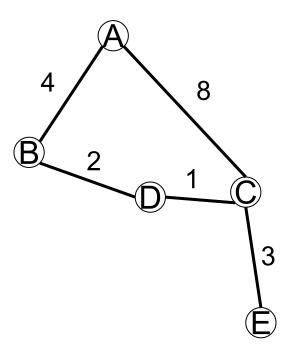
All-pairs shortest paths

	Dingle An Daingean	Annascaul Abbainn an Scáil	Ballydavid <i>Baile na n Gall</i>	Ballyferriter Baile an Fheirtéaraigh	Brandon Cé Bhréanainn	Сатр <i>Ап Сот</i>	Castlegregory Caisleán Ghriaire	Cloghane <i>An Gochán</i>	Conor Pass An Conair	Dunquin <i>Dún Chaoin</i>	Feohanagh An Fheothanach	Inch An Inse	Kinard Ceann Áird	Lispole Lios Póil	Minard Minn Aird	Ventry Ceann Trá
Dingle An Daingean		17.4	11.5	11.7	20.0	32.5	25.8	14.9	8.3	20.9	12.2	23.7	9.1	8.3	13.9	7.5
Annascaul Abhainn an Scáil	10.8		28.8	29.0	42.2	15.1	24.2	37.1	25.7	38.2	29.6	7.1	13.6	9.1	8.4	24.9
Ballydavid Baile na nGall	7.1	17.9	-	7.2	31.4	43.9	37.3	26.4	19.8	15.8	3.9	35.1	20.7	19.8	25.3	11.4
Ballyferriter Baile an Fheirtéaraigh	7.3	18.0	4.5		31.6	44.2	37.5	26.6	20.0	8.6	10.3	35.3	20.9	20.0	25.5	5.9
Brandon <i>Cé Bhréanainn</i>	12.4	26.2	19.5	19.6		25.7	19.8	5.0	11.7	40.8	31.2	39.9	29.2	28.3	33.9	27.5
Camp An Com	20.2	9.4	27.3	27.4	16.0		9.1	22.0	23.4	52.5	42.9	14.2	28.7	24.2	23.5	40.0
Castlegregory Caisleán Ghriaire	16.1	15.0	23.2	23.3	12.3	5.7		16.2	17.5	46.6	37.1	23.3	37.7	33.3	32.6	33.3
Cloghane An Clochán	9.3	23.1	16.4	16.5	3.1	13.7	10.0	2	6.6	35.7	26.2	34.9	23.8	23.3	28.8	22.5
Conor Pass An Conair	5.2	16.0	12.3	12.4	7.3	14.5	10.9	4.1	8	29.1	19.5	32.0	24.4	16.6	22.2	15.8
Dunquin <i>Dún Chaoin</i>	13.0	23.7	9.8	5.3	25.3	32.6	29.0	22.2	18.1	,	18.9	44.5	29.9	29.2	34.7	13.4
Feohanagh An Fheothanach	7.6	18.4	2.4	6.4	19.4	26.7	23.0	16.3	12.1	11.7		35.9	21.3	20.5	26.1	17.1
Inch An Inse	14.7	4.4	21.8	22.0	24.8	8.8	14.5	21.7	19.9	27.7	22.3	0	20.1	15.4	14.7	31.2
Kinard Ceann Áird	5.6	8.4	12.9	13.0	18.2	17.8	23.4	14.8	15.2	18.6	13.2	12.5		4.4	8.4	16.6
Lispole Lios Póil	5.2	5.6	12.3	12.4	17.6	15.0	20.7	14.5	10.3	18.1	12.8	9.5	2.7	6	3.4	15.8
Minard Minn Aird	8.6	5.2	15.7	15.9	21.0	14.6	20.3	17.9	13.8	21.6	16.2	9.1	5.2	5.5		21.4
Ventry Ceann Trá	4.7	15.5	7.1	3.7	17.1	24.9	20.7	14.0	9.8	8.3	10.6	19.4	10.3	9.8	13.3	

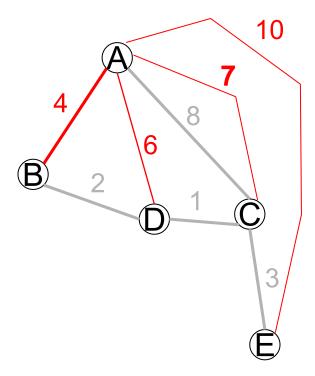
K L O M E T R E S

Algorithm?



Repeated runs of Dijkstra?

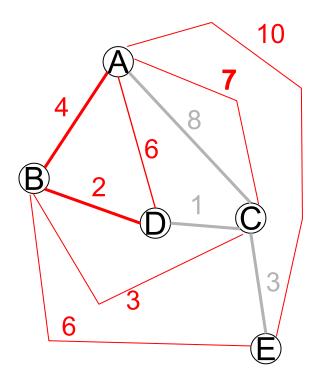
Source A: B C D E 4 7 6 10



Repeated runs of Dijkstra?

Source A: B C D E 4 7 6 10

Source B: A C D E 4 3 2 6

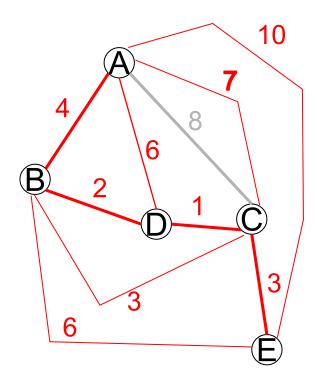


Repeated runs of Dijkstra?

Source A: B C D E 4 7 6 10

Source B: A C D E 4 3 2 6

Source C: A B D E 7 3 1 3



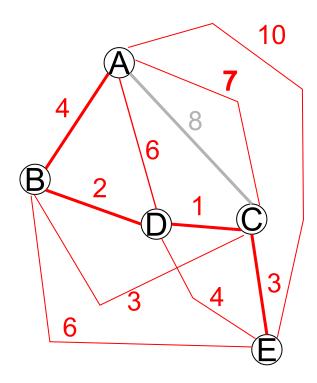
Repeated runs of Dijkstra?

Source A: B C D E 4 7 6 10

Source B: A C D E 4 3 2 6

Source C: A B D E 7 3 1 3

Source D: A B C E 6 2 1 4



Repeated runs of Dijkstra?

Source A: B C D E 4 7 6 10

Source B: A C D E

4 3 2 6

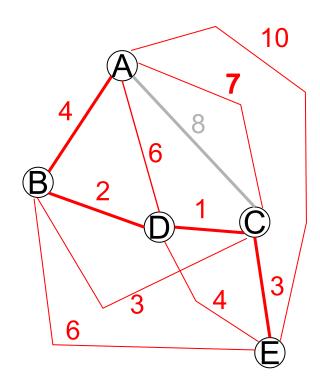
Source C: A B D E 7 3 1 3

Source D: A B C E

Source E: A B C D

10 6

(don't need to run Dijkstra for this one ...)



Maintain as a dictionary of dictionaries?

How should we compute 'all pairs shortest paths'?

For each vertex v in the graph compute the shortest path from v to all other vertices using Dijkstra?

Our Dijkstra implementation found paths from source to all other vertices in its component

 therefore, running Dijkstra n-1 times will find all pairs path costs in an undirected graph (need n runs for a directed graph)

Single run of Dijkstra:

	Sparse graph	Dense graph
Dijkstra-heap	O(n log n)	O(n² log n)
Dijkstra-list	O(n ²)	O(n ²)

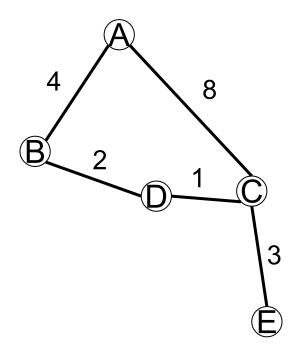
So for all pairs: (O(n) runs of Dijkstra ...)

	Sparse graph	Dense graph
Dijkstra-heap	O(n² log n)	O(n ³ log n)
Dijkstra-list	O(n ³)	O(n ³)

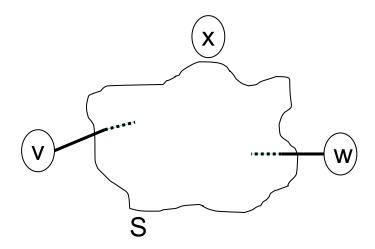
Algorithm?

Adapt the Floyd Warshall algorithm for finding the transitive closure?

- Find all-pairs shortest paths that only transit through vertices in {A}
- Find all pairs shortest paths that only transit through vertices in {A,B}



- Find all-pairs shortest paths in G0 that only transit through A, and if they are better, add an edge for those paths, to get G1
- Find all pairs shortest paths in G1 that only transit through B, and if they are better, add an edge for those paths, to get G2 etc



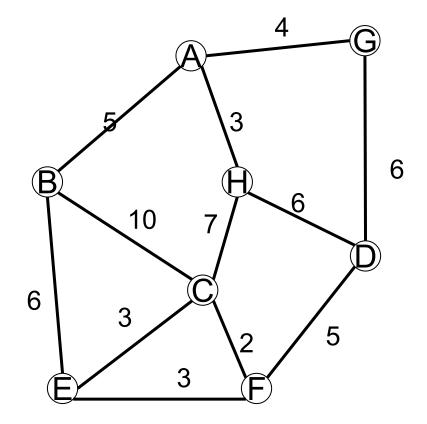
Let P be the shortest path from v to w which only visits vertices in S, and we will say cost(P) = sp(v,w,S).

Now let Q be the shortest path from v to w which only visits vertices in $S \cup \{x\}$

Either Q = P, or Q is made up of the shortest path from v to x which only visits vertices in S, then the shortest path from x to w which only visits vertices in S.

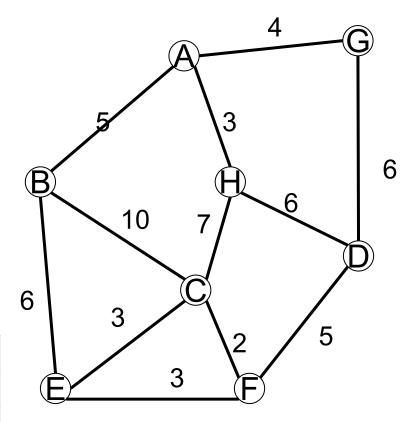
So if we have sp(v,w,S), and sp(v,x,S) and sp(x,w,S), we can compute $sp(v,w,S \cup \{x\}) = minimum(sp(v,w,S), sp(v,x,S)+sp(x,w,S))$

```
floydwarshall(): pseudocode
  initialise an nxn 2D structure with value ∞ for each entry
  for each v in graph
     assign table[v][v] = 0 #cost of path from v to v = 0
  #begin visitable set S = {}, so shortest paths visiting only S start as just edge costs
  for each pair of vertices (x,y)
     if {x,y} is an edge in the graph
       table[x][y] = w((x,y)) #initial cost of path is the edge weight, if edge exists
       table[y][x] = w((x,y))
     else
       table[x][y] = infinity # i.e. no path yet found
       table[y][x] = infinity
  for each v in the graph #each time round the loop, add v to S
     for each w in the graph #but not v
       for each x in the graph #but not v
          if table[w][x] > table[w][v] + table[v][x]:
                                                     #if path via v is cheaper
             table[w][x] = table[w][v] + table[v][x]
                                                     #record that as shortest path
  return table
```



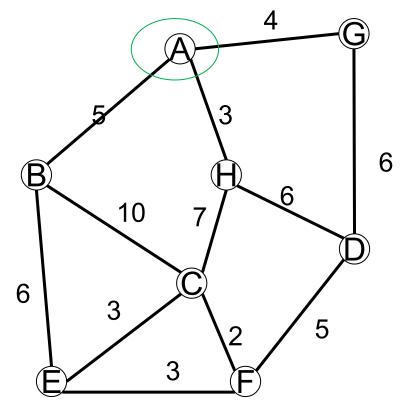
Initialised – cost of edges in graph, or 0 for the main diagonal, ∞ if no edge

	А	В	С	D	E	F	G	Н
А	0	5	8	8	8	8	4	3
В	5	0	10	8	6	8	8	8
С	8	10	0	8	3	2	8	7
D	8	8	8	0	8	5	6	6
E	8	6	3	8	0	3	8	8
F	8	8	2	5	3	0	8	8
G	4	∞	8	6	∞	∞	0	8
Н	3	8	7	6	8	8	8	0



Augmented with all paths via: {A}

	А	В	С	D	E	F	G	Н
А	0	5	8	8	8	8	4	3
В	5	0	10	8	6	8	9	8
С	8	10	0	8	3	2	8	7
D	8	8	∞	0	8	5	6	6
E	8	6	3	∞	0	3	8	∞
F	8	8	2	5	3	0	8	∞
G	4	9	∞	6	8	8	0	7
Н	3	8	7	6	8	8	7	0

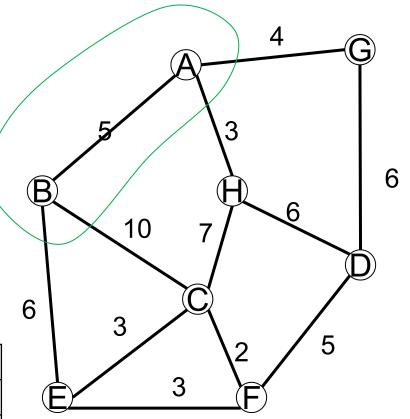


[B] [A] + [A] [G] =
$$5+4$$
 = $9 < \infty$
[B] [A] + [A] [H] = $5+3$ = $8 < \infty$
[G] [A] + [A] [H] = $4+3$ = $7 < \infty$

(and symmetric ...)

Augmented with all paths via: {A, B}

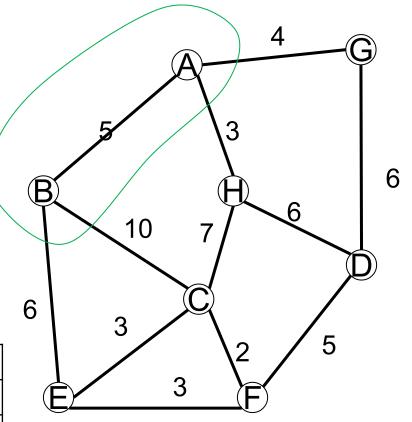
	А	В	U	D	E	F	U	Н
А	0	5	8	8	8	8	4	3
В	5	0	10	8	6	8	9	8
С	8	10	0	8	3	2	8	7
D	8	∞	8	0	8	5	6	6
E	8	6	3	8	0	3	8	∞
F	8	∞	2	5	3	0	8	∞
G	4	9	8	6	∞	8	0	7
Н	3	8	7	6	8	8	7	0



E.g. [A][C] was ∞ but [A][B]=5 + [B][C]=10 = 15 So update [A][C] to 15

Augmented with all paths via: {A, B}

	А	В	С	D	E	F	G	Н
А	0	5	∞	∞	∞	∞	4	3
В	5	0	10	∞	6	∞	9	8
С	8	10	0	8	3	2	8	7
D	8	8	8	0	8	5	6	6
E	8	6	3	8	0	3	8	∞
F	∞	8	2	5	3	0	∞	∞
G	4	9	∞	6	∞	∞	0	7
Н	3	8	7	6	∞	∞	7	0

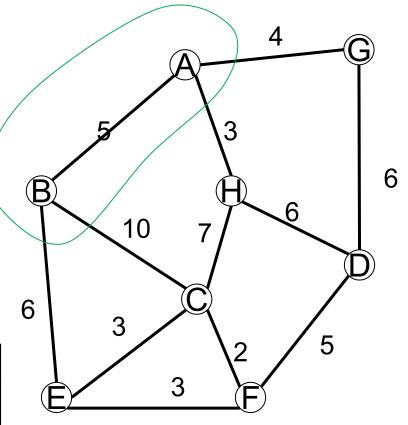


E.g. [C][H] was 7 and [C][B]=10 + [B][H]=8 = 18

So do not update [C][H]

Augmented with all paths via: {A, B}

	А	В	С	D	E	F	U	Н
А	0	5	15	8	11	8	4	3
В	5	0	10	8	6	8	9	8
С	15	10	0	8	3	2	19	7
D	8	8	8	0	8	5	6	6
E	11	6	3	8	0	3	15	14
F	8	8	2	5	3	0	8	8
G	4	9	19	6	15	8	0	7
Н	3	8	7	6	14	8	7	0

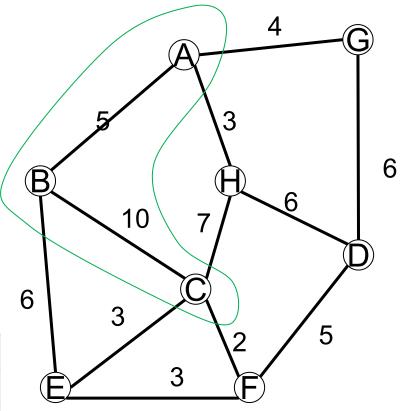


[A] [B]+[B] [C]=
$$5+10=15 < \infty$$

[A] [B]+[B] [E]= $5+6 =11 < \infty$
[C] [B]+[B] [G]= $10+9=19 < \infty$
[E] [B]+[B] [G]= $6+9 =15 < \infty$
[E] [B]+[B] [H]= $6+8 =14 < \infty$

Augmented with all paths via: {A, B, C}

	А	В	U	D	E	F	U	Н
А	0	5	15	8	11	17	4	3
В	5	0	10	8	6	12	9	8
С	15	10	0	∞	3	2	19	7
D	8	∞	8	0	8	5	6	6
E	11	6	3	8	0	3	15	10
F	17	12	2	5	3	0	21	9
G	4	9	19	6	15	21	0	7
Н	3	8	7	6	10	9	7	0

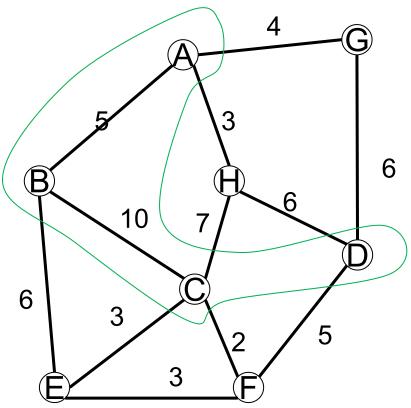


[A] [C]+[C] [F] =
$$15+2=17 < \infty$$

[B] [C]+[C] [F] = $10+2=12 < \infty$
[E] [C]+[C] [H] = $3+7 =10 < 14$
[F] [C]+[C] [G] = $2+19=21 < \infty$
[F] [C]+[C] [H] = $2+7 = 9 < \infty$

Augmented with all paths via: {A, B, C, D}

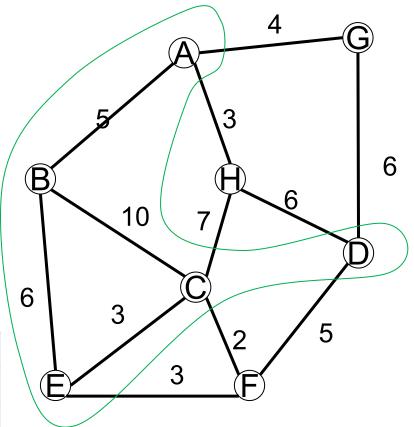
	А	В	C	D	E	F	G	Н
А	0	5	15	8	11	17	4	3
В	5	0	10	8	6	12	9	8
С	15	10	0	8	3	2	19	7
D	8	8	8	0	8	5	6	6
E	11	6	3	8	0	3	15	10
F	17	12	2	5	3	0	11	9
G	4	9	19	6	15	11	0	7
Н	3	8	7	6	10	9	7	0



$$[F][D]+[D][G]=5+6=11 < 21$$

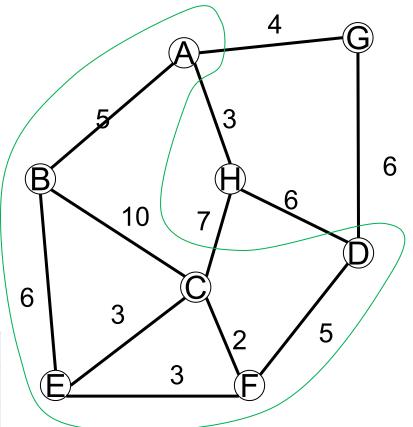
Augmented with all paths via: {A, B, C, D, E}

	А	В	С	D	E	F	G	Н
А	0	5	14	8	11	14	4	3
В	5	0	9	8	6	9	9	8
С	14	9	0	8	3	2	19	7
D	8	∞	∞	0	8	5	6	6
E	11	6	3	8	0	3	15	10
F	14	9	2	5	3	0	11	9
G	4	9	19	6	15	11	0	7
Н	3	8	7	6	10	9	7	0



Augmented with all paths via: {A, B, C, D, E, F}

	А	В	С	D	E	F	G	Н
А	0	5	14	19	11	14	4	3
В	5	0	9	14	6	9	9	8
С	14	9	0	7	3	2	13	7
D	19	14	7	0	8	5	6	6
E	11	6	3	8	0	3	14	10
F	14	9	2	5	3	0	11	9
G	4	9	13	6	14	11	0	7
Н	3	8	7	6	10	9	7	0

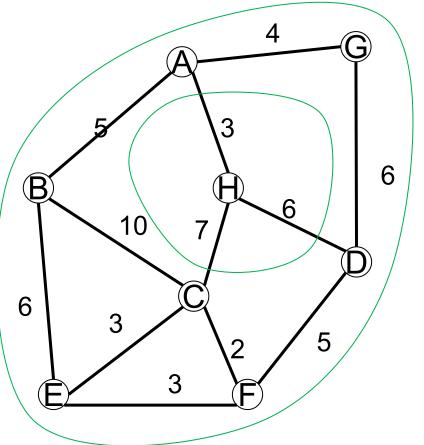


[A] [F]+[F] [D] =
$$14+5=19 < \infty$$

[B] [F]+[F] [D] = $9+5 =14 < \infty$
[C] [F]+[F] [D] = $2+5 = 7 < \infty$
[C] [F]+[F] [G] = $2+11=13 < 19$
[D] [F]+[F] [E] = $5+3 = 8 < \infty$
[E] [F]+[F] [G] = $3+11=14 < 15$

Augmented with all paths via: {A, B, C, D, E, F, G}

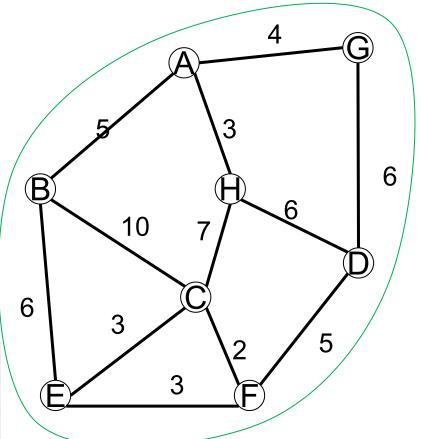
	А	В	С	D	E	F	U	Н
А	0	5	14	10	11	14	4	3
В	5	0	9	14	6	9	9	8
С	14	9	0	7	3	2	13	7
D	10	14	7	0	8	5	6	6
E	11	6	3	8	0	3	14	10
F	14	9	2	5	3	0	11	9
G	4	9	13	6	14	11	0	7
Н	3	8	7	6	10	9	7	0



$$[A][G]+[G][D] = 4+6 = 10 < 19$$

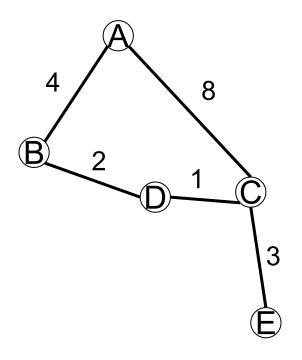
Augmented with all paths via: {A, B, C, D, E, F, G,H}

	А	В	С	D	E	F	G	Н
А	0	5	10	9	11	12	4	3
В	5	0	9	14	6	9	9	8
С	10	9	0	7	3	2	13	7
D	9	14	7	0	8	5	6	6
E	11	6	3	8	0	3	14	10
F	12	9	2	5	3	0	11	9
G	4	9	13	6	14	11	0	7
Н	3	8	7	6	10	9	7	0



H was last vertex to be added, so this is the final matrix

	А	В	O	D	E
А					
В					
С					
D					
E					



```
def floydwarshall(self):
    allpairs = {}
                                  #create a dictionary, vertices as keys
    for v in self. structure:
        allpairs[v] = {}
                         #each value is a dictionary
        for w in self. structure:
            allpairs[v][w] = float('inf')
        allpairs[v][v] = 0
    for e in self.edges():
        (v, w) = e.vertices()
        allpairs[v][w] = e.element()
        allpairs[w][v] = e.element()
    for v in self. structure:
        for w in self. structure:
            for x in self. structure:
                if allpairs[w][x] > allpairs[w][v] + allpairs[v][x]:
                    allpairs[w][x] = allpairs[w][v] + allpairs[v][x]
```

return allpairs

Complexity:

- initialising the 2D dictionary is O(n²)
- adding the edge costs is O(m), which is $O(n^2)$
- triple loop, n times round each loop: O(n³)

So complete algorithm is O(n³)

If graph is dense, this is lower complexity than repeated Dijkstra-heap (and same as Dijkstra-list, but tends to be faster)

If graph is sparse, this is higher complexity than repeated Dijkstra-heap, so don't use it for sparse graphs.

Final recommendation for all-pairs shortest path costs:

Sparse graph	Dense graph
O(n² log n) [Dijkstra-heap]	O(n ³) [Floyd-Warshall]

Exercise:

Augment the algorithm to store, for each pair, the 'intermediate' vertex which last improved the cost of the path (i.e. what 'v' was being considered in the outer loop when the cost was last updated?).

How would you reconstruct the shortest path for any pair from the result?

Next lecture

Directed acyclic graphs
Topological Sort