02-712 Biological Modeling and Simulations: Homework 2

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Question 1

a)

$$\begin{bmatrix} c_{1,1} & c_{1,2} & \dots & c_{1,n} & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ c_{n+1,1} & c_{n+1,2} & \dots & c_{n+1,n} & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \\ g_0 \end{bmatrix} = \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_n \\ g_{n+1} \end{bmatrix}$$

 $c_{i,j}$ is the j'th condition during the i'th experiment. x_i is the contribution that environment condition c_i contributes to the overall growth rate. g_i is the growth rate of the i'th experiment. The system is full rank since there are n+1 weights to learn and there are n+1 equations. Since the matrix is full rank, an iterative solving algorithm like Krylov-Subspace can be used.

b)

$$\begin{bmatrix} c_{1,1} & c_{1,2} & \dots & c_{1,n} & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ c_{2n,1} & c_{2n,2} & \dots & c_{2n,n} & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \\ g_0 \end{bmatrix} = \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_n \\ g_{2n} \end{bmatrix}$$

 $c_{i,j}$ is the j'th condition during the i'th experiment. x_i is the contribution that environment condition c_i contributes to the overall growth rate. g_i is the growth rate of the i'th experiment. The system is over determined $\forall n > 1$ since there are n+1 weights to learn and there are 2n equations. Since the system is over determined, there are multiple solutions, so we can use least squares regression to find a solution that minimizes $\sum_i a_i x - g_i$ where a_i is one row of the matrix of conditions $[c_{1,1}, c_{1,2}, ...]$. This can be solved by solving the solution for $A^T A x = A^T g$.

c)

$$\begin{bmatrix} c_{1,1} & c_{1,2} & \dots & c_{1,n} & c_{1,1}c_{1,1} & c_{1,1}c_{1,2} & \dots & c_{1,n-1}c_{1,n} & c_{1,n}c_{1,n} & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ c_{2n,1} & c_{2n,2} & \dots & c_{2n,n} & c_{2n,1}c_{2n,1} & c_{2n,1}c_{2n,2} & \dots & c_{2n,n-1}c_{2n,n} & c_{2n,n}c_{2n,n} & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{\frac{n^2-3n}{2}} \\ g_0 \end{bmatrix} = \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_n \\ g_{2n} \end{bmatrix}$$

 $c_{i,j}$ is the j'th condition during the i'th experiment. x_i is the contribution that environment condition c_i contributes to the overall growth rate. g_i is the growth rate of the i'th experiment. The system is under determined since there are $1 + \frac{n^2 - 3n}{2}$ weights to learn and there are 2n equations. Since the system is under determined there are infinite solutions. So one approach that we can use to solve for x is to find the pseudo-inverse of A, which is denoted as \bar{A} and then calculate $\bar{A}b = x$. The pseudo inverse of A is $Q_2\bar{\Sigma}Q_1^T$ where $\bar{\Sigma}$ the negative transpose of the singular value matrix Σ of A, Q_1 is the left singular matrix of A and Q_2 is the right singular matrix of A ($A = Q_1\Sigma Q_2^T$).

c)

$$\begin{bmatrix} c_{1,1} & c_{1,2} & \dots & c_{1,n} & c_{1,1}c_{1,1} & c_{1,1}c_{1,2} & \dots & c_{1,n-1}c_{1,n} & c_{1,n}c_{1,n} & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ c_{n^2,1} & c_{n^2,2} & \dots & c_{n^2,n} & c_{n^2,1}c_{n^2,1} & c_{n^2,1}c_{n^2,2} & \dots & c_{n^2,n-1}c_{n^2,n} & c_{n^2,n}c_{n^2,n} & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{\frac{n^2-3n}{2}} \\ g_n \\ g_{n^2} \end{bmatrix} = \begin{bmatrix} g_1 \\ g_2 \\ \vdots \\ g_n \\ g_{n^2} \end{bmatrix}$$

 $c_{i,j}$ is the j'th condition during the i'th experiment. x_i is the contribution that environment condition c_i contributes to the overall growth rate. g_i is the growth rate of the i'th experiment. The system is over determined since there are $1 + \frac{n^2 - 3n}{2}$ weights to learn and there are n^2 equations and $n^2 > 1 + \frac{n^2 - 3n}{2}$. Since the system is over determined, there are multiple solutions, so we can use least squares regression to find a solution that minimizes $\sum_i a_i x - g_i$ where a_i is one row of the matrix of conditions $[c_{1,1}, c_{1,2}, \ldots]$. This can be solved by solving the solution for $A^T A x = A^T q$.

Question 2

$$f(x) = \frac{4}{x^7} - \frac{3}{x^2} + 0.1$$

a)

$$f(x_{max}) = f(1) = \frac{4}{1^7} - \frac{3}{1^2} + 0.1 = 1.1$$

$$f(x_{mid}) = f(2) = \frac{4}{2^7} - \frac{3}{2^2} + 0.1 = -0.61875$$

$$f(x_{min}) = f(3) = \frac{4}{3^7} - \frac{3}{3^2} + 0.1 = -0.23150434385$$
(1)

$$f(x_{max}) = f(1) = \frac{4}{1^7} - \frac{3}{1^2} + 0.1 = 1.1$$

$$f(x_{mid}) = f(1.5) = \frac{4}{1.5^7} - \frac{3}{1.5^2} + 0.1 = -0.99922267947$$

$$f(x_{min}) = f(2) = \frac{4}{2^7} - \frac{3}{2^2} + 0.1 = -0.61875$$
(2)

$$f(x_{max}) = f(1) = \frac{4}{1^7} - \frac{3}{1^2} + 0.1 = 1.1$$

$$f(x_{mid}) = f(1.25) = \frac{4}{1.25^7} - \frac{3}{1.25^2} + 0.1 = -0.9811392$$

$$f(x_{min}) = f(1.5) = \frac{4}{2^7} - \frac{3}{2^2} + 0.1 = -0.99922267947$$
(3)

The backwards error is 0.5 and the forwards error is 0.9811392 after the 3^{rd} bisection.

b)

$$f(x_{max}) = f(1) = \frac{4}{1^7} - \frac{3}{1^2} + 0.1 = 1.1$$

$$f(x_{mid}) = f(2.65226648352) = \frac{4}{2^7} - \frac{3}{2^2} + 0.1 = -0.322135968884$$

$$f(x_{min}) = f(3) = \frac{4}{3^7} - \frac{3}{3^2} + 0.1 = -0.23150434385$$
(4)

$$f(x_{max}) = f(1) = \frac{4}{1^7} - \frac{3}{1^2} + 0.1 = 1.1$$

$$f(x_{mid}) = f(2.2780023652) = \frac{4}{1.5^7} - \frac{3}{1.5^2} + 0.1 = -0.465547707306$$

$$f(x_{min}) = f(2.65226648352) = \frac{4}{2^7} - \frac{3}{2^2} + 0.1 = -0.322135968884$$
(5)

$$f(x_{max}) = f(1) = \frac{4}{1^7} - \frac{3}{1^2} + 0.1 = 1.1$$

$$f(x_{mid}) = f(1.89796216057) = \frac{4}{1.25^7} - \frac{3}{1.25^2} + 0.1 = -0.687723865076$$

$$f(x_{min}) = f(2.2780023652) = \frac{4}{1.5^7} - \frac{3}{1.5^2} + 0.1 = -0.465547707306$$
(6)

The backwards error is 2.2780023652 and the forwards error is 0.687723865076

c)

$$f'(x) = -7(\frac{4}{x^8}) + 2(\frac{3}{x^3}) + 0 = \frac{21}{x^8} + \frac{6}{x^3}$$

$$f(1) = \frac{4}{17} - \frac{3}{12} + 0.1 = 1.1 \tag{7}$$

$$f(1.05) = \frac{4}{1.05^7} - \frac{3}{1.05^2} + 0.1 = 0.221636885146$$
 (8)

$$f(1.06609) = \frac{4}{1.06609^7} - \frac{3}{1.06609^2} + 0.1 = 0.0159992621509$$

$$f(1.06745) = \frac{4}{1.06745^7} - \frac{3}{1.06745^2} + 0.1 = 0.000102031079136$$
(10)

$$f(1.06745) = \frac{4}{1.06745^7} - \frac{3}{1.06745^2} + 0.1 = 0.000102031079136 \tag{10}$$

The estimate of backward error is 1.06609 - 1.06754 = 0.00145 and the forward error is 0.000102

Question 3

a)

$$2a + b + 3c \le 10$$

$$a + b + 2c \le 7$$

$$3a + b + c \le 12$$

$$a \ge 0$$

$$b \ge 0$$

$$c \ge 0$$

 $\underset{a,b,c}{\operatorname{argmax}} \quad f(a,b,c) = a + 2b + 5c$

b)

$$2a + b + 3c + k_1 = 10$$

$$a + b + 2c + k_2 = 7$$

$$3a + b + c + k_3 = 12$$

$$a \ge 0$$

$$b \ge 0$$

$$c \ge 0$$

$$k_1 \ge 0$$

$$k_2 \ge 0$$

$$k_3 \ge 0$$

$$\underset{a,b,c}{\operatorname{argmin}} \quad g(a,b,c,k_1,k_2,k_3) = -f(a,b,c) = -a - 2b - 5c$$

c) Let
$$a = b = c = 0$$

$$k_1 = 10$$
 $k_2 = 7$ $k_3 = 12$ $g(a, b, c, k_1, k_2, k_3) = 0$

Increase c since it causes g(a, b, c) to drop the fastest.

$$k_1 = 10 - 3c$$

$$k_2 = 7 - 2c$$

$$k_3 = 12 - c$$

Set LHS to 0 for each of the constraints to find how much c can be increased before some other variable gets set to 0.

$$0 = 10 - 3c$$

$$0 = 7 - 2c$$

$$0 = 12 - c$$

$$c = \frac{10}{3}$$

$$c = \frac{7}{2}$$

$$c = 12$$

 $c = \frac{10}{3}$ is the minimum value of c before some other variable becomes 0, so we set $c = \frac{10}{3}$ which makes $k_1 = 0$. Next we rearrange the constraint with k_1 so that c is expressed in terms of variables that have been set to 0 and substitute the expression into the other constraints where there is a c.

$$c = \frac{1}{3}(10 - 2a - b - k_1)$$

$$k_2 = 7 - \frac{2}{3}(10 - 2a - b - k_1) - a - b$$

$$= \frac{1}{3} + \frac{1}{3}a - \frac{1}{3}b = \frac{1}{3}$$

$$k_3 = 12 - \frac{1}{3}(10 - 2a - b - k_1) - 3a - b$$

$$= \frac{26}{3} - \frac{7}{3}a - \frac{2}{3}b = \frac{26}{3}$$

$$g(a, b, c, k_1, k_2, k_3) = -a - 2b - \frac{5}{3}(10 - 2a - b - k_1)$$

$$= \frac{7}{3}a - \frac{1}{3}b + \frac{5}{3}k_1 - \frac{50}{3} = -\frac{50}{3}$$

g decreases fastest with b so b is the next variable to be increased. As before find the minimum amount b can be increased before some other parameter becomes 0.

$$0 = \frac{1}{3}(10 - 2a - b - k_1)$$

$$0 = \frac{1}{3} + \frac{1}{3}a - \frac{1}{3}b$$

$$0 = \frac{26}{3} - \frac{7}{3}a - \frac{2}{3}b$$

$$b = 1 + a = 1$$

$$b = \frac{1}{2}(26 - 7a) = 13$$

b=1 is the minimum. So we set b=1 which makes $k_2=0$.

$$b = 1 + a - 3k_2$$

$$c = \frac{1}{3}(10 - 2a - (1 + a - 3k_2) - k_1)$$

$$= \frac{1}{3}(9 - 3a - k_1 + 3k_2) = 3$$

$$k_3 = \frac{26}{3} - \frac{7}{3}a - \frac{2}{3}(1 + a - 3k_2)$$

$$= 8 - 3a + 2k_2 = 8$$

$$g(a, b, c, k_1, k_2, k_3) = \frac{7}{3}a - \frac{1}{3}(1 + a - 3k_2) + \frac{5}{3}k_1 - \frac{50}{3}$$

$$= 2a + \frac{5}{3}k_1 + k_2 - 17 = -17$$

Now no variable can decrease g so the solution is:

$$a = 0$$
 $b = 1$ $c = 3$ $k_1 = 0$ $k_2 = 0$ $k_3 = 8$

- d) The optimal solution is to perform single-cell RNA-seq 0 times, a=0, perform bulk RNA-seq once, b=1, and perform spatial RNA-seq 3 times c=3. The utility of this solution is 17
- e) This solution would use \$10,000, take 7 days of time, and require 4 grams of tissue.

Question 4

a)

$$\begin{bmatrix} f(A,T,x+dx,y)-f(A,T,x-dx,y)\\ 2dx\\ \\ \frac{f(A,T,x,y+dy)-f(A,T,x,y-dy)}{2dy} \end{bmatrix}$$

b)

$$\begin{bmatrix} \frac{d^2f}{dx^2} & \frac{d^2f}{dxdy} \\ \\ \frac{d^2f}{dydx} & \frac{d^2f}{dy^2} \end{bmatrix}$$

$$\begin{split} \frac{df}{dx^2} &= \frac{f(A,T,x+2dx,y) - 2f(A,T,x,y) + f(A,T,x-2dx,y)}{4dx^2} \\ \frac{df}{dxdy} &= \frac{f(A,T,x+dx,y+dy) - f(A,T,x-dx,y+dy) - f(A,T,x+dx,y-dy) + f(A,T,x-dx,y-dy)}{4dxdy} \\ \frac{df}{dydx} &= \frac{f(A,T,x+dx,y+dy) - f(A,T,x-dx,y+dy) - f(A,T,x+dx,y-dy) + f(A,T,x-dx,y-dy)}{4dxdy} \\ \frac{df}{dy^2} &= \frac{f(A,T,x,y+2dy) - 2f(A,T,x,y) + f(A,T,x,y-2dy)}{4dy^2} \end{split}$$

c) Newton Rathson Algorithm

```
Data: \Delta x, \Delta y = \text{increment size of 'finer' grid; } dx, dy = \text{step size for finite derivatives}
M, N \leftarrow \text{SHAPE}(A)
m, n \leftarrow \text{Shape}(T)
best\_score \leftarrow \infty
best_x, best_y \leftarrow 0, 0
for i \leftarrow 0 to (N-n)\Delta x do
     for j \leftarrow 0 to (M-m)\Delta y do
          x \leftarrow i \times dx
          y \leftarrow j \times dy
          for k \leftarrow 0 to 10 do
               Grad \leftarrow Gradient(A, T, x, y, dx, dy)
               Hess \leftarrow Hessian(A, T, x, y, dx, dy)
               x \leftarrow x + \mathrm{Hess}^{-1}\mathrm{Grad}[0]
              y \leftarrow y + \mathrm{Hess}^{-1}\mathrm{Grad}[1]
          if SCORE(A, T, x, y) < best_score then
               best\_score \leftarrow SCORE(A, T, x, y)
               best\_x \leftarrow x
               best\_y \leftarrow y
          end
     end
end
\operatorname{return}(best\_x, best\_y)
```

d, e) For test case 1 the best coordinates were (4.499997017072263, 3.5) For test case 2 the best coordinates were (4.876557112637574, 0.3019367812834329)

Question 5

a)
$$a_{i}\overrightarrow{x} - b_{i} = c_{i} - d_{i} \quad \forall i \in \{1, 2, ..., m\}$$

$$\underset{x}{argmin} \quad f(c, d) = \sum_{i} c_{i} + d_{i}$$

$$c_{i} \geq 0 \quad \forall i \in \{1, 2, ..., m\}$$

$$d_{i} \geq 0 \quad \forall i \in \{1, 2, ..., m\}$$

m is the number of rows of the matrix A. a_i is the i'th row of the matrix A. b_i is the i'th element in vector b. An algorithm that can be used to solve this linear program is an iterative algorithm like Krylov-Subspace if the program is full rank. If the matrix is over determined then we can use least-squares optimization. Lastly if the matrix is under determined we can just solve for the pseudo-inverse and calculate $\bar{A}b$.

b)
$$x_{i} = c_{i} - d_{i} \quad \forall i \in \{1, 2, ..., m\}$$

$$argmin \quad f(x, c, d) = \sum_{i} (a_{i} \overrightarrow{x}_{i} - b_{i})^{2} + \lambda(c_{i} + d_{i})$$

$$c_{i} \geq 0 \quad \forall i \in \{1, 2, ..., m\}$$

$$d_{i} > 0 \quad \forall i \in \{1, 2, ..., m\}$$

m is the number of rows of the matrix A. a_i is the i'th row of the matrix A. b_i is the i'th element in vector b. One algorithm that we can use to solve for \overrightarrow{x} is the conjugate gradient algorithm which generally works with non-linear programs.

c) The least squares regressions optimization equation is $\|\overrightarrow{Ax} - \overrightarrow{b}\|_2^2$. This is a convex function. The L1 regularization term is an absolute value, which is also a convex function. The objective function for part b, is the sum of two convex functions, and the sum of two convex functions is also convex. Thus the objective function for b which is:

$$f(x, c, d) = \sum_{i} (a_i \overrightarrow{x}_i - b_i)^2 + \lambda (c_i + d_i)$$

is also convex.