A non-examinable sketch proof of the Cook-Levin theorem COMS20010 2020, Video 10-2

John Lapinskas, University of Bristol

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Then we will construct a CNF formula $F_{\vec{x}}$, of size polynomial in $|\vec{x}|$, which is satisfiable if and only if \vec{x} is a Yes instance. Our Cook reduction then just applies the SAT oracle to $F_{\vec{x}}$ and outputs the result.

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By definition of NP, there is a polynomial-time algorithm Verify such that \vec{x} is a Yes instance if and only if $\text{Verify}(\vec{x}, \vec{w}) = \text{Yes}$ for some \vec{w} . So we would like to express the statement " $\text{Verify}(\vec{x}, \vec{w}) = \text{Yes}$ " as a CNF formula in \vec{w} .

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Problem: We know **nothing** about how Verify works. So to do this, we need to be able to express "A computer running program P on input I for t steps outputs Yes" as a CNF formula of polynomial size...!

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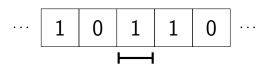
We could in principle do this for an actual computer architecture, but it would be unspeakably awful. So let's use a Turing machine instead.

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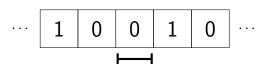


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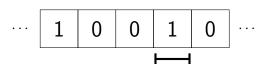


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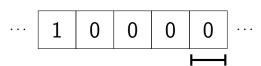
Machine in state 3, head reads $1 \longrightarrow \text{Write 0}$, move right, enter state 3.

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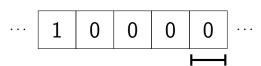
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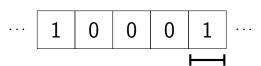
Machine in state 3, head reads $0 \longrightarrow Write 1$, move left, enter state 7.

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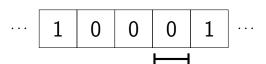


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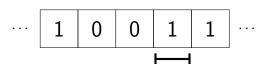


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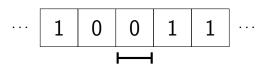


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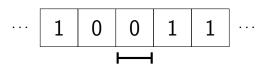


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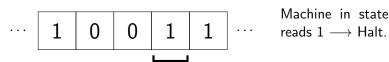


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Machine in state 10. head

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So we can take our program in the form of a Turing machine, which is much easier to simulate!

Our new goal: Given a **Turing machine** M, we would like a CNF formula $f(M, \vec{l}, t)$ which is satisfiable iff after running M on input \vec{l} for t steps, it halts with output Yes.

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Problem: The tape is infinite, so we need infinitely many variables!

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Solution: In time t the tape head can only move t spaces, so the state of the Turing machine is determined entirely by cells $-t, -t+1, \ldots, t$. So actually we only need $O(t^2)$ variables.

We would like to construct $f(M, \vec{l}, t)$ in time $poly(\vec{l}, t)$.

Our variables: We want: $C_{p,\tau}=$ contents of cell p at time τ ; $S_{s,\tau}=1$ iff machine is in state s at time τ ; $P_{p,\tau}=1$ iff head is at cell p at time τ .

We would like to construct $f(M, \vec{l}, t)$ in time poly (\vec{l}, t) .

Our variables: We want: $C_{p, au}=$ contents of cell p at time au; $S_{s, au}=1$ iff machine is in state s at time au; $P_{p, au}=1$ iff head is at cell p at time au.

Write \mathcal{M}_{τ} for the collection of variables corresponding to the machine's state at time τ , i.e. $\{C_{-t,\tau}, \ldots, C_{t,\tau}, S_{1,\tau}, \ldots, S_{q,\tau}, P_{-t,\tau}, \ldots, P_{t,\tau}\}$.

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If we can express these as CNF statements of length polynomial in t, we're done since an AND of CNFs is in CNF.

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This is painful but ultimately doable!

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So we check consistency with an AND of **many** clauses that look like:

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Each such clause has only 4 variables, so it can be expressed as an O(1)-length CNF formula.

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Each such clause has only 4 variables, so it can be expressed as an O(1)-length CNF formula. We need $\Theta(t)$ such formulae for every variable in $\mathcal{M}_{\tau+1}$, one for each possible (position, state, cell contents) tuple, so in total our consistency check will have length $\Theta(t^2)$ and $|f(M,\vec{l},t)| \in \Theta(t^3)$.

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