Minimum Spanning Trees I: Prim's algorithm COMS20010 2020, Video 5-3

John Lapinskas, University of Bristol

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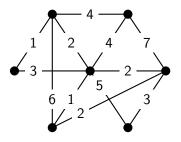
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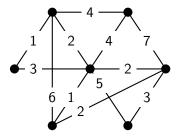


You need every town to be connected to every other town, and you want to spend as little as possible. So you want something like this, not like **this**.

We think of this situation as a connected weighted graph G = ((V, E), w): the vertices are towns, and w(x, y) is the cost of building a connection from x to y. (In this case, E would contain every possible edge.)

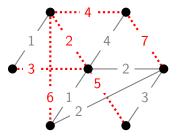


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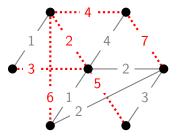
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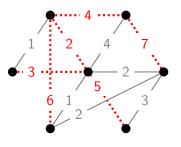
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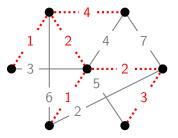


Total weight:

$$4+2+7+3+6+5=27$$

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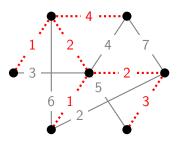
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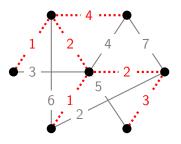


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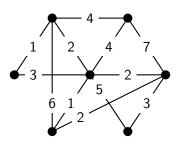
- this is "NP-hard" (read: no polynomial-time algorithm);
- all the approximation algorithms are based on minimum spanning tree;
- using a minimum spanning tree is already "good enough" at worst twice the weight of a minimum Steiner tree (see problem sheet).

Input: A connected weighted graph G = ((V, E), w). **Output:** A minimum spanning tree of G.

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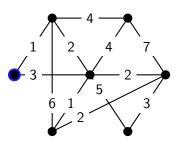
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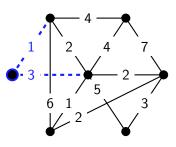
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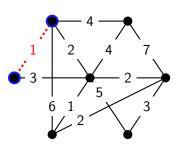
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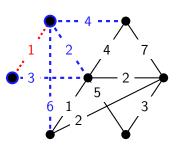
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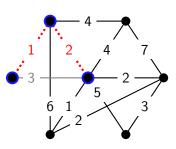
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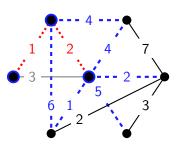
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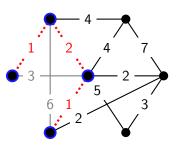
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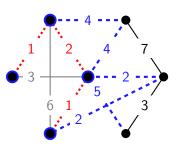
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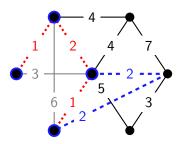
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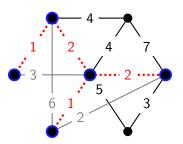


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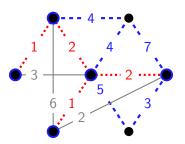


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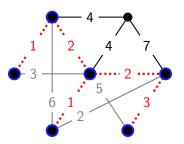


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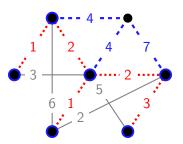


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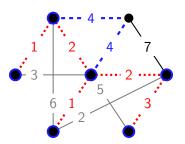


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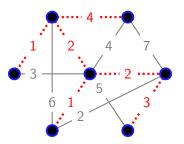


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Prim's algorithm: Formal version and correctness

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Formally: Let $T_1 = (\{v\}, \emptyset)$ for some arbitrary $v \in V$.

Let E_i be the set of edges from $V(T_i)$ to $V \setminus V(T_i)$.

Form T_{i+1} by adding a lowest-weight edge $e_i \in E_i$ to T_i , so $V(T_{i+1}) = V(T_i) \cup e_i$ and $E(T_{i+1}) = E(T_i) \cup \{e_i\}$.

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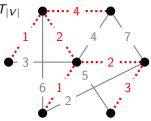
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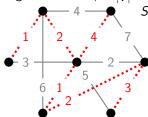
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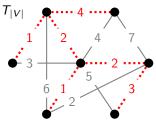
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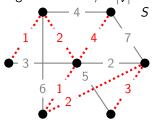
To prove it's a minimum spanning tree, we use an exchange argument.

That is, we show we can turn any minimum spanning tree into $T_{|V|}$ without increasing its weight (like with interval scheduling).

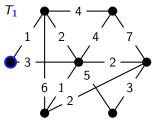


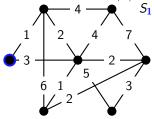






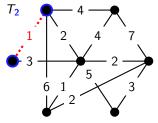
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, and let $I = \min\{i \colon S_i \neq T_i\}$.
We have $S_1 = T_1$ and $S_{|V|} \neq T_{|V|}$, so $2 \le I \le |V|$.

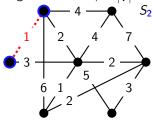




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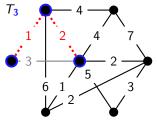
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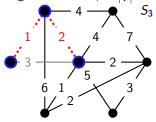




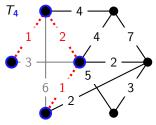
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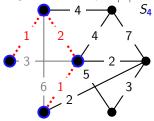
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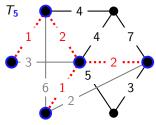


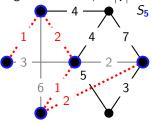
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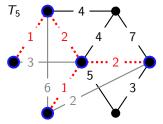
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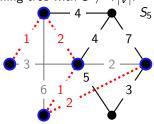




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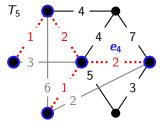


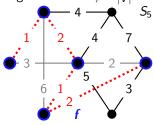


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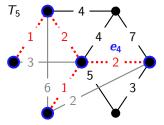


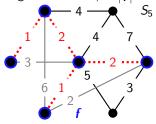
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 $S_{l-1} = T_{l-1}$ is a tree, so there is only one edge f from $V(S_{l-1})$ to $V \setminus V(S_{l-1})$ in S_l (or S_l would contain a cycle). Remove it and replace it with e_{l-1} .

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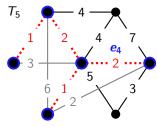


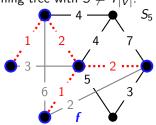
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 $S_{l-1} = T_{l-1}$ is a tree, so there is only one edge f from $V(S_{l-1})$ to $V \setminus V(S_{l-1})$ in S_l (or S_l would contain a cycle). Remove it and replace it with e_{l-1} .

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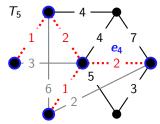
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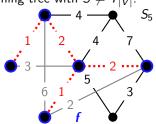
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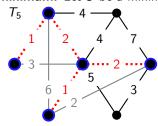
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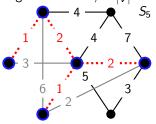
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Still a tree: Since there is only one edge f, $S[V \setminus V(S_{l-1})]$ is a tree as well (by the FLoT). Joining two disjoint trees by an edge gives another tree (by the FLoT).

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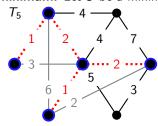
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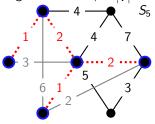
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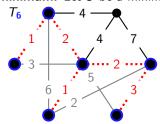
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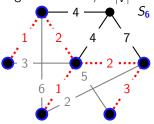
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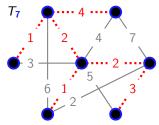
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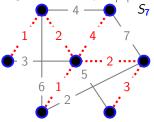
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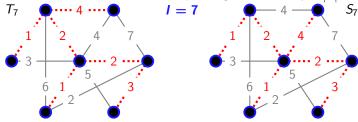
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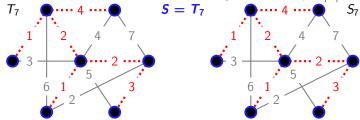
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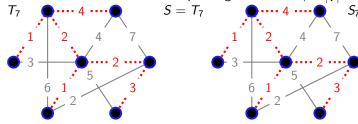
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By repeating the process, we can turn S **into** $T_{|V|}$ without increasing its weight. Hence $w(S) \ge w(T_{|V|})$. Since S was minimum, we're done!

Prim's algorithm: Implementation

10

11 Return pred.

Literally just breadth-first search with a priority queue!

```
Algorithm: BFS
  Input : Connected weighted graph G = ((V, E), w).
  Output : A minimum spanning tree for G.
1 Number the vertices of G arbitrarily as v_1, \ldots, v_n.
2 Let L[i] \leftarrow \infty for all i \in [n].
3 Let L[1] \leftarrow 0, pred[1] \leftarrow None.
4 Let queue be a length-|E| priority queue containing all tuples (v, v_i) with \{v, v_i\} \in E,
     using their edge weights as priorities.
6 while queue is not empty do
       Remove front tuple (v_i, v_i) from queue.
       if L[j] = \infty then
            Add (v_i, v_k) to queue for all \{v_i, v_k\} \in E, k \neq i.
            Set L[j] \leftarrow L[i] + 1, pred[j] = i.
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Time analysis: As with breadth-first search, each edge is only processed twice. Processing each edge now takes $\Theta(\log |E|)$ worst-case time, so overall the algorithm runs in $O(|E|\log |E|)$ time. (Note $|E| \geq |V|$.)

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Like with Dijkstra, we could "improve" this to $O(|E| + |V| \log |V|)$ time (with a much worse constant) by using a Fibonacci heap in place of the priority queue.