DCP: Fast Recursive Copy

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1 Overview

An improved version of 'cp -r,' dcp, was implemented. This version takes advantage of Linux's asynchronous IO interfaces to create opportunities for parallelism, and minimizes the time spent blocking on disk IO by leveraging fallocate and readahead. In order to ensure reads are more likely to result in hits in the buffer cache when memory is scarce, POSIX fadvise is used. To ensure optimal layout of files for writing, POSIX fallocate is used. The main goal of dcp is to fully saturate disk IO at all times in order to have a fast, portable solution which supports any POSIX compliant filesystem interface.

GNU coreutils has rejected [?] a number of feature requests and one of them was "cp –parallel", which would read and write from different file offsets in parallel [?]. This feature was rejected on the suggestion of using multiple dd processes instead and its github project [?] is incomplete and inactive. Splitting larger files may in fact improve performance but this project did not explore it.

2 Implementation

2.1 MPSCQ

The implementation uses a multi-producer, single-consumer queue (MPSCQ) to manage its work queue. The producers are the asynchronous directory read operations and the consumer is the main loop, which begins work and limits in-progress task count.

The MPSCQ is implemented with a linked list and atomic compare exchange instructions. The consumer has a pointer to the next node to be freed. Its next data to read is in the next node, so an empty list has one node. This way, the consumer frees one node per read. Each linked list node is annotated with a count and each node's count is one more than the previous. A producer creates the next node in its entirety based on its understanding of the end of the queue and then compare exchanges the address of that node into the node's next pointer, expecting NULL. To assist future threads in finding the end, it does compare exchange on the linked list's tail in a loop until either its proposed node is the tail or a node of greater count is the tail. The MPSCQ is thus lock free but not wait free and would be interrupt-reentrant safe as well (discussion below) if it did not call glibc malloc.

2.2 Multithreading

The implementation uses the POSIX asynchronous i/o [?]. Job completion was initially received with a signal (SIGEV_SIGNAL) and the file work was entirely signal-driven but interrupts were happening at antagonistic times within and without interrupt handlers. In particular, glibc lazily protects alo with a reentrant mutex [?], so an interrupt handler within an interrupt handler would violate its interrupted handler's critical section. Initially this was fixed by making a MPSCQ for all operations to schedule so that they were scheduled by the main loop and not by handlers but this deadlocked with low probability because glibc malloc, required by the MPSCQ, is protected by a spinlock [?] and would be interrupted inside its critical section and that interrupt would not be able to acquire the lock from itself. Moving off of signals and onto threads (SIGEV_THREAD) vastly simplified the implementation and got around

2.3 Readahead and buffer size

POSIX fadvise is used to ensure that pages will be available in the buffer cache when read [?], and that pages will be evicted from the cache as soon as possible. All reads in dcp are sequential, so FADV_SEQUENTIAL is used.

Additionally, readahead is used to provide hints to the kernel regarding the number of bytes which should be read into the buffer cache. Currently, dcp uses a fixed-size buffer of 0x80000 bytes for reads. As part of future work, a buffer which adaptively resizes itself based on system load and IO speed is proposed. However, adaptively resizing the buffer introduces some overhead and it is difficult to tune the size of the buffer for performance gains in all workloads and across all systems.

2.4 Fallocate

POSIX fallocate is used to allow the destination filesystem to allocate blocks in an efficient way [?]. The copying program knows the source file size and supplies it to the operating system. The use of fallocate is fairly straightforward and measurably increases write speeds on target ext4 filesystems, as demonstrated by some of the following benchmarks.

3 Test platforms

Test Platform 1

Component	Specification	Interface
CPU	Intel i7-4770k @ 3.50GHz	
RAM	8 GB @ 1333 Mhz	
OS	Linux 3.13.0	
HDD A	1TB @ 7200rpm	SATA II 3.0Gb/s
HDD B	2TB @ 5600rpm	SATA II 3.0Gb/s
SSD A	250GB	SATA II 3.0Gb/s
External A	3TB @ 5400rpm	USB 3.0

Test Platform 2

Component	Specification	Interface
CPU	Intel i7-2670QM @ $2.20GHz$	
RAM	8 GB @ 1333 MHz	
OS	Linux 3.17.4-1	
HDD	1TB @ 5400rpm	SATA II $3.0\mathrm{Gb/s}$

4 Benchmarking methodology

Dcp was tested on consumer-grade personal computers using 3 different types of drive: solid state drive, traditional disk-based hard drive, and an external USB3.0 disk based hard drive. With the exception of the external hard drive, which is formatted in NTFS, the disks are formatted in ext4. The combinations of stable storage media tested include:

source	destination	graph label
SSD A	SSD A	ssd - self
SSD A	HDD A	ssd - hdd
SSD A	External A	ssd - ext
HDD A	SSD A	hdd - ssd
HDD A	HDD B	hdd - hdd
HDD A	External A	hdd - ext
External A	SSD A	ext - ssd
External A	HDD A	ext - hdd

These drive configurations were tested using test platform 1.

In addition to the tests done on different drive configurations, dcp was benchmarked with certain optimizations disabled or modified, including the number of threads, fadvise, and readahead. These tests were done on test platform 2.

In order to ensure that the benchmark files are not stored in the buffer cache for subsequent executions of 'cp -r' or dcp, each benchmark was regenerated before each execution using random data read from /dev/urandom. Additionally, the resulting copied data from calling dcp was compared to the generated data using 'diff -r' in order to ensure that a full copy of the data was in fact executed.

An interesting problem which arose when testing these various combinations was that HDD B and External A had aggressive power-saving mechanisms built into the disk controller firmware. This caused inconsistent performance, which manifested initially as a bimodal distribution of execution times. This problem was remedied by running 'ls' on the root directory of the drive immediately before running each test to ensure the disk was not in power-saving mode.

Three main benchmarks were run on the data, named broad, fat, and deep. These will be elaborated upon in the following section.

5 Results

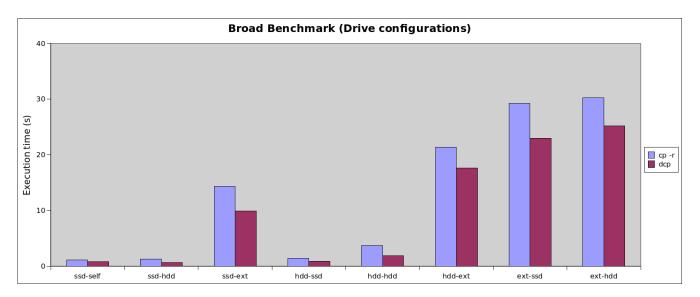
The benchmarks were run 5 times each for dcp and 'cp -r,' and the execution times were recorded. The sample mean and sample standard deviation were taken, and a 2-sample 1-tailed unpaired t-test was executed to compare the execution times for dcp and 'cp -r' for each disk configuration within a benchmark.

5.1 Broad Benchmark

Each file in the broad benchmark is 300kb (300000 bytes), and the top level directory contains 7 files and 15 subdirectories. Each of the 15 subdirectories contains 7 files and 15 subdirectories, which in turn contain 7 files. The broad benchmark is similar to copying a documents folder, as it is relatively

shallow but contains many subdirectories with files similar in size to pdf documents. This benchmark was chosen to test dcp's ability to prioritize work to keep IO saturated, as file reads blocking directory reads would severely bottleneck the creation of new IO jobs and thus reduce saturation.

The following graph shows the mean execution time across 5 trials of the broad benchmark across multiple disk configurations.

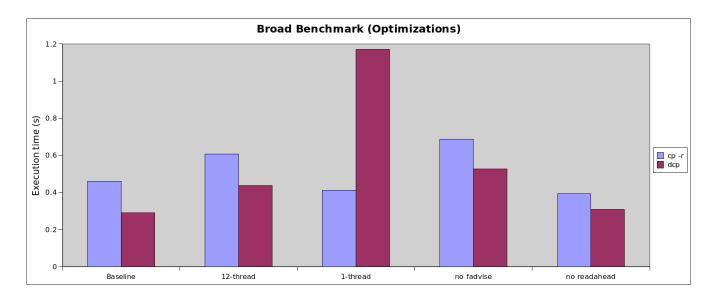


The results show that dcp can gracefully handle workloads involving similar numbers of directories and files, and prioritizes work well to beat 'cp -r.' In all cases, p < 0.005, indicating that the performance of dcp is statistically significantly different from that of 'cp -r,' and the graph clearly shows that dcp outperforms 'cp -r' on this benchmark.

The poor performance of the external drive benchmarks is apparent here, and is a common theme throughout the various tests run on the system. The external drive is not only consistently slow, but also suffers from inconsistent throughput, suffering from standard deviations from 1.5 for hdd-ext dcp to 2.4 for ext-ssd 'cp -r' and dcp. This is likely due to the extremely aggressive power-saving features of the external hard drive, the relatively low rpm of the drive (5400) and the slow speed of the USB interface.

Important to note here is that dcp outperformed 'cp -r' by a factor of 1.9 on the hdd-hdd configuration and a factor of 1.7 on the ssd-hdd configuration, which is important because these are common usage patterns for many people. Backups are often done between disk drives or from an SSD to a disk-based hard drive, and these cases are representative of these situations.

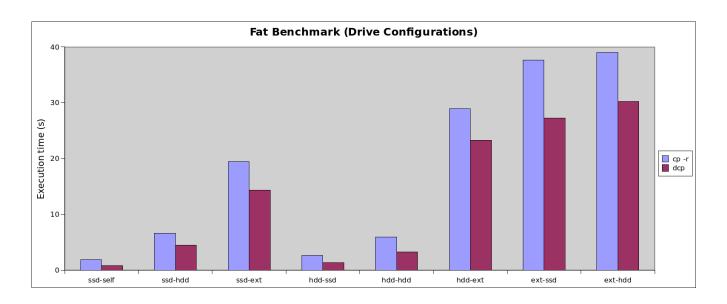
The results of running the broad benchmark with certain optimizations turned are displayed in the following graph.



Comparing the performance of unmodified dcp and dcp with certain optimizations disabled, the statistically significant differences from baseline include (using $\alpha = 0.05$) 1-thread (p = 0.002), and no-fadvise (p = 0.04). This indicates that for the broad benchmark, the more important optimizations include multithreading and fadvise. The former is rather self-explanatory, and the latter makes sense as broad uses somewhat large files which benefit from contiguous block allocation on the target disk.

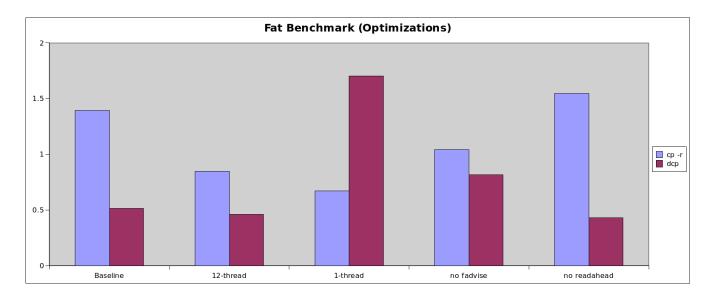
5.2 Fat Benchmark

Each file in the fat benchmark is 200kb (200000 bytes), and the top level directory contains 3 files and 35 subdirectories. Each of the 35 subdirectories contains 3 files and 35 subdirectories, which in turn contain 3 files. The fat benchmark contains a large number of subdirectories and not many files per subdirectory. This benchmark represents a sort of 'worst-case' for recursive copying, as files are small and numerous, and directory trees have high branching factors with sparsely distributed files. This is an important benchmark, as the performance of normal system copy utilities is often subpar for these operations, so it is a prime target for optimization in dcp. The following graph shows the mean execution time across 5 trials of the fat benchmark across multiple disk configurations.



Again, as with the broad benchmark results, the fat benchmark results confirm that dcp consistently outperforms 'cp -r.' In all cases, the mean execution time for dcp is statistically significantly lower than that of 'cp -r' (p < 0.005). Again, in the important cases of ssd-hdd and hdd-hdd, dcp outperforms 'cp -r' by a factor of 1.5 and 1.8 respectively.

The results of running the fast benchmark with certain optimizations turned off are displayed in the following graph.

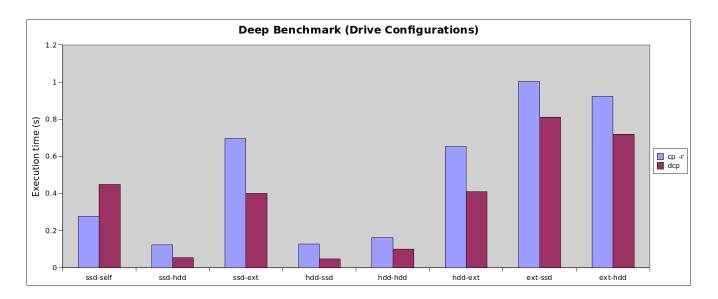


The statistically significant performance decreases from baseline include 1-thread ($p = 2 \times 10^{-7}$), 12-thread (p = 0.04), and no-readahead (p = 0.009). Due to the larger number of smaller files and the high branching factor in the directory tree compared to the broad benchmark, having 12 threads likely helped to saturate the IO speed since queueing/executing these smaller jobs could possibly cause downtime with a smaller number of threads. This opens another question of how to determine the number of simultaneous jobs being generated, as having too many threads generating jobs could result in downtime due to threads contending for system resources, while having too few threads can result in downtime if not enough jobs are generated to saturate IO. This angle is one which will be explored in further research.

5.3 Deep Benchmark

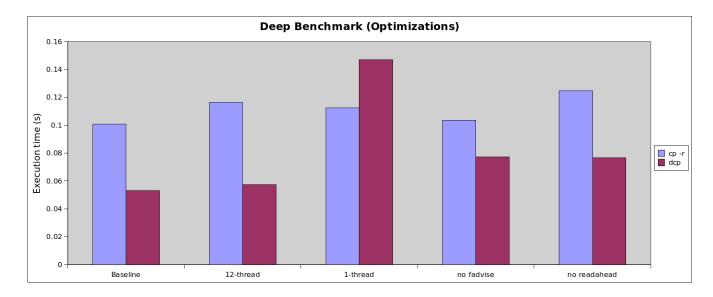
Each file in the deep benchmark is 20mb (20000000 bytes), and the top level directory contains 1 file and 1 subdirectory. There are 6 nested subdirectories in this benchmark. The deep benchmark is purposely small in order to ensure that dcp prioritizes directories over files in such a way that it avoids blocking as much as possible. If dcp were to prioritize reading and writing files over directories, it would end up blocking on all 6 subdirectories and thus would lose to 'cp -r.' This is demonstrated when evaluating the performance of dcp with certain optimizations removed.

The following graph shows the mean execution time across 5 trials of the deep benchmark across multiple disk configurations.



The deep benchmark results reflect the same statistically significantly lower execution time of dcp than 'cp -r' (p < 0.005). Contrasting with the previous benchmarks, ssd-ext shows a significantly (1.7x) higher copy time for 'cp -r' than dcp. This is perhaps indicative of the fact that raw throughput may be the limiting factor when copying files across a USB interface, and that smart prioritization of tasks when copying smaller amounts of data allows the kernel to intelligently batch writes in such a way that the external drive minimizes seek time. This particular test, due to the small volume of data copied, is aimed more at testing a potential weakness of dcp than a practical situation.

Finally, the results of running the deep benchmark with certain optimizations turned off are displayed in the following graph.



The statistically significant optimizations for the deep benchmark included only the 1-thread test (p < 0.001). However, the deep benchmark experienced large standard deviations in each data set, ranging from 21% to over 40% of the mean. This volatility contrasts with the previous fat benchmark, where standard deviations were typically around 10% of the mean. Thus, it is difficult to draw conclusions from the performance of the deep benchmark, but as mentioned earlier the deep benchmark is not an entirely realistic test case, so it is not overly important to fully understand which optimizations work hardest in this benchmark.

In all 3 selective optimization benchmarks, it is apparent that the major factors which make dcp faster than cp -r are, as expected, multithreading, and by extension asynchronous IO, and, to a lesser extent, fadvise and readahead. Disabling multithreading in any of the benchmarks resulted in a large decrease in performance for all 3 benchmarks. The other effects, including changing the number of threads and the effects of fadvise and readahead are a bit more difficult to describe qualitatively. For different workloads, different optimizations are applicable, and the previous sections have attempted to explain why these particular optimizations caused statistically significant variance in performance for each benchmark.

6 Practical test

Additionally, one practical test was done to demonstrate the advantage of dcp over standard cp -r. 5.7gb of video files split among 5 subdirectories were copied between HDD A and HDD B to simulate a backup of videos, a usage pattern common for one of the researchers. This benchmark was not repeated for other drive types as it is simply intended to convey a practical example use case.

The results on this practical test show that dcp in its current state outperforms cp -r by a decent margin even in situations where a disk's theoretical maximum throughput is approached (typically with large sequential reads/writes). The mean execution time of cp -r is approximately 2:10, while the mean execution time of dcp is 1:50, with a sample standard deviation of 5 seconds and p < 0.01. Roughly calculating the raw throughput, dcp copies at approximately 53 mb/s while 'cp -r' copies at approximately 45mb/s. It is noteworthy that the CrystalDiskBenchmark results for HDD B indicated that it has a sequential write throughput of 55mb/s when the disk was benchmarked 2.5 years earlier (when it was new) by one of the researchers.

7 Observations

One interesting observation is that tests done on the first test platform took significantly longer than tests done on the second test platform for similar disk configurations. While more testing and research is necessary to ascertain the cause of this performance discrepancy, one key difference between the platforms which may have caused this behavior is that test platform 1 used older disks which were about 50-60% full, as opposed to test platform 2 which used a single new mostly-empty disk. Additionally, the solid state drive used by test platform 1 was the boot drive, whereas the disk used by platform 2 was not. Finally, the specific behavior of prefetching, buffer caching, and file IO may have been affected by differences in the kernel version between the two platforms, as well as the fact that platform 1 runs Ubuntu while platform 2 runs Arch.

References

- [1] Asynchronous IO http://man7.org/linux/man-pages/man7/aio.7.html
- [2] Fallocate http://man7.org/linux/man-pages/man3/posix_fallocate.3.html

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