

# The Heterogeneous causes and effects of Climate Change

WORK IN PROGRESS

*Thomas Bourany*

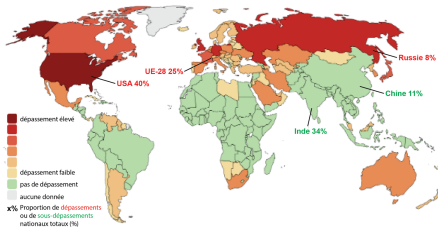
THE UNIVERSITY OF CHICAGO

*Economic Dynamics*

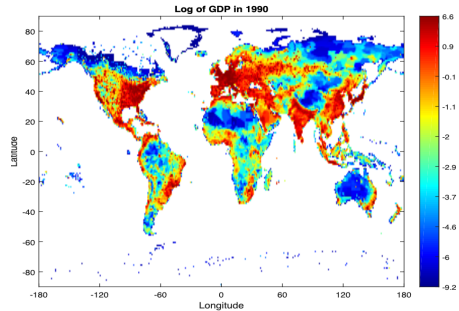
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## Introduction – Motivation

- The cumulative GHG emissions are mostly in developed countries / advanced economies ...

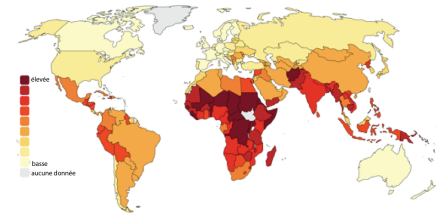


Source : Lancet planetary Health - Quantifying national responsibility for climate breakdown: an equality-based attribution approach for carbon dioxide emissions in excess of the planetary boundary - Jason Hickel 2020

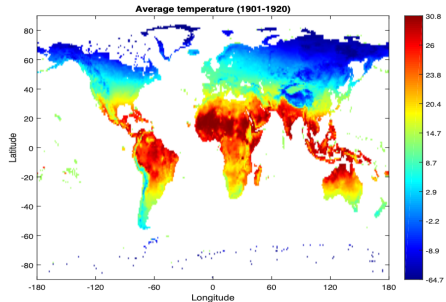


## Introduction – Motivation

- ... while the impact will affect mostly developing economies, where temperature is already very high



Source : Notre Dame Global Adaptation Initiative



## Introduction

- ▶ In presence heterogeneity, no country has an incentive to internalize the climate externality
  - Is the equilibrium without policy intervention bound to collapse?
- ▶ What is the optimal policy against climate change?
  - Should countries contribute according to their present/past emissions they have caused?
  - Or the damage they are contributing? (standard Pigouvian tax)
  - Can the social planner allocation be attained with tax instruments?
- ▶ Policy based on carbon taxes
  - Different taxes per region?
  - Or uniform taxes and transfers
  - Is a country better off joining the world "social planner policy" or deviating?

# Introduction

- ▶ Integrated assessment models rely on strong assumptions
  - ... about the economy (NCG model)
  - ... about the climate system (may not be consistent w/ climate models)
  - ... about the damage function (in DICE, only affecting TFP)
- ▶ IAMs also tend to be computational/untractable
  - Nordhaus' Multi-regions DICE (2016), Cai, Lontzek, Judd (2019), Kotlikoff, Kubler, Polbin, Scheidegger (2021), Hassler, Krusell, Olovsson, Smith (2019-2021), Cruz, Rossi-Hansberg (2021)
- ▶ This project :
  - Theoretical investigation on the importance of heterogeneity
  - Design of the social planner allocation in comparison to the competitive equilibrium allocation
  - Sensitivity analysis on which dimension of heterogeneity matters the most, and uncertainty about the models

# Model

- ▶ Neoclassical economy, in continuous time
  - countries/regions  $i \in \mathcal{I}$  : ex ante heterogeneous in dimensions  $\underline{s}$
  - heterogeneous ex post in dimensions  $\bar{s}$  (c.f. next slide), total state  $s = \{\underline{s}, \bar{s}\}$

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    - The heterogeneity  $\underline{s}_i$  doesn't change over time
    - For now  $s_i$  is productivity  $z_i$  and/or population  $N_i$ 
      - Productivity grow at rate  $\mu$  and population grow at rate  $n$

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      - Productivity grow at rate  $\mu$  and population grow at rate  $n$
- ▶ Households owns the representative firm
  - No trade/no migration/no agglomeration economies
  - Maximize :

$$U_{i,t_0}(s) = \int_{t_0}^{\infty} e^{-(\rho-n)t} u_i(c_t, T_t) dt$$



## Model and dynamics

### ► Utility of HH vs. social planner

$$U_{i,t_0}(s) = \int_{t_0}^{\infty} e^{-(\rho-n)t} u_i(c_t, T_t) dt$$

$$W_{t_0} = \int_{\mathcal{I}} \omega_i U_{i,t_0} di = \int_{\mathbb{S}} \omega(s) U_{i,t_0}(s) g(s) ds$$

- Distribution over states  $g(s)$
- Some states  $\bar{s}$  vary over time : capital  $k_i$  and temperature  $T_i$

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- Some states  $\bar{s}$  vary over time : capital  $k_i$  and temperature  $T_i$

### ► Dynamics of capital :

$$\dot{k}_t = \mathcal{D}(T_t) f(k_t, e_t) - (n + \mu + \delta) k_t - c_t - \nu(e_t)$$

### ► Two choices :

- $c$  consumption,  $e$  energy/emissions, Production fct  $f(k, e) = z k^\alpha e^\varepsilon$
- Fossil energy is produced subject to a cost  $\nu(e) = \bar{\nu} e^\nu$
- Exhaustible resource with a world stock  $R$
- Damage  $\mathcal{D}_i(T_t)$  affect country's PPF
- (Future) include abatement/clean energy

## Energy and externality

- ▶ Energy/emission is a choice and cause two types of externality
  - Decrease the world stock of resources  $R_t$  (à la Hotelling)

$$\dot{R}_t = - \int_{\mathcal{I}} e_{i,t} di = - \int_{\mathbb{S}} e_t(s) g_t(s) ds$$

- Change the world climate  $\mathcal{T}$  : analytical formula :

$$\dot{S}_t = \int_{\mathbb{S}} \xi e_t(s) g_t(s) ds - \delta_s S_t$$

$$\dot{\mathcal{T}}_t = \varepsilon(\chi S_t - T_t)$$

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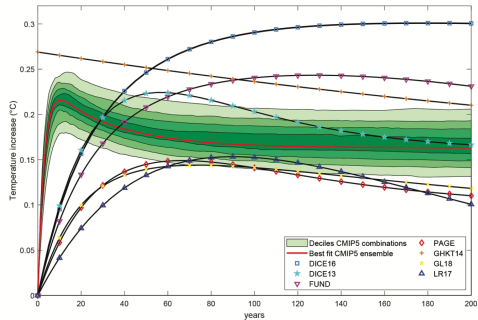
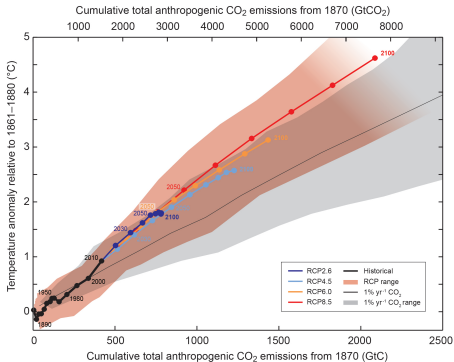
$$\dot{\mathcal{T}}_t = \varepsilon(\chi S_t - T_t)$$

- $\varepsilon$  is the inverse of persistence, so if  $\varepsilon \rightarrow \infty$ , we obtain a linear model :

$$\mathcal{T}_t = \bar{\mathcal{T}} + \chi S_t = \bar{\mathcal{T}} + \chi \int_{t_0}^t \int_{\mathcal{I}} \xi e_i di d\tau \Big|_{GrC}$$

- The externality depends on the policy  $e(s)$  as function of state  $s$ 
  - Naturally countries richer/more productive/with a larger population use more energy !

# Temperature dynamics



Linear temperature model - IPCC report / Dietz, van der Ploeg, Rezai, Venmans (2021)

## Temperature dynamics

- Emissions of all countries change the world climate  $\mathcal{T}$  through cumulative emission

$$\dot{\mathcal{S}}_t = \int_{\mathbb{S}} \xi e_t(s) g_t(s) ds - \delta_s \mathcal{S}_t$$

$$\dot{\mathcal{T}}_t = \varepsilon(\chi \mathcal{S}_t - T_t)$$

- Temperature in country  $i$  potentially affected with sensitivity  $\Delta_i$

$$\dot{T}_t = \Delta_i \dot{\mathcal{T}}_t$$

- Possibility of a more complex climate block :
  - Add 5 or 6 more state variables !

$$\dot{\mathbf{J}}_t = \Phi \mathbf{J}_t + \rho^e \int_{\mathbb{S}} \xi e(s) g(s) ds$$

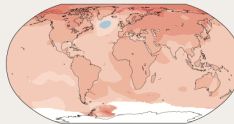
$$F_t = \mathcal{F} \mathbf{J}_t \quad \dot{\mathcal{T}}_t = \Phi^T \mathcal{T} + \eta F_t$$

# Temperature dynamics

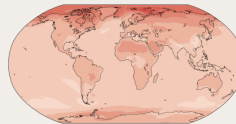
**(a) Annual mean temperature change (°C)  
at 1°C global warming**

Warming at 1°C affects all continents and is generally larger over land than over the oceans in both observations and models. Across most regions, observed and simulated patterns are consistent.

Observed change per 1°C global warming



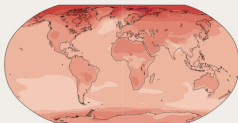
Simulated change at 1°C global warming



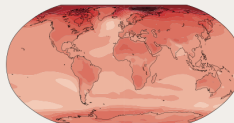
**(b) Annual mean temperature change (°C)  
relative to 1850–1900**

Across warming levels, land areas warm more than ocean areas, and the Arctic and Antarctica warm more than the tropics.

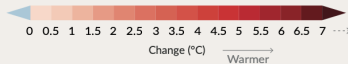
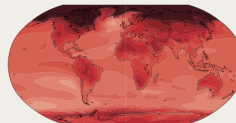
Simulated change at 1.5°C global warming



Simulated change at 2°C global warming



Simulated change at 4°C global warming



## Damage functions

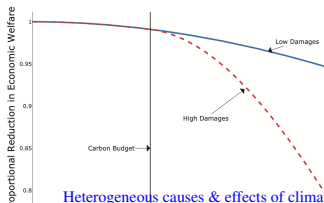
- Climate change has two effects :
  - Affect household utility function  $u(c, T)$

$$u(c_t, T_t) = \mathcal{D}^u(T_t) \frac{c_t^{1-\eta}}{1-\eta} \quad \mathcal{D}^u(T) = \exp(-\phi(T - T^*)^2)$$

- Affect firm productivity  $Z_t = \mathcal{D}(T_t)z$  as a shifter – as in Nordhaus DICE-2016

$$\mathcal{D}^y(T) = \exp(-\gamma(T - T^*)^2)$$

- Deviation (positive/negative) from "ideal" temperature  $T^* = 15^\circ\text{C}$
- Damage sensitivity  $\gamma_i$  and  $\phi_i$  can also be heterogeneous and uncertain





## Summing up

### ► System of coupled ODEs - PMP :

- State variables  $s = (z, k, R, S, T)$  and two controls  $(c, e)$

$$\dot{k}_t = \mathcal{D}(T_t)z_t f(k_t, e_t) - (n + \mu + \delta)k_t - c_t - \nu(e_t)$$

$$\dot{R}_t = -E_t \quad E_t = e^{(n+\mu)t} \int_{\mathbb{S}} e_t(s) g_t(s) ds$$

$$\dot{T}_t = \Delta_i \varepsilon (\chi S_t - T_t) \quad \dot{S}_t = \xi E_t - \delta^S S_t$$

$$s_0 = (z_{0,i}, k_{0,i}, R_0, T_{0,i})$$

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- Hamiltonian :

$$\mathcal{H}(s, c, e, \{\lambda\}) = u(c, T) + \lambda^k \dot{k} + \lambda^R \dot{R} + \lambda^S \dot{S} + \lambda^T \dot{T}$$

- Costates :  $\tilde{\rho} = \rho - n + \mu(\eta - 1)$

$$\begin{aligned} -\dot{\lambda}_t + \tilde{\rho} \lambda_t^k &= \partial_k \mathcal{H}(\cdot) & \Rightarrow & \dot{\lambda}_t^k = -\lambda_t^k (r_t - \tilde{\rho}) \\ -\dot{\lambda}_t^R + \tilde{\rho} \lambda_t^R &= \partial_R \mathcal{H}(\cdot) = 0 & \Rightarrow & \dot{\lambda}_t^R = \tilde{\rho} \lambda_t^R \\ -\dot{\lambda}_t^S + \tilde{\rho} \lambda_t^S &= \partial_S \mathcal{H}(\cdot) & \& & -\dot{\lambda}_t^T + \tilde{\rho} \lambda_t^T &= \partial_T \mathcal{H}(\cdot) \end{aligned}$$

## Marginal value of temperature

- Marginal values of the climate variables :  $\lambda^S$  and  $\lambda^T$

$$\dot{\lambda}_t^T = \lambda_t^T (\tilde{\rho} + \Delta\varepsilon) + \overbrace{\gamma(T_t - T^*)\mathcal{D}^y(T_t)}^{\partial_T \mathcal{D}^y} f(k_t, e_t) \lambda_t^k + \overbrace{\phi(T_t - T^*)\mathcal{D}^u(T_t)}^{\partial_T \mathcal{D}^u} u(c_t)$$

$$\dot{\lambda}_t^S = \lambda_t^S (\tilde{\rho} - \delta^s) - \Delta\varepsilon \chi \lambda_t^T$$

- Marg. value of carbon  $\lambda^S$  in location w/ state  $s$  increases with :
- Temperature  $T - T^*$
  - Damage sensitivity to temperature for TFP  $\gamma$  and utility  $\phi$
  - The development level  $f(k, e)$  and  $u(c)$

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- Marg. value of carbon  $\lambda^S$  in location w/ state  $s$  increases with :
- Temperature  $T - T^*$
  - Damage sensitivity to temperature for TFP  $\gamma$  and utility  $\phi$
  - The development level  $f(k, e)$  and  $u(c)$
- The cost of carbon can be defined SCC closed form

$$CC_{i,t} = \frac{\partial U_{i,t} / \partial \mathcal{S}_{i,t}}{\partial U_{i,t} / \partial c_{i,t}} = \frac{\lambda_t^S(s)}{\lambda_t^k(s)}$$

- Ratio of marg. value of carbon/marg. value of consumption !
- Can integrate over time  $t$  & state-space  $i$  :  $SCC_t = \int_{\mathbb{S}} \frac{\lambda_t^S(s)}{\lambda_t^k(s)} g(s) ds$
- Uncertainty SCC with uncertainty

## Choice of energy and emission

- ▶ Different choices of emissions depending on the level of externality !
  - Small economies ? Additional  $e_t(s)$  don't affect  $E_t = \int_{\mathbb{S}} e_t(s) g_t(s) ds$ 
    - 1. Only private tradeoff : marg. product of energy = marg cost

$$\mathcal{D}(T_t) z_t \partial_e f(k_t, e_t) = \nu'(e_t)$$

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$$\mathcal{D}(T_t)z_t \partial_e f(k_t, e_t) = \nu'(e_t)$$

- 2. Private tradeoff + energy monopolist : MPE = MC + Hotelling rent

$$\mathcal{D}(T_t)z_t \partial_e f(k_t, e_t) = \nu'(e_t) + \frac{\lambda_t^R}{\lambda_t^k(s)}$$

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- Large economies ?  $e(s)$  does affect  $E_t = \sum_{\mathbb{S}} \xi e(s)$ 
  - 3. Internalize scarcity and externality (for yourself, state  $s$  !)

$$\mathcal{D}(T_t)_{z_t} \partial_e f(k_t, e_t) = \nu'(e_t) + \frac{\lambda_t^R}{\lambda_t^k(s)} + \frac{\xi \lambda_t^S(s)}{\lambda_t^k(s)}$$

## Choice of energy and emission

- Different choices of emissions depending on the level of externality !
  - Social planner allocation ? Choose the policies of all  $s \in \mathbb{S}$  :
    - 4. Internalize aggregate effect of scarcity and externality :

$$\mathcal{D}(T_t)_{z_t} \partial_e f(k_t, e_t) = \nu'(e_t) + \frac{\lambda_t^R}{\lambda_t^k(s)} + \underbrace{\frac{\xi}{\omega(s)\lambda_t^k(s)} \int_{\mathbb{S}} \omega(\tilde{s}) \lambda_t^s(\tilde{s}) g(\tilde{s}) d\tilde{s}}_{=\text{Carbon tax } \tau^e(s)}$$



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- Static carbon tax : internalize damage *weighted* by  $\lambda_t^k = u'(c_t)$  !  
(assume Pareto weights  $\omega(s) = 1$ )

$$\tau^e(s) = \frac{1}{\lambda_t^k(s)} \int_{\mathbb{S}} \lambda_t^S(\tilde{s}) g(\tilde{s}) d\tilde{s} \neq \int_{\mathbb{S}} \frac{\lambda_t^S(\tilde{s})}{\lambda_t^k(\tilde{s})} g(\tilde{s}) d\tilde{s} = SCC_t$$

- Future : Joint choice of  $e$ ,  $e^{\text{fossil}}$  and  $e^{\text{renew.}}$  and/or  $\xi$

## Competitive equilibrium vs. Social planner

- ▶ Social planner : choose all controls  $\{c, e\}$

$$W_{t_0} = \max_{\{c(s), e(s)\}_{s \in \mathbb{S}}} \int_{\mathbb{S}} \omega(s) U_{i, t_0}(s) g(s) ds$$

- ▶ In this environment, different sources of externality :
  1. Choice of energy/emissions  $s$  given the states  $s$  : **Static**
    - ▶ Externality of the finite resource problem
    - ▶ Damage due to temperature
  2. Evolution of state and cstate  $s = (z, k, R, S, T)/\lambda$  : **Dynamic**
    - Dynamic problem :  
state matters for optimal choice and for future emission !
    - More productive/capital-rich countries emit more :
    - Climate change should affect the marginal value of  $z$  and  $k$
  3. Social planner corrects these two features
    - ▶ First : c.f. previous slides, Second : see the next slide !

## Competitive equilibrium vs. Social planner

- Competitive equilibrium : state  $s = (z, k, R, S, T)$  and costate  $\lambda$  evolution

$$-\dot{\lambda}_t + \tilde{\rho}\lambda_t = \partial_s \mathcal{H}(s, \lambda)$$

- Social planner allocation :

- Take into account the distribution  $g(s)$  in the costate dynamics :
- Second term : effect of shifting the distribution  $g(s)$  by one unit of  $s$
- Impact of  $\bar{E}_t = \int_{\mathbb{S}} e_t(s) g_t(s) ds$

$$-\dot{\lambda}_t + \tilde{\rho}\lambda_t = \partial_s \mathcal{H}(s, \lambda(s)) + \partial_s e(s) \int_{\mathbb{S}} \partial_{\bar{E}} \mathcal{H}(\tilde{s}, \lambda(\tilde{s})) g(\tilde{s}) d\tilde{s}$$

- Marginal effect of state  $s$  on choice of energy  $e(s)$  through  $\partial_s e(s)$
- Marginal value of state  $\lambda_t$  increases with the externality of  $\bar{E}!!$

$$\partial_{\bar{E}} \mathcal{H}(s, \lambda(s)) = \lambda_t^R + \xi \lambda_t^S(\tilde{s})$$

## Competitive equilibrium vs. Social planner : Example

- ▶ Competitive equilibrium, state : capital  $k$  and costate  $\lambda^k$

$$\dot{\lambda}_t^k = (\tilde{\rho} - r_t) \lambda_t^k$$

- ▶ Social planner allocation :

- Impact of  $\bar{E}_t = \int_{\mathbb{S}} e_t(s) g_t(s) ds$

$$\dot{\lambda}_t^k = (\tilde{\rho} - r_t) \lambda_t^k - \frac{\partial e(s)}{\partial k} \int_{\mathbb{S}} (\lambda_t^R + \xi \lambda_t^S(\tilde{s})) g(\tilde{s}) d\tilde{s}$$

- Marginal value of state  $\lambda_t$  decreases with the externality of  $\bar{E}$
- Consume more today because more capital in the future affects the choice of energy  $e(s)$  through  $\partial_s e(\tilde{s})$

$$\frac{\partial e}{\partial k} = \left( \frac{\mathcal{D}(T_t) z \epsilon}{\bar{\nu}} \right)^{\frac{1}{\nu - \epsilon}} \frac{\alpha}{\nu - \epsilon} k^{\frac{\alpha}{\nu - \epsilon} - 1}$$

## Carbon taxation

- ▶ Impose a tax on energy, denote resulting welfare  $W_{t_0}^{tax}$

$$\tau^e \xi = SCC = \int_{\mathbb{S}} \frac{\lambda_t^S}{\lambda_t^k} g(\tilde{s}) d\tilde{s}_t \quad \text{or} \quad \tau^e(s) \xi = \frac{1}{\lambda_t^k} \int_{\mathbb{S}} \lambda_t^S(\tilde{s}) g(\tilde{s}) d\tilde{s}_t$$

- ▶ Is carbon taxation a way to reach the first best ?

$$W_{t_0}^{tax} \geq W_{t_0}^{SP}$$

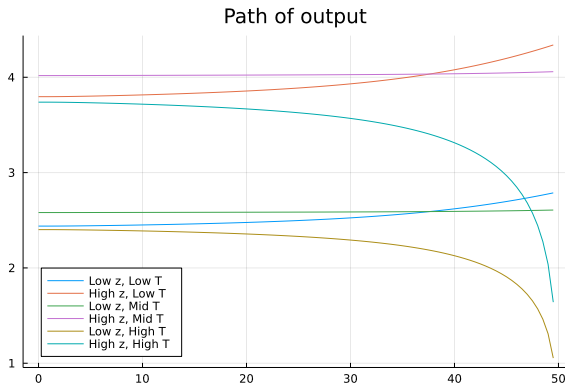
- No ! Dynamic externalities still present !
- ▶ Will countries join the policy/social planner allocation ? Only if :

$$U_{t_0}^{SP} > U_{i,t_0}^{tax} > U_{i,t_0}^{CE}$$

- No coordination ! Some countries benefit from climate change !
- ▶ Can tax  $\tau$  be made "more" country-specific / more progressive ? + Correlated with current/past emissions ?

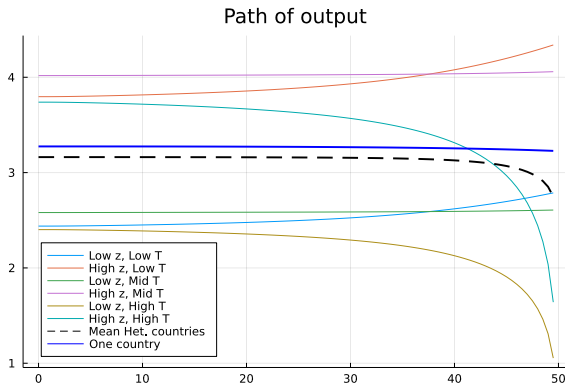
## Toy example - simulation

- "Business as usual" scenario : no internalization
- 6 countries : productivity  $z \in \{z_\ell, z_h\}$  & temperature  $T_t \in \{T_\ell, T_m, T_h\}$
- Compare to one country with  $z = \bar{z}$  and  $T_t = \bar{T}$



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- 6 countries : productivity  $z \in \{z_\ell, z_h\}$  & temperature  $T_t \in \{T_\ell, T_m, T_h\}$
- Compare to one country with  $z = \bar{z}$  and  $T_t = \bar{T}$



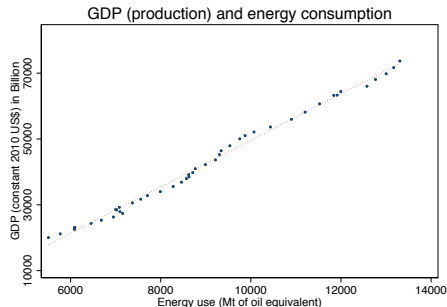
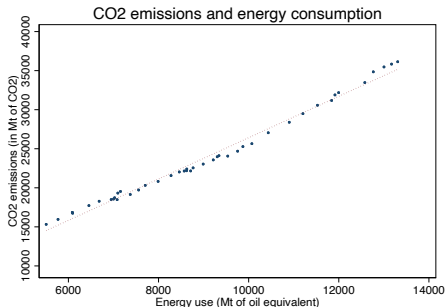
## Conclusion

- ▶ Climate change is induced by externality
  - Energy/Emission choice doesn't include the impact on other countries
  - Cause strengthened by heterogeneity in wealth (capital/productivity)
  - Effect strengthened by heterogeneity in impact (temperature/damage)
- ▶ Social planner allocation correct for these different dimensions
  - Both Static correction  $\equiv$  modified Pigouvian carbon taxation
  - And dynamic : through the marginal value of states
- ▶ Future plans :
  - Simulation of the three equilibria  $CE/tax/SP$
  - Match the distribution of  $y = z f(k, e)$  and  $T$  to the data
  - Social cost of carbon including heterogeneity and model uncertainty



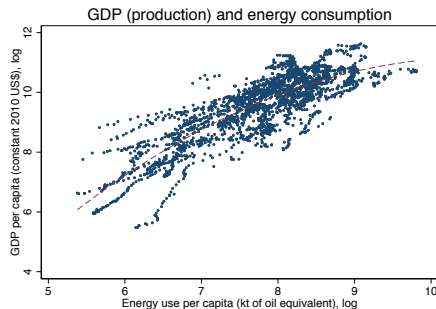
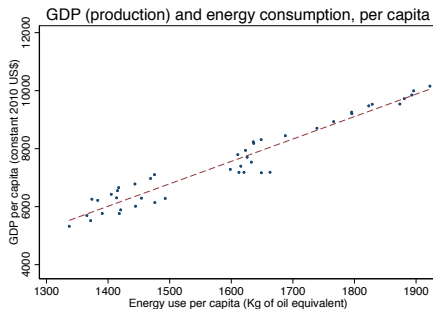
# Motivation

- ▶  $CO_2$  emissions correlate linearly with energy use
- ▶ Energy use (85% from fossils) correlates with output/growth



## Introduction – Motivation

- ▶ Also true per capita and for the trajectory of individual countries



## Cost of carbon / Marginal value of temperature

- Solving for the cost of carbon and temperature  $\Leftrightarrow$  solving ODE

$$\dot{\lambda}_t^T = \lambda_t^T(\tilde{\rho} + \Delta\varepsilon) + \gamma(T - T^*)\mathcal{D}^y(T)f(k, e)\lambda_t^k + \phi(T - T^*)\mathcal{D}^u(T)u(c)$$

$$\dot{\lambda}_t^S = \lambda_t^S(\tilde{\rho} - \delta^S) - \Delta\varepsilon\chi\lambda_t^T$$

- Solving for  $\lambda_t^T$  and  $\lambda_t^S$ , in stationary equilibrium  $\dot{\lambda}_t^S = \dot{\lambda}_t^T = 0$

$$\lambda_t^S = \int_t^\infty e^{-(\tilde{\rho} - \delta^S)\tau} \Delta\varepsilon\chi\lambda_\tau^T d\tau$$

$$\lambda_t^T = \int_t^\infty e^{-(\tilde{\rho} + \Delta\varepsilon)\tau} (T_\tau - T^*) \left( \gamma\mathcal{D}^y(T_\tau)y_\tau\lambda_\tau^k + \phi\mathcal{D}^u(T_\tau)u(c_\tau) \right) d\tau$$

$$\lambda_t^T = \frac{1}{\tilde{\rho} + \Delta\varepsilon} (T - T^*) \left( \gamma\mathcal{D}^y(T_\infty)y_\infty\lambda_\infty^k + \phi\mathcal{D}^u(T_\infty)u(c_\infty) \right)$$

$$\lambda_t^S = \frac{1}{\tilde{\rho} - \delta^S} \Delta\varepsilon\chi\lambda_\infty^T$$

$$= \frac{\Delta\chi}{\tilde{\rho} - \delta^S} \frac{\varepsilon}{\tilde{\rho} + \Delta\varepsilon} (T - T^*) \left( \gamma\mathcal{D}^y(T_\infty)y_\infty\lambda_\infty^k + \phi\mathcal{D}^u(T_\infty)u(c_\infty) \right)$$

$$\lambda_t^S \xrightarrow{\varepsilon \rightarrow \infty} \frac{\Delta\chi}{\tilde{\rho} - \delta^S} (T - T^*) \left( \gamma\mathcal{D}^y(T_\infty)y_\infty\lambda_\infty^k + \mathcal{D}^u(T_\infty)u(c_\infty) \right)$$

## Cost of carbon / Marginal value of temperature

► Closed form solution for CC :

- In stationary equilibrium :  $\dot{\lambda}_t^S = \dot{\lambda}_t^T = 0$
- Fast temperature adjustment  $\varepsilon \rightarrow \infty$
- no internalization of externality (business as usual)

$$CC_t(s) \equiv \frac{\Delta\chi}{\tilde{\rho} - \delta^s} (T_t - T^*) \left( \gamma \mathcal{D}^y(T_\infty) y_\infty + \phi \mathcal{D}^u(T_\infty) \frac{c_\infty}{1 - \eta} \right)$$

► Heterogeneity + uncertainty about models

## Uncertainty about models :

- ▶ In our model, we rely strongly on model specification :
  - Parameters  $\theta$  of models :
    - Climate system and damages :  $(\chi, \varepsilon, \delta^s, \gamma, \phi)$
    - Economic model :  $\xi, \epsilon, \nu^f, \mu, n, \eta$  or extended :  $\omega, \sigma^e, \sigma^f, \nu^{\text{renew}}, z^{\text{renew}}$
    - Models with probability weight  $\pi(\theta)$
  - Social cost of carbon, weighted for model uncertainty :

$$SCC_t(\theta) = \int_{\mathbb{S}} \frac{\lambda_t^s(s, \theta)}{\lambda_t^k(s, \theta)} g(s) ds$$

$$S\bar{C}C_t = \int_{\Theta} SCC_t(\theta) \pi(\theta) d\theta = \int_{\Theta} \int_{\mathbb{S}} \frac{\lambda_t^s(s, \theta)}{\lambda_t^k(s, \theta)} g(s) ds \pi(\theta) d\theta$$

- Counterfactual computation of  $SCC$ 
  - Representative country / no uncertainty  $\frac{\lambda_t^s}{\lambda_t^k}$
  - With heterogeneous regions / no uncertainty  $SCC_t(\bar{\theta})$
  - No heterogeneity / model uncertainty  $\int_{\Theta} \frac{\lambda_t^s(\bar{s}, \theta)}{\lambda_t^k(\bar{s}, \theta)} \pi(\theta) d\theta$
  - With heterogeneous regions / with model uncertainty  $S\bar{C}C_t$

## Sequential vs. recursive method

- ▶ Previous treatment : sequential approach :
  - Solve a system of ODE (because no uncertainty here) :
    - Monte Carlo for state  $s$
    - Shooting algorithm for states  $s$  and costate  $\lambda^s$
    - Can handle many states  $s = (z, k, R, S, T)$  or  $s = (z, N, k, \gamma/\phi, R, F, T)$
- ▶ Alternative treatment : recursive approach :
  - Solve a system of (S)PDE : Mean Field Game system
    - Hamilton Jacobi Bellman equation
    - Kolmogorov Forward/Fokker Plank equation
  - Master equation ?

## Recursive approach

- Solve a system of PDE : Mean Field Game system
  - State Dynamics :

$$\begin{aligned}\dot{k}(s, c, e) &= \exp(-\gamma T^2) z f(k, e) - (n + \mu + \delta)k - c - \nu(e) \\ \dot{T}(s, c, e) &= \bar{\tau}_t \tau(T) \int_{\mathbb{S}} e(\tilde{s}) g(\tilde{s}) d\tilde{s}\end{aligned}$$

- Hamilton Jacobi Bellman equation

$$-\partial_t v(s) + (\rho - n)v(s) = \max_{c, e} u(c, T) + \partial_k v(s) \dot{k}(s, c, e) + \partial_R v(s) \dot{R} + \partial_T v(s) \dot{T}(s, c, e)$$

- Kolmogorov Forward/Fokker Plank equation

$$\partial_t g(s) = -\partial_k [g(s) \dot{k}(s, c, e)] - \partial_R [g(s) \dot{R}] - \partial_T [g(s) \dot{T}(s, c, e)]$$