



# 矩阵对角化与本征值问题



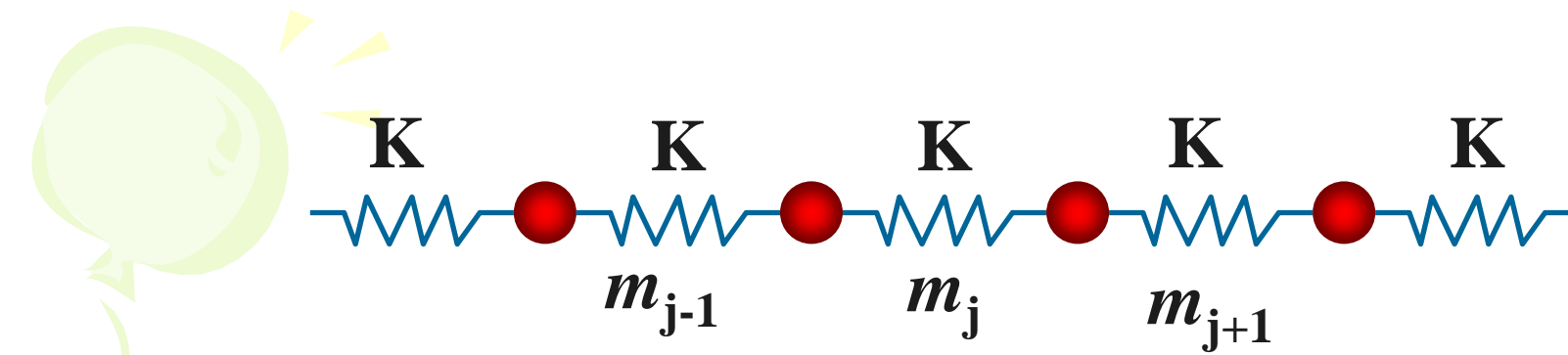
# 矩阵对角化与本征值问题

线性方程组：

$$AX = B$$

本征值问题：

$$AX = \lambda X$$



$$F_1 = m \frac{d^2 x_1}{dt^2} = -Kx_1 + K(x_2 - x_1)$$

$$F_2 = m \frac{d^2 x_2}{dt^2} = K(x_1 - x_2) + K(x_3 - x_2)$$

...

$$F_j = m \frac{d^2 x_j}{dt^2} = K(x_{j-1} - x_j) + K(x_{j+1} - x_j)$$

...

$$F_N = m \frac{d^2 x_N}{dt^2} = K(x_{N-1} - x_N) - Kx_N.$$

$$F_1 = m \frac{d^2 x_1}{dt^2} = -Kx_1 + K(x_2 - x_1)$$

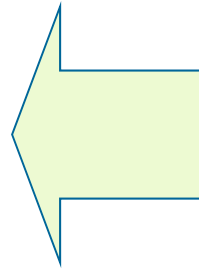
$$F_2 = m \frac{d^2 x_2}{dt^2} = K(x_1 - x_2) + K(x_3 - x_2)$$

...

$$F_j = m \frac{d^2 x_j}{dt^2} = K(x_{j-1} - x_j) + K(x_{j+1} - x_j)$$

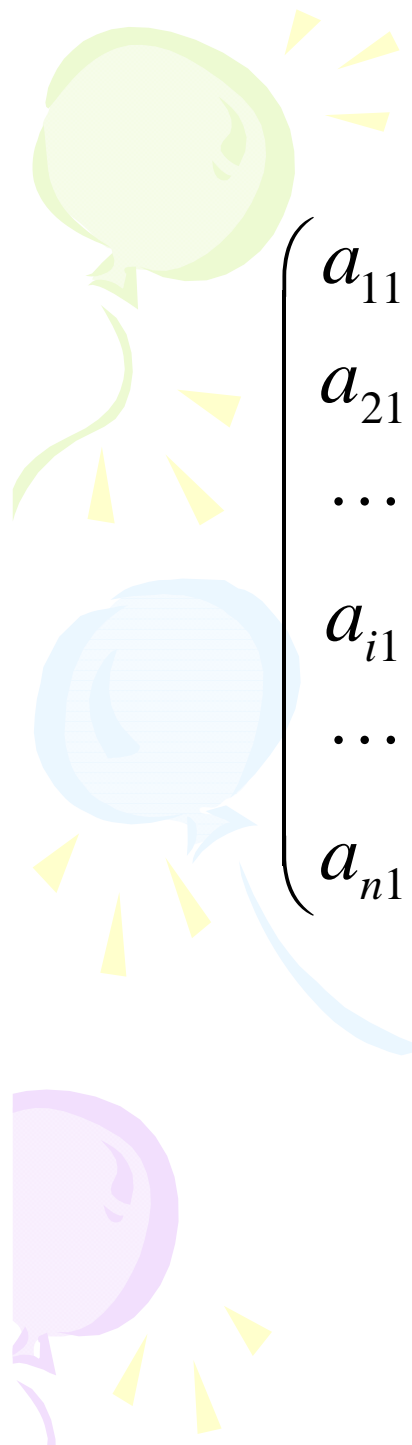
...

$$F_N = m \frac{d^2 x_N}{dt^2} = K(x_{N-1} - x_N) - Kx_N.$$



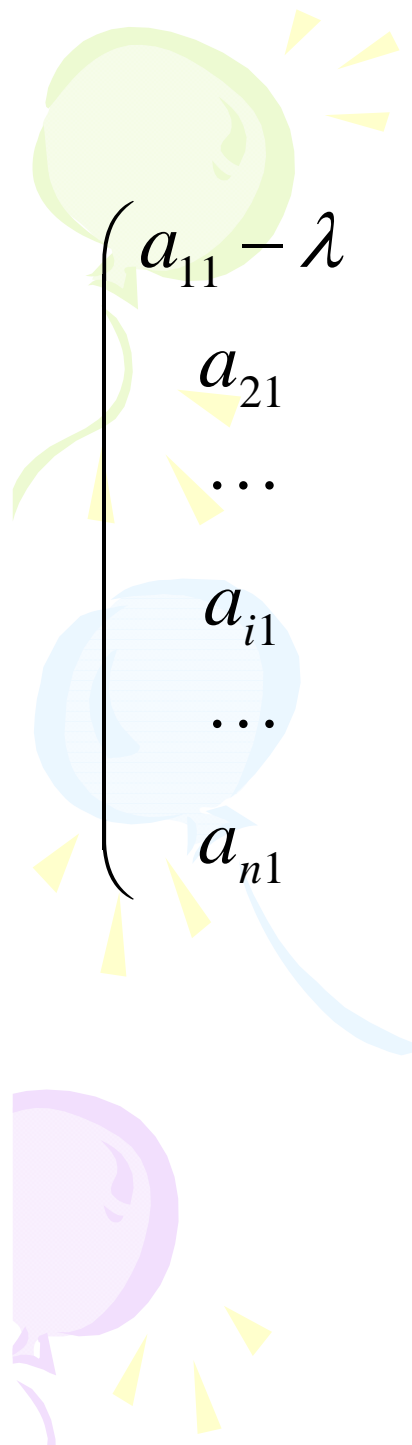
$$x_j = A_j e^{-i\omega t}$$

$$\frac{m\omega^2}{K} \begin{pmatrix} A_1 \\ A_2 \\ \dots \\ A_j \\ \dots \\ A_N \end{pmatrix} = \begin{pmatrix} 2 & -1 & 0 & 0 & \dots & 0 \\ -1 & 2 & -1 & 0 & \dots & 0 \\ 0 & -1 & 2 & -1 & \dots & 0 \\ \dots & & & & & \\ 0 & \dots & 0 & 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} A_1 \\ A_2 \\ \dots \\ A_j \\ \dots \\ A_N \end{pmatrix}$$




$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1j} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2j} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{i1} & \cdots & \cdots & a_{ij} & \cdots & a_{in} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nj} & \cdots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_i \\ \vdots \\ x_n \end{pmatrix} = \lambda \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_i \\ \vdots \\ x_n \end{pmatrix}$$

$$AX = \lambda X$$



$$\begin{pmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1j} & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & \cdots & a_{2j} & \cdots & a_{2n} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{i1} & \cdots & \cdots & a_{ij} - \lambda & \cdots & a_{in} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{n1} & a_{n2} & \cdots & a_{nj} & \cdots & a_{nn} - \lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_i \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$



$$\det(A - \lambda I) = 0$$



# 求矩阵特征值与特征向量的方法

1. 乘幂法 (最大特征值)
2. 反幂法 (最小特征值)
3. Jacobi方法 (对称矩阵)
4. QR方法 (更一般的算法)
5. SVD

.....



# Jacobi 方法

## (实对称矩阵的全部特征根与特征向量)

定理：P为n阶可逆阵，则A与 $P^{-1}AP$ 相似，相似阵有相同的特征值；  
若A对称，则存在正交矩阵 $Q(Q^T Q = I)$ ，使得

$$Q^T A Q = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix}$$





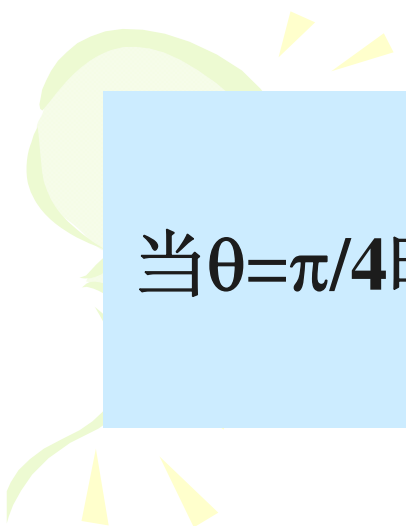
计算如下矩阵的特征值和相应的特征向量

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad B = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

计算如下矩阵的特征值和相应的特征向量

$$\begin{aligned} B^T A B &= \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \\ &= \begin{pmatrix} -2 \sin \theta \cos \theta & \cos^2 \theta - \sin^2 \theta \\ \cos^2 \theta - \sin^2 \theta & 2 \sin \theta \cos \theta \end{pmatrix} \end{aligned}$$

当 $\theta = \pi/4$ 时:  $B^T A B = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$   $B = \begin{pmatrix} \sqrt{2}/2 & \sqrt{2}/2 \\ -\sqrt{2}/2 & \sqrt{2}/2 \end{pmatrix}$


$$\text{当}\theta=\pi/4\text{时: } B^T A B = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \quad B = \begin{pmatrix} \sqrt{2}/2 & \sqrt{2}/2 \\ -\sqrt{2}/2 & \sqrt{2}/2 \end{pmatrix}$$

**A**的特征值为 $\lambda_1=-1$ ,  $\lambda_2=1$



**A**对应于 $\lambda_1=-1$ 的特征向量为:

$$v_1 = \begin{pmatrix} \sqrt{2}/2 \\ -\sqrt{2}/2 \end{pmatrix}$$



**A**对应于 $\lambda_2=1$ 的特征向量为:

$$v_2 = \begin{pmatrix} \sqrt{2}/2 \\ \sqrt{2}/2 \end{pmatrix}$$



## Jacobi法基本思路:

构造一系列特殊形式的正交阵 $Q_1, \dots, Q_n$

对 $A$ 作正交变换使得对角元素比重逐次增加，非对角元变小。

当非对角元已经小得无足轻重时，可以近似认为对角元就是 $A$ 的所有特征值。

## *Givens*旋转变换:

$$Q(p, q, \theta) = \begin{pmatrix} 1 & & & & \\ & \ddots & & & \\ & & \cos \theta & \sin \theta & \\ & & -\sin \theta & \cos \theta & \\ & & & \ddots & \\ & & & & 1 \end{pmatrix}$$

$p$ 列       $q$ 列

$p$ 行       $q$ 行

记:

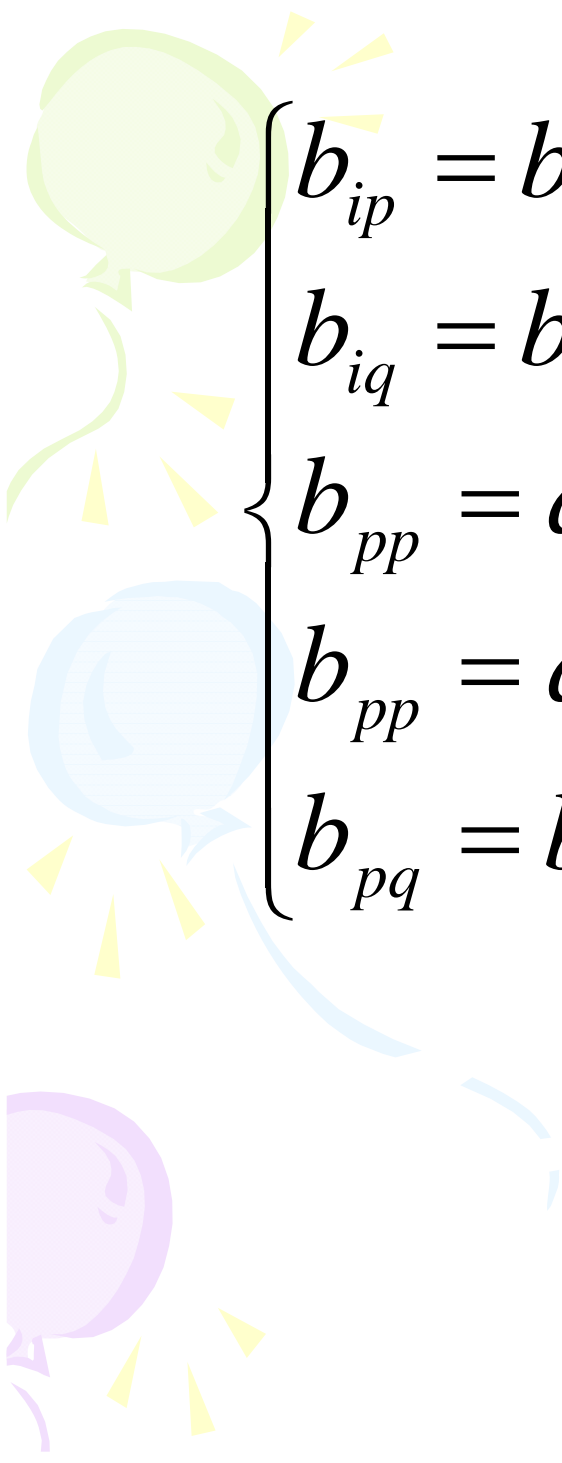
$$A = (a_{ij}) , \quad B = Q^T(p, q, \theta) A Q(p, q, \theta) = (b_{ij})$$

则:

$$\begin{cases} b_{ip} = b_{pi} = a_{pi} \cos \theta - a_{qi} \sin \theta, i \neq p, q \\ b_{iq} = b_{qi} = a_{pi} \sin \theta + a_{qi} \cos \theta, i \neq p, q \\ b_{pp} = a_{pp} \cos^2 \theta + a_{qq} \sin^2 \theta - a_{pq} \sin 2\theta \\ b_{qq} = a_{pp} \sin^2 \theta + a_{qq} \cos^2 \theta + a_{pq} \sin 2\theta \\ b_{pq} = b_{qp} = a_{pq} \cos 2\theta + \frac{a_{pp} - a_{qq}}{2} \sin 2\theta \end{cases}$$

变换的目的是为了减少非对角元的分量，因此：

$$b_{pq} = b_{qp} = a_{pq} \cos 2\theta + \frac{a_{pp} - a_{qq}}{2} \sin 2\theta = 0$$


$$b_{ip} = b_{pi} = ca_{pi} - da_{qi}, i \neq p, q$$

$$b_{iq} = b_{qi} = da_{pi} + ca_{qi}, i \neq p, q$$

$$b_{pp} = a_{pp} - ta_{pq}$$

$$b_{qq} = a_{qq} + ta_{pq}$$

$$b_{pq} = b_{qp} = 0$$

其中  $s = \frac{a_{qq} - a_{pp}}{2a_{pq}}$

$$t^2 + 2ts - 1 = 0$$

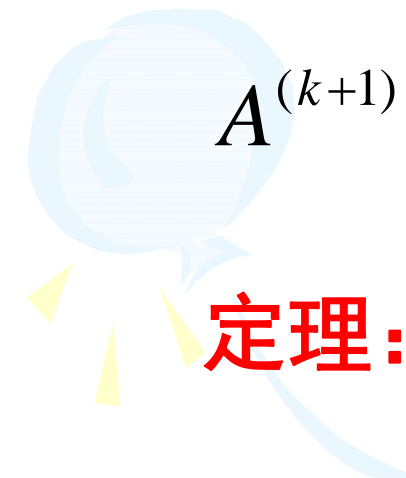
$$t = \tan \theta$$

$$c = \cos \theta = \frac{1}{\sqrt{1+t^2}}, d = \sin \theta = \frac{t}{\sqrt{1+t^2}}$$



## Jacobi 迭代算法:

取  $p, q$  使  $|a_{pq}| = \max_{i \neq j} |a_{ij}|$ , 则


$$A^{(k+1)} = Q^T(p, q, \theta) A^{(k)} Q(p, q, \theta)$$

**定理:** 若  $A$  对称, 则


$$A^{(k+1)} \rightarrow \text{diag}\{\lambda_1, \dots, \lambda_n\}$$



例：用Jacobi 方法计算对称矩阵的全部特征值

$$\mathbf{A} = \begin{pmatrix} 4 & 2 & 2 \\ 2 & 5 & 1 \\ 2 & 1 & 6 \end{pmatrix}$$

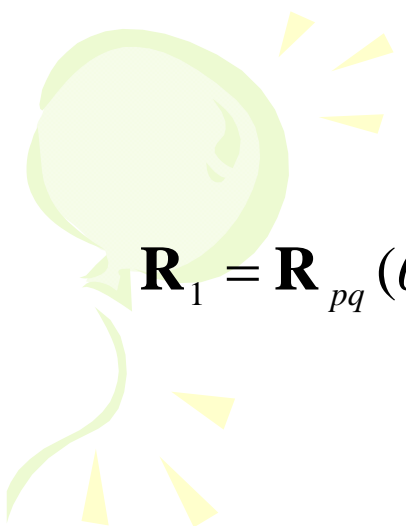
解 记  $\mathbf{A}^{(0)} = \mathbf{A}$ , 取  $p=1, q=2$ ,  $a_{pq}^{(0)} = a_{12}^{(0)} = 2$ , 于是有

$$s = \frac{a_{11}^{(0)} - a_{22}^{(0)}}{2a_{12}^{(0)}} = -0.25$$

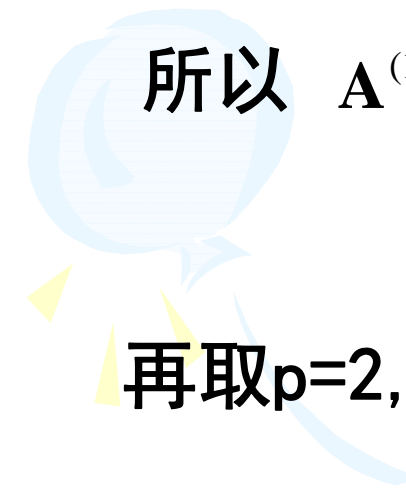
$$t = -0.780776$$

$$\cos \theta = \frac{1}{\sqrt{1+t^2}} = 0.788206$$

$$\sin \theta = \frac{t}{\sqrt{1+t^2}} = -0.615412$$

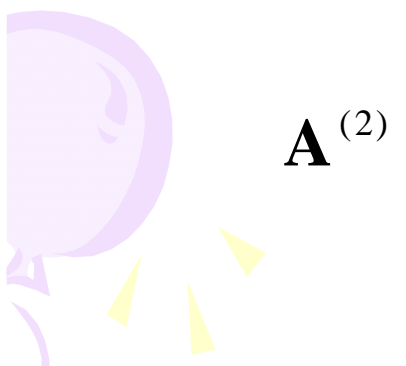


$$\mathbf{R}_1 = \mathbf{R}_{pq}(\theta) = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0.788206 & 0.615412 & 0 \\ -0.615412 & 0.788206 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



所以  $\mathbf{A}^{(1)} = \mathbf{R}_1^T \mathbf{A}^{(0)} \mathbf{R}_1 = \begin{pmatrix} 2.438448 & 0 & 0.961 \\ 0 & 6.561552 & 2.020190 \\ 0.961 & 2.020190 & 6 \end{pmatrix}$

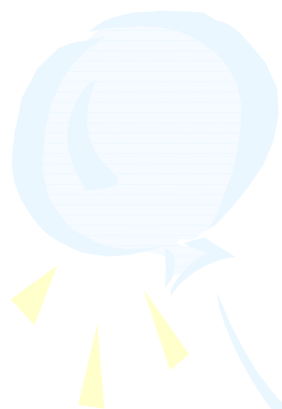
再取  $p=2, q=3, a_{pq}^{(1)} = a_{23}^{(1)} = 2.020190$ , 类似地可得



$$\mathbf{A}^{(2)} = \begin{pmatrix} 2.438448 & 0.631026 & 0.724794 \\ 0.631026 & 8.320386 & 0 \\ 0.724794 & 0 & 4.241166 \end{pmatrix}$$




$$\mathbf{A}^{(3)} = \begin{pmatrix} 2.183185 & 0.595192 & 0 \\ 0.595192 & 8.320386 & 0.209614 \\ 0 & 0.209614 & 4.496424 \end{pmatrix}$$

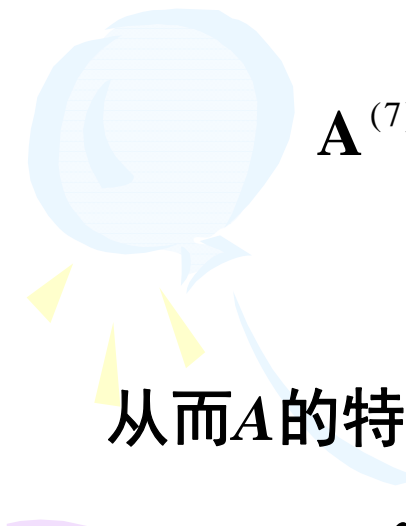


$$\mathbf{A}^{(4)} = \begin{pmatrix} 2.125995 & 0 & -0.020048 \\ 0 & 8.377576 & 0.208653 \\ -0.020048 & 0.208653 & 4.496424 \end{pmatrix}$$

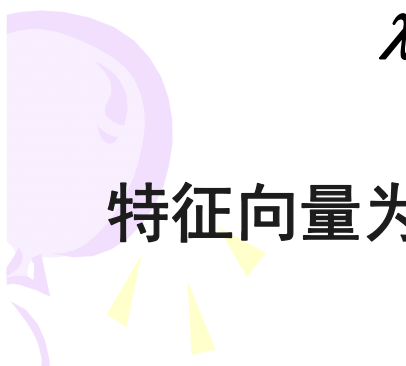


$$\mathbf{A}^{(5)} = \begin{pmatrix} 2.125995 & -0.001073 & -0.020019 \\ -0.001073 & 8.388761 & 0 \\ -0.020019 & 0 & 4.485239 \end{pmatrix}$$

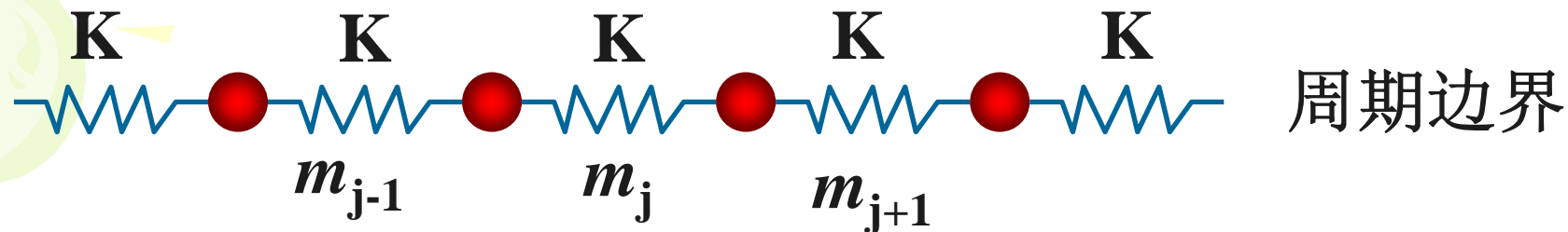

$$\mathbf{A}^{(6)} = \begin{pmatrix} 2.125825 & -0.001072 & 0 \\ 0 & 8.388761 & 0.000009 \\ -0.001072 & 0.000009 & 4.485401 \end{pmatrix}$$


$$\mathbf{A}^{(7)} = \begin{pmatrix} 2.125825 & 0 & 0 \\ 0 & 8.388761 & 0.000009 \\ 0 & 0.000009 & 4.485401 \end{pmatrix}$$

从而A的特征值可取为


$$\lambda_1 \approx 2.125825, \lambda_2 \approx 8.388761, \lambda_3 \approx 4.485401$$

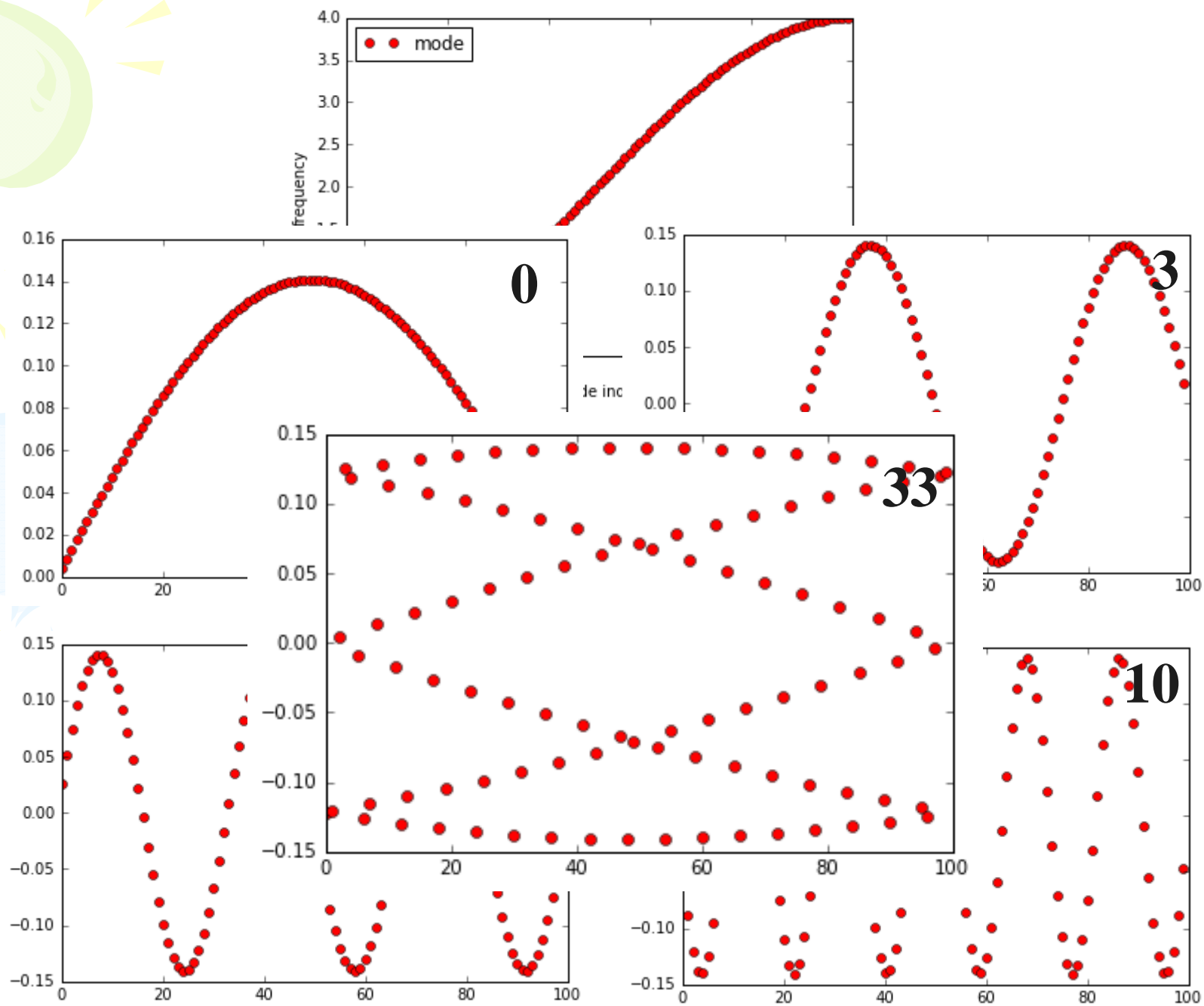
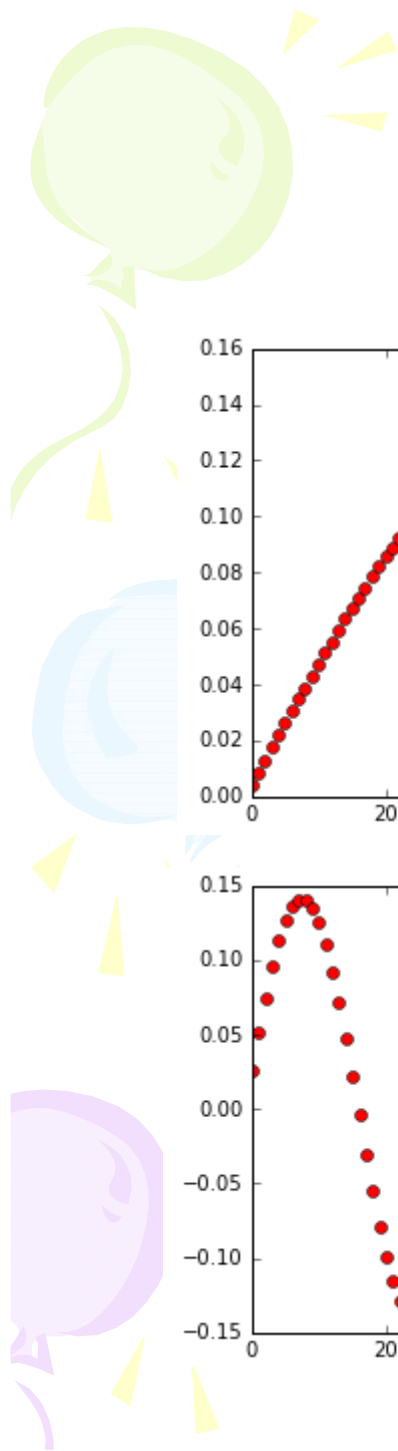
特征向量为旋转矩阵 $\mathbf{R}=\mathbf{R}_1\mathbf{R}_2\dots$ 的相应的各列矢量



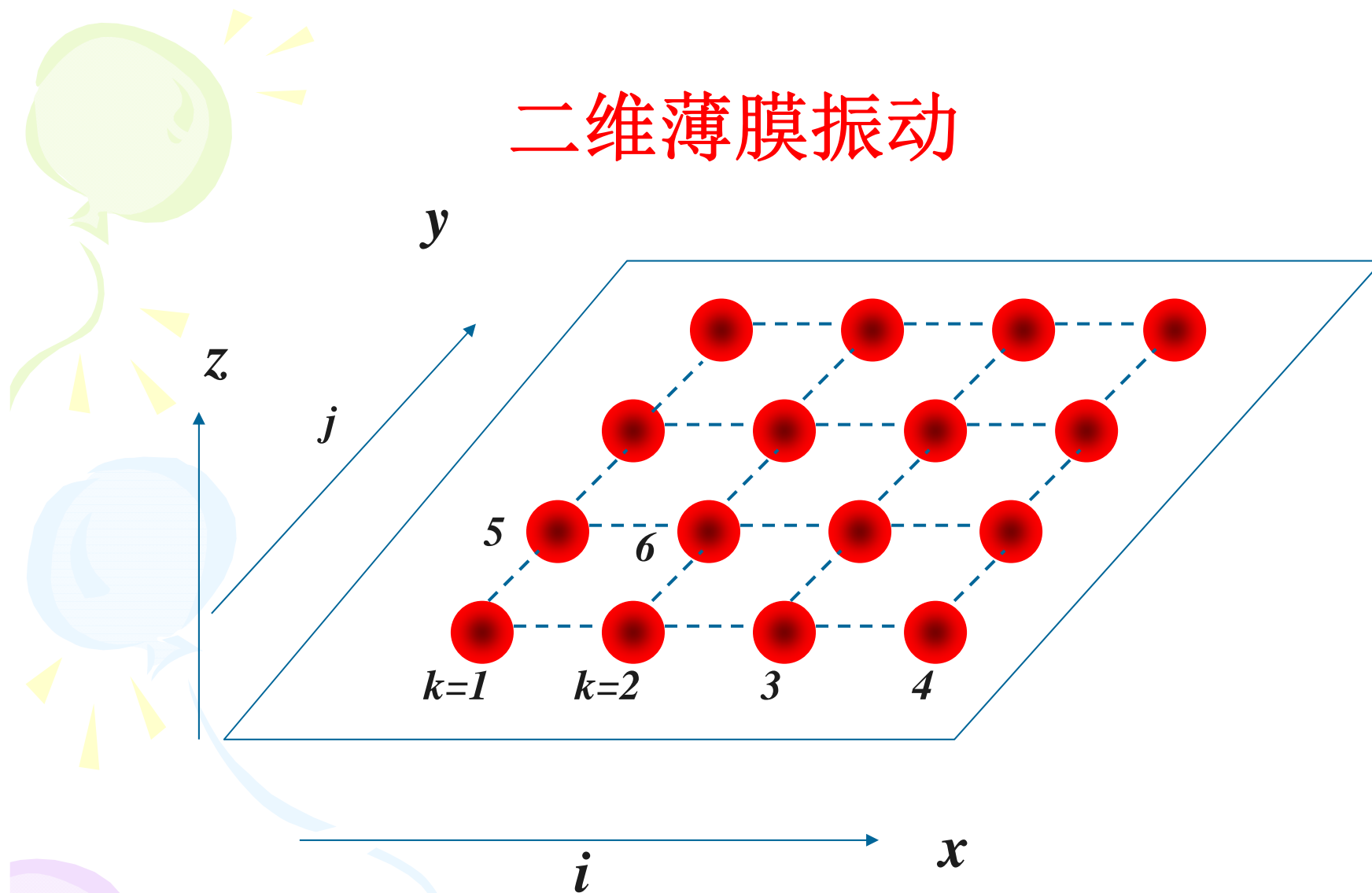
$$m \frac{d^2}{dt^2} x_i = k(x_{i+1} - x_i) - k(x_i - x_{i-1}) \quad x_i = A_i \exp(-i\omega t)$$

$$\frac{m\omega^2}{K} \begin{pmatrix} A_1 \\ A_2 \\ \dots \\ A_j \\ \dots \\ A_N \end{pmatrix} = \begin{pmatrix} 2 & -1 & 0 & 0 & \dots & 0 \\ -1 & 2 & -1 & 0 & \dots & 0 \\ 0 & -1 & 2 & -1 & \dots & 0 \\ \dots & & & & & \\ 0 & \dots & 0 & 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} A_1 \\ A_2 \\ \dots \\ A_j \\ \dots \\ A_N \end{pmatrix}$$

$$N=100, K=1, m=1$$



## 二维薄膜振动



$$\frac{\partial^2 z}{\partial t^2} = \frac{T}{\sigma} \left( \frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial y^2} \right)$$



$$k = i + Nj$$

$$(\sigma \Delta x \Delta y) \frac{\partial^2 z_k}{\partial t^2} = T(z_{k+1} + z_{k-1} + z_{k+N} + z_{k-N} - 4z_k)$$

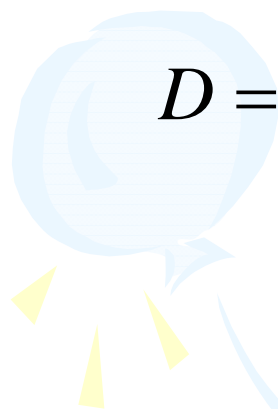


$$z_k = A_k e^{-i\omega t}$$

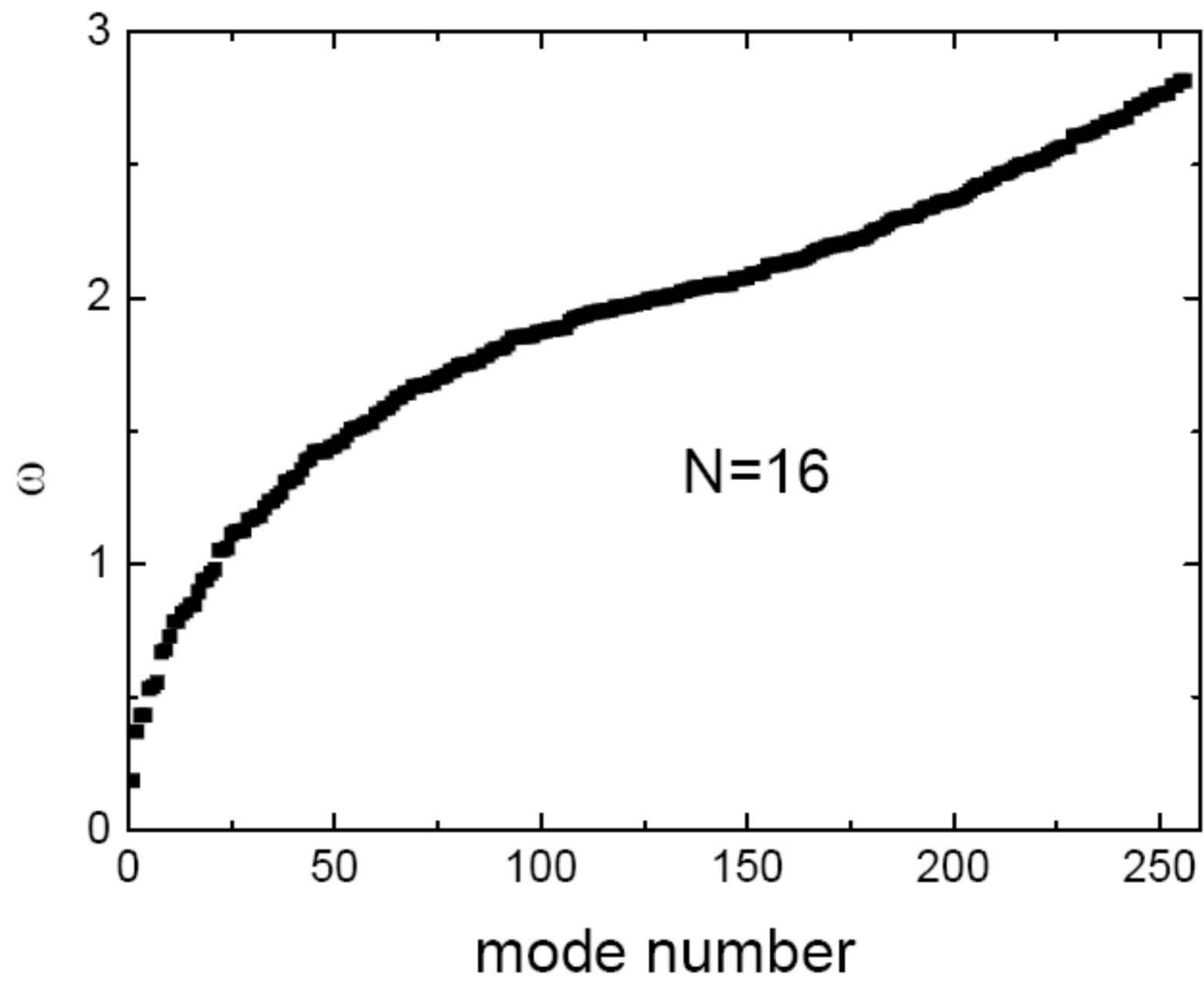
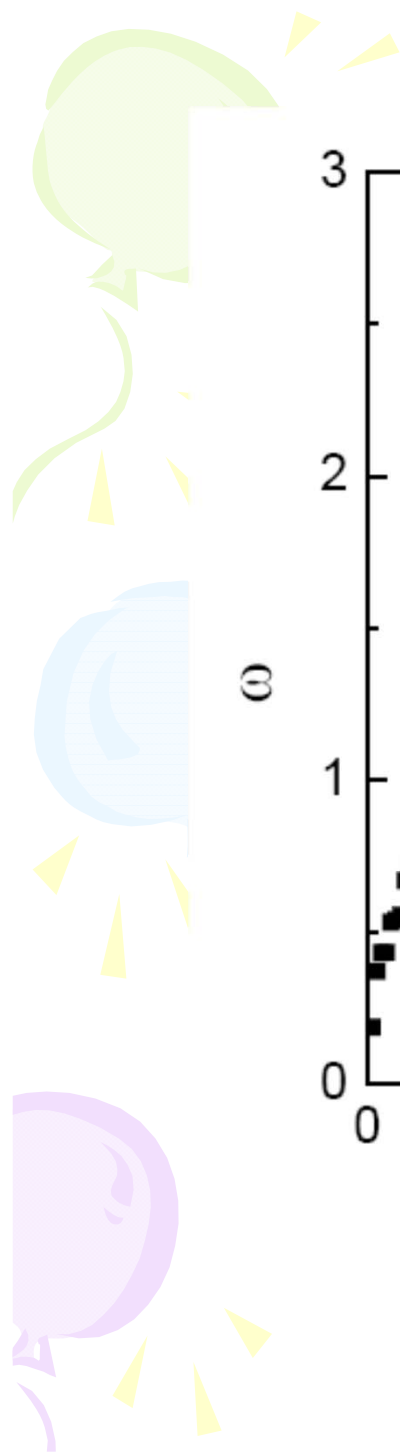
$$\frac{\sigma \Delta x \Delta y}{T} \omega^2 \vec{A} = D \vec{A}$$



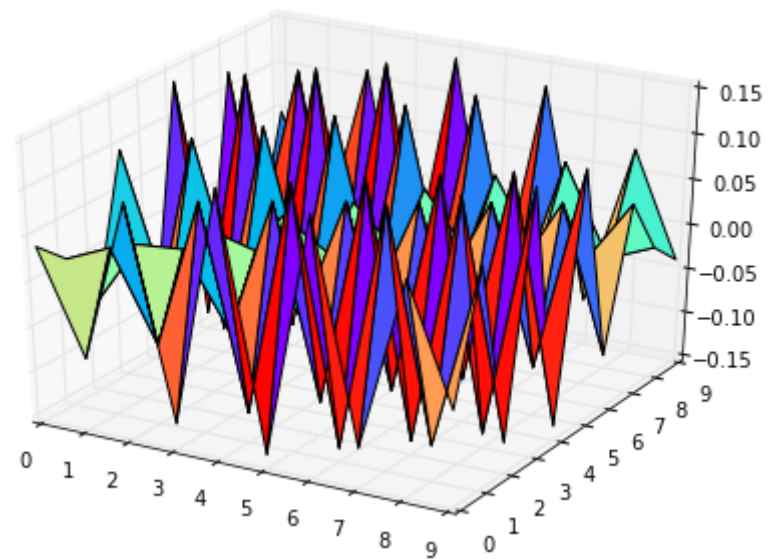
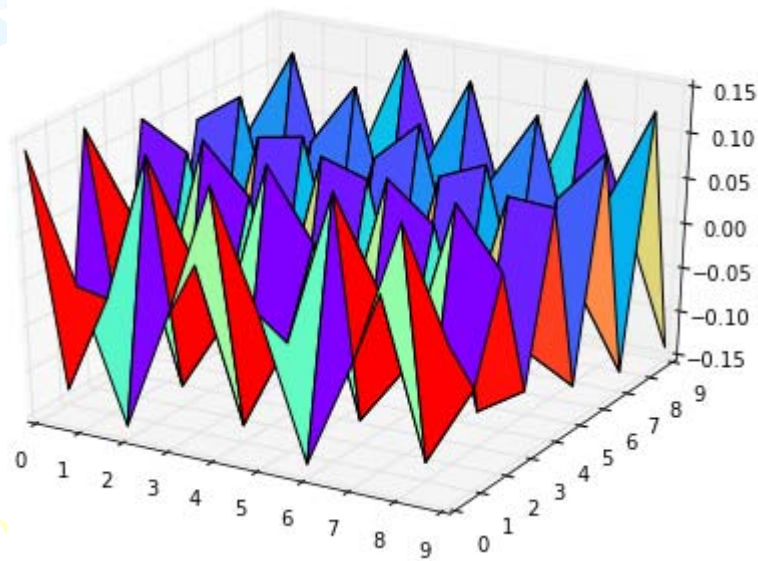
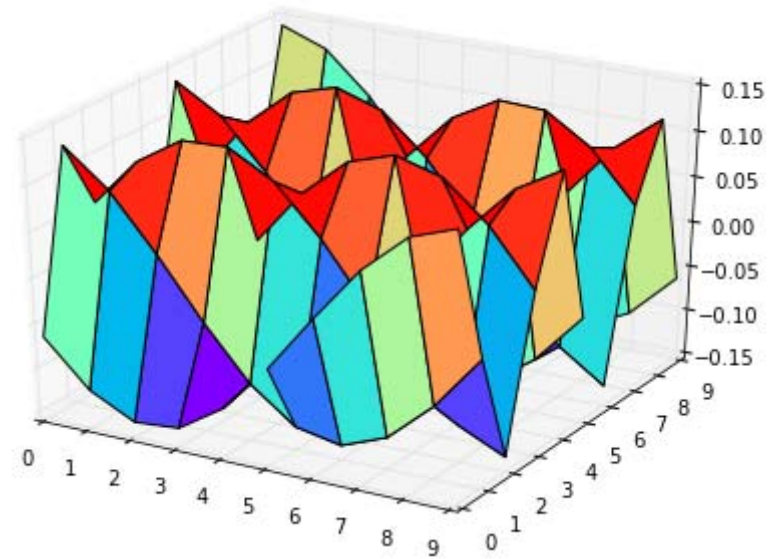
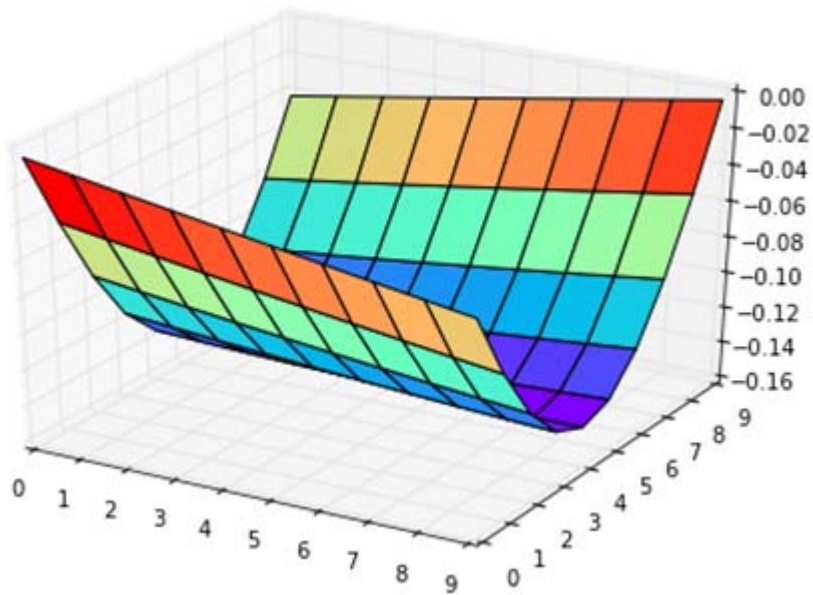




$$D = \begin{pmatrix} 4 & -1 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & 0 \\ -1 & 4 & -1 & 0 & \dots & -1 & 0 & 0 & \dots & 0 \\ 0 & -1 & 4 & -1 & \dots & 0 & -1 & 0 & \dots & 0 \\ \dots & & & & & & & & & \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 4 \end{pmatrix}$$



$$N=10*10=100$$





## 课堂练习

```
from numpy import array, arange, zeros, linalg
import pylab as pl
```

```
#在下面给A赋值
```

```
A = ...
```

```
eigenValues, eigenVectors = linalg.eig(A)
```

```
print("eigenValues", eigenValues)
```

```
print("eigenVectors ", eigenVectors)
```

```
n=...
```

```
pl.plot(range(n), eigenValues, 'ro')
```

```
pl.show()
```

```
pl.plot(range(n), eigenVectors[0,:], 'ro')
```

```
pl.show()
```

$$\mathbf{A} = \begin{pmatrix} 4 & 2 & 2 \\ 2 & 5 & 1 \\ 2 & 1 & 6 \end{pmatrix}$$

$$\begin{pmatrix} 2 & -1 & 0 & 0 & \dots & 0 \\ -1 & 2 & -1 & 0 & \dots & 0 \\ 0 & -1 & 2 & -1 & \dots & 0 \\ \dots & & & & & \\ 0 & \dots & 0 & 0 & -1 & 2 \end{pmatrix}$$

```
from mpl_toolkits.mplot3d import Axes3D
eigenValues, eigenVectors
    = linalg.eig(A)
```

```
ns = 4
```

```
N=ns*ns
```

```
x = arange(ns)
```

```
y = arange(ns)
```

```
x,y = meshgrid(x,y)
```

```
id=3 #画第三个本征矢
```

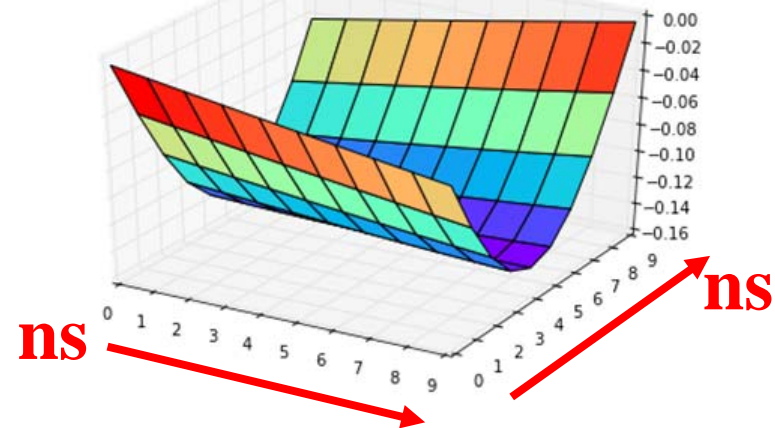
```
fig = pl.figure()
```

```
ax = Axes3D(fig)
```

```
ev = eigenVectors[:,id]
```

```
ev.shape = (ns,ns)
```

```
ax.plot_surface(x,y,ev, rstride=1, cstride=1,
                cmap='rainbow')
```



ns为二维膜一个方向格点数  
即矩阵大小N的平方根。

$$D = \begin{pmatrix} 4 & -1 & 0 & 0 & \dots & 0 & 0 & 0 & 0 & 0 \\ -1 & 4 & -1 & 0 & \dots & -1 & 0 & 0 & \dots & 0 \\ 0 & -1 & 4 & -1 & \dots & 0 & -1 & 0 & \dots & 0 \\ \dots & & & & & & & & & \\ 0 & \dots & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 4 \end{pmatrix}$$



**E N D**

