

# FINA4380 Stock Return Model

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## 1 Our model

We model return of stock  $i$  as

$$r_{it} = \beta_{i0t} + \beta_{i1t}PC_1 + \beta_{i2t}PC_2 + \dots + \beta_{int}PC_n + \varepsilon_{it}$$

where  $PC_i$  is the  $i$ th principal component obtained by PCA,  $\beta_i$  are state variables that follow random walk and we assume that  $\varepsilon_{it} \sim \mathcal{N}(0, \sigma_i^2)$  and  $Cov(\varepsilon_{it}, \varepsilon_{jt}) = 0$  for  $i \neq j$ .

## 2 Principal Components

We select the first  $n$  (not necessarily 5) principal components such that the proportion of variance explained exceeds 0.8.

Denoting the value of the  $i$ th principal component at time  $t$  as  $y_{it}$ , we assume that

$$y_{it} = \mu + \sum_{j=1}^p a_{ij}y_{t-j} + \sum_{j=1}^q b_{ij}\varepsilon_{t-j} + \varepsilon_{it}$$
$$\varepsilon_{it} = \sigma_{it}\epsilon_{it}, \quad \sigma_{it}^2 = \alpha_{i0} + \alpha_{i1}\varepsilon_{i,t-1}^2 + \beta_{i1}\sigma_{i,t-1}^2$$
$$\epsilon_{it} \stackrel{iid}{\sim} \mathcal{N}(0, 1)$$

And the correlation matrix between error terms (and hence stock return) is given by DCC.

## 3 Betas

We assume that betas change over time and can be modeled by

$$\beta_{\mathbf{t}} = I\beta_{\mathbf{t}} + \epsilon_{\mathbf{t}}$$

$$\text{where } \epsilon_{\mathbf{t}} \sim N(0, \mathbf{Q})$$

We obtain the forecast for  $\beta$  and  $\mathbf{Q}$  by Kalman filter.

## 4 Residual of Returns

We use GARCH(1, 1) model to estimate the variance of residual of returns  $\varepsilon_{it}$ .  
i.e.,

$$\varepsilon_{it} = \sigma_{it}\epsilon_{it}, \quad \sigma_{it}^2 = \alpha_{i0} + \alpha_{i1}\varepsilon_{i,t-1}^2 + \beta_{i1}\sigma_{i,t-1}^2$$

$$\epsilon_{it} \stackrel{iid}{\sim} \mathcal{N}(0, 1)$$

and the variance is given by  $\sigma_{it}^2$

## 5 Covariance matrix of stock return

when  $p \neq q$ ,

$$Cov(r_p, r_q) =$$