(double(convimgd))))); PercnetageDiff = Diff/sum(sum(double(imgd)./norm(double(imgd)))*100);

 $fprintf(The information loss using %dx%d convolution kernel is %.6f%% \n\n', KERNAL_SIZE, KERNAL_SIZE, PercnetageDiff);$

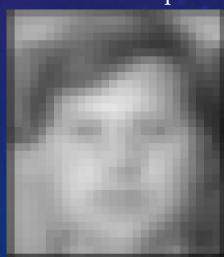
Original Image



Convolution Processing



Feature Map



Exercise 2.4 Design Convolution Filter

Please download 2-4_Convolution_Example.zip and design your own convolution filter with a

- (1) 3x3 convolution filter
- (2) 5x5 convolution filter
- (3) 7x7 convolution filter

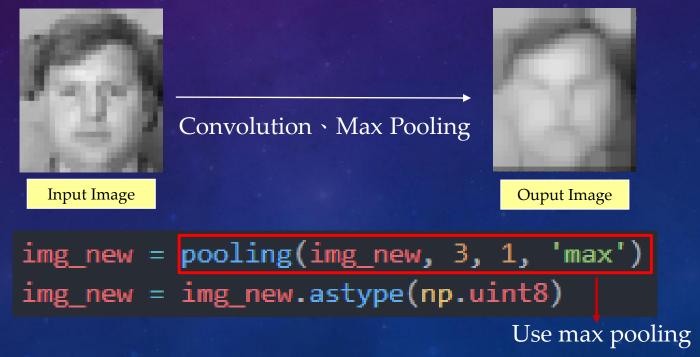
with random coefficients in normal distribution (std=1, mean=5), and compute the output by convolving $I_{\rm mg}$ with $F_{\rm conv}$. Then, calculate the information loss with original image. Please write down the results, codes and your observations in the Word and upload to Moodle.

Change it in to normal distribution

```
KERNAL_SIZE = 3
STRIDE = 1
PADDING = (KERNAL_SIZE - STRIDE)/2
PADDING = int(PADDING)
img = cv2.imread('./006_01_01_051_08.png')
img = cv2.cvtCclor(img,cv2.COLOR_RCB2CRAY)
Conv_Filter = np.random.rand(KERNAL_SIZE,KERNAL_SIZE)
#Conv_Filter = np.random.normal(mean,std,(KERNAL_SIZE,KERNAL_SIZE)) #Normal distribution
Conv_Filter = Conv_Filter/np.sum(Conv_Filter)
img_F = img
```

Example 2.5 Max Pooling

• Given a face image $I_{\rm img'}$ please generate $F_{\rm conv}$, a 3x3 convolution filter with random coefficients in normal distribution (std = 0, mean=2), and use "same zeros padding" with unit stride. Use "max pooling" with 3x3 kernel size and unit stride. Please compute the output by convolving $I_{\rm img}$ with $F_{\rm conv}$ and calculate the information loss between original image and the one after convolving.



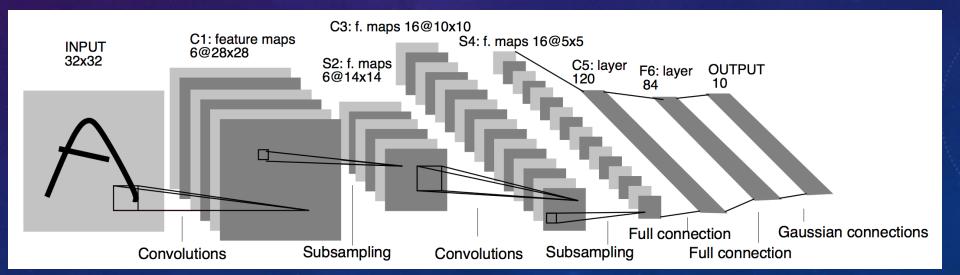
Exercise 2.5 Average Pooling

Please download 2-5_Pooling_Example.zip from the Moodle.

- Given a face image I_{img} , please generate F_{conv} , a 3x3 convolution filter with random coefficients in normal distribution (std = 0, mean=2).
- Use "same zeros padding" with unit stride to pool the feature maps.
- Use "average pooling" with 3x3 kernel size and unit stride.
- Compute the output by convolving I_{img} with F_{conv} .
- Please write down the results, codes and your observations in the Word and upload to Moodle.

Please download 2-6_CNN_MNIST.zip and unzip it.

- Given a CNN base network architecture in the figure below.
- Consider the MNIST dataset as the input data: 90% for training and 10% for testing.
- Use the "Softmax with Cross Entropy" as objective function.
- Please follow the instruction to train the CNN base handwritten digits classifier.
- With the predicted results and its ground-truth, please compute the confusion matrix for each class.



```
class LeNet(nn.Module):
    def         init (self):
        super(LeNet, self).__init__()
        self.conv1 = nn.Conv2d(in_channels=1, out_channels=6, kernel_size=5, padding=2, stride=1)
        self.conv2 = nn.Conv2d(in_channels=6, out_channels=16, kernel_size=5)
        self.fc1 = nn.Linear(in_features=16*5*5, out_features=120)
        self.fc2 = nn.Linear(in_features=120, out_features=84)
        self.fc3 = nn.Linear(in_features=84, out_features=10)
```

Define the LeNet network

In MNIST dataset, we have 10,000 test images with the ground-truth digits 1 to 10, where the GT denotes the ground-truth of each image, and Pred denotes the predicted digit number.

	GT_1	GT_2	GT_3	GT_4	GT_5	GT_6	GT_7	GT_8	GT_9	GT_10
Pred_1	938	0	15	5	1	19	18	5	7	11
Pred_2	0	1099	27	4	5	6	4	27	16	7
Pred_3	5	3	855	24	5	9	16	23	21	7
Pred_4	2	5	25	874	1	76	1	2	38	9
Pred_5	0	0	21	2	882	12	22	8	15	99
Pred_6	25	1	8	49	2	686	26	2	47	16
Pred_7	8	3	28	1	14	26	869	0	16	1
Pred_8	1	2	14	20	1	13	0	906	10	37
Pred_9	1	(22)	34	27	6	36	2	8	779	9
Pred_10	0	01	5	4	65	9	0	47	25	813

GT: ground truth Pred: prediction

To compute the confusion matrix, we take class "1" as the example.

	GT_1	GT_2	GT_3	GT_4	GT_5	GT_6	GT_7	GT_8	GT_9	GT_10
Pred_1	938	0	15	5	1	19	18	5	7	11
Pred_2	0	1099	27	4	5	6	4	27	16	7
Pred_3	5	3	855	24	5	9	16	23	21	7
Pred_4	2	5	25	874	1	76	1	2	38	9
Pred_5	0	0	21	2	882	12	22	8	15	99
Pred_6	25	1	8	49	2	686	26	2	47	16
Pred_7	8	3	28	1	14	26	869	0	16	1
Pred_8	1	2	14	20	1	13	0	906	10	37
Pred_9	1	22	34	27	6	36	2	8	779	9
Pred_10	0	0	5	4	65	9	0	47	25	813

FP =
$$0 + 15 + 5 + \dots + 11 = 81$$

TN =
$$1099 + 27 + 4 + ... + 25 + 813 = 8939$$

FN =
$$0 + 5 + 2 + ... + 1 + 0 = 42$$

$$Precision = \frac{TP}{TP + FP} = \frac{938}{938 + 81} = 0.92$$

$$Recall = \frac{TP}{TP + FN} = \frac{938}{938 + 42} = 0.957$$

Let's use the class "4" as the example.

	GT_1	GT_2	GT_3	GT_4	GT_5	GT_6	GT_7	GT_8	GT_9	GT_10
Pred_1	938	0	15	5	1	19	18	5	7	11
Pred_2	0	1099	27	4	5	6	4	27	16	7
Pred_3	5	3	855	24	5	9	16	23	21	7
Pred_4	2	5	25	874	1	76	1	2	38	9
Pred_5	0	0	21	2	882	12	22	8	15	99
Pred_6	25	1	8	49	2	686	26	2	47	16
Pred_7	8	3	28	1	14	26	869	0	16	1
Pred_8	1	2	14	20	1	13	0	906	10	37
Pred_9	1	22	34	27	6	36	2	8	779	9
Pred_10	0	0	5	4	65	9	0	47	25	813

FP =
$$2 + 5 + 25 + \dots + 38 = 159$$

TN =
$$938 + 0 + 15 + \dots + 25 + 813 = 8831$$

FN =
$$5 + 4 + 24 + \dots + 27 + 4 = 136$$

$$Precision = \frac{TP}{TP + FP} = \frac{874}{874 + 159} = 0.846$$

$$Recall = \frac{TP}{TP + FN} = \frac{874}{874 + 136} = 0.865$$

TP, FP, TN, FN, Precision and Recall distributions in each class.

	No. TP	No. FP	No. TN	No. FN	Precision	Recall
Class 1	938	81	8939	42	0.921	0.957
Class 2	1099	96	8769	36	0.920	0.968
Class 3	855	113	8855	177	0.883	0.828
Class 4	874	159	8831	136	0.846	0.865
Class 5	882	179	8839	100	0.831	0.898
Class 6	686	176	8932	206	0.796	0.769
Class 7	869	97	8945	89	0.900	0.907
Class 8	906	98	8874	122	0.902	0.881
Class 9	779	145	8881	195	0.843	0.800
Class 10	813	155	8836	196	0.840	0.806

Exercise 2.6 Train the LeNet Network

Please download 2-6_CNN_MNIST.zip and unzip it.

- Given a CNN base network architecture in the figure below.
- Adjust the CNN layer, e.g. kernel size, input and output channel.
- Consider the MNIST dataset as the input data: 90% for training and 10% for testing.
- With the predicted results and its ground-truth, please compute the confusion matrix for each class.
- Please write down the results, codes and your observations in the Word and upload to Moodle.

