

PHY 480 - Computational Physics

Project 1: Linear Algebra Methods

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Github Repository at <https://github.com/ThomasBolden/PHY-480-Spring-2016>

Abstract

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Introduction

An important part of physics is being able to efficiently solve differential equations. There are many situations in which differential equations can be solved as a system of linear equations. Such equations are called linear second-order differential equations, of the form

$$\frac{d^2 y}{dx^2} + k^2(x)y = f(x), \quad (1)$$

where $f(x)$ is the inhomogenous term, and k^2 is a real function. An example of this is Poisson

Methods

Given a differential equation of the form

$$-\frac{d^2}{dx^2}u(x) = f(x) \quad (2)$$

where $f(x)$ is continuous on the domain $x \in (0,1)$. We also assume the boundary conditions $u(0) = u(1) = 0$. The second derivative can be approximated as

$$u'' = \frac{u_{i+1} + u_{i-1} - 2u_i}{\Delta x^2} \quad (3)$$

$$\mathbf{A} = \begin{pmatrix} 2 & -1 & 0 & \cdots & \cdots & \cdots & 0 \\ -1 & 2 & -1 & 0 & \cdots & \cdots & 0 \\ 0 & -1 & 2 & -1 & \ddots & & 0 \\ \vdots & 0 & -1 & 2 & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & 0 \\ \vdots & \vdots & & \ddots & \ddots & \ddots & -1 \\ 0 & 0 & \cdots & \cdots & 0 & -1 & 2 \end{pmatrix}, \quad \mathbf{v} = \begin{pmatrix} v_0 \\ v_1 \\ \vdots \\ v_{n-1} \\ v_n \end{pmatrix}$$

Results

.

$$\tilde{d}i = i/i - 1$$

Conclusions

.

Code

../Code/Project1.cpp

```
1 // Project 1 - Vector and Matrix Operations
2
3 #include <iostream>
4 #include <fstream>
5 #include <cmath>
6 #include <iomanip>
7 #include <string>
8 #include "armadillo"
9
10 using namespace std;
11 using namespace arma;
12
13 ofstream myfile;
14
15 // --- Functions --- \\
16
17 double f(double x){
18     return 100*exp(-10*x);
19 }
20
21 double analyze(double x){
22     return 1.0-(1-exp(-10))*x-exp(-10*x);
23 }
24
25 // --- Main --- \\
26
27 int main(){
28
29     // --- Declaration of Variables --- \\
30
31     double n;
32     string outfilename;
33
34     cout << "Dimensions of the nxn matrix: ";
35     while(!(cin >> n)){
36         cout << "Not a valid number! Try again: ";
37         cin.clear();
38         cin.ignore(numeric_limits<streamsize>::max(), '\n');
39     }
40     cout << "Enter a name for the output file: ";
41     cin >> outfilename;
42
43     // body of the program
44
45
46
47     // writing value to file, to be read and graphed in python later
48     myfile.open(outfilename);
49     myfile << setiosflags(ios::showpoint | ios::uppercase); //sci notation
50     myfile << n << endl;
```

```

51
52     myfile.close();
53
54     return 0;
55
56 }

```

../Code/plots.py

```

1  # From matplotlib examples
2
3  # obvi not real useful yet
4
5  import numpy as np
6  import matplotlib.pyplot as plt
7
8  plt.subplots_adjust(hspace=0.4)
9  t = np.arange(0.01, 20.0, 0.01)
10
11 # log y axis
12 plt.subplot(221)
13 plt.semilogy(t, np.exp(-t/5.0))
14 plt.title('semilogy')
15 plt.grid(True)
16
17 # log x axis
18 plt.subplot(222)
19 plt.semilogx(t, np.sin(2*np.pi*t))
20 plt.title('semilogx')
21 plt.grid(True)
22
23 # log x and y axis
24 plt.subplot(223)
25 plt.loglog(t, 20*np.exp(-t/10.0), basex=2)
26 plt.grid(True)
27 plt.title('loglog base 4 on x')
28
29 # with errorbars: clip non-positive values
30 ax = plt.subplot(224)
31 ax.set_xscale("log", nonposx='clip')
32 ax.set_yscale("log", nonposy='clip')
33
34 x = 10.0*np.linspace(0.0, 2.0, 20)
35 y = x**2.0
36 plt.errorbar(x, y, xerr=0.1*x, yerr=5.0 + 0.75*y)
37 ax.set_ylim(ymin=0.1)
38 ax.set_title('Errorbars go negative')
39
40
41 plt.show()

```

References

- [1] M. Hjorth-Jensen, *Computational Physics*, University of Oslo (2013).
- [2] W. McLean, *Poisson Solvers*, Northwestern University (2004).