

Evaluating Human Electromagnetic Exposure in a UAV-aided Network

Thomas Detemmerman

Student number: 01707806

Supervisors: Prof. dr. ir. Wout Joseph, Prof. dr. ir. Luc Martens

Counsellors: Dr. ir. Margot Deruyck, German Dario Castellanos Tache

Master's dissertation submitted in order to obtain the academic degree of
Master of Science in Information Engineering Technology

Academic year 2019-2020

Acknowledgement

I would like to thank Prof. dr. ir. Wout Joseph, Prof. dr. ir. Luc Martens and Dr. ir. Margot Deruyck for providing me access to their capacity based deployment tool which allowed me to complete my research regarding electromagnetic exposure but also for helping me to map the road of my research. Further I would like to express my gratitude to MPhil German Dario Castellanos Tache who followed up my weekly progress by providing answers to questions or problems I had and gave me extensive feedback and suggestions to the results I booked. I would also like to show my deepest appreciation towards mrs Carine Lambrecht and miss Anke Blommaert for taking a second - and even a third - eye on the linguistic part of this document but also for the general mental support during this journey making this entire degree possible, allowing me to stand where I am today.

The author(s) gives (give) permission to make this master dissertation available for consultation and to copy parts of this master dissertation for personal use. In all cases of other use, the copyright terms have to be respected, in particular with regard to the obligation to state explicitly the source when quoting results from this master dissertation.

Evaluating Human Electromagnetic Exposure in a UAV-aided Network

by Thomas Detemmerman

Master's dissertation submitted in order to obtain the academic degree of Master of Science in
Information Engineering Technology industriële wetenschappen: informatica
Academiejaar 2019-2020

Supervisors: Prof. dr. ir. Wout Joseph, Prof. dr. ir. Luc Martens
Counsellors: Dr. ir. Margot Deruyck, MPhil. German Dario Castellanos Tache
Faculty of engineering and architecture
Ghent University

Abstract

Society relies more than ever on the availability of wireless networks. Due to the mobility of a UAV, a UAV-aided network is able to provide this necessary access in case the existing terrestrial network gets damaged. However, the public is concerned about the potential health effects of the electromagnetic radiation caused by these networks. Therefore, mobile devices and base stations have to comply to strict legislation enforced by the government.

This research investigates how different scenarios influence power consumption, electromagnetic exposure and specific absorption rate. These different scenarios are defined by various flying heights, number of UAVs available and population sizes. Further, the proper microstrip patch antenna is defined and attached to the UAV. The antenna will be responsible for the communication between the UAV and the users it covers. Its performance is compared to an equivalent isotropic radiator. Thereafter, the network will be optimized towards goals like electromagnetic exposure of the average user or power consumption of the entire network; which results in conflicting requirements.

To accomplish this goal, the capacity based deployment tool of the WAVES research group at Ghent University will be extended so it would be able to calculate electromagnetic exposure. Further, the tool now also provides support to optimize the networks towards electromagnetic exposure or power consumption.

It looks from the results that the microstrip patch antenna with an aperture angle of 90° is a suitable starting point for an antenna. This directional antenna focusses electromagnetic radiation where it is needed. Unwanted sideways radiation is therefore reduced by design. The sufficiently large aperture angle covers enough users. The antenna is recommended to be deployed in a power consumption optimized network since less drones are required and therefore also less expensive. The optimal flying height for the city centre of Ghent is believed to be

situated at 80 metres since lower flying heights require much more UABSs and higher flying heights have a negative influence on the electromagnetic exposure.

Keywords

Deployment tool, Electromagnetic exposure, LTE Microstrip patch antenna, Power consumption, Radiation pattern, Specific absorption rate (SAR), UAV, Unmanned aerial base stations Wireless access network, Emergency network.

Evaluatie van de electromagnetische blootstelling van de mens in een netwerk van drones

door

Thomas Detemmerman

Masterproef ingediend tot het behalen van de academische graad van Master of Science in de industriële wetenschappen: informatica
Academiejaar 2019-2020

Promotoren: Prof. dr. ir. Wout Joseph, Prof. dr. ir. Luc Martens
Begeleider: Dr. ir. Margot Deruyck, MPhil. German Dario Castellanos Tache
Faculteit Ingenieurswetenschappen en architectuur
Universiteit Gent

De hedendaagse samenleving vertrouwt meer dan ooit op de aanwezigheid van draadloze netwerken. Dankzij de mobiliteit van drones kan een drone-gestuurd netwerk de nodige mobiele data voorzien indien het bestaande netwerk beschadigd is. Er is echter een groeiende vrees voor mogelijke gezondheidseffecten veroorzaakt door deze mobiele netwerken. De overheid stelt strikte wetgevingen op waaraan deze mobiele netwerken dienen te voldoen.

Dit onderzoek bekijkt hoe verschillende scenario's het energieverbruik, electromagnetische blootstelling en specifieke absorptietempo kunnen beïnvloeden. Drie verschillende scenario's zijn gedefinieerd waarbij verschillende vlieghoogtes, aantal drones en populatiegroottes onderzocht worden. Verder is er ook een microstrip patch antenne gedefinieerd en bevestigd op een drone. De antenne zal de communicatie tussen de drone en de gebruikers verzorgen. De performantie van deze antenne zal vergeleken worden met een istorope antenne. Vervolgens zal het netwerk geoptimaliseerd worden naar electromagnetische straling van het individu of naar het energieverbruik van het gehele netwerk. Deze twee doelstellingen resulteren in tegenstrijdige vereisten.

Om dit doel te bereiken is de capacity based deployment tool van de onderzoeksgroep WAVES op de Universiteit Gent verder uitgebreid zodoende dat electromagnetische straling berekend kan worden. Verder is de tool nu ook in staat om te optimaliseren naar electromagnetische straling of energieverbruik.

Uit de resultaten blijkt dat een microstrip patch antenne met een openingshoek van 90° een geschikt startpunt is voor een antenne. Deze directionele antenne focust de electromagnetische straling daar waar het nodig is. Ongewenste zijwaardse straling wordt gereduceerd door het design. Het wordt aangeraden om de antenne toe te passen in een netwerk dat energieverbruik minimaliseert omdat hierbij minder drones nodig zijn en daardoor goedkoper is. De optimale

vlieghoogte voor het stadscentrum in Gent bevindt zich rond 80 meter. Lagere vlieghoogtes vereisen veel meer drones terwijl hogere vlieghoogtes de electromagnetische straling laten toenemen.

Trefwoorden

LTE, Electromagnetische blootstelling, Energieverbruik, Drone, Femtocell, Microstrip patch antenna, Stralingspatronen, Specific absorption rate (SAR).

Evaluating Human Electromagnetic Exposure in a UAV-aided Network

Thomas Detemmerman

Supervisor(s): Prof. dr. ir. Wout Joseph, Prof. dr. ir. Luc Martens

Abstract—Society relies more than ever on the availability of wireless networks. Due to the mobility of a UAV, a UAV-aided network is able to provide this necessary access in case the existing terrestrial network gets damaged. However, the public is concerned about the potential health effects of the electromagnetic radiation caused by these networks. Therefore, mobile devices and base stations have to comply to strict legislation enforced by the government.

This research investigates how different scenarios influence power consumption, electromagnetic exposure and specific absorption rate. These different scenarios are defined by various flying heights, number of UAVs available and population sizes. Also, the proper microstrip patch antenna is defined and attached to the UAV. The antenna will be responsible for the communication between the UAV and the users it covers. Its performance is compared to an equivalent isotropic radiator. Thereafter, the network will be optimized towards goals like electromagnetic exposure of the average user or power consumption of the entire network; which results in conflicting requirements.

To accomplish this goal, the capacity based deployment tool of the WAVES research group at Ghent University will be extended so it would be able to calculate electromagnetic exposure. Further, the tool now also provides support to optimize the networks towards electromagnetic exposure or power consumption.

It looks from the results that the microstrip patch antenna with an aperture angle of 90° is a suitable starting point for an antenna. This directional antenna focusses electromagnetic radiation where it is needed. Unwanted sideways radiation is therefore reduced by design. The sufficiently large aperture angle covers enough users. The antenna is recommended to be deployed in a power consumption optimized network since less Unmanned Aerial Vehicle (UAV)s are required and therefore also less expensive. The optimal flying height for the city centre of Ghent is believed to be situated at 80 metres since lower flying heights require much more UABSs and higher flying heights have a negative influence on the electromagnetic exposure.

Keywords—Deployment tool, Electromagnetic exposure, LTE Microstrip patch antenna, Power consumption, Radiation pattern, Specific absorption rate (SAR), UAV, Unmanned aerial base stations, Wireless access network, Emergency network

I. Introduction

SOCIETY is constantly getting more and more dependent on wireless communication. On any given moment, in any given location, an electronic device can request to connect to the bigger network, starting from small Internet of Things (IoT) up to self-driving cars.

Also in exceptional and possibly life threatening situations, the public relies on the cellular network despite the fact that the network might be severely damaged and not properly functioning anymore. One solution for a fast temporarily deployable back-up network is to use UAVs. A base station can be attached to these flying UAVs to support the network over a limited area. This approach is also useful in case of an unexpected increase in traffic. For example during the terrorist attacks at Brussels Airport, mobile network operators saw all telecommunications drastically increasing causing moments of contention. Some

operators even decided to temporarily exceed the exposure limits in order to handle all connections [1]. Electromagnetic exposure caused by these networks can however not be neglected. Research shows how excessive electromagnetic radiation can cause diverse biological side effects [2], [3]. It becomes clear that electromagnetic exposure is a key value when designing a UAV-aided network and should definitely not surpass the limits predefined by the government.

UAV-aided networks can, thanks to their mobility, easily be repositioned towards a certain goal. Several papers explain how a network can be optimized towards different goals like power consumption. However, very limited research has been done where a UAV-aided network is optimized towards electromagnetic exposure. While several publications exist, discussing how the electromagnetic exposure can be calculated, most of them only consider a limited number of sources; e.g. only base stations or only the user's mobile device. Papers who cover electromagnetic exposure from all the different sources and convert it into a single value are rather limited.

This research proposes a method to optimize the network towards electromagnetic exposure and power consumption when considering all four sources of radiation in a telecommunications network, being: the user's own phone, the base station that is serving this user, all devices from other users in the network and all other active base stations that are not serving this user. In this way, the contribution of each source towards the total electromagnetic exposure can easily be identified.

The behaviour of the electromagnetic exposure and power consumption of the network will be analysed by applying the tool in different scenarios by using different types of antennae, various flying height and population densities. Values like Specific Absorption Rate (SAR), electromagnetic exposure and power consumption will give insight in how the network behaves so the network could be optimized accordingly.

To make this research possible, an existing capacity based deployment tool developed by the WAVES research group at Ghent University is extended for the specific purpose. This planning tool describes a fully configured UAV-network which is a suitable starting point for this research.

II. State of the Art

A. Electromagnetic exposure

Users in a telecommunication network are exposed to various sources of electromagnetic radiation, expressed in

V/m . Once the exposure is absorbed by the human body, we speak of the specific absorption rate (SAR) which is expressed in W/kg . The International Commission on Non-Ionizing Radiation Protection (ICNIRP) has concluded that the threshold effect for SAR_{10g}^{wb} is at 4 W/kg meaning that any higher absorption rate would overwhelm the thermoregulatory capacity of the human body [4], [5]. All these values are subjected to limitations enforced by the government. This research is based in Ghent, a Flemish city in Belgium where an individual antenna in the 2.6 GHz frequency band could not exceed 4.5 V/m and the cumulative sum of all fixed sources has its maximum at 31 V/m [4], [6]. The maximum whole body SAR-values for a mobile device over a 10 g tissue (SAR_{10g}) is defined at 0.08 W/kg [7], [4], [8]. The Federal Communications Commission (FCC) of the United States of America (USA) follows the recommendations of the Institute of Electrical and Electronics Engineers (IEEE) Std C95.1-1999 [9], [10] that defines regulations based on 1 g tissue. The SAR_{1g}^{wb} is therefore defined at 1.6 W/kg despite the fact that this value has been reviewed and changed by the IEEE to 8 W/kg in Std C95.1-2005 [10]. An overview is given in table I.

Description	Value	Units
SAR_{10g}^{wb} (ICNIRP)	4	W/kg
SAR_{10g}^{wb} for base station(BE)	0.08	W/kg
SAR_{10g}^{head} for UE (BE)	2	W/kg
SAR_{1g}^{head} for UE (USA)	1.6	W/kg

TABLE I: Overview of the different SAR limitations.

Several papers calculate exposure originating from specific sources [11], [12], [13], [14] where some convert the up-link (UL) radiation into localized SAR for head and torso [13], [14]. With the advent of 5G, paper [15] describes how the localized SAR-values are achieved from all different sources. Finally, [16] describes how the electronic radiation can be converted into whole body SAR values.

In a realistic network, some users are calling while others are using other types of telecommunication services like browsing the web. Therefore, all absorbed electromagnetic exposure should be expressed in whole body SAR while still covering all sources.

B. Optimized UAV-aided networks

A UAV knows several applications. It was originally mainly used to support the military for surveillance and remote attacks without endangering pilots [17]. However, UAVs have recently become more accessible by the general public due to decreasing costs. This allowed UAVs to be researched for various applications.

A UAV equipped with a femtocell base station antenna is called a Unmanned Arial Base Station (UABS) which brings several advantages like mobility and rapid deployment. However, it brings also challenges like limited weight of the payload and sparse power supply.

Kawamoto et al. introduced in [18] a WiFi network with the support of UAVs while considering resource allocation

and antenna directivity. Gangula et al. illustrates in [19] how UAVs can be used as a relay for Long-Term Evolution (LTE) and Zeng et al. proposes in [17] a tutorial in 5G-and-beyond wireless systems where challenges like energy consumption, mobility and antenna direction are discussed. In [20], Deruyck et al. designed a capacity based deployment tool for UAV-aided emergency networks for large-scale disaster scenarios where an ideal flying height of 100 m is suggested. This was expanded in [21] with a performance evaluation of the direct-link backhaul of this tool where a slightly lower flying height of 80 metres is recommended.

Mozaffari et al. provides in [22] guidelines on how to optimize and analyse UAVs equipped for wireless communication equipment. A research area that has been excessively studied is the location solution optimization problem where networks are designed in such a way that certain goals like minimal power consumption or shortest flying distance are achieved [23], [24], [25], [26]. These optimizations can be done through different implementation methods like exact algorithms or machine learning [22], [27].

Research where network is optimized towards electromagnetic exposure is rather limited. Deruyck et al. discusses in [12] how a terrestrial network can be optimized towards either a minimal exposure or minimal power consumption of the entire network. However, to the best of the author knowledge, no research has been done where a UABS-network has been optimized towards electromagnetic exposure.

C. Technologies

For the deployment of the network, the more robust UAV from [20] will be used (details in table III) and will be operating in the 2.6 GHz bandwidth. Since the users are assumed to experience a constant electromagnetic exposure without interruptions, frequency division duplex is used.

The onboard antenna of the UAV will act as the gateway between the UE and the backhaul network. However, determining which antenna to use and how to position it, can be challenging. The radiation pattern from the antenna can be influenced by the UAV [28]. Also the fact that the UAV will hover above the user makes traditional 2D modelling insufficient. A 3D-model which accounts for both elevation and azimuth directivity will be required [17].

The easiest radiation pattern is a hypothetical isotropic radiator which radiates equally in all directions. Antennae that radiate equal quantities for a certain plane are called omnidirectional antennae [17] and several UABSs use antennae like monopoles, dipoles and wing antennae [29], [30], [31], [32]. Another type of antennae are directional antennae which save energy by focussing the electromagnetic energy where it is needed. One type that has excessively been researched in various array-configurations is a microstrip patch antenna [33], [34], [35]. These provide several advantages compared to traditional antennae [36], [37] like lightweightness and being low in cost, causing them to be more aerodynamic.

A basic microstrip antenna consists of a ground plane and a radiating patch, both separated by a dielectric sub-

strate. Several variations exist like microstrip patch antennae, microstrip slot antennae and printed dipole antennae which all have similar characteristics [36], [37]. They all are thin, support dual frequency operation and they all have the disadvantage that they will transmit at frequencies outside the aimed band which is also known as spurious radiation. The microstrip patch and slot antenna support both linear and circular polarization while the printed dipole only supports linear polarization. Further, the fabrication of a microstrip patch antenna is considered to be the easiest of the considered patch antennae [36].

Fig. 1 shows a microstrip patch antenna made of Teflon and an aluminium patch. The antenna is attached to a UAV and is pointing towards the ground where the users are located.



Fig. 1: Image of a microstrip patch antenna attached to the bottom of a UAV.

III. Methodology

The first subsection explains how electromagnetic radiation is calculated for each source and how to convert these values to SAR. The second subsection gives a overview of how a microstrip patch antenna can be designed. The third section discusses how the network can be optimized towards either electromagnetic exposure or power consumption and finally the algorithm itself is explained.

A. Electromagnetic Exposure

A.1 Total Electromagnetic Exposure

The total whole body SAR ($SAR_{10g}^{wb,total}$) of a user can be calculated by a simple sum of individual SAR values from the different sources and is based on [15]. This formula assumes that the users are holding their device next to their ear and therefore investigates localized SAR for head and torso area. However for this case, this would result into incorrect conclusions since the position of the device relative to the user is unknown. The position of the phone can be next to the head but also in front of the user. The induced electromagnetic radiation will therefore be expressed in function of the entire body.

$$SAR_{10g}^{wb,total} = SAR_{10g}^{wb,myUE} + SAR_{10g}^{wb,myUABS} + SAR_{10g}^{wb,otherUE} + SAR_{10g}^{wb,otherUABSS} \quad (1)$$

The first parameter, $SAR_{10g}^{wb,myUE}$, indicates the absorbed electromagnetic radiation by the whole body originating from the user's own device. Despite that the UL radiation is destined for the serving UABS, a portion of that radiation is directly absorbed by its user, due to the omnidirectional nature of the mobile's antenna. The second parameter, $SAR_{10g}^{wb,myUABS}$, represents the downlink (DL) radiation caused by the UABS that is serving the user. As the third parameter, we have the $SAR_{10g}^{wb,otherUE}$ which is radiation caused by other people's devices. The radiation of these devices is once again destined for a specific UABS but again, a portion of that UL radiation will also be absorbed by our user. Finally, $SAR_{10g}^{wb,otherUABSS}$ represents the DL radiation by the other UABSSs to which our user is exposed to but not served by. An illustration is given in fig. 2. The green arrow stands for near-field radiation, the others represent far-field radiation.

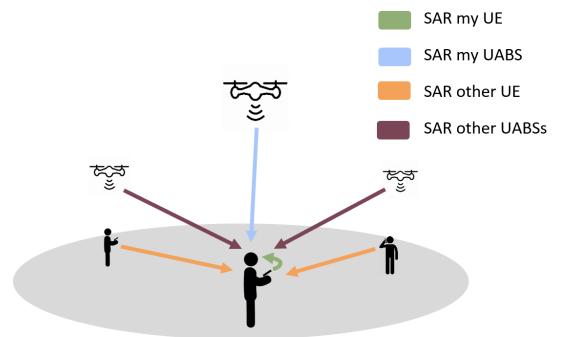


Fig. 2: Illustration of the network that shows how the average user (here shown in the center) is influenced by different types of sources.

A.2 Electromagnetic Radiation from a Single Source

In order to find the total electromagnetic radiation to which a user is exposed, the electromagnetic radiation from each sources needs to be calculated first. This is done with formula 2 which applies to all sources in the far-field. This includes all UABSSs and all User Equipment (UE) belonging to other people. The exposure E of a single user u from a single radiator i can be calculated as follows.

$$E_i(u)[V/m] = 10^{\frac{RRP(u)[dBm] - 43.15 + 20 * \log(f[MHz]) - PL(u)[dB]}{20}} \quad (2)$$

Calculating the real radiation power (RRP) for a certain user u , requires first the equivalent isotropic radiation power (EIRP)-value to be calculated [11], [12]. This is achieved by adding the transmission power P_{tx} to the transmitter gain G_t and thereafter subtracting the feeder loss L_t . This formula needs to be expanded to also account for attenuation from the used antenna. This value depends on the angle between this user and the antenna's main beam. The attenuation from an equivalent isotropic radiator is always zero. This leads to the following formula.

$$RRP[dBm] = P_{tx}[dBm] + G_t[dBi] - L_t[dB] - \text{attenuation}(u)[dB] \quad (3)$$

The used frequency in formula 2 is denoted as f and is expressed in MHz. Since LTE is used, this value will be 2600 MHz.

At last, formula 2 requires the path loss PL . In order to calculate this, an appropriate propagation model — of which several exist — is required. The Walfish-Ikegami model is used since it performs well for femtocell networks in urban areas [20].

A.3 Combining Exposure

The total electromagnetic exposure E_{tot} , in a certain spot, originating from different sources can be calculated with formula 4. E_i stands for the electromagnetic exposure from source i and n stands for all far-field radiators of a certain category which will either be UABSs or UE from other people. E_{tot} will be calculated for each location where a user is positioned.

$$E_{tot}[V/m] = \sqrt{\sum_{i=1}^n (E_i[V/m])^2} \quad (4)$$

A.4 Converting electromagnetic radiation into SAR-values

Formula 1 expects that the radiation is expressed in whole body SAR-values. To make this calculation possible, a distinction has to be made between near-field SAR ($SAR^{wb,nf}$) and far-field SAR ($SAR^{wb,ff}$). $SAR_{10g}^{wb,myUE}$ is a form of near-field radiation, all the other types are far-field radiation.

Converting the electromagnetic radiation is done with a conversion factor which is based on Duke of the Virtual Family. Duke is a 34-year old male with a weight of 72 kg, a height of 1.74 m and BMI of 23.1 kg/m [16]. Research shows that the conversion factors for WiFi in the far-field is $0.0028 \frac{W/kg}{W/m^2}$ and $0.0070 \frac{W/kg}{W}$ for the near-field [16]. Since WiFi, at a frequency of 2400 MHz, is very close to LTE, at 2600 MHz, it is assumed in [16] that this value is also applicable for LTE. Calculating SAR from far-field radiation is done as follows:

$$S[W/m^2] = \frac{(E_{tot}[V/m])^2}{337} \quad (5)$$

$$SAR_{10g}^{wb,ff}[W/kg] = S[W/m^2] * 0.0028 \left[\frac{W/kg}{W/m^2} \right] \quad (6)$$

The constant in equation 6 converts the power flux density S to the required $SAR_{10g}^{ff,wb}$. To make this possible, the electromagnetic radiation from formula 4 should first be converted to the power flux density with formula 5.

The SAR caused by near-field radiation is calculated by multiplying the constant with the used transmission power P_{tx} of the UE which results in the following formula:

$$SAR_{10g}^{wb,nf}[W/kg] = 0.0070 \left[\frac{W/kg}{W} \right] * P_{tx}[W] \quad (7)$$

The power of the UE can be calculated using equation 8 [16].

$$P_{tx}^{UE} = \min \{ P_{max}[dBm], \\ P_{pusch}[dBm] + \alpha * PL[dB] + 10\log(M) + \sigma \} \quad (8)$$

P_{max} is the maximum allowed transmission power by UE for LTE, defined at 23 dBm. However, this is the worst case and the actual used power is usually much lower thanks to power control. P_{pusch} is the required received power at the UABS and will here be -120 dBm. α is the path loss compensation factor set to one which means full compensation [38], [39]. For the 20-MHz channel used in this paper, M will be set to 100 and σ , as the correction factor, is set to zero [16], [38].

B. Microstrip Patch antenna

A microstrip patch antenna is chosen because it allows easy production but more important, it has a low weight and has a thin profile causing it to be very aerodynamic which is useful when attaching it to a drone [36].

The dimensions of the antenna depend on the frequency it is operating at and the characteristics of the used substrate. The antenna will be radiating at a centre frequency f_0 of 2.6 GHz. Each substrate has a dielectric constant ϵ_r representing the permittivity of the substrate that depends on the used material. Substrates with a high dielectric constant and low height reduce the dimensions of the antenna while a lower dielectric constant with a high height improves the performance of the antenna [37], [40]. In this research, a substrate like glass is chosen because of the higher dielectric constant of $\epsilon_r = 4.4$ compared to materials like Teflon with only a dielectric constant of $\epsilon_r = 2.2$ [37]. Doing this in combination with an antenna height of 2.87 mm will decrease the dimensions of the entire antenna surface. This comes in handy since UAVs only have limited space available.

Description	Symbol	Value
Center frequency	f_0	2600 MHz
Dielectric constant	ϵ_r	4.4
Height of the substrate	h	0.00287 m

TABLE II: Overview of configuration parameters.

The dimensions of the radiating patch can be calculated with the formulas from [37], [40]. Doing so will result in a radiating patch of 35.09 mm by 26.55 mm and a ground-plane of at least 52.40 mm by 43.80 mm. The microstrip patch antenna as illustrated in fig. 3 will result in the radiation pattern of fig. 4.

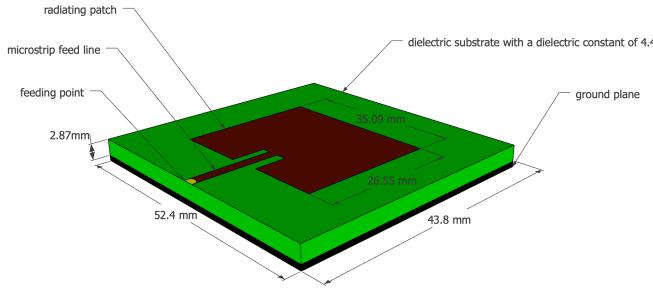


Fig. 3: Design of the microstrip patch antenna.

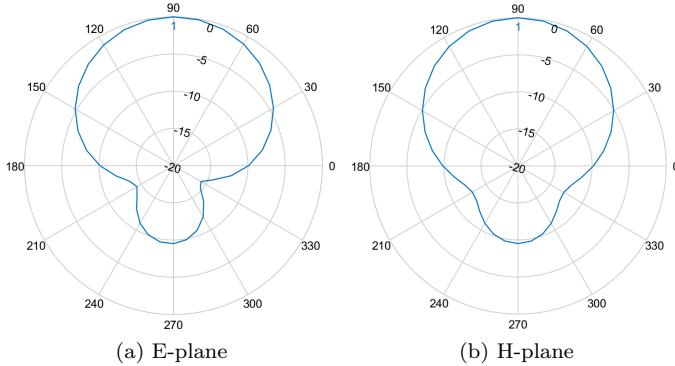


Fig. 4: Radiation patterns generated by the used microstrip patch antenna.

C. Optimizing the network

Deruyck et al. discusses in [12] how a terrestrial telecommunication network either can be optimized towards electromagnetic exposure of an individual or towards power consumption of the entire network. However, an increasing transmission power of an antenna comes with an increasing electromagnetic exposure. This is not the case considering both values for an entire network. In fact, the authors from [12] prove that both become inversely equivalent. The reason why the network behaves like this is because it is often cheaper to increase the exposure of an already active base station than activating a new one. This leads to the following fitness function which is based on [12].

$$f = w * \left(1 - \frac{E_m}{E_{max}}\right) + (1 - w) * \left(1 - \frac{P}{P_{max}}\right) * 100 \quad (9)$$

Formula 9 returns a fitness value which represents the performance of the entire network. w is the importance factor of electromagnetic exposure ranging from 0 to 1, boundaries included. A w set to 0 means that electromagnetic exposure is not important. Such network will therefore be called a power consuption optimized (PwrC. Opt.) network. Likewise, a w set to 1 means that minimizing exposure is top priority and will result in an exposure optimized (Exp. Opt.) network. P_{max} is the power consumption of all UABSs, both active and inactive, when radiating at the highest level possible while P is the effective power

used by the current designed network. This will be the power required for the flying UAVs themselves and their antennae. E_m will be the weighted exposure of the average user for the current designed network and E_{max} the weighted average of the electromagnetic exposure when all antennae are at their highest power level.

When optimizing the network, it is not only important to consider the average exposure of all users, but also to limit high extremes [12]. A weighted average will be used not only considering the median but also the 95 percentile from all users' DL exposure using formula 10. Since both values are considered to have equal importance, the weight factors w_1 and w_2 will both have an equal importance of 50%.

$$E_m = \frac{w_1 * E_{50} + w_2 * E_{95}}{w_1 + w_2} \quad (10)$$

D. Simulation Tool

D.1 Main Algorithm

First, a description of the area has to be provided to the tool. This is done with so-called shape-files. These files contain a complete description about the shape of the buildings. Thereafter, users are uniformly distributed over the area and a temporary UABS is positioned above each user. Now, the decision algorithm needs to decide which of these UABSs can actually remain and how strong each one should be radiating. Once the decision algorithm is done, the tool checks whether the number of online UABSs does not exceed the capacity of the facility where the UABSs are stored. If this is the case, the UABSs covering the least amount of users will be removed.

D.2 Decision Algorithm

Solving the network is done by the decision algorithm and starts by calculating the path loss between all users and between users and UABSs. Thereafter, the algorithm iterates over each user and tries to connect that user to each UABS. This connection is not always possible. A UABS might be saturated with users and will not be able to cover yet another one or maybe the user is so far away that in order to cover that user, the UABS would have to exceed its maximum allowed input power. If however a connection is possible, the user will be connected to that UABS and the fitness function (eq. 9) is applied. This is repeated for each UABS. Only the connection which results in the best fitness value for the entire network will be used. Doing so will make sure that, given the currently designed network, the user is optimized. In other words, each user is optimized and not the entire network. It is however assumed that the average network will be optimized as well. Thereafter, the tool shifts to the next user. When the last user has been processed, the network is fully designed for an unlimited number of UAVs and the result is returned to the main algorithm for further processing. The flowchart of this algorithm is given in fig. 5.

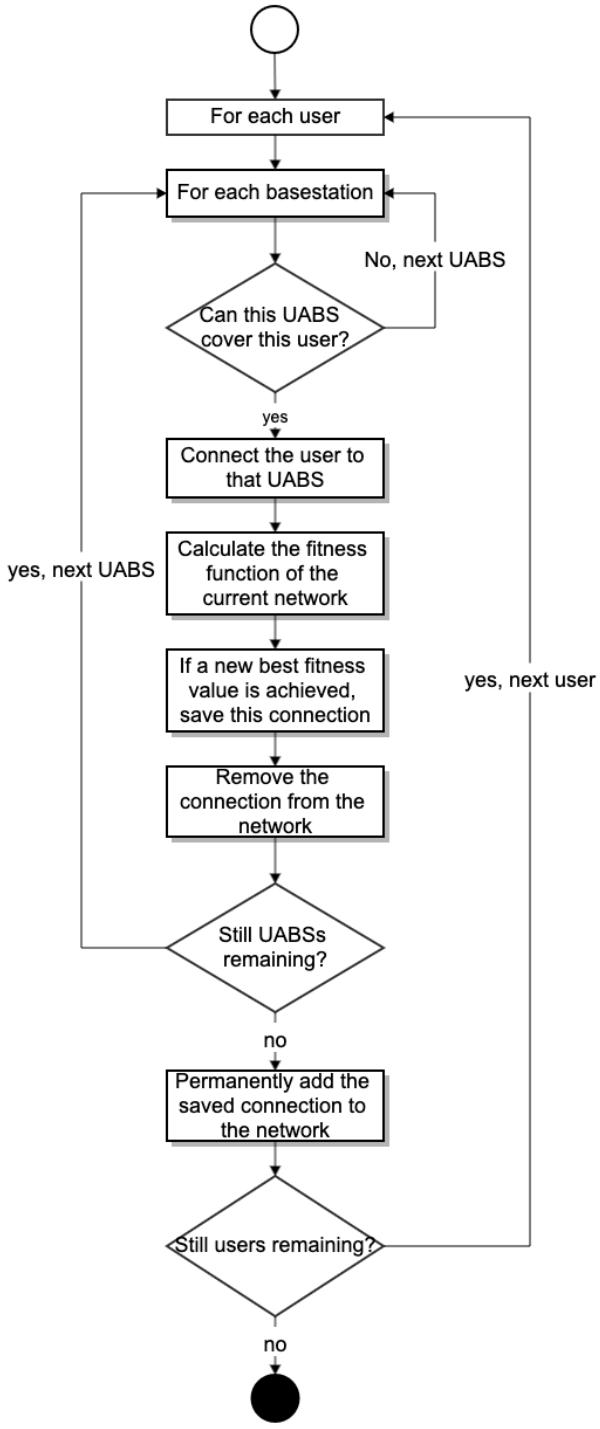


Fig. 5: Flowchart of the decision algorithm.

IV. Scenarios

The default configuration is given in table III and is applicable in all scenarios unless mentioned otherwise in the restrictions of that specific scenario.

Three main scenarios will be investigated. The first one has only one user and one UABS present in the network. SAR, electromagnetic exposure, power consumption and

Broadband cellular network

Technology	LTE
Frequency	2.6 GHz
Power offset (P_{pusch})	-120 dBm
Path loss compensation (α)	1
Correction value	0 dBm
Number of used resource blocks	100
<hr/>	
Femtocell antenna	
Maximum P_{tx} antenna direction	33 dBm downwards (az: 0°; el: 90°)
Gain	4 dBm
Feeder loss	2 dBm
Implementation loss radiation pattern	0 dBm EIRP or microstrip patch
Flying altitude	100 m
<hr/>	
UAV	
UAV power	13.0 A
Average UAV speed	12.0 m/s
Average UAV power usage	17.33 Ah
UAV battery voltage	22.2 V
<hr/>	
UE Antenna	
Height	1.5m from the floor
Gain	0 dBm
Feeder loss	0 dBm
Radiation pattern	EIRP
Quantity in network	224

TABLE III: Overview of default configuration values.

antenna transmission power are investigated at different flying heights.

In a second scenario, the network is expanded for multiple users while still considering only one UABS. Two parameters will be evaluated. The first one will be a variable flying height ranging from 20 to 200 metres with a fixed number of 224 users. This is the average population size on an usual day at 5 p.m. in Ghent [20]. The second evaluated parameter is the number of users ranging from 50 to 600 users while flying height is set to 100 metres [20]. The power consumption, electromagnetic exposure and specific absorption rate are investigated for each parameter.

The third scenario is quite similar to the previous scenario. The same two parameters are investigated, but now an unlimited number of UABSs is available.

Four configurations are considered for each evaluated parameter in each scenario. There are two possible antennae, namely EIRP and microstrip patch antenna, which can both be applied in a PwrC. Opt. network or an Exp. Opt. network. An overview of the simulation configuration scenarios is presented in fig. 6

It is important to note that all measured values are strictly limited to the sources mentioned in the previous section and thus only cover data traffic between UE and UABSs. Any other potential sources like backhaul links or any other technology will not be covered.

Antenna type	Optimization strategy	
	Exposure optimized	Power consumption optimized
	EIRP Exp Opt	EIRP PwrC Opt
Equivalent isotropic radiator	Microstrip Exp Opt	Microstrip PwrC Opt
Microstrip patch antenna	Microstrip Exp Opt	Microstrip PwrC Opt

Fig. 6: Matrix with the four possible configurations

V. Results

Four configurations will be investigated while evaluating two parameter, being the population size and flying height. The parameters are evaluated for three different scenarios by monitoring the power consumption, electromagnetic exposure and SAR-values. The electromagnetic radiation and SAR are measured for the weighted average user using equation 10 with both w_1 and w_2 set to 50%. Each result is averaged over 20 simulations.

A. One User and One UABS

The results show that for a varying flying height, a logarithmic relationship exists between the P_{tx} and the flying height. This is mainly caused by the logarithmic scale in which the decibels of the P_{tx} are expressed. Each time the flying height becomes too large to cover, the P_{tx} increases with one dBm. When using the default configuration, with a maximum P_{tx} of 33 dBm, a UABS can fly up to 387 m before losing connection in a free line of sight (LoS) scenario.

This scenario is investigated with a microstrip patch antenna using power consumption optimization. However, the chosen optimization strategy does not really matter because the decision algorithm decides which user needs to be connected to which UABS. Since only one UABS is available, both optimization strategies will behave identical. Further, the used antenna will not make any difference. The user is positioned in the perfect centre of the main beam where there is no attenuation experienced for both antennae.

When investigating this scenario at different flying heights, it is noticed that the UL radiation increases exponentially while the DL radiation remains constant at 10 nW/kg during the entire time as shown in fig. 7. The reason that the DL radiation remains constant is because of the power control which makes sure that no more power is used than strictly necessary. We can therefore confirm that the electromagnetic exposure is a constant fraction of power and distance. The UL radiation starts very low at 1 nW/kg but surpasses the DL radiation around 80 metres.

B. Increased Population with one UABS

B.1 Variable Flying Height

A PwrC. Opt. network has higher exposure compared to an Exp. Opt. network; a behaviour that was already proven by [12]. However, for this scenario, a PwrC. Opt.

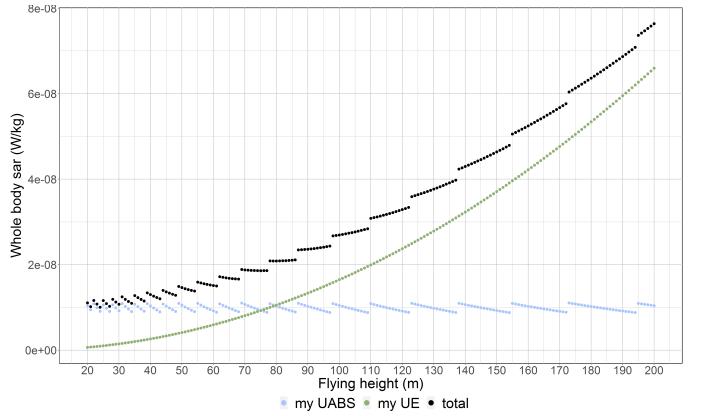


Fig. 7: This figure shows how SAR values from different sources are influenced by different flying altitudes.

network will not necessarily result in a lower power consumption. For example, at 100 metres, an EIRP Exp. Opt. network exposes the average user to 1.5 mV/m less but requires 20 mW more. To understand this, the behaviour of the deployment tool needs to be understood first. A PwrC. Opt. network will result in a few high powered UABSs because increasing the input power of an antenna costs less than activating a new UAV. Likewise, an Exp. Opt. network generates a lot of low powered UABSs because the lower the power of the antenna, the lower the exposure. This has the consequence that the cover radius is less and therefore requires more UABSs which costs more energy. When only a limited amount of UABSs are available, like only one in this scenario, the tool will only keep UABSs which cover the most users. Since the power consumption of an individual UABS is higher in a PwrC. Opt. network and only one UABS remains in each configuration, the power consumption in a PwrC. Opt. network is often higher.

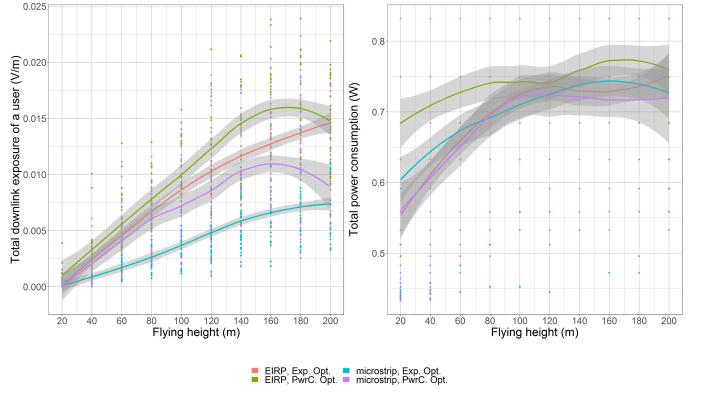


Fig. (a) show how the flying height influences the downlink electromagnetic radiation of the average user and fig. (b) the power consumption of the entire network for the only UABS available in the network.

Further, fig. 8 also show that the exposure increases with higher flying altitudes because there is a lower probability

of having non line of sight (NLoS) links by obstructing buildings. This has as consequence that more users become covered. Increasing the flying height from 20 to 100 metres improves the coverage between 1% and 2% for all four configurations. The increasing electromagnetic radiation is however not unlimited. A microstrip PwrC. Opt. network is at his highest point around 162 metres and an EIRP PwrC. Opt. is at his highest at 195 metres. This decline starts later for exposure optimized networks and is situated outside the investigated flying range. The decreasing electromagnetic radiation at high flying altitudes is not caused by the obstructing buildings but by the distance in general.

Fig. 9 shows the whole body SAR_{10g} for the weighted average user, deducted from all electromagnetic sources. When investigating the three different sources, we see that the SAR^{myUABS} shows the same curve as it did with the electromagnetic exposure in fig. 8.a. This is normal behaviour considering that equation 6 is able of converting the DL exposure to SAR by simply multiplying with a constant. During the entire time, SAR^{myUABS} is the most dominant factor followed by the near-field radiation from the user's own device. The far-field radiation from other UE barely has influence. As an illustration, when the UABS flies at 140 metres, the average user in an EIRP PwrC. Opt. network will experience around 2.1 nW/kg from the UABS and around 0.2 nW/kg from his own device. The exposure from other UE can be neglected with 0.03 pW/kg . A low but plausible value considering that most UE are not radiating anything since they are uncovered.

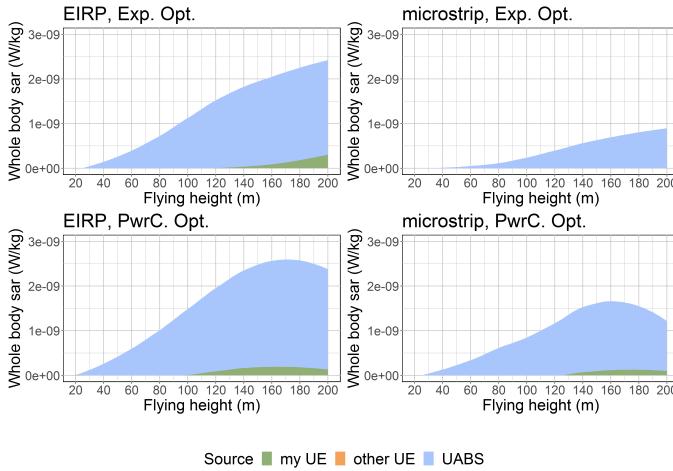


Fig. 9: Influence of the flying height for each considered configuration.

B.2 Variable Number of Users

The number of users present in the network increases from 50 to 600. Fig. 10.b shows that the number of covered users increases linearly compared to the number of users present in the network. It illustrates how an equivalent isotropic radiator is able to reach more users compared

to a microstrip patch antenna. Just like an power consumption optimized network is able to reach more users than an exposure optimized network.

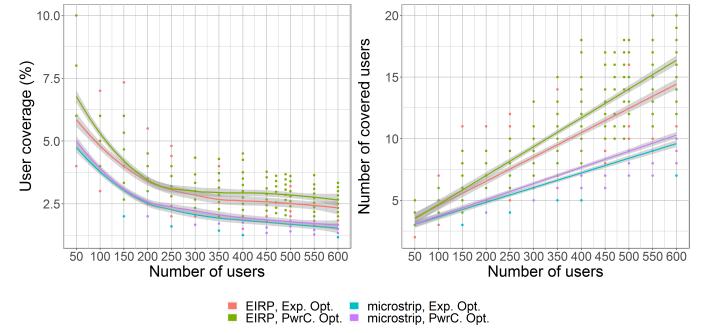


Fig. 10: The influence of increasing traffic on the user coverage.

For example, with 600 users, 5 to 7 additional people can be covered when replacing a microstrip patch antenna with an equivalent isotropic radiator and changing an exposure optimized network with an power consumption optimized network will cover one or two additional users.

Fig. 11.a gives the electromagnetic exposure of the weighted average user for different populations sizes while 11.b presents the power consumption of the entire network for all these population sizes. Figure 11.a is influenced by 10.a. When less users are covered, the exposure of the average user will decrease as well. For example, in an EIRP PwrC. Opt. network, 50 users have a 6.75% coverage which corresponds with a weighted average exposure of 18 mV/m while 600 users with 2.75% coverage only have 9 mV/m . Further, fig. 11.b is directly influence by fig. 10.b. When the UABS has to cover more users, the probability that some of these users have a worse path loss is higher. The UABS solves this problem by increasing the power consumption. Increasing the population from 50 to 600 will require between 0.05 and 0.1 W more. For this scenario, no clear difference in power consumption exists between the four configurations.

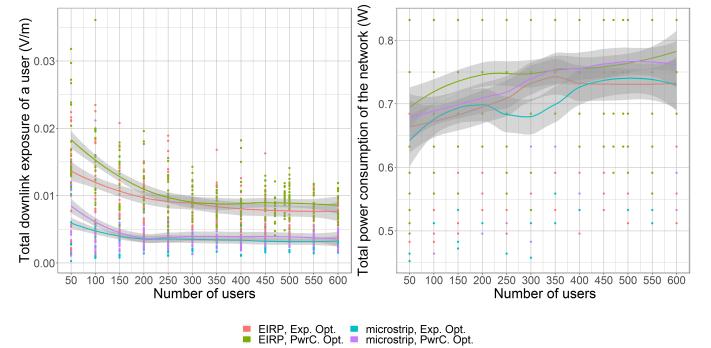


Fig. 11: These two figures show how various sizes of population influence the downlink electromagnetic radiation of the average user (left) and power consumption of the entire network (rights) for one UABS available in the network.

The SAR coming from the users own device is on average zero since most users are uncovered. Fig. 12 shows the exposure for the covered user just below the UABS. Scenario I already showed that the SAR from the user's own device is only influenced by the flying height and is also confirmed by the results in fig. 12.a where constant SAR^{myUE} is measured of $0.15 \mu\text{W}/\text{kg}$. The SAR from the UABS experiences a slight increase of $0.005 \mu\text{W}/\text{kg}$.

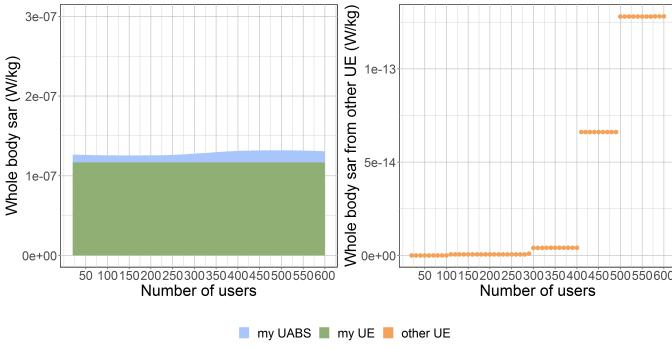


Fig. 12: SAR-values for the user who is directly beneath the only UABS available.

When the population grows, more users will be near the UABS. The UABS will likely decide to cover these users as well as visible in fig. 13. These users might have a slightly worse path loss because of obstructing buildings or somewhat bigger distance. The UABS reacts to this by increasing his power consumption causing an increase in the DL SAR for the central user. The far-field radiation from UE is very low as mentioned before and therefore added separately in fig. 12.b. It shows that the SAR from other UE increases from zero to $0.15 \mu\text{W}/\text{kg}$.

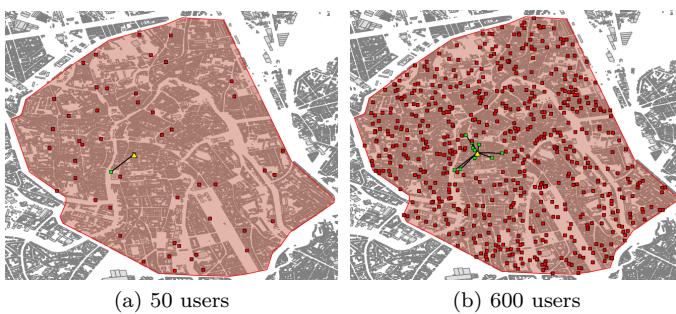


Fig. 13: Overview of which users are connected to the UABS.

C. Unlimited Number of UABSs

C.1 Variable Flying Height

The same scenario as in the previous section is investigated. Only now, an unlimited number of UABSs is available. The results prove that the different optimization strategies work as intended. A PwrC. Opt. network has indeed a lower power consumption and therefore result

in higher electromagnetic radiation. On the other hand, an Exp. Opt. network will reduce the electromagnetic exposure by using more UAVs and hence increase the network's power consumption. This conclusion was already made in [12] and is supported by these results. For example, when comparing both optimization strategies for the same equivalent isotropic radiator and the same default flying height, we see that the power consumption optimized network requires 51 W and therefore exposes its users to 15 mV/m . When optimizing towards electromagnetic radiation, the exposure drops to 11.5 mV/m but at a cost of a higher power consumption of 54 W .

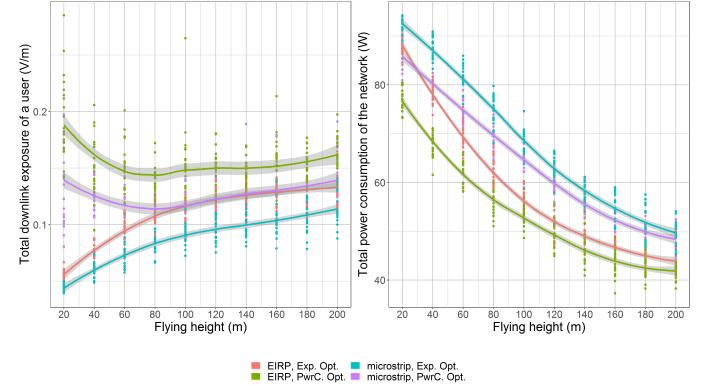


Fig. 14: These two figures show how the flying height influences the downlink electromagnetic radiation of the average user (left) and power consumption of the entire network (right) for an unlimited number of UAVs.

The exposure in fig. 14 shows that an Exp. Opt. network increases logarithmically while the PwrC. Opt. network rather has a concave relationship with the flying height, and has its lowest point at around 70 metres .

Fig. 15.a shows that the optimal coverage is achieved at a low flying height of 40 metres with around 99% coverage. However, there is a downside to this. Fig. 15.b shows that the number of required UAVs increases when the flying altitude becomes lower; a behaviour which was also determined in [20]. For example, an microstrip Exp. Opt. network and an EIRP PwrC. Opt. network require respectively 84 and 64 UABSs at a flying altitude of 200 m which increases respectively to 211 and 162 UABSs at a much lower flying altitude of 20 m .

Fig. 16 shows how each source contributes to the total SAR. A first consequence of raising the flying altitude from 20 to 200 metres is an increase between 89 and 141 nW/kg for SAR originating the user's own device; a behaviour also explained in the first scenario. Fig. 16 shows that once the flying altitude surpasses the NLoS of the buildings, around 70 to 80 metres, the SAR^{myUABS} remains more or less constant for all configurations. This is situated around 160 nW/kg for microstrip PwrC. Opt. networks. The microstrip Exp. Opt. and EIRP PwrC. Opt. networks has on average 98 nW/kg and the EIRP Exp. Opt. network is situated around 47 nW/kg . These higher flying altitudes will also result in an increase in electromagnetic radiation

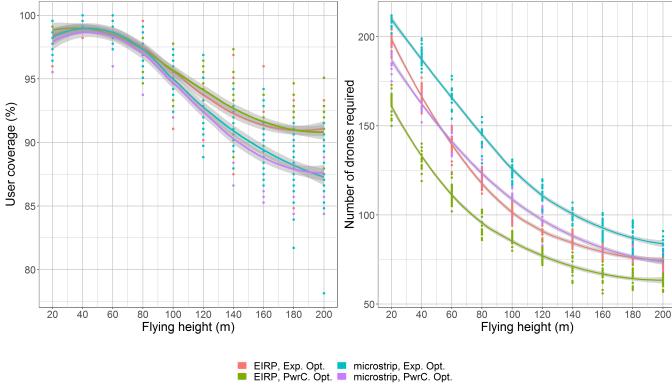


Fig. 15: This graph shows how much UAVs are required at different flying heights while trying to achieve a 100% coverage.

from other UABSSs. Raising the flying altitude from 20 to 200 metres will increase the the $SAR_{otherUABS}$ between 115 and 140 nW/kg for EIRP antennae and between 54 and 74 nW/kg for microstrip patch antennae for both optimization strategies.

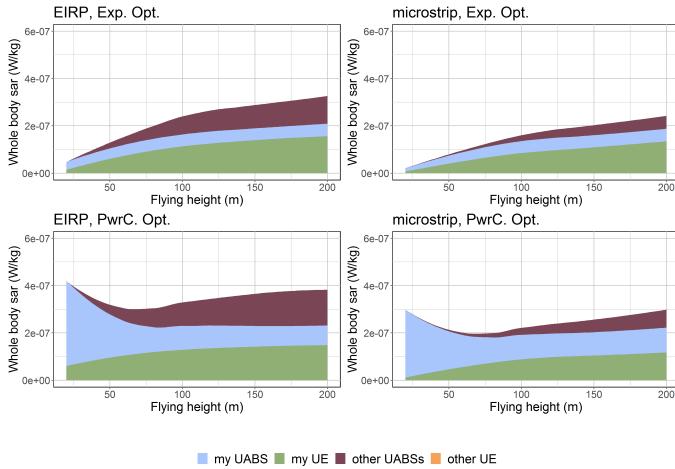


Fig. 16: Each chart corresponds with one of the four possible configurations. The contribution of each source towards the total SAR for a varying flying height is shown.

C.2 Variable Number of Users

The second evaluated parameter of this scenario is a variable number of users while the flying height is fixed to 100 metres. Fig. 17.a shows how the deployment tool tries to reach a 100% coverage. The percentage of covered users is slightly less for smaller networks. For only 50 users, an average coverage of around 93% is achieved while a network with 600 users has a coverage of around 97%. Fig. 17.b prove that more UAVs are required for these large populations. The difference in optimization strategy is very little for a small amount of people but increases very quickly. When the population increases from 50 to 600 users, 200

more UABSSs are required by a microstrip Exp. Opt. network, around 130 more UABSSs for an EIRP Exp. Opt. network or a microstrip PwrC. Opt. network and 110 more UABSSs for an EIRP PwrC. Opt. network. This is an expected behaviour when looking at scenario II, the percentage of covered users decreases for these larger populations.

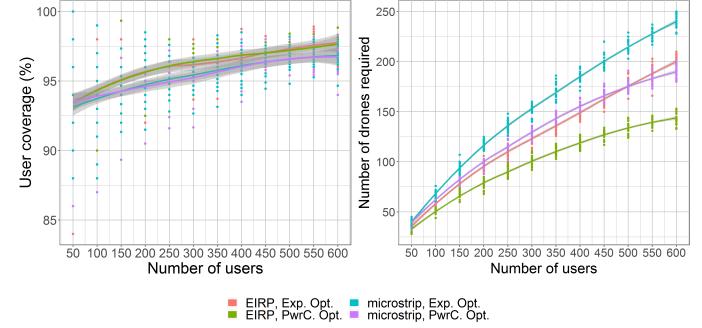


Fig. 17: This graph shows how much UAVs are required for different flying heights while trying to achieve a 100% coverage.

Fig. 18 shows that the electromagnetic radiation and power consumption increase for larger populations which is normal since more UABSSs will be available. When the population increases from 50 to 600 users, the electromagnetic radiation increases between 80 and 130 mV/m depending on the configuration. The power consumption with 50 users is for all configurations around 20 W. Once the population is increased to 600 users, a microstrip Exp. Opt. network will require 130 W, a microstrip PwrC. Opt. network requires 117 W, EIRP Exp. Opt. networks require 107 W and EIRP PwrC. Opt. network requires 92 W.

The correct behaviour of the decision algorithm became already clear in the previous subsection but is also confirmed here. When comparing both optimization strategies, a power consumption optimized network requires around 5 W less but exposes its users between 27 mV/m and 30 mV/m more than exposure optimized networks. Further, it is also noticed that equivalent isotropic radiators cause more electromagnetic radiation for less energy compared to microstrip patch antennae. When comparing the two types of antennae for a default number of 224 users, an equivalent isotropic radiator will expose the average user between 25 mV/m and 27 mV/m more while requiring around 12 W less than when the network would be using a microstrip patch antennae.

Fig. 19 represents the SAR from the weighted average user and shows how the SAR coming from the user's own device remains almost constant. The flying altitude is always the same so also the required energy to cover that distance will remain the same. For both optimization strategies, the SAR^{myUE} for networks with equivalent isotropic radiators vary around 1.1 $\mu W/kg$ and around 0.7 $\mu W/kg$ for networks using microstrip patch antennae. The SAR^{myUABS} barely increases in an exposure optimized network and is situated around 0.5 $\mu W/kg$ for both antennae. The power consumption optimized network also

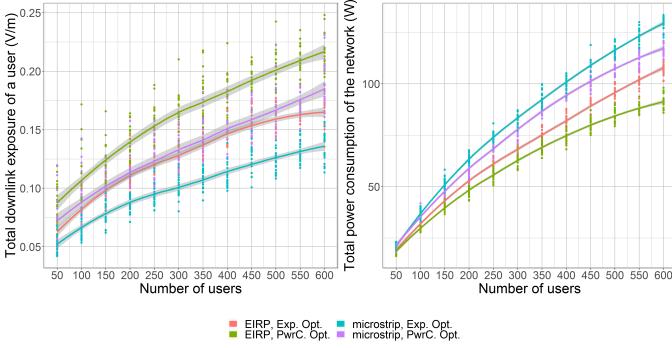


Fig. 18: The influence of the population size on the downlink electromagnetic radiation (a) and power consumption (b).

starts around $0.5 \mu\text{W}/\text{kg}$ but increases when more users become online. A normal behaviour when considering that these UABSSs try to cover much more users. Therefore, the SAR^{myUABS} with 600 users increases up to $1 \mu\text{W}/\text{kg}$ for an equivalent isotropic radiator and almost $2 \mu\text{W}/\text{kg}$ for a microstrip patch antenna. The SAR value that increases the most is $SAR^{otherUABS}$ which starts really low with less than $0.1 \mu\text{W}/\text{kg}$ for 50 users for all configurations. The SAR increases however very fast. The biggest increase is noticed in an EIRP PwrC. Opt. network where $3 \mu\text{W}/\text{kg}$ is measured for 600 users. The $SAR^{otherUE}$ increases the least for microstrip Exp. Opt. with only $1 \mu\text{W}/\text{kg}$ for 600 users.

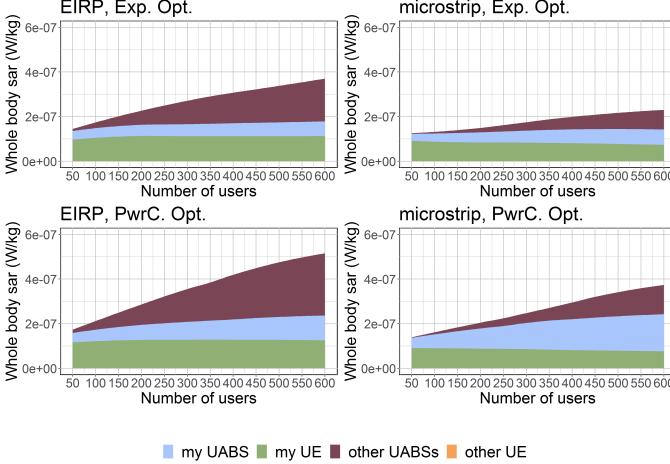


Fig. 19: Each figure corresponds with a certain configuration and shows how the SAR from different sources are influenced by an increasing population size. An unlimited number of UABSSs is available.

VI. Conclusion

A capacity-based deployment tool has been used to identify the SAR of a user and how a network can be optimized towards DL electromagnetic exposure and overall power consumption. This has been investigated for differ-

ent flying heights, number of users and number of available UABSSs. The results confirm that optimizing towards electromagnetic exposure and total power consumption indeed result in conflicting requirements as it was already stated in [12]. The proposed fitness function works as intended. For default configurations, the electromagnetic field radiation from a power consumption optimized network can be reduced up to 23% for equivalent isotropic radiators and 30% for microstrip patch antennae by optimizing towards electromagnetic exposure. Doing so, decreases the range of the UABSS and much more UABSSs will be needed. Therefore, exposure optimized networks will, on average, use 18 UAVs more than power consumption optimized networks and require therefore 5 W more energy.

A directional microstrip patch antenna is introduced because it gives several advantages compared to omnidirectional antennae. Directional antennae are able to focus their energy there where it is needed, namely towards the ground. Microstrip patch antennae further benefit from their thin and lightweight design. A microstrip patch antenna with an aperture angle of 90° causes less electromagnetic exposure and coverage and requires more power compared to an equivalent isotropic radiator. For a default configuration, a microstrip patch antenna can reduce between 30% and 34% of the electromagnetic exposure emitted by an equivalent isotropic radiator. This will increase the power consumption with 11 W.

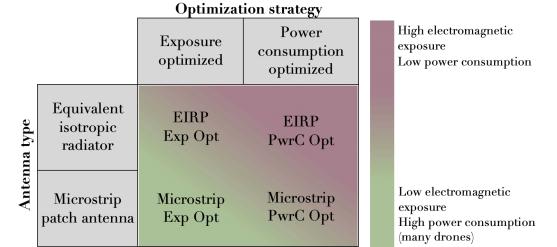


Fig. 20: Matrix with the four possible configurations, colour-coded based on the results.

Fig. 20 shows an overview based on the results from the two optimization strategies and the two types of antenna. Remarkable is that an EIRP exposure optimized network behaves very similar to a microstrip power consumption optimized network. Therefore, the microstrip patch antenna in a power consumption optimized network is recommended. The microstrip patch antenna will generate less electromagnetic radiation by design and the power consumption optimization reduces the number of required UAVs and power. A microstrip patch antenna with an aperture angle of 90° is considered as a good solution but if budget is more limited, an antenna with a larger aperture angle would further reduce cost without interfering with the Flemish legislation regarding electromagnetic exposure. The SAR from the configuration with the most exposure is still a hundred thousandth of the maximal allowed whole body SAR.

Fig. 21 gives an overview of the contribution of SAR in

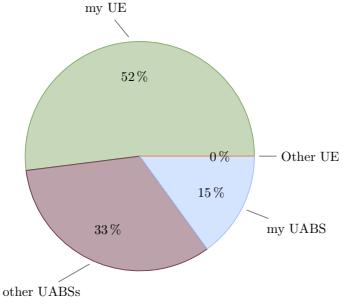


Fig. 21: Contribution from each source towards the total SAR that is experienced by the weighted average user. The percentages are averaged over the four considered configurations.

percentage to the total exposure for a default network. The values have been averaged over all four considered configurations. The user's main source of exposure is clearly the user's own device which contributes 52% of the total experienced exposure. A conclusion that was also made by the authors of [15] and [41]. Further, in [41] is also concluded that, thanks to power control, the electromagnetic radiation from the mobile phone comes really close to the exposure from the UABS. Also this is confirmed by the results. Fig. 21 shows that the electromagnetic exposure from all UABSs together covers the remaining 48% of which 15% is from the serving UABS. The electromagnetic exposure from devices belonging to other people can be ignored compared to the much higher electromagnetic exposure from the other sources and contributes only 0.0001%.

Further, the results show that power consumption and electromagnetic exposure increases when more users needs to be covered. When the population increases from 50 to 600 users, the electromagnetic radiation increases between 80 and 130 mV/m depending on the configuration. The power consumption increases with 110 W for all configurations. The main source that is influenced by the number of users is the SAR from other UABSs with an increase between 1 and 3 $\mu\text{W}/\text{kg}$, depending on the configuration. Further, increasing the flying altitude has a positive influence on the number of required UAVs which on their turn have a positive influence on power consumption. Increasing the flying altitude from 20 m to 200 m, decreases the number of required UAVs around 59%. This decrease was also noticed in [20]. Also authors from [15] made the conclusion that reduced path loss decreases electromagnetic exposure. The electromagnetic radiation from the UABSs remains more or less the same for flying altitudes between 80 and 200 metres. Most UABSs are in LoS and no more power will be used thanks to power control. However, the electromagnetic radiation from the user's own device does increase in order to reach the high flying UAVs. At around 80 metres, the exposure from the user's device surpasses the exposure from the serving UABS. When more UABSs are available in the network, electromagnetic exposure from other UABS will increase as well. This is because more UABSs come into LoS when the flying height

becomes larger. Raising the flying altitude from 20 to 200 m will increase the SAR from other UABSs between 46 and 49 times when using an equivalent isotropic radiator antenna and between 70 and 85 times when using a microstrip patch antenna. When also considering the results from [21] where a flying altitude of 80 metres is suggested for an optimal access and backhaul connectivity, a flying height of 80 metres is also here proposed for the city centre of Ghent.

In conclusion, a microstrip patch antenna with an aperture angle of 90° is a suitable starting point for an antenna. This directional antenna focusses electromagnetic radiation where it is needed and unwanted sideways radiation is reduced. The sufficiently large aperture angle covers enough users. The antenna is recommended to be deployed in a power consumption optimized network since less UAVs are required and therefore also less expensive. The optimal flying height for the city centre of Ghent is believed to be situated at 80 metres since lower flying heights require much more UABSs and higher flying heights have a negative influence on the electromagnetic exposure.

As a future work, still some parameters require further evaluation. Different Physical Uplink Shared Channel (PUSCH) values are expected to have a big influence on UL radiation and exposure from backhaul connections still have to be considered. Further, MiMo and massive MiMo are ready to be supported since the tool can easily be extended with some more complex radiation patters like beamforming. Another consideration is improving the time complexity by replacing the exact algorithm with an heuristic algorithm.

Acknowledgement

Special thanks to the WAVES research group at Ghent University for providing access to their capacity based deployment tool and therefore making this research possible.

References

- [1] “Base overschred stralingsnormen na aanslagen,” De standaard, 2016.
- [2] L. Hardell and C. Sage, “Biological effects from electromagnetic field exposure and public exposure standards,” *Biomedicine and Pharmacotherapy*, vol. 62, no. 2, pp. 104 – 109, 2008.
- [3] “What are electromagnetic fields.” <https://www.who.int/peh-emf/about/WhatisEMF/en/index1.html>. Accessed: 15-10-2019.
- [4] “Elektromagnetische velden en gezondheid: Uw wegwijzer in het elektromagnetische landschap,” Federale overheidsdienst: volksgezondheid, veiligheid van de voedselketen en leefmilieu, vol. 5, 2014.
- [5] A. Ahlbom, U. Bergqvist, J. Bernhardt, J. Cesarini, M. Grandolfo, M. Hietanen, A. Mckinlay, M. Repacholi, D. H. Sliney, J. A. Stolwijk, et al., “Guidelines for limiting exposure to time-varying electric, magnetic, and electromagnetic fields (up to 300 ghz),” *Health physics*, vol. 74, no. 4, pp. 494–521, 1998.
- [6] “Normen zendantennes.” <https://omgeving.vlaanderen.be/normen-zendantennes>. Accessed: 19-03-2020.
- [7] E. Commission, “Council recommendation of 12 july 1999 on the limitation of exposure of the general public to electromagnetic fields (0 hz to 300 ghz),” *Official Journal of the European Communities*, vol. 59, 1999.
- [8] “Wireless devices.” <https://www.health.belgium.be/en/wireless-devices>. Accessed: 13-05-2020.
- [9] A.-K. Lee, S.-E. Hong, M. Taki, K. Wake, and H. Do Choi, “Comparison of different sar limits in sam phantom for mo-

- bile phone exposure," in 2018 Asia-Pacific Microwave Conference (APMC), pp. 687–689, IEEE, 2018.
- [10] W. H. Bailey, R. Bodemann, J. Bushberg, C.-K. Chou, R. Cleaveland, A. Faraone, K. R. Foster, K. E. Gettman, K. Graf, T. Harrington, et al., "Synopsis of ieee std c95. 1™-2019 "ieee standard for safety levels with respect to human exposure to electric, magnetic, and electromagnetic fields, 0 hz to 300 ghz"," IEEE Access, vol. 7, pp. 171346–171356, 2019.
 - [11] D. Plets, W. Joseph, K. Vanhecke, and L. Martens, "Exposure optimization in indoor wireless networks by heuristic network planning," Progress In Electromagnetics Research, vol. 139, pp. 445–478, 01 2013.
 - [12] M. Deruyck, E. Tanghe, D. Plets, L. Martens, and W. Joseph, "Optimizing lte wireless access networks towards power consumption and electromagnetic exposure of human beings," Computer Networks, vol. 94, 12 2015.
 - [13] D. Plets, W. Joseph, S. Aerts, K. Vanhecke, G. Vermeeren, and L. Martens, "Prediction and comparison of downlink electric-field and uplink localised sar values for realistic indoor wireless planning," Radiation Protection Dosimetry, vol. 162, no. 4, pp. 487–498, 2014.
 - [14] D. Plets, W. Joseph, K. Vanhecke, and L. Martens, "Downlink electric-field and uplink sar prediction algorithm in indoor wireless network planner," in The 8th European Conference on Antennas and Propagation (EuCAP 2014), pp. 2457–2461, IEEE, 2014.
 - [15] S. Kuehn, S. Pfeifer, B. Kochali, and N. Kuster, "Modelling of total exposure in hypothetical 5g mobile networks for varied topologies and user scenarios," Final Report of Project CRR-816, Available on line at: <https://tinyurl.com/r6z2gqn>, 2019.
 - [16] D. Plets, W. Joseph, K. Vanhecke, G. Vermeeren, J. Wiart, S. Aerts, N. Varsier, and L. Martens, "Joint minimization of uplink and downlink whole-body exposure dose in indoor wireless networks," BioMed research international, vol. 2015, 2015.
 - [17] Y. Zeng, Q. Wu, and R. Zhang, "Accessing from the sky: A tutorial on uav communications for 5g and beyond," Proceedings of the IEEE, vol. 107, no. 12, pp. 2327–2375, 2019.
 - [18] Y. Kawamoto, H. Nishiyama, N. Kato, F. Ono, and R. Miura, "Toward future unmanned aerial vehicle networks: Architecture, resource allocation and field experiments," IEEE Wireless Communications, vol. 26, no. 1, pp. 94–99, 2018.
 - [19] R. Gangula, O. Esrafilian, D. Gesbert, C. Roux, F. Kaltenberger, and R. Knopp, "Flying robots: First results on an autonomous uav-based lte relay using open airinterface," in 2018 IEEE 19th International Workshop on Signal Processing Advances in Wireless Communications (SPAWC), pp. 1–5, IEEE, 2018.
 - [20] M. Deruyck, J. Wyckmans, W. Joseph, and L. Martens, "Designing uav-aided emergency networks for large-scale disaster scenarios," EURASIP Journal on Wireless Communications and Networking, vol. 2018, 12 2018.
 - [21] G. Castellanos, M. Deruyck, L. Martens, and W. Joseph, "Performance evaluation of direct-link backhaul for uav-aided emergency networks," Sensors, vol. 19, no. 15, p. 3342, 2019.
 - [22] M. Mozaffari, W. Saad, M. Bennis, Y.-H. Nam, and M. Debbah, "A tutorial on uavs for wireless networks: Applications, challenges, and open problems," IEEE communications surveys & tutorials, vol. 21, no. 3, pp. 2334–2360, 2019.
 - [23] Q. Wu, L. Liu, and R. Zhang, "Fundamental trade-offs in communication and trajectory design for uav-enabled wireless network," IEEE Wireless Communications, vol. 26, no. 1, pp. 36–44, 2019.
 - [24] M. Deruyck, A. Marri, S. Mignardi, L. Martens, W. Joseph, and R. Verdone, "Performance evaluation of the dynamic trajectory design for an unmanned aerial base station in a single frequency network," in 2017 IEEE 28th Annual International Symposium on Personal, Indoor, and Mobile Radio Communications (PIMRC), pp. 1–7, IEEE, 2017.
 - [25] A. V. Savkin and H. Huang, "Deployment of unmanned aerial vehicle base stations for optimal quality of coverage," IEEE Wireless Communications Letters, vol. 8, no. 1, pp. 321–324, 2018.
 - [26] H. Huang and A. V. Savkin, "A method for optimized deployment of unmanned aerial vehicles for maximum coverage and minimum interference in cellular networks," IEEE Transactions on Industrial Informatics, vol. 15, no. 5, pp. 2638–2647, 2018.
 - [27] C. T. Cicek, H. Gultekin, B. Tavli, and H. Yanikomeroglu, "Uav base station location optimization for next generation wireless networks: Overview and future research directions," in 2019 1st International Conference on Unmanned Vehicle Systems-Oman (UVS), pp. 1–6, IEEE, 2019.
 - [28] A. Rizwan, D. Biswas, and V. Ramachandra, "Impact of uav structure on antenna radiation patterns at different frequencies," in 2017 IEEE International Conference on Antenna Innovations & Modern Technologies for Ground, Aircraft and Satellite Applications (iAIM), pp. 1–5, IEEE, 2017.
 - [29] M. Nosrati, A. Jafargholi, and N. Tavassolian, "A broadband blade dipole antenna for uav applications," in 2016 IEEE International Symposium on Antennas and Propagation (APSURSI), pp. 1777–1778, IEEE, 2016.
 - [30] M. Nosrati, A. Jafargholi, R. Pazoki, and N. Tavassolian, "Broadband slotted blade dipole antenna for airborne uav applications," IEEE Transactions on Antennas and Propagation, vol. 66, no. 8, pp. 3857–3864, 2018.
 - [31] B. A. Arand, R. Shamsaei, and B. Yektakhah, "Design and fabrication of a broadband blade monopole antenna operating in 30 mhz–600 mhz frequency band," in 2013 21st Iranian Conference on Electrical Engineering (ICEE), pp. 1–3, IEEE, 2013.
 - [32] L. Akhoondzadeh-Asl, J. Hill, J.-J. Laurin, and M. Riel, "Novel low profile wideband monopole antennae for avionics applications," IEEE transactions on antennas and propagation, vol. 61, no. 11, pp. 5766–5770, 2013.
 - [33] S. S. Siddiq, G. Karthikeya, T. Tanjavur, and N. Agnihotri, "Microstrip dual band millimeter-wave antenna array for uav applications," in 2016 21st International Conference on Microwave, Radar and Wireless Communications (MIKON), pp. 1–4, IEEE, 2016.
 - [34] Y. Zheng, J. Zhou, W. Wang, and M. Chen, "A low-profile broadband circularly polarized antenna array for uav ground-to-air communication," in 2018 IEEE Asia-Pacific Conference on Antennas and Propagation (APCAP), pp. 219–220, IEEE, 2018.
 - [35] X. Sun, R. Blázquez-García, A. García-Tejero, J. M. Fernández-González, M. Burgos-García, and M. Sierra-Castañer, "Circular array antenna for uav-uav communications," in 2017 11th European Conference on Antennas and Propagation (EUCAP), pp. 2025–2028, IEEE, 2017.
 - [36] I. Singh and V. Tripathi, "Micro strip patch antenna and its applications: a survey," Int. J. Comp. Tech. Appl, vol. 2, no. 5, pp. 1595–1599, 2011.
 - [37] K. Kashwan, V. Rajeshkumar, T. Gunasekaran, and K. S. Kumar, "Design and characterization of pin fed microstrip patch antennae," in 2011 Eighth International Conference on Fuzzy Systems and Knowledge Discovery (FSKD), vol. 4, pp. 2258–2262, IEEE, 2011.
 - [38] R. Mullner, C. F. Ball, K. Ivanov, J. Lienhart, and P. Hric, "Contrasting open-loop and closed-loop power control performance in utran lte uplink by ue trace analysis," in 2009 IEEE International Conference on Communications, pp. 1–6, IEEE, 2009.
 - [39] M. Lauridsen, A. R. Jensen, and P. Mogensen, "Reducing lte uplink transmission energy by allocating resources," in 2011 IEEE Vehicular Technology Conference (VTC Fall), pp. 1–5, 2011.
 - [40] A. Sudarsan and A. Prabhu, "Design and development of microstrip patch antenna," International Journal of Antennas (JANT) Vol, vol. 3, 2017.
 - [41] A. Gati, E. Conil, M.-F. Wong, and J. Wiart, "Duality between uplink local and downlink whole-body exposures in operating networks," IEEE transactions on electromagnetic compatibility, vol. 52, no. 4, pp. 829–836, 2010.

Evaluatie van de elektromagnetische blootstelling van de mens in een netwerk van drones

Thomas Detemmerman

Supervisor(s): Wout Joseph, Luc Martens

Abstract—

De hedendaagse samenleving vertrouwt meer dan ooit op de aanwezigheid van draadloze netwerken. Dankzij de mobiliteit van drones kan een drone-gestuurd netwerk de nodige mobiele data voorzien indien het bestaande netwerk beschadigd is. Er is echter een groeiende vrees voor mogelijke gezondheidseffecten veroorzaakt door deze mobiele netwerken. De overheid stelt strikte wetgevingen op waaraan deze mobiele netwerken dienen te voldoen.

Dit onderzoek bekijkt hoe verschillende scenario's het energieverbruik, elektromagnetische blootstelling en specifieke absorptietempo kunnen beïnvloeden. Drie verschillende scenario's zijn gedefinieerd waarbij verschillende vlieghoogtes, aantal drones en populatiegroottes onderzocht worden. Verder is er ook een microstrip patch antenne gedefinieerd en bevestigd op een drone. De antenne zal de communicatie tussen de drone en de gebruikers verzorgen. De performantie van deze antenne zal vergeleken worden met een istorope antenne. Vervolgens zal het netwerk geoptimaliseerd worden naar elektromagnetische straling van het individu of naar het energieverbruik van het gehele netwerk. Deze twee doelstellingen resulteren in tegenstrijdige vereisten.

Om dit doel te bereiken is de capacity based deployment tool van de onderzoeksgroep WAVES op de Universiteit Gent verder uitgebreid zodoende dat elektromagnetische straling berekend kan worden. Verder is de tool nu ook in staat om te optimaliseren naar elektromagnetische straling of energieverbruik.

Uit de resultaten blijkt dat een microstrip patch antenne met een openingshoek van 90° een geschikt startpunt is voor een antenne. Deze directionele antenne focust de elektromagnetische straling daar waar het nodig is. Ongewenste zijwaardse straling wordt gereduceerd door het design. Het wordt aangeraden om de antenne toe te passen in een netwerk dat energieverbruik minimaliseert omdat hierbij minder drones nodig zijn en daardoor goedkoper is. De optimale vlieghoogte voor het stadscentrum in Gent bevindt zich rond 80 meter. Lagere vlieghoogtes vereisen veel meer drones terwijl hogere vlieghoogtes de elektromagnetische straling laten toenemen.

Sleutelwoorden— LTE, Electromagnetische blootstelling, Energieverbruik, Drone, Femtocell, Microstrip patch antenna, Stralingspatronen, Specific absorption rate (SAR)

I. Introductie

De samenleving is meer dan ooit afhankelijk van draadloze communicatie. Een elektronisch apparaat kan op elk gegeven moment in elke willekeurige plaats beroep doen op het draadloos netwerk, gaande van kleine Internet of Things (IoT) apparaten tot volwaardige zelf-rijdende auto's.

Ook in uitzonderlijke en zelfs mogelijks levensbedreigende situaties verwacht de samenleving de aanwezigheid van het mobiele netwerk. Desondanks het feit dat dit netwerk zelf mogelijk beschadigd kan zijn door de situatie. Een mogelijk tijdelijke oplossing om een beschadigd netwerk bij te staan is met behulp van onbemande vliegtuigen zoals drones. Een base station kan geplaatst worden op een drone en zo efficiënt verplaatst worden naar de nodige locatie.

Deze aanpak is niet alleen handig als het bestaande netwerk beschadigd is maar ook voor een onverwachte toename aan gebruikers. Bijvoorbeeld tijdens de aanslagen op de Brusselse luchthaven zagen alle mobiele operatoren een toename in data verkeer. Sommige operatoren raakten zodanig verzwakt dat ze besloten om de elektromagnetische straling te laten toenemen boven de opgelegde limieten zodat toch iedereen behandeld kon worden [1].

De elektromagnetische straling die vrijkomt bij netwerken kan echter niet met onachtzaamheid behandeld worden. Onderzoek toont aan dat buitensporige elektromagnetische straling verscheidende biologische neveneffecten kan veroorzaken [2], [3]. Het is dus duidelijk dat elektromagnetische straling een sleutelrol speelt bij het ontwikkelen van een met drones beholpen netwerk waarbij de wetgeving nauwkeurig nageleefd dient te worden.

Drone-gestuurde netwerken kunnen dankzij hun mobiliteit eenvoudig verplaatst worden. Verschillende onderzoeken tonen aan hoe deze netwerken geoptimaliseerd kunnen worden zodat bepaalde doelstellingen zoals minimaal energieverbruik bereikt kunnen worden.

Niettemin is er zeer beperkt onderzoek gedaan waarbij een drone-gestuurd netwerk wordt geoptimaliseerd naar elektromagnetische straling. Verscheidene publicaties bespreken hoe elektromagnetische straling berekend kan worden maar overwegen zelden alle verschillende bronnen van straling.

Dit onderzoek stelt een methode voor waarbij rekening gehouden wordt met elektromagnetische straling en energieverbruik voor alle bronnen in een mobiel netwerk, zijnde: de gebruiker zijn eigen mobiel apparaat, de base station dat deze gebruiker aan het behandelen is, alle andere mobiele apparaten en alle andere base stations die andere gebruikers behandelen. Op deze manier kan de bijdrage in elektromagnetische straling van elke bron duidelijk geïdentificeerd worden.

Het gedrag van de elektromagnetische straling en het energieverbruik zullen geanalyseerd worden door de tool toe te passen op verschillende scenario's door gebruik te maken van verschillende soorten antennes, vlieghoogtes en populatiegroottes. Waarden zoals Specific Absorptietempo (SAT), elektromagnetische straling en energieverbruik zullen inzicht geven in hoe het netwerk reageert op deze veranderende scenario's en hoe het netwerk ernaar geoptimaliseerd kan worden.

Om dit onderzoek mogelijk te maken zal een bestaande deployment tool, ontwikkeld door de onderzoeksgroep WAVES van de universiteit van Gent, uitgebreid worden.

Deze tool beschrijft een volledig geconfigureerd netwerk van drones wat een geschikt startpunt is voor dit onderzoek.

II. State of the Art

A. Elektromagnetische Straling

Personen in een mobiel netwerk worden blootgesteld aan verscheidene bronnen van elektromagnetische straling, uitgedrukt in V/m . Eenmaal deze elektromagnetische straling geabsorbeerd wordt door het menselijk lichaam spreken we van het specifieke absorptietempo (SAT) (dat uitgedrukt wordt in W/kg). De International Commission on Non-Ionizing Radiation Protection (ICNIRP) heeft geconcludeerd dat het drempeleffectwaarde voor SAR_{10g}^{wb} zich bevindt op 4 W/kg wat inhoudt dat elk hoger absorptietempo de thermoregulerende capaciteit van de mens zou overstijgen [4], [5]. Al deze waarden zijn onderworpen aan limieten opgelegd door de overheid. Dit onderzoek vindt plaats in Gent, een Vlaamse stad in België, waarbij voor het 2.6 GHz spectrum een individuele zendmast is gelimiteerd tot 4.5 V/m en de totale elektrische veldsterkte voor elk punt niet meer dan 31 V/m mag bedragen. [4], [6]. De maximale SAT voor het volledige lichaam komende van een mobiel apparaat verspreid over een 10 g tissue (SAR_{10g}) is beperkt tot 0.08 W/kg [7], [4], [8].

Verschillende onderzoeken berekenen de elektromagnetische veldsterkte van verschillende bronnen [9], [10], [11], [12] waarbij sommigen de uplink (UL) elektromagnetische veldsterkte converteren naar lokale SAT voor het hoofd en torso [11], [12]. Met de naderende 5G technologie werd [13] gepubliceerd waarbij beschreven wordt hoe deze lokale SAT-waarden van alle verschillende bronnen berekend kunnen worden en bij elkaar opgeteld worden. Uiteindelijk beschrijft [14] hoe de elektromagnetische veldsterkte omgezet kan worden naar SAT-waarden voor het volledige lichaam.

In een realistisch netwerk kunnen sommige gebruikers telefoneren terwijl anderen andere vormen van communicatie gebruiken zoals surfen op het internet. Aangezien de positie van het mobiel apparaat tegenover zijn gebruiker niet gekend is, is het belangrijk dat de SAT-waarden berekend worden in functie van het volledige lichaam.

B. Geoptimaliseerde drone-gestuurde netwerken

Drones kennen verschillende toepassingen. Ze werden oorspronkelijk voornamelijk gebruikt door het leger waarbij ze dienst doen als camera ondersteuning of om aanvallen uit te voeren zonder piloten in gevaar te brengen [15]. Deze drones zijn de laatste jaren in prijs gedaald waardoor ze beter toegankelijk worden voor het algemene publiek. Hierdoor is het onderzoek naar nieuwe toepassingen ervan sterk toegenomen.

Een drone uitgerust met een femtocell base station wordt een Unmanned Arial Base Station (UABS) genoemd en geniet verschillende voordelen zoals mobiliteit en snelle inzetbaarheid. Desondanks zijn er ook verschillende nadelen zoals het beperkte gewicht dat een drone kan dragen en de schaarse energievoorziening.

Kawamoto et al. introduceert in [16] een WiFi netwerk

met behulp van drones waarbij rekening gehouden wordt met de richting van de geplaatste antennes op de drone. Gangula et al. illustreert in [17] hoe drones gebruikt kunnen worden voor Long-Term Evolution (LTE) en Zeng et al. presenteert in [15] een handleiding waarbij uitdagingen zoals energieverbruik, mobiliteit en de richting van de antenne voor een 5G netwerk besproken worden. In [18] ontwikkelt Deruyck et al. een deployment tool voor een drone gestuurd netwerk voor rampsituaties waarbij een ideale vlieghoogte van 100 meter aangeraden wordt. Dit wordt verder uitgebreid in [19] waarbij ook rekening gehouden wordt met direct-link backhaul connecties waarbij een ietwat lagere vlieghoogte van 80 meter bekomen wordt.

Mozaffari et al. voorziet in [20] richtlijnen hoe een drone-gestuurd netwerk geoptimaliseerd en geanalyseerd kan worden. Eén onderzoeksgebied dat uitgebreid onderzocht wordt, is het optimaliseren van de locaties waar drones zich moeten positioneren. Deze algoritmen trachten bepaalde doelstellingen zoals minimaal energieverbruik of kortste vliegafstand te bereiken [21], [22], [23], [24]. Deze optimalisatie kan gebeuren door verschillende implementaties waaronder exacte algoritmen of machinaal leren [20], [25].

Onderzoek waarbij de elektromagnetische straling gelimiteerd wordt is echter beperkt. Deruyck et al. bespreekt in [10] hoe een conventioneel mobiel netwerk geoptimaliseerd kan worden zodoende dat het energieverbruik van het volledige netwerk minimaal wordt of de elektromagnetische blootstelling van een individu geminimaliseerd wordt. Echter, onderzoek waarbij een drone-gestuurd netwerk geoptimaliseerd wordt naar elektromagnetische straling is door de auteur niet gekend.

C. Technologieën

Voor het ontwikkelen van het netwerk zullen de meer robuuste drones uit [18] gebruikt worden (details in tabel II). De gekoppelde antennes zullen opereren in het 2.6 GHz spectrum. Aangezien het aangenomen wordt dat de gebruikers een voortdurende blootstelling van elektromagnetische straling ondervinden, zonder onderbrekingen, wordt frequency division duplexing gebruikt.

De antenne op de drone zal dienst doen als gateway tussen de mobiele apparaten op de grond en het backbone netwerk. Bepalen welke antenne gebruikt moet worden en hoe deze vervolgens het beste gepositioneerd kan worden brengt verschillende uitdagingen met zich mee. Het stratingspatroon van de antenne kan beïnvloed worden door de drone [26]. Maar ook het feit dat deze drones boven de gebruikers zullen vliegen zorgt er voor dat 2D modelleren onvoldoende is. Een 3D model waarbij rekening gehouden wordt met zowel horizontale als verticale richting zal een vereiste vormen [15].

Het eenvoudigste stratingspatroon is een hypothetische isotrope antenne die straalt met gelijke hoeveelheid in elke richting. Een antenne die gelijkwaardig straalt over een specifiek vlak wordt een omnidirectionele antenne genoemd [15]. Hiervan bestaan verschillende soorten voor te bevestigen op drones zoals monopoolantennes, dipoolantennes

en vleugel antennes [27], [28], [29], [30]. Een andere vorm van antenne zijn directionele antennes die energie besparen door de elektromagnetische straling te focussen daar waar het nodig is. Eén soort hiervan die uitgebreid onderzocht is in verscheidene antenne-arrays zijn de microstrip antennes [31], [32], [33]. Deze bieden verschillende voordelen ten opzichte van meer traditionele antennes zoals het beperkte gewicht, lage productiekosten en aerodynamica [34], [35].

Een microstrip antenne is opgebouwd uit een grondplaat en een stralingsplaat met daartussen een diëlectrisch substraat. Verscheidene variaties bestaan zoals microstrip patch antennes, microstrip slot antennes en geprinte dipool antennes die allemaal gelijkende karakteristieken hebben [34], [35]. Ze zijn allemaal dun, ondersteunen dubbele frequenties en hebben allemaal het nadeel dat ze interferentie kunnen veroorzaken op frequenties buiten het bedoelde spectrum. De microstrip patch en slot antenne ondersteunen beiden circulaire en lineaire polarisatie terwijl de geprinte dipool antenne enkel lineaire polarisatie ondersteunt. Verder is de microstrip patch antenne het eenvoudigste te produceren ten opzichte van de andere overwogen antennes [34].

Fig. 1 toont een microstrip patch antenne die bestaat uit aluminium en bevestigd is op een substraat van Teflon. De microstrip patch antenne wijst naar de grond aangezien de drone boven de mensen zal vliegen.



Fig. 1: Afbeelding van een microstrip patch antenne bevestigd aan de onderkant van een drone.

III. Methodologie

De eerste subsectie legt uit hoe elektromagnetische straling berekend kan worden voor elke bron en hoe deze om te zetten naar SAT. De tweede subsectie geeft een overzicht van hoe een microstrip patch antenne ontwikkeld kan worden. De derde subsectie bespreekt hoe het netwerk geoptimaliseerd kan worden en als laatste wordt het algoritme uitgelegd.

A. Elektromagnetische Straling

A.1 Totale Electromagnetische Straling

De totale SAT voor het volledige lichaam ($SAT_{10g}^{wb,totaal}$) van een individu kan berekend worden als een eenvoudige som van de SAT-waarden van de individuele bronnen. Dit is gebaseerd op de formule uit [13] die aanneemt dat het mobiele apparaat tegen het oor van zijn gebruiker gehouden wordt. Hierdoor worden alle waarden in lokale SAT-waarden voor het hoofd uitgedrukt. In dit netwerk is de plaats van het mobiele apparaat echter niet gekend wat zou

leiden tot onjuiste conclusies. Bijgevolg zal alles uitgedrukt worden in functie van het volledige lichaam.

$$SAT_{10g}^{wb,totaal} = SAT_{10g}^{wb,myUE} + SAT_{10g}^{wb,myUABS} \\ + SAT_{10g}^{wb,otherUE} + SAT_{10g}^{wb,otherUABS} \quad (1)$$

In bovenstaande formule staat *wb* voor whole body ofwel het volledige lichaam en *UE* voor User Equipment ofwel het mobiele apparaat op de grond. De eerste parameter, $SAT_{10g}^{wb,myUE}$, duidt de geabsorbeerde elektromagnetische straling aan komende van de gebruiker zijn eigen apparaat. Ondanks het feit dat de UL straling bedoeld is voor de UABS die deze gebruiker behandelt, wordt een deel van deze straling ook geabsorbeerd door de gebruiker zelf. Dit komt door de omnidirectionele antenne die door het mobiele apparaat gebruikt wordt. Een tweede parameter is $SAT_{10g}^{wb,myUABS}$ die de straling aanduidt veroorzaakt door downlink (DL) dataverkeer, komende van de UABS die deze gebruiker behandelt. Als derde parameter hebben we $SAT_{10g}^{wb,otherUE}$ die de straling aanduidt veroorzaakt door andere gebruikers hun mobiel apparaat. Als laatste stelt $SAT_{10g}^{wb,otherUABS}$ de DL straling voor komende van alle UABSen die andere gebruikers behandelen. Een illustratie is te vinden in fig. 2 waarbij de groene pijl straling in het nabije veld voorstelt en alle andere pijlen straling in het verre veld voorstellen.

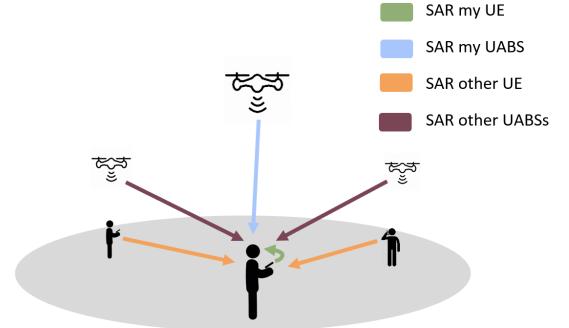


Fig. 2: Deze illustratie toont hoe de gemiddelde gebruiker (hier getoond in het midden) beïnvloed wordt door verschillende bronnen van elektromagnetische straling.

A.2 Electromagnetische straling van een individuele bron

Om de totale elektromagnetische straling te vinden waaraan de gebruiker is blootgesteld, dient eerst de straling van elke individuele bron berekend te worden. Dit wordt gedaan met formule 2 en is van toepassing voor alle bronnen in het verre veld. Dit houdt in: alle UABS's en alle mobiele apparaten die niet tot de gebruiker behoren. De elektromagnetische veldsterkte E voor het individu u komende van een bron i wordt als volgt berekend:

$$E_i(u)[V/m] = 10^{\frac{ES(u)[dBm] - 43.15 + 20 * \log(f[MHz]) - PL(u)[dB]}{20}} \quad (2)$$

Het berekenen van de effectieve straling (ES) voor een gebruiker u vereist eerst om de equivalent isotropic radiation power (EIRP) te hebben berekend [9], [10]. Dit kan bekomen worden door het zendvermogen P_t op te tellen met de zendversterking G_t en het kabelverlies L_t ervan af te trekken. Deze formule dient echter uitgebreid te worden zodoende dat er rekening gehouden wordt met signaalverzwakking wat afhankelijk is van het gebruikte stralingspatronen. Deze waarde hangt af van de hoek tussen de gebruiker en de richting waarnaar de antenne wijst. De signaalverzwakking bij een isotrope antenne is altijd nul ongeacht de hoek. Dit leidt tot de volgende formule:

$$RRP[dBm] = P_t[dBm] + G_t[dBi] - L_t[dB] - \text{attenuation}(u)[dB] \quad (3)$$

De gebruikte frequentie f in formule 2 is uitgedrukt in MHz. Aangezien LTE gebruikt wordt, zal deze waarde 2600 MHz bevatten.

Als laatste dient formule 2 ook het padverlies PL te kennen. Een geschikt propagatie model dient gekozen te worden. Hier wordt geopteerd voor het Walfish-Ikegami model aangezien die goed presteert voor femtocell netwerken in stedelijke gebieden [18].

A.3 Samenvoegen van meerdere bronnen

De totale elektromagnetische straling E_{tot} in een bepaald punt, komende van alle verschillende bronnen, kan berekend worden door formule 4. Hierin staat E_i voor de elektromagnetische veldsterkte voor dat punt komende van bron i en n staat voor alle bronnen in het verre veld van een bepaalde categorie wat hier ofwel UABS's of mobiele apparaten van andere personen zijn. E_{tot} zal berekend worden in elk punt waar er zich een gebruiker bevindt.

$$E_{tot}[V/m] = \sqrt{\sum_{i=1}^n (E_i[V/m])^2} \quad (4)$$

A.4 Omzetten van elektromagnetische veldsterkte naar SAT

Formule 1 verwacht dat de SAT waarden in functie van het volledige lichaam uitgedrukt zijn. Om de elektromagnetische veldsterkte te kunnen omzetten naar deze SAT-waarden dient er een onderscheid gemaakt te worden tussen bronnen in het nabije veld ($SAR^{wb,nf}$) en het verre veld ($SAR^{wb,ff}$). $SAR_{10g}^{wb,myUE}$ is een bron waarbij de gebruiker zich in het nabije veld bevindt terwijl de gebruiker zich voor alle andere bronnen in het verre veld bevindt.

Het omzetten van deze waarden gebeurt door middel van een conversie constante die gebaseerd is op Duke van de Virtual Family. Duke is een 34 jarige man met een gewicht van 72 kg, een lengte van 1.74 m en een BMI van 23.1 kg/m [14]. Onderzoek toont aan dat de conversie constante voor WiFi in het verre veld $0.0028 \frac{W/kg}{W/m^2}$ bedraagt en $0.0070 \frac{W/kg}{W}$ in het nabije veld [14]. WiFi maakt gebruik van het 2400 MHz spectrum wat heel dicht bij LTE is met 2600 MHz. Daarom wordt in [14] aangenomen dat de conversie

constante ook van toepassing is voor LTE. Het berekenen van SAT in het verre veld wordt als volgt gedaan:

$$S[W/m^2] = \frac{(E_{tot}[V/m])^2}{337} \quad (5)$$

$$SAR_{10g}^{wb,ff}[W/kg] = S[W/m^2] * 0.0028 \left[\frac{W/kg}{W/m^2} \right] \quad (6)$$

De constante in vergelijking 6 zet de vermogensdichtheid S om naar de verwachte $SAR_{10g}^{ff,wb}$. Om dit mogelijk te maken moet het resultaat van formule 4 eerst nog omgezet worden naar vermogensdichtheid met behulp van formule 5.

De SAT die veroorzaakt wordt door het mobiel apparaat in het nabije veld kan gevonden worden door het zendvermogen P_{tx} van het apparaat te vermenigvuldigen met de conversie constante voor het nabije veld en is berekend als volgt:

$$SAR_{10g}^{wb,nf}[W/kg] = 0.0070 \left[\frac{W/kg}{W} \right] * P_{tx}[W] \quad (7)$$

De energie die door het mobiele apparaat wordt gebruikt kan berekend worden met formule 8 [14].

$$\begin{aligned} P_{tx}^{UE} &= \min \{ P_{max}[dBm], \\ &P_{pusch}[dBm] + \alpha * PL[dB] + 10\log(M) + \sigma \} \end{aligned} \quad (8)$$

Hierbij staat P_{max} voor het maximaal toegestane zendvermogen van het mobiele apparaat wat voor LTE 23 dBm bedraagt. Dit is echter in het slechtste geval. De effectieve waarde ligt dankzij power control doorgaans lager. P_{pusch} is de minimale energie vereist door de UABS en bedraagt hier -120 dBm. α is de compensatiefactor voor het padverlies en is gelijk aan één wat hier volledige compensatie betekent [36], [37]. Voor het 20 MHz kanaal in deze paper zal M gelijk zijn aan 100 en zal σ , als correctiefactor, nul bedragen [14], [36].

B. Microstrip Patch Antenne

Een microstrip patch antenne is gekozen vanwege zijn eenvoudige productieproces maar voornamelijk vanwege het lage gewicht en aerodynamica wat heel voordelig is wanneer het aan een drone gekoppeld wordt [34].

De dimensies van de antenne hangen af van de gebruikte frequentie en de eigenschappen van het diëlectrisch substraat. De antenne zal opereren met een frequentie f_0 van 2.6 GHz. Elk substraat heeft een diëlectrische constante ϵ_r die de doorlaatbaarheid van het substraat aanduidt en hangt af van het gebruikte materiaal. Substraten met een hoge diëlectrische constante en kleine hoogte zullen de dimensies van de antenne reduceren terwijl een lager diëlectrische constante met een hogere hoogte de performantie van de antenne zullen bevorderen [35], [38]. Voor dit onderzoek is glas gekozen vanwege zijn hogere diëlectrische constante $\epsilon_r = 4.4$ ten opzichte van andere materialen zoals Teflon met een diëlectrische constante van $\epsilon_r = 2.2$ [35]. Glas met een hoogte van 2.87 mm zal de dimensies van de

Beschrijving	Symbol	Waarde
Middenfrequentie	f_0	2600 MHz
Diëlectrische constante	ϵ_r	4.4
Hoogte van het substraat	h	0.00287 m

TABEL I: Overzicht van de configuratie parameters

volledige antenne opperlakte verminderen wat voordeelig is bij de beperkte ruimte die beschikbaar is op een drone.

De dimensies van de stralingsplaat kunnen berekend worden met de formules uit [35], [38]. Dit leidt tot een stralingsplaat van 35.09 mm bij 26.55 mm en een grondplaat van minstens 52.40 mm bij 43.80 mm. De resulterende microstrip patch antenne is geïllustreerd in fig. 3 en zal resulteren in het stralingspatroon getekend in fig. 4.

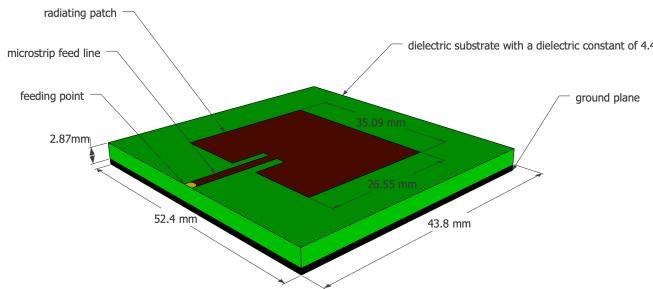


Fig. 3: Schema van een microstrip patch antenne.

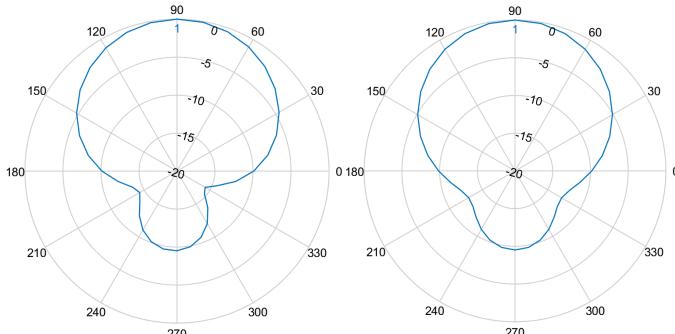


Fig. 4: Links is het stralingspatroon voor het E-vlak en rechts voor het H-vlak.

C. Optimaliseren van het netwerk

Deruyck et al. bespreekt in [10] hoe een traditioneel mobiel netwerk geoptimaliseerd kan worden naar elektromagnetische straling of energieconsumptie. Hoewel een toenamezend zendvermogen wel degelijk resulteert in hogere elektromagnetische veldsterkte is deze regel niet van toepassing indien we het energieverbruik bekijken over het hele netwerk heen. De auteurs van [10] tonen een omgekeerd equivalente relatie aan. De reden hierachter is dat het vaak minder energie kost om de elektromagnetische straling van een reeds actieve base station verder te laten toenemen in plaats van een nieuwe base station te activeren. Dit leidt

tot de fitness functie in vergelijking 9 en is gebaseerd op [10].

$$f = w * \left(1 - \frac{E_m}{E_{max}}\right) + (1 - w) * \left(1 - \frac{P}{P_{max}}\right) * 100 \quad (9)$$

Formule 9 geeft een score terug dat aanduidt hoe goed het netwerk preseteert. w is de belangrijkheidsfactor die loopt van 0 tot 1, grenzen inbegrepen. Een w gelijk aan 0 betekent dat elektromagnetische straling niet belangrijk is. Een dergelijk netwerk wordt een power consuption optimized (PwrC. Opt.) netwerk genoemd. Aan de andere kant, een w gelijk aan 1 implieert dat het minimaliseren van elektromagnetische blootstelling top prioriteit is en zal bijgevolg resulteren in een exposure optimized (Exp. Opt.) netwerk. P_{max} is het energieverbruik van alle UABS's op maximaal zendvermogen, ongeacht of ze op non-actief staan of niet. P stelt de effectieve verbruikte energie van het huidig ontwikkelde netwerk voor. E_m is de elektromagnetische straling van de gewogen gemiddelde gebruiker van het huidig ontwikkelde netwerk en E_{max} is dezelfde waarde maar met alle UABS's op maximaal zendvermogen.

Bij het optimaliseren van het netwerk is het niet enkel belangrijk om de gemiddelde gebruiker te overwegen maar ook het limiteren van extrema [10]. Daarom wordt er gebruik gemaakt van het gewogen gemiddelde waarbij niet enkel rekening gehouden wordt met de mediaan maar ook met het 95^{ste} percentiel. Dit leidt tot formule 10 waarbij w_1 en w_2 de gewichten zijn van respectievelijk de mediaan en het 95^{ste} percentiel. Aangezien verondersteld wordt dat beide waarden een gelijkwaardige rol spelen zullen beiden een gewicht van 0.5 krijgen.

$$E_m = \frac{w_1 * E_{50} + w_2 * E_{95}}{w_1 + w_2} \quad (10)$$

D. Simulatie Tool

D.1 Hoofdalgoritme

In eerste instantie dient een beschrijving van het gebied voorzien te worden. Dit wordt verwezenlijkt met behulp van zogenaamde shape-bestanden. Deze bestanden bevatten een volledige beschrijving van de vorm van elk gebouw. Vervolgens worden gebruikers uniform verdeeld over het gebied en zal er een tijdelijke UABS geplaatst worden boven elke gebruiker. Nu is het aan het beslissingsalgoritme om te bepalen welke UABS's effectief zullen blijven en hoe hoog het zendvermogen van elke UABS zal zijn. Eens het beslissingsalgoritme voltooid is zal de tool controleren of het nummer van online drones niet meer is dan de capaciteit van de stockageruimte toelaat. Indien dit wel het geval is zullen drones offline gehaald worden, beginnend bij drones die het minste personen behandelen.

D.2 Beslissingsalgoritme

Het oplossen van het netwerk is de verantwoordelijkheid van het beslissingsalgoritme en start met het berekenen van het padverlies tussen alle gebruikers en tussen gebruikers

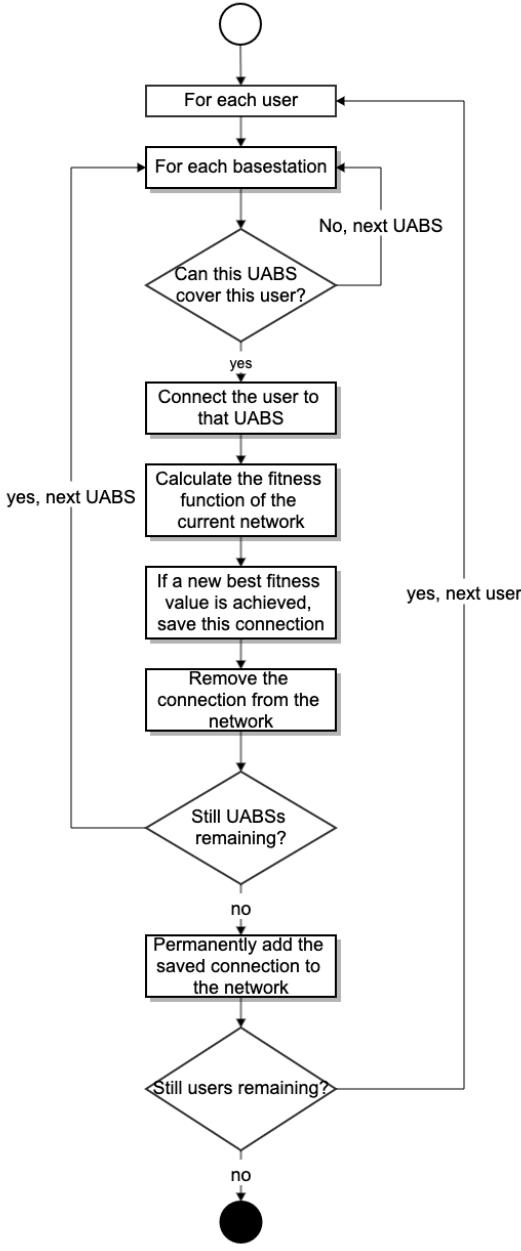


Fig. 5: Flowchart of the decision algorithm.

en drones. Hierna doorloopt het algoritme elke gebruiker waarbij getracht wordt deze te verbinden met elke mogelijke UABS. Deze verbinding is niet altijd mogelijk omdat een UABS al reeds ver zadigd kan zijn met andere gebruikers of de UABS is zo ver verwijderd van deze gebruiker dat de UABS de maximale toegestane zendvermogen zou overschreiden. Indien een verbinding toch mogelijk is, zal de gebruiker met deze UABS verbonden worden en zal een score toegekend worden met behulp van de fitness functie uit vergelijking 9. Dit proces wordt herhaald voor elke UABS. Uitsluitend de verbinding die resulteert in de beste score voor het volledige netwerk zal gebruikt worden. Op deze manier zal elke gebruiker de beste oplossing krijgen vanuit de huidige toestand van het netwerk. Met andere

woorden, elke gebruiker wordt geoptimaliseerd en niet het netwerk zelf. Er wordt echter wel aangenomen dat op deze manier het gemiddelde netwerk zelf ook optimaal zal zijn. Wanneer de laatste gebruiker behandeld is geweest, bekomen we een volledig netwerk voor een ongelimiteerd aantal drones. Het netwerk wordt vervolgens terug aan het hoofdalgoritme gegeven voor eventuele verdere afhandeling. Een stroomdiagram van dit algoritme is gegeven in fig. 5.

IV. Scenario's

De standaard configuratie is gegeven in tabel II en is van toepassing in elk scenario tenzij anders vermeld door de restricties van dat specifieke scenario.

Mobiel netwerk

technologie	LTE
frequentie	2.6 GHz
Power offset (P_{pusch})	-120 dBm
Compenstatie voor padverlies (α)	1
Correctie waarde	0 dBm
Aantal resource blokken	100

Drone

Energie van de drone	13.0 A
Gemiddelde snelheid	12.0 m/s
Gemiddeld energieverbruik	17.33 Ah
Voltage batterij	22.2 V

Femtocell antenna

Maximum P_{tx}	33 dBm
Richting van de antenne	neerwaarts
Zendversterking	4 dBm
Kabelverlies	2 dBm
Implementatieverlies	0 dBm
Stralingspatroon	EIRP or microstrip patch
Vlieghoogte	100m

UE Antenna

Hoogte	1.5m vanaf de vloer
Zendversterking	0 dBm
Kabelverlies	0 dBm
Stralingspatroon	EIRP
Aantal aanwezig in het netwerk	224

TABEL II: Overzicht van de waarden voor een standaard configuratie.

Drie scenario's zullen onderzocht worden. Het eerste zal één enkele gebruiker en één enkele drone overwegen voor het gehele netwerk. De SAT, elektromagnetische straling, energieverbruik en het nodige zendvermogen van de antenne zullen onderzocht worden voor verschillende vlieghoogtes.

Bij het tweede scenario zal het netwerk uitgebred worden met meerdere gebruikers maar er zal nog steeds uitsluitend één drone aanwezig zijn. De eerste onderzochte parameter is een varierende vlieghoogte gaande van 20 meter tot 200 meter. Hierbij zullen 224 gebruikers uniform verdeeld worden over het centrum van Gent. Dit is de gemiddelde populatiegrootte op een werkdag om 17 uur in

Gent [18]. De tweede parameter is een varierende populatie lopend van 50 tot 600 gebruikers. Hierbij zal de vlieghoogte vastgezet worden op 100 meter [18]. Het energieverbruik, elektromagnetische straling en SAT zullen onderzocht worden.

Een derde scenario is sterk gelijkend aan het vorige. Dezelfde twee parameters zullen onderzocht worden maar nu voor een onbeperkt aantal UABS's.

Vier configuraties zijn mogelijk voor elke onderzochte parameter in elk scenario. Er zijn namelijk twee antennes, een isotrope antenne en een microstrip patch antenne die beide kunnen opereren in een PwrC. Opt. netwerk en een Exp. Opt. netwerk. Dit maakt een totaal van 4 configuraties. Een overzicht is gegeven in fig. 6.

Het is belangrijk om op te merken dat alle meetwaarden strikt gelimiteerd zijn tot de hiervoor vermoende bronnen en bijgevolg enkel dataverkeer overwegen tussen de gebruiker zijn apparaat en de UABS. Andere bronnen zoals connecties naar het backhaul netwerk of andere technologieën zullen niet overwogen worden.

Antenna type	Optimization strategy	
	Exposure optimized	Power consumption optimized
Equivalent isotropic radiator	EIRP Exp Opt	EIRP PwrC Opt
Microstrip patch antenna	Microstrip Exp Opt	Microstrip PwrC Opt

Fig. 6: Matrix met de vier mogelijke configuraties.

V. Resultaten

Vier configuraties zullen overwogen worden tijdens het evalueren van twee parameters, zijnde populatiegrootte en vlieghoogte. Deze parameters zullen onderzocht worden in drie scenario's door het gedrag van het energieverbruik, elektromagnetische straling en SAT-waarden te monitoren. De elektromagnetische straling en SAT zullen genomen worden van de gewogen gemiddelde gebruiker met behulp van vergelijking 10 waarbij w_1 en w_2 gelijk gesteld zijn aan 50%. Elk resultaat wordt uitgemiddeld over 20 simulaties.

A. Eén gebruiker en één UABS

De resultaten tonen aan dat voor een variabele vlieghoogte, een logaritmische relatie bestaat tussen de P_{tx} en de vlieghoogte. Dit komt door de logaritmische schaal waarin de decibels van de P_{tx} in zijn uitgedrukt. Elke keer dat de vlieghoogte te hoog wordt, neemt de P_{tx} met één dBm toe. Voor een standaard configuratie met een maximum P_{tx} van 33 dBm en een line of sight (LoS) verbinding kan een UABS tot 387 m hoogte vliegen zonder het verliezen van deze verbinding.

Dit scenario is onderzocht voor een microstrip patch antenne die energieverbruik minimaliseert. De gekozen optimalisatie maakt echter niet uit aangezien er uitsluitend één UABS beschikbaar is. Het beslissingsalgoritme bepaalt welke gebruiker met welke UABS verbonden wordt. Aangezien er maar een UABS beschikbaar is, zullen beide opti-

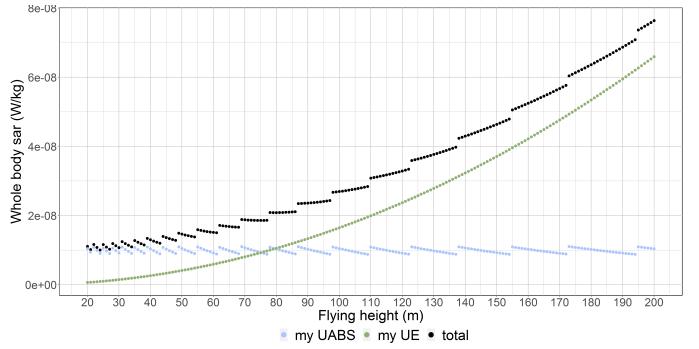


Fig. 7: Deze figuur toont hoe SAT-waarden van verschillende bronnen beïnvloed worden door een variabele vlieghoogte.

malisatie technieken gelijkaardig werken. Verder zal de gebruikte antenne ook geen verschil maken. De gebruiker zal zich namelijk boor beide antennes in de hoofdstraal van het stralingspatroon bevinden waar voor beide antennes geen verzwakking van het signaal is.

Tijdens het onderzoeken van verschillende vlieghoogtes stellen de resultaten vast dat UL straling exponentieel toeneemt terwijl de DL straling constant blijft rond 10 nW/kg zoals te zien is in fig. 7. De reden dat de DL straling constant blijft is vanwege power control die ervoor zorgt dat niet meer energie gebruikt wordt dan strikt noodzakelijk. Daardoor kan bevestigd worden dat de elektromagnetische straling een constante fractie is van energie en afstand. De UL straling start laag met 1 nW/kg maar steekt de DL straling voorbij rond de 80 meter.

B. Toenemende populatie met één UABS

B.1 Variabel vlieghoogte

Een PwrC. Opt. heeft een hogere elektromagnetische blootstelling in vergelijking met een Exp. Opt. netwerk; een fenomeen dat reeds werd vastgesteld bij [10]. Uit de resultaten van dit scenario blijkt echter dat een PwrC. Opt. niet noodzakelijk resulteert in een lager energieverbruik. Zo blijkt dat bij 100 m in een EIRP Exp. Opt. netwerk de elektromagnetische straling van de gewogen gemiddelde gebruiker 1.5 mV/m minder zal zijn maar dat het energieverbruik met 20 mW zal toenemen. Om dit te verstaan dient het algoritme eerst uitgelegd te worden. Een PwrC. Opt. netwerk zal resulteren in enkele UABS's met een hoog energieverbruik omdat het toenemen van de P_{tx} van de antenne minder energie kost dan het activeren van een nieuwe UABS. Op dezelfde manier zal een Exp. Opt. netwerk meer UABS's gebruiken met een laag energieverbruik waardoor ook de elektromagnetische straling minder zal zijn. Wanneer slechts een beperkt aantal UABS's beschikbaar is, zoals maar één in dit netwerk, zullen enkel de UABS's gebruikt worden die de meeste mensen behandelen. Aangezien het energieverbruik van een individuele UABS hoger is in een PwrC. Opt. netwerk en er uitsluitend één UABS beschikbaar is in elke configuratie, zal het energieverbruik in een PwrC. Opt. netwerk vaak hoger lig-

gen.

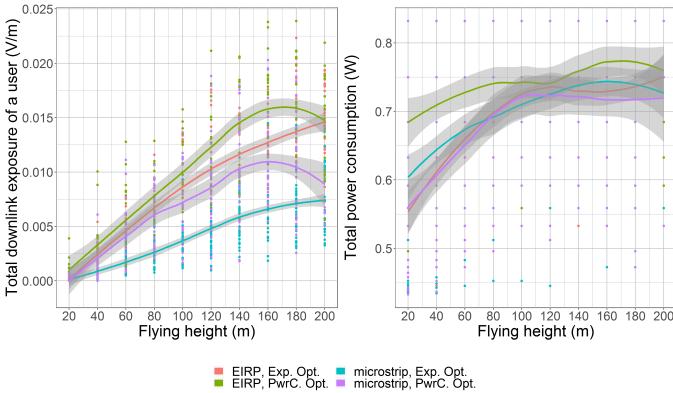


Fig. 8: Fig. (a) toont hoe de vlieghoogte beïnvloed wordt door DL elektromagnetische straling van de gewogen gemiddelde gebruiker en fig. (b) toont het En energieverbruik van het volledige netwerk wanneer een enkele drone beschikbaar is.

Verder toont fig. 8 hoe de elektromagnetische blootstelling toeneemt wanneer de vlieghoogte hoger wordt. Dit komt omdat de waarschijnlijkheid op een non line of sight (NLoS) afneemt. Dit leidt eveneens ook tot een hogere dekkingsgraad. Wanneer de vlieghoogte toeneemt van 20 tot 100 m zal de dekkingsgraad met 1% tot 2% voor alle configuraties toenemen. Deze toename in elektromagnetische straling is echter niet ongelimiteerd. Een microstrip PwrC. Opt. is op zijn hoogste punt rond 162 m en een EIRP PwrC. Opt. is op zijn hoogste punt rond 195 m. De wederafname van elektromagnetische straling start later voor Exp. Opt. netwerken en bevindt zich buiten de onderzochte vlieghoogtes. Deze wederafname is niet veroorzaakt door gebouwen maar door de grotere afstand in het algemeen.

Fig. 9 toont de SAR_{10g}^{wb} van de gewogen gemiddelde gebruiker voor elke individuele bron. De resultaten stellen vast dat de SAR^{myUABS} dezelfde curve toont als deze van de elektromagnetische straling in fig. 8.a. Dit komt omdat vergelijking 6 de elektromagnetische straling converteert naar SAT door het te vermenigvuldigen met een constante. Gedurende de gehele tijd is de SAR^{myUABS} de meest dominante factor gevuld door de straling van de gebruiker zijn eigen mobiel apparaat. Straling komende van andere personen hun mobiel apparaat heeft amper invloed. Als voorbeeld, bij een vlieghoogte van 140 m en een EIRP PwrC. Opt. netwerk zal de gewogen gemiddelde gebruiker een SAT van 2.1 nW/kg ondervinden van de UABS en rond 0.2 nW/kg van zijn eigen apparaat. De blootstelling van andere mobiele apparaten kan verwaarloosd worden met een elektromagnetische straling van slecht 0.03 pW/kg . Dit is een lage maar plausibele waarde aangezien de meeste mensen niet gedekt zijn en daardoor zelf geen straling veroorzaken.

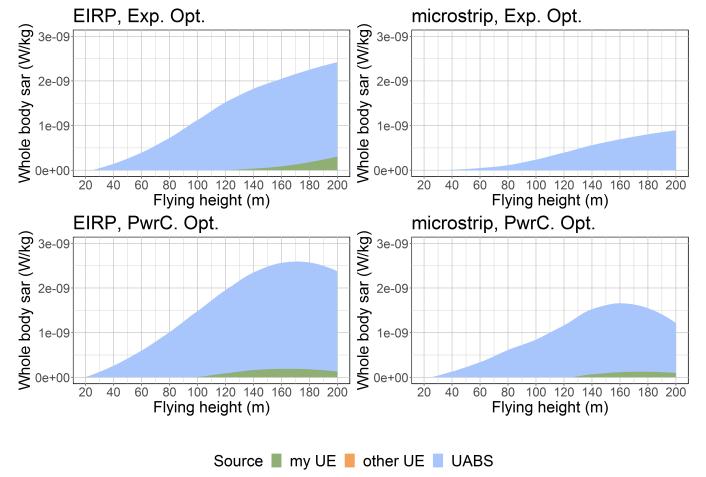


Fig. 9: Elke grafiek komt overeen met een specifieke configuratie en toont hoe de SAT van verschillende bronnen beïnvloed wordt door een toenemende vlieghoogte.

B.2 Variabel aantal gebruikers

Het aantal gedeakte gebruikers neemt lineair toe met het aantal personen aanwezig in het netwerk zoals getoond wordt in fig. 10.b. Het toont hoe een isotrope antenne in staat is om meer personen te behandelen in vergelijking tot een eenvoudige microstrip patch antenne. Eveneens is een energiezuinig netwerk in staat om meer mensen te behandelen dan een netwerk dat elektromagnetische straling minimaliseert. Bijvoorbeeld met 600 gebruikers zullen 5 tot 7 personen extra behandeld kunnen worden wanneer een microstrip patch antenne vervangen wordt door een isotrope antenne. Door van een Exp. Opt. netwerk naar een PwrC. Opt. netwerk te gaan, kan er één extra persoon behandeld worden.

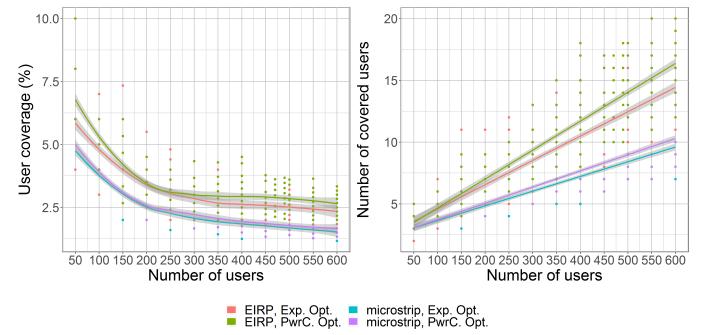


Fig. 10: De invloed van de populatiengrootte op de dekkingsgraad.

Fig. 11.a geeft de elektromagnetische blootstelling van de gewogen gemiddelde gebruiker weer bij verschillende populatiengroottes terwijl 11.b het energieverbruik weergeeft voor al deze populatiengroottes. Fig. 11.a is beïnvloed door fig. 10.a. De elektromagnetische straling neemt af wanneer minder gebruikers behandeld worden. Bijvoorbeeld, in een EIRP PwrC. Opt. netwerk met 50 gebruikers

heeft 6,75% dekking wat overeenkomt met een gewogen gemiddelde blootstelling van 18 mV/m . Dit terwijl 600 gebruikers met een dekking van 2,75% maar 9 mV/m heeft. Verder is fig. 11.b rechtstreeks beïnvloed door fig. 10.b. Wanneer de UABS meer mensen behandelt, neemt de kans op gebruikers met een ietwat slechter padverlies toe. De UABS zal dit probleem oplossen door het energieverbruik toe te laten nemen. Een toenemende populatie van 50 naar 600 gebruikers zal het energieverbruik tussen 0,05 en 0,1 W verhogen. Voor dit scenario is geen duidelijk verschil te merken tussen energieverbruik van de vier verschillende configuraties.

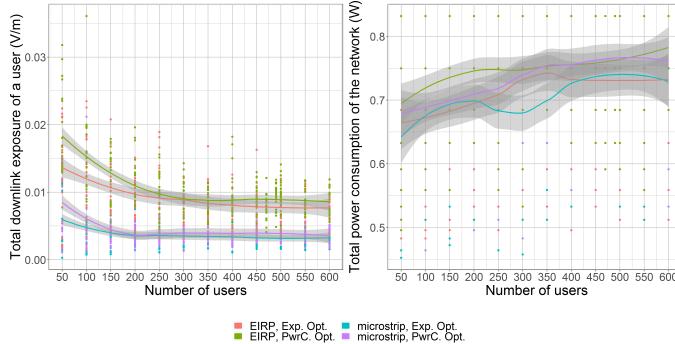


Fig. 11: Deze twee figuren tonen hoe de verschillende populatiesgroottes invloed hebben op de DL elektromagnetische straling (fig. a) en het energieverbruik (fig. b).

De SAT komende van de gebruiker zijn eigen apparaat is gemiddeld nul aangezien de meeste gebruikers niet behandeld worden. Fig. 12 toont de elektromagnetische blootstelling van de gedekte gebruiker die zich onmiddellijk onder de UABS bevindt. Het eerste scenario toont hoe de SAT van de gebruiker zijn eigen mobiel apparaat enkel beïnvloed wordt door de vlieghoogte. Dit wordt ook bevestigd door de resultaten in fig. 12 waar een constante SAR^{myUE} van $0.15 \mu\text{W/kg}$ gemeten wordt. De SAT van de UABS ondervindt een kleine toename van $0,005 \mu\text{W/kg}$.

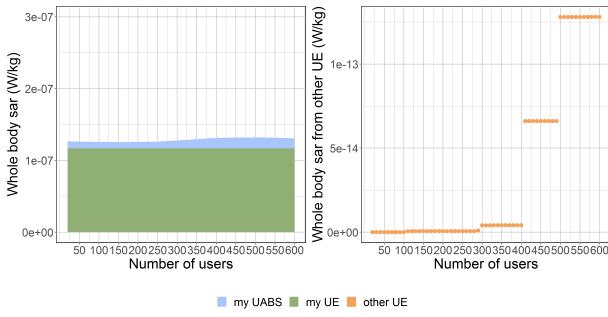


Fig. 12: SAR-waarden voor de gebruiker die zich onder de UABS bevindt.

Wanneer de populatie toeneemt, zullen meer gebruikers dichtbij de UABS terechtkomen. De UABS zal waarschijnlijk beslissen om deze gebruiker ook te behandelen zoals

zichtbaar is in fig. 13. Het is mogelijk dat deze gebruiker een slechter padverlies heeft door gebouwen of een ietwat grotere afstand. Hierdoor zal de DL SAT van de gebruiker onder de drone toenemen. De elektromagnetische straling van andere personen hun mobiel apparaat is heel laag zoals reeds vermeld en is daarom apart toegevoegd in fig. 12.b. De figuur toont hoe de SAT van andere mobiele apparaten toeneemt van nul tot $0,15 \mu\text{W/kg}$.

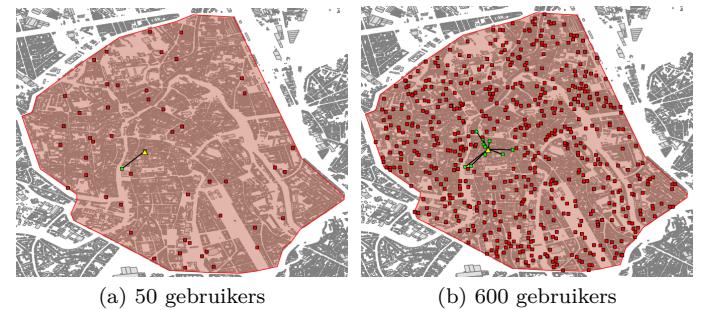


Fig. 13: Overzicht van welke gebruikers die verbonden zijn met de UABS.

C. Ongelimiteerd aantal UABS's

C.1 Variabel vlieghoogte

Hetzelfde scenario als in de voorgaande sectie wordt hier onderzocht. Enkel is er hier een ongelimiteerd aantal UABS's beschikbaar. De resultaten bewijzen dat de verschillende optimalisatiestrategieën werken zoals bedoeld. Een PwrC. Opt. netwerk heeft inderdaad een lager energieverbruik maar dit komt ten koste van een hogere elektromagnetische straling. Aan de andere kant zal een Exp. Opt. netwerk de elektromagnetische blootstelling reduceren door meer drones te gebruiken waardoor tevens het energieverbruik zal toenemen. Deze conclusie werd reeds gemaakt in [10] en is bevestigd door deze resultaten. Bijvoorbeeld bij het vergelijken van beide optimalisatiestrategieën zal, voor dezelfde isotrope antenne en dezelfde standaard vlieghoogte, een energieuwig netwerk 51 W verbruiken en de gebruikers blootstellen aan 15 mV/m . Terwijl optimaliseren naar elektromagnetische straling de blootstelling zal laten zakken naar 11.5 mV/m ten koste van een hoger energieverbruik van 54 W .

De elektromagnetische blootstelling in fig. 14 toont een logaritmische toename bij een Exp. Opt. netwerk terwijl een PwrC. Opt. netwerk eerder een concaaf verband met de vlieghoogte weergeeft waarbij het laagste punt zich op 70 meter bevindt.

Fig. 15.a toont aan dat een optimale dekking van 90% bereikt wordt bij een lagere vlieghoogte van 40 m. Hier is echter een nadeel aan verbonden. Fig. 15.b toont dat het aantal vereiste drones toeneemt wanneer de vlieghoogte lager wordt; een vaststelling die reeds gemaakt is in [18]. Bijvoorbeeld, een microstrip Exp. Opt. netwerk en een EIRP PwrC. Opt. netwerk vereisen respectievelijk 84 en 64 drones op een vlieghoogte van 200 m wat respectievelijk

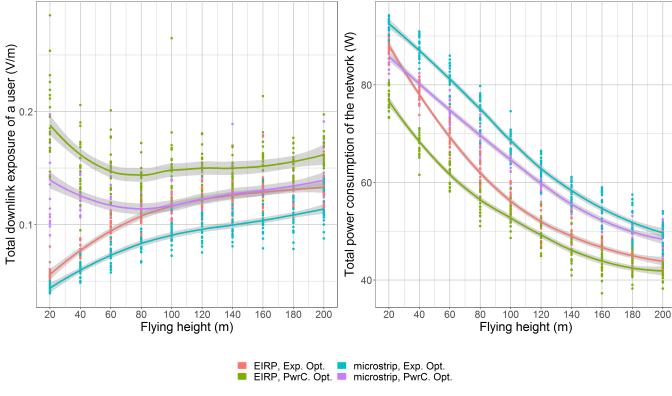


Fig. 14: Deze twee figuren tonen hoe de vlieghoogte invloed heeft op de DL elektromagnetische straling (fig. a) en het energieverbruik (fig. b).

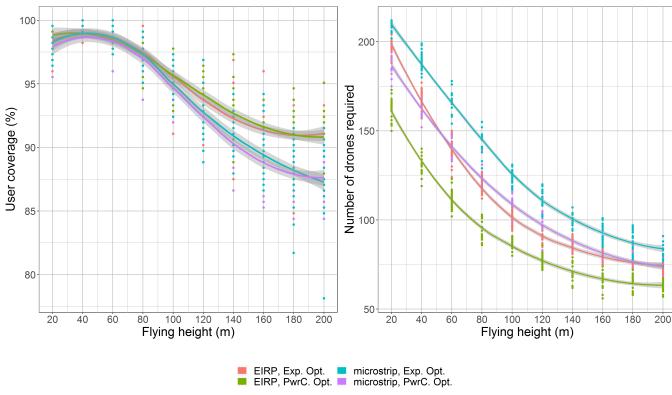


Fig. 15: Deze grafiek toont hoeveel drones vereist zijn op verschillende vlieghoogtes terwijl er getracht wordt om 100% dekking te bereiken.

toeneemt naar 211 en 162 drones bij een lagere vlieghoogte van 20 m.

Fig. 16 toont de bijdrage van elke bron aan de totale SAT. Het eerste gevolg van de vlieghoogte te laten toename van 20 naar 200 m is de SAT van de gebruiker zijn eigen apparaat die toeneemt tussen 89 en 141 nW/kg; een gedrag dat reeds geconstateerd werd in het eerste scenario. Fig. 16 toont aan dat de vlieghoogte hoger wordt dan de NLoS van de gebouwen rond 70 tot 80 meter. Hierna blijft de SAR^{myUABS} min of meer gelijk voor alle configuraties. Voor een microstrip PwrC. Opt. netwerk is dit rond 160 nW/kg. Een microstrip Exp. Opt. en EIRP PwrC. Opt. netwerk is gemiddeld 98 nW/kg en de EIRP Exp. Opt. netwerk bevindt zich rond 47 nW/kg. Deze hogere vlieghoogtes zullen tevens resulteren in een toegenomen elektromagnetische straling van andere UABS's. Wanneer de vlieghoogte toeneemt van 20 tot 200 m zal de $SAR^{otherUABS}$ tussen 115 en 140 nW/kg voor EIRP antennes bedragen en tussen 54 en 74 nW/kg voor microstrip patch antennes. Dit voor beide optimalisatiestrategieën.

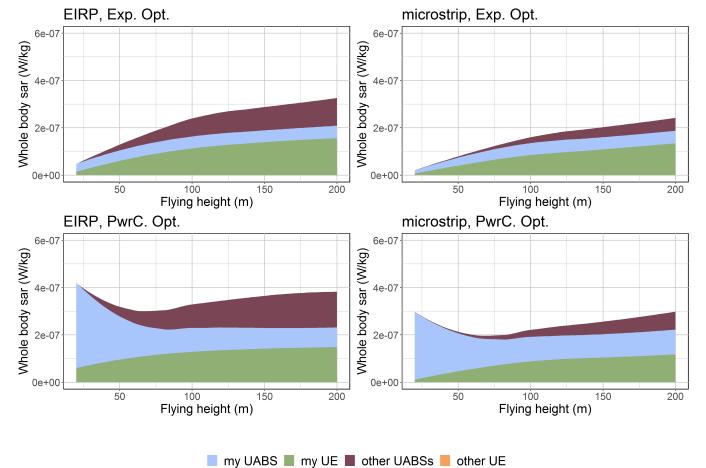


Fig. 16: Elke grafiek komt overeen met één van de vier mogelijke configuraties. De bijdrage van elke bron aan de totale SAT is voor een variërende vlieghoogte.

C.2 Variabel aantal gebruikers

De tweede onderzochte parameter van dit scenario is een variërende populatiegrootte terwijl de vlieghoogte zich op 100 m zal bevinden. Fig. 17.a toont hoe de tool tracht 100% dekking te bereiken. Voor slechts 50 personen zal de gemiddelde dekking rond 93% bevinden terwijl een netwerk van 600 personen een dekking van 97% heeft. Fig. 17.b toont aan dat meer UABS's vereist zijn voor grotere populaties. Het verschil in optimalisatiestrategie is miniem voor kleine netwerken maar neemt snel toe. Wanneer de populatie groeit van 50 tot 600 gebruikers zullen 200 UABS's extra vereist zijn bij een microstrip Exp. Opt. netwerk, rond 130 extra UABS's voor een EIRP Exp. Opt. netwerk of een microstrip PwrC. Opt. netwerk en 110 extra UABS's voor een EIRP PwrC. Opt. netwerk. Dit is een verwacht gedrag wanneer er gekeken wordt naar Scenario II, waarbij het percentage van behandelde gebruikers afnam voor grotere populaties.

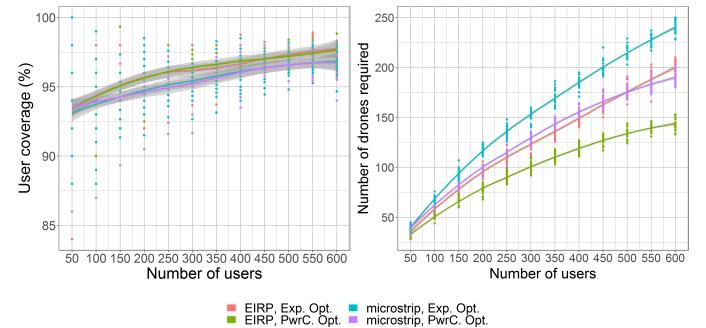


Fig. 17: Deze grafiek toont hoeveel drones vereist zijn op verschillende vlieghoogtes terwijl er getracht wordt een een dekking van 100% te hebben.

Fig. 18 toont aan dat de elektromagnetische straling en het energieverbruik toenemen voor grotere populaties wat

normaal is aangezien meer UABS's gebruikt worden. Wanneer de populatie toeneemt van 50 naar 600 gebruikers zal de elektromagnetische straling toenemen tussen 80 en 130 mV/m , afhankelijk van de configuratie. Het energieverbruik bij 50 gebruikers is voor alle configuraties rond 20 W . Eenmaal de populatie is toegenomen naar 600 gebruikers zal dit voor een microstrip Exp. Opt. netwerk 130 W bedragen, 115 W voor een microstrip PwrC. Opt. netwerk, 102 W voor een EIRP Exp. Opt. netwerk en 92 W voor een EIRP PwrC. Opt. netwerk.

Dat het beslissingsalgoritme werkt zoals bedoeld, werd reeds duidelijk in de voorgaande subsectie maar wordt ook hier bevestigd. Wanneer beide optimalisatiestrategieën vergeleken worden, blijkt dat een energieuwig netwerk ongeveer 5 W minder energie nodig heeft maar hierdoor de gebruikers wel blootstelt aan 27 mV/m tot 30 mV/m meer ten opzichte van Exp. Opt. netwerk. Verder zal een isotrope antenne ook meer elektromagnetische straling veroorzaken voor minder energie in vergelijking met een microstrip patch antenne. Wanneer beide antennes vergeleken worden voor 224 gebruikers blijkt dat de isotrope antenne de gemiddelde gebruiker tussen 25 mV/m tot 27 mV/m extra zal blootstellen terwijl het gemiddeld 12 W minder zal nodig hebben in vergelijking met de microstrip patch antenne.

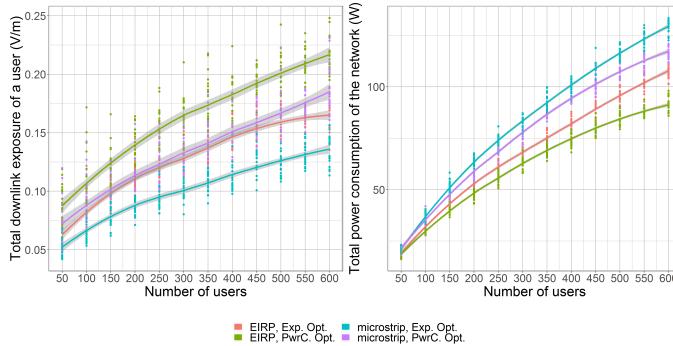


Fig. 18: De invloed van de populatiegrootte op de DL elektromagnetische straling (a) en energieverbruik (b).

Fig. 19 stelt de SAT van de gewogen gemiddelde gebruiker voor en toont aan hoe de SAT van de gebruiker zijn eigen mobiele apparaat zo goed als constant is. De vlieghoogte is namelijk altijd dezelfde waardoor ook de energie die nodig is om de afstand te overbruggen gelijk blijft. Voor beide optimalisatiestrategieën zal de SAR^{myUE} voor netwerken met isotrope antennes variëren rond 1.1 $\mu W/kg$ en rond 0.7 $\mu W/kg$ voor netwerken met een microstrip patch antenne. De SAR^{myUABS} neemt nauwelijks toe in een Exp. Opt. netwerk en bevindt zich rond 0.5 $\mu W/kg$ voor beide antennes. Een energieuwig netwerk start ook rond 0.5 $\mu W/kg$ maar neemt toe wanneer meer mensen online komen. Dit is normaal aangezien deze UABS's trachten om meer mensen te behandelen. Hierdoor zal de SAR^{myUABS} voor 600 gebruikers toenemen tot 1 $\mu W/kg$ voor een isotrope antenne en tot wel 2 $\mu W/kg$ voor een microstrip patch antenne. De SAT-waarde neemt het meeste toe bij

$SAR^{otherUABS}$ die heel laag start rond minder dan 0.1 $\mu W/kg$ voor 50 gebruikers in alle configuraties. Deze SAT neemt echter snel toe. De grootste toename wordt waargenomen in een EIRP PwrC. Opt. netwerk waarbij 3 $\mu W/kg$ gemeten wordt voor 600 gebruikers. De $SAR^{otherUE}$ neemt het minste toe in een microstrip Exp. Opt. met slechts 1 $\mu W/kg$ voor 600 gebruikers.

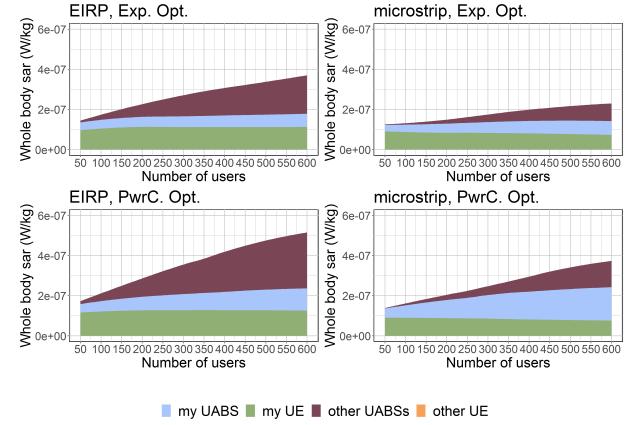


Fig. 19: Elke grafiek komt overeen met een specifieke configuratie en toont aan hoe de SAT van verschillende bronnen beïnvloed wordt door een toenemende populatie.

VI. Conclusie

Een capacity-based deployment tool is gebruikt voor het onderzoeken van de SAT van gebruikers die geoptimaliseerd zijn naar DL elektromagnetische straling en totaal energieverbruik. Dit is onderzocht voor verschillende vlieghoogtes, populatiegroottes en aantal beschikbare UABS's. De resultaten bevestigen de vaststellingen uit [10] waarbij elektromagnetische straling en totaal energieverbruik leiden tot tegenstrijdige vereisten. De voorgestelde fitness functie werkt zoals bedoeld. Voor een netwerk met standaard configuratie kan de elektromagnetische straling in een energieuwig netwerk gereduceerd worden tot wel 23% voor isotrope antennes en 30% voor microstrip patch antennes door te optimaliseren naar elektromagnetische straling. Hierdoor zal het bereik van de UABS afnemen en zullen meer UABS's nodig zijn. Gemiddeld gaat het om 18 extra drones die tot 5 W extra energieconsumptie leiden.

Een directionele microstrip patch antenne wordt geïntroduceerd omdat het verschillende voordelen biedt in vergelijking met een omnidirectionele antenne. Directionele antennes zijn in staat om hun energie te richten waar het nodig is, namelijk de grond. Een microstrip patch antenne is verder dun en heeft een licht gewicht. Deze antenne, met een openingshoek van 90°, veroorzaakt minder elektromagnetische blootstelling, een lager bereik en vereist meer energie. Voor een netwerk met standaard configuratie kan de microstrip patch antenne de elektromagnetische straling van een isotrope antenne tussen 30% en 34% reduceren. Dit zal het energieverbruik met 11 W doen toenemen.

Figuur 20 toont een overzicht gebaseerd op de resulta-

ten van de twee optimalisatiestrategieën en de twee soorten antennes. Opmerkelijk is dat de EIRP Exp. Opt. netwerk zich gelijkaardig gedraagt als een microstrip patch antenne in een PwrC. Opt. netwerk. Hierdoor wordt een microstrip patch antenne in een energiezuinig netwerk aangeraden. De microstrip patch antenne zal minder elektromagnetische straling veroorzaken dankzij het design. Verder zal het optimaliseren naar energieverbruik ervoor zorgen dat minder drones nodig zullen zijn. Een microstrip patch antenne met een openingshoek van 90° is verondersteld een goede oplossing te zijn maar als het budget beperkt is, kan een antenne met een grotere openingshoek een geschikt alternatief vormen om kosten verder te reduceren zonder de limieten opgelegd door de Vlaamse overheid te overschreiden. De SAT van de configuratie met de meeste blootstelling is nog steeds een honderduizendste van de maximale toegestane SAT voor het volledige lichaam.

Figuur 21 geeft een overzicht van de SAT-bijdrage in percentages ten opzichte van de totale SAT. De waarden zijn uitgemiddeld over de vier overwogen configuraties. De gebruiker wordt voornamelijk blootgesteld aan zijn eigen mobiel apparaat met 52% van de totale elektromagnetische blootstelling. Deze conclusie werd reeds gemaakt door de auteurs van [13] en [39]. Verder wordt er in [39] ook geconcludeerd dat, dankzij power control, de elektromagnetische straling van het mobiele apparaat heel dicht komt bij de blootstelling van de UABS. Dit wordt ook bevestigd door deze resultaten. Figuur 21 toont aan dat de elektromagnetische straling van alle andere UABS's gezamenlijk de 48% omvat waarvan 15% komt van de UABS die deze gebruiker aan het behandelen is. De elektromagnetische blootstelling van mobiele apparaten die tot andere mensen behoren is verwaarloosbaar in tegenstelling tot de veel grotere blootstelling komende van alle andere bronnen en draagt slechts 0.0001% bij aan de totale blootstelling.

De resultaten tonen verder aan dat energieverbruik en elektromagnetische straling toenemen wanneer meer mensen aanwezig zijn in het netwerk. Wanneer de populatie toeneemt van 50 naar 600 gebruikers zal de elektromagnetische straling tussen 80 en 130 mV/m toenemen afhankelijk van de configuratie. Het energieverbruik neemt toe met 110 W voor alle configuraties. De bron die het meest beïnvloed wordt door het aantal gebruikers is de SAT van andere UABS's en neemt toe tussen de 1en3 $\mu\text{W}/\text{kg}$. Verder heeft de vlieghoogte een positief effect op het aantal

Antenna type	Optimization strategy		High electromagnetic exposure Low power consumption
	Exposure optimized	Power consumption optimized	
Equivalent isotropic radiator	EIRP Exp Opt	EIRP PwrC Opt	
Microstrip patch antenna	Microstrip Exp Opt	Microstrip PwrC Opt	Low electromagnetic exposure High power consumption (many drones)

Fig. 20: Matrix met de vier mogelijke configuraties. Gekleurd op basis van de resultaten.

nodige drones die op hun beurt een positief effect hebben op het energieverbruik. Wanneer de vlieghoogte toeneemt van 20 m naar 200 m, neemt het aantal drones af met 59%. Deze afname werd ook vastgesteld in [18]. Ook de auteurs van [13] concludeerden dat elektromagnetische straling afneemt wanneer het padverlies minder wordt. De elektromagnetische straling van de UABS's blijven min of meer gelijk voor alle vlieghoogtes tussen 80 en 200 meter. Meeste UABS's zijn in LoS en dankzij power control zullen deze niet meer energie verbruiken dan strikt noodzakelijk. De elektromagnetische straling van de gebruiker zijn eigen apparaten neemt echter wel toe om de hoog vliegende drones te kunnen bereiken. Rond 80 meter zal de straling van de gebruiker zijn eigen apparaat de straling van de behandelde UABS voorbijsteken. Wanneer meerdere UABS beschikbaar zijn in het netwerk, zal de blootstelling van andere UABS's toenemen naarmate de vlieghoogte toeneemt. Dit komt omdat bij hogere vlieghoogtes steeds meer UABS's in LoS komen. De vlieghoogte laten toenemen van 20 naar 200 m zal de SAT van andere UABS's tussen 46 en 49 keer groter maken voor een isotrope antenne en tussen 70 en 85 keer groter voor een microstrip patch antenne. Wanneer ook de resultaten van [19] overwogen worden waarbij een vlieghoogte van 80 meter voorgesteld wordt als optimale vlieghoogte voor optimaal bereik en bacheloor verbindingen zal ook hier de vlieghoogte van 80 meter voorgesteld worden voor het stadscentrum van Gent.

Tot besluit wordt een microstrip patch antenne met een openingshoek van 90° als geschikt startpunt beschouwd. Deze directionele antenne focust de elektromagnetische straling daar waar het nodig is. en reduceert hierdoor ongewenste zijwaardse straling. Het wordt aangeraden om de antenne toe te passen in een netwerk dat energieverbruik minimaliseert omdat hierbij minder drones nodig zijn en daardoor goedkoper is. De optimale vlieghoogte voor het stadscentrum in Gent bevindt zich rond 80 meter. Lagere vlieghoogtes vereisen veel meer drones terwijl hogere vlieghoogtes de elektromagnetische straling laten toenemen.

Voor toekomstig onderzoek kunnen nog extra parameters onderzocht worden. Verschillende Physical Uplink Shared

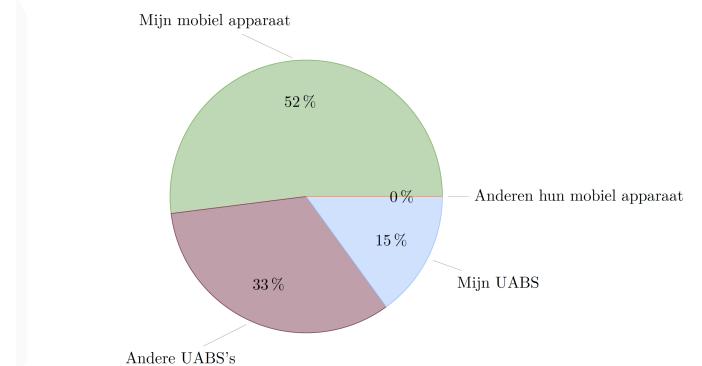


Fig. 21: Bijdrage van elke bron aan de totale SAR waaraan de gemiddelde gebruiker blootgesteld is. De percentages zijn uitgemiddeld over de vier overwogen configuraties.

Channel (PUSCH)-waarden worden verondersteld om een grote invloed te hebben op de UL straling en ook de blootstelling van backhaul verbindingen moeten nog overwogen worden. Verder is de tool klaar om MiMo en massive MiMo te ondersteunen aangezien de tool eenvoudig uitgebreid kan worden om meer complexe stralingspatronen zoals beamforming te ondersteunen. Als laatste is er ook nog ruimte om de tijdscomplexiteit van het programma te verbeteren door het exacte algoritme te vervangen door heuristische methodes.

Dankwoord

Ik wens de onderzoeksgroep WAVES van de Universiteit Gent te bedanken voor het beschikbaar stellen van hun capacity based deployment tool om zo dit onderzoek mogelijk te maken.

Referenties

- [1] “Base overschreed stralingsnormen na aanslagen,” De standaard, 2016.
- [2] L. Hardell and C. Sage, “Biological effects from electromagnetic field exposure and public exposure standards,” *Biomedicine and Pharmacotherapy*, vol. 62, no. 2, pp. 104 – 109, 2008.
- [3] “What are electromagnetic fields.” <https://www.who.int/peh-emf/about/WhatisEMF/en/index1.html>. Accessed: 15-10-2019.
- [4] “Elektromagnetische velden en gezondheid: Uw wegwijzer in het elektromagnetische landschap,” Federale overheidsdienst: volksgezondheid, veiligheid van de voedselketen en leefmilieu, vol. 5, 2014.
- [5] A. Ahlbom, U. Bergqvist, J. Bernhardt, J. Cesarini, M. Grandolfo, M. Hietanen, A. Mckinlay, M. Repacholi, D. H. Sliney, J. A. Stolwijk, et al., “Guidelines for limiting exposure to time-varying electric, magnetic, and electromagnetic fields (up to 300 ghz),” *Health physics*, vol. 74, no. 4, pp. 494–521, 1998.
- [6] “Normen zendantennes.” <https://omgeving.vlaanderen.be/normen-zendantennes>. Accessed: 19-03-2020.
- [7] E. Commission, “Council recommendation of 12 july 1999 on the limitation of exposure of the general public to electromagnetic fields (0 hz to 300 ghz),” *Official Journal of the European Communities*, vol. 59, 1999.
- [8] “Wireless devices.” <https://www.health.belgium.be/en/wireless-devices>. Accessed: 13-05-2020.
- [9] D. Plets, W. Joseph, K. Vanhecke, and L. Martens, “Exposure optimization in indoor wireless networks by heuristic network planning,” *Progress In Electromagnetics Research*, vol. 139, pp. 445–478, 01 2013.
- [10] M. Deruyck, E. Tanghe, D. Plets, L. Martens, and W. Joseph, “Optimizing lte wireless access networks towards power consumption and electromagnetic exposure of human beings,” *Computer Networks*, vol. 94, 12 2015.
- [11] D. Plets, W. Joseph, S. Aerts, K. Vanhecke, G. Vermeeren, and L. Martens, “Prediction and comparison of downlink electric-field and uplink localised sar values for realistic indoor wireless planning,” *Radiation Protection Dosimetry*, vol. 162, no. 4, pp. 487–498, 2014.
- [12] D. Plets, W. Joseph, K. Vanhecke, and L. Martens, “Downlink electric-field and uplink sar prediction algorithm in indoor wireless network planner,” in *The 8th European Conference on Antennas and Propagation (EuCAP 2014)*, pp. 2457–2461, IEEE, 2014.
- [13] S. Kuehn, S. Pfeifer, B. Kochali, and N. Kuster, “Modelling of total exposure in hypothetical 5g mobile networks for varied topologies and user scenarios,” Final Report of Project CRR-816, Available on line at: <https://tinyurl.com/r6z2gqn>, 2019.
- [14] D. Plets, W. Joseph, K. Vanhecke, G. Vermeeren, J. Wiart, S. Aerts, N. Varsier, and L. Martens, “Joint minimization of uplink and downlink whole-body exposure dose in indoor wireless networks,” *BioMed research international*, vol. 2015, 2015.
- [15] Y. Zeng, Q. Wu, and R. Zhang, “Accessing from the sky: A tutorial on uav communications for 5g and beyond,” *Proceedings of the IEEE*, vol. 107, no. 12, pp. 2327–2375, 2019.
- [16] Y. Kawamoto, H. Nishiyama, N. Kato, F. Ono, and R. Miura, “Toward future unmanned aerial vehicle networks: Architecture, resource allocation and field experiments,” *IEEE Wireless Communications*, vol. 26, no. 1, pp. 94–99, 2018.
- [17] R. Gangula, O. Esrafilian, D. Gesbert, C. Roux, F. Kaltenberger, and R. Knopp, “Flying robots: First results on an autonomous uav-based lte relay using open airinterface,” in *2018 IEEE 19th International Workshop on Signal Processing Advances in Wireless Communications (SPAWC)*, pp. 1–5, IEEE, 2018.
- [18] M. Deruyck, J. Wyckmans, W. Joseph, and L. Martens, “Designing uav-aided emergency networks for large-scale disaster scenarios,” *EURASIP Journal on Wireless Communications and Networking*, vol. 2018, 12 2018.
- [19] G. Castellanos, M. Deruyck, L. Martens, and W. Joseph, “Performance evaluation of direct-link backhaul for uav-aided emergency networks,” *Sensors*, vol. 19, no. 15, p. 3342, 2019.
- [20] M. Mozaffari, W. Saad, M. Bennis, Y.-H. Nam, and M. Debbah, “A tutorial on uavs for wireless networks: Applications, challenges, and open problems,” *IEEE communications surveys & tutorials*, vol. 21, no. 3, pp. 2334–2360, 2019.
- [21] Q. Wu, L. Liu, and R. Zhang, “Fundamental trade-offs in communication and trajectory design for uav-enabled wireless network,” *IEEE Wireless Communications*, vol. 26, no. 1, pp. 36–44, 2019.
- [22] M. Deruyck, A. Marri, S. Mignardi, L. Martens, W. Joseph, and R. Verdome, “Performance evaluation of the dynamic trajectory design for an unmanned aerial base station in a single frequency network,” in *2017 IEEE 28th Annual International Symposium on Personal, Indoor, and Mobile Radio Communications (PIMRC)*, pp. 1–7, IEEE, 2017.
- [23] A. V. Savkin and H. Huang, “Deployment of unmanned aerial vehicle base stations for optimal quality of coverage,” *IEEE Wireless Communications Letters*, vol. 8, no. 1, pp. 321–324, 2018.
- [24] H. Huang and A. V. Savkin, “A method for optimized deployment of unmanned aerial vehicles for maximum coverage and minimum interference in cellular networks,” *IEEE Transactions on Industrial Informatics*, vol. 15, no. 5, pp. 2638–2647, 2018.
- [25] C. T. Cicek, H. Gultekin, B. Tavli, and H. Yanikomeroglu, “Uav base station location optimization for next generation wireless networks: Overview and future research directions,” in *2019 1st International Conference on Unmanned Vehicle Systems-Oman (UVS)*, pp. 1–6, IEEE, 2019.
- [26] A. Rizwan, D. Biswas, and V. Ramachandra, “Impact of uav structure on antenna radiation patterns at different frequencies,” in *2017 IEEE International Conference on Antenna Innovations & Modern Technologies for Ground, Aircraft and Satellite Applications (iAIM)*, pp. 1–5, IEEE, 2017.
- [27] M. Nosrati, A. Jafargholi, and N. Tavassolian, “A broadband blade dipole antenna for uav applications,” in *2016 IEEE International Symposium on Antennas and Propagation (APSURSI)*, pp. 1777–1778, IEEE, 2016.
- [28] M. Nosrati, A. Jafargholi, R. Pazoki, and N. Tavassolian, “Broadband slotted blade dipole antenna for airborne uav applications,” *IEEE Transactions on Antennas and Propagation*, vol. 66, no. 8, pp. 3857–3864, 2018.
- [29] B. A. Arand, R. Shamsaei, and B. Yektakhan, “Design and fabrication of a broadband blade monopole antenna operating in 30 mhz–600 mhz frequency band,” in *2013 21st Iranian Conference on Electrical Engineering (ICEE)*, pp. 1–3, IEEE, 2013.
- [30] L. Akhoondzadeh-Asl, J. Hill, J.-J. Laurin, and M. Riel, “Novel low profile wideband monopole antenna for avionics applications,” *IEEE transactions on antennas and propagation*, vol. 61, no. 11, pp. 5766–5770, 2013.
- [31] S. S. Siddiq, G. Karthikeya, T. Tanjavur, and N. Agnihotri, “Microstrip dual band millimeter-wave antenna array for uav applications,” in *2016 21st International Conference on Microwave, Radar and Wireless Communications (MIKON)*, pp. 1–4, IEEE, 2016.
- [32] Y. Zheng, J. Zhou, W. Wang, and M. Chen, “A low-profile broadband circularly polarized antenna array for uav ground-to-air communication,” in *2018 IEEE Asia-Pacific Conference on Antennas and Propagation (APCAP)*, pp. 219–220, IEEE, 2018.
- [33] X. Sun, R. Blázquez-García, A. García-Tejero, J. M. Fernández-González, M. Burgos-García, and M. Sierra-Castañer, “Circular array antenna tor uav-uav communications,” in *2017 11th European Conference on Antennas and Propagation (EUCAP)*, pp. 2025–2028, IEEE, 2017.

- [34] I. Singh and V. Tripathi, "Micro strip patch antenna and its applications: a survey," *Int. J. Comp. Tech. Appl.*, vol. 2, no. 5, pp. 1595–1599, 2011.
- [35] K. Kashwan, V. Rajeshkumar, T. Gunasekaran, and K. S. Kumar, "Design and characterization of pin fed microstrip patch antennae," in 2011 Eighth International Conference on Fuzzy Systems and Knowledge Discovery (FSKD), vol. 4, pp. 2258–2262, IEEE, 2011.
- [36] R. Mullner, C. F. Ball, K. Ivanov, J. Lienhart, and P. Hric, "Contrasting open-loop and closed-loop power control performance in utram lte uplink by ue trace analysis," in 2009 IEEE International Conference on Communications, pp. 1–6, IEEE, 2009.
- [37] M. Lauridsen, A. R. Jensen, and P. Mogensen, "Reducing lte uplink transmission energy by allocating resources," in 2011 IEEE Vehicular Technology Conference (VTC Fall), pp. 1–5, 2011.
- [38] A. Sudarsan and A. Prabhu, "Design and development of microstrip patch antenna," *International Journal of Antennas (JANT)* Vol, vol. 3, 2017.
- [39] A. Gati, E. Conil, M.-F. Wong, and J. Wiart, "Duality between uplink local and downlink whole-body exposures in operating networks," *IEEE transactions on electromagnetic compatibility*, vol. 52, no. 4, pp. 829–836, 2010.

Contents

List of Figures	ii
List of Tables	iii
List of Listings	iv
1 Introduction	1
1.1 Outline of the Issue	1
1.2 Objective	2
1.3 Outline	4
2 State of the Art	5
2.1 Electromagnetic Exposure	5
2.1.1 Electromagnetic Field Radiation	5
2.1.2 Specific Absorption Rate	6
2.1.3 Related Work	7
2.2 Optimized UAV-aided networks	8
2.3 Technologies	9
2.3.1 Type of Drone	9
2.3.2 Long Term Evolution	10

2.3.3	Type of Antennae	11
2.4	Summary	14
3	Methodology	15
3.1	Electromagnetic Exposure	15
3.1.1	Calculation of the Total Specific Absorption Rate	15
3.1.2	Electromagnetic Exposure Caused by Far-Field Radiation	17
3.1.3	Electromagnetic Exposure Caused by Near-Field Radiation	20
3.2	Microstrip Patch Antenna	22
3.2.1	Design of a Microstrip Patch Antenna	22
3.2.2	Radiation Pattern	24
3.3	Optimizing the Network	26
3.4	Simulation Tool	28
3.4.1	Implementation of the Deployment Tool	28
3.4.2	Implementation of the Radiation Pattern	31
3.4.3	Performance Improvement	33
3.5	Summary	35
4	Scenarios	36
4.1	Scenario I: A Single User	38
4.2	Scenario II: Increasing Traffic with only one Drone available	40
4.3	Scenario III: Increasing Traffic with an Undefined Amount of Drones	42
4.4	Overview of Configurations	43
5	Results and Discussion	44

5.1	Scenario I: One User and One Unmanned Aerial Vehicle (UAV)	45
5.1.1	The Influence of the Maximum Transmission Power	45
5.1.2	Influence of the Flying Height	46
5.2	Scenario II: Increased Population	48
5.2.1	Influence of the Flying Altitude	48
5.2.2	Influence of the Number of Users	53
5.3	Scenario III: Unlimited UAVs	58
5.3.1	Influence of the Flying Altitude	58
5.3.2	Influence of the Number of Users	62
5.4	Summary	65
6	Conclusions	66
6.1	Conclusion	66
6.2	Summary	70
6.3	Future work	70
Appendices		71
A	Radiation Patterns: Datasheet	72
B	Radiation patterns: Example Configuration	74

List of Figures

1.1	This illustration shows how a UAV-aided network is able to either assist or replace existing transmission towers.	2
2.1	Resource allocation scheme for FDD.	11
2.2	Resource allocation scheme for TDD.	11
2.3	General design of a microstrip antenna.	12
2.4	Image of a microstrip patch antenna attached to the bottom of a UAV.	13
3.1	Illustration of the radiation affecting the average user (here shown in the center) by different types of sources.	16
3.2	Distribution of how many phones belong to a certain SAR interval. Upper boundary not included.	21
3.3	Design of the microstrip patch antenna.	24
3.4	Radiation pattern 1 (in dBi) with the configuration as described above.	26
3.5	Radiation pattern 2 (in dBi) which is generated with a groundplane of 0.06m by 0.06m.	26
3.6	Example of how users are randomly distributed over the city centre of Ghent.	28
3.7	Flowchart of the main algorithm.	29
3.8	Flowchart of the decision algorithm.	30
3.9	Illustration of the two possible movements. The UAV in fig. (a) is a top view while the UAV in fig. (b) is a side view.	31

3.10	Schematic example of slices in a radiation pattern.	32
3.11	Schematic example of how bilinear interpolation works.	33
3.12	Example of a KD-tree in two dimensions.	34
3.13	Distribution of how many connections belong to a certain interval of distance. Upper boundaries are not included.	35
4.1	The red area covers the city centre of Ghent, Belgium.	37
4.2	Illustration of an example network that satisfies the restrictions of Scenario I. . .	39
4.3	Location of ‘Koningin Maria Hendrikaplein’ on the town planning map of Ghent	39
4.4	Illustration of an example network that satisfies the restrictions of Scenario II. .	41
4.5	Illustration of an example network according to the description of Scenario III. .	42
5.1	Minimal required transmission power by the antenna to reach the ground just below it. The red line shows the default maximum transmission power.	46
5.2	This figure shows how SAR values from different sources are influenced by different flying altitudes.	47
5.3	This figure shows the behaviour of the power consumption over the entire network at different flying heights. For this scenario, the power is used by only one UABS.	48
5.4	Example of an EIRP power consuption optimized network (PwrC Opt) network with only one UABS (yellow triangle). Only a very few users (green) are con- nected. All other users (red) remain uncovered.	49
5.5	Fig. (a) show how the flying height influences the downlink electromagnetic radiation of the average user and fig. (b) the power consumption of the entire network for the only UABS available in the network.	50
5.6	Schematic overview of Scenario II with only 2 users.	50
5.7	Scenario II with only 2 users. The coloured areas are only applicable for the red user. The blue user is connected during the entire time.	51
5.8	This graph shows the percentage of covered users for only one UABS at different flying heights.	52

5.9	Each figure corresponds with a certain configuration and shows how the SAR from different sources are influenced by an increasing flying height.	53
5.10	The influence of increasing traffic on the user coverage.	54
5.11	These two figures show how various sizes of population influence the downlink electromagnetic radiation of the average user (left) and power consumption of the entire network (rights) for one UABS available in the network.	55
5.12	This figure shows how different sources are influenced by an increasing number of users.	56
5.13	Overview of which users are connected to the UABS.	57
5.14	SAR-values for the user who is directly beneath the only UABS available.	57
5.15	Example of two networks with users distributed over the area. Yellow triangles represent UABSs and are connected with black lines to users in green. Uncovered users are coloured in red.	58
5.16	These two figures show how the flying height influences the downlink electromagnetic radiation of the average user (left) and power consumption of the entire network (right) for an unlimited number of drones.	59
5.17	This graph shows how much UAVs are required at different flying heights while trying to achieve a 100% coverage.	60
5.18	Each figure corresponds with a certain configuration and shows how the SAR from different sources are influenced by an increasing flying height.	62
5.19	This graph shows how much UAVs are required for different flying heights while trying to achieve a 100% coverage.	63
5.20	The influence of the population size on the downlink electromagnetic radiation (a) and power consumption (b).	64
5.21	Each figure shows the SAR from different sources for an increasing population size. .	65
6.1	The contribution of each source towards the total SAR for each considered configuration. The values are achieved with default values.	67
6.2	Matrix with the four possible configurations, colour-coded based on the results. .	68

6.3 Contribution from each source towards the total SAR that is experienced by the weighted average user. The percentages are averaged over the four considered configurations.	69
---	----

List of Tables

2.1	Overview of the different SAR limitations.	6
2.2	Specifications of the used drone.	10
3.1	Overview of the configuration parameters.	23
4.1	Overview of default configuration values.	38
4.2	Evaluated parameters	40
4.3	Restrictions	40
4.4	Evaluated parameters	41
4.5	Restrictions	42
4.6	Evaluated parameters	43
4.7	Matrix with the four possible configurations	43
A.1	Overview of attenuation in dBm.	73

List of Listings

1	Matlab code to generate the radiation patterns for the microstrip patch antenna.	25
2	Example configuration of a radiation pattern.	75

1

Introduction

This chapter gives a general introduction to the subject. First, the problem with classic terrestrial networks is explained and illustrated with some examples. Thereafter, the research questions that are believed to give a solution to this problem are discussed. Finally, an overview of the entire document is given.

1.1 Outline of the Issue

Society is constantly getting more and more dependent on wireless communication. On any given moment, in any given location, an electronic device can request to connect to the bigger network. Devices need more than ever to be connected, starting from small Internet of Things (IoT) up to self-driving cars which all need to be supported by the existing infrastructure. It is not surprising that the city centre of Ghent has an average coverage of 97% of 4G over all telecom operators [?]. Once again it becomes clear why we're on the eve of a new generation of cellular communication named 5G.

Also in exceptional and possibly life-threatening situations, the public relies on the cellular network. In 2011, Pukkelpop, a yearly festival in Belgium, got struck by a severe storm. However the storm was quite short, the damage was done, including the mobile network which remained

defective for the rest of the evening [?]. One solution for a fast temporarily deployable network is with the usage of UAVs. Base stations can be attached to these flying UAVs to support the damaged network over a limited area. This approach does not only come in handy for damaged networks but also in case of an unexpected increase of traffic. For example during the terrorist attacks at Brussels Airport, mobile network operators saw all telecommunications drastically increasing causing moments of contention. Some operators even decided to temporarily exceed the exposure limits in order to handle all connections [?]. This is illustrated in figure 1.1. Electromagnetic exposure can however not be neglected. Research shows how excessive electromagnetic radiation can cause diverse biological side effects [?]. Because of increasing public concern [?], the World Health Organization (WHO) had launched a large multidisciplinary research effort which eventually concluded that there was no sufficient evidence that confirmed that exposure to low level electromagnetic fields is harmful [?]. A large part of the population remains nevertheless very concerned about potential health risks [?]. It becomes clear that electromagnetic exposure is a key value when designing a UAV-aided network and should definitely not surpass the predefined limits.

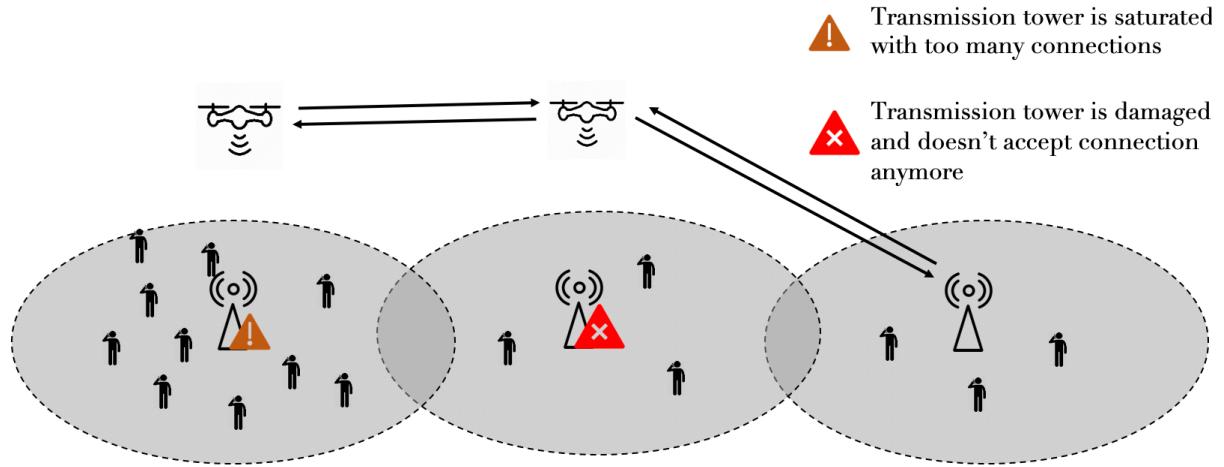


Figure 1.1: This illustration shows how a UAV-aided network is able to either assist or replace existing transmission towers.

1.2 Objective

UAV-aided networks can, thanks to their mobility, easily be repositioned towards a certain goal. Several papers in literature exist, explaining how a network can be optimized towards different goals like power consumption. However, very limited research has been done where a UAV-aided network is optimized towards electromagnetic exposure. While several publications exist, discussing how the electromagnetic exposure can be calculated, most of them only consider a

limited number of sources like only base stations or only mobile phones. Papers who cover electromagnetic exposure from all the different sources and convert it into a single value are rather limited.

This master dissertation proposes a method to optimize the network towards electromagnetic exposure and power consumption when considering all four sources of radiation in a telecommunications network, being: the user's own phone, the base station that is serving this user, all devices from other users in the network and all other active base stations that are not serving this user. In this way, the contribution of each source towards the total electromagnetic exposure can easily be identified.

The behaviour of the electromagnetic exposure and power consumption of the network will be analysed by applying the tool in different scenarios to give insight into which variables influence the exposure and how the network can be optimized accordingly. Further, also the difference between omnidirectional and directional antennae will be considered. This leads to the following research questions:

Research question 1: How can a UAV-aided network be optimized to minimize electromagnetic exposure of the user and overall power consumption? What are the effects on the network?

Research question 2: How does the network behave differently after the introduction of a realistic antenna?

Research question 3: How does the Unmanned Arial Base Station (UABS) flying height and number of users influence electromagnetic exposure and power consumption?

Research question 4: What is the contribution of each source towards the total electromagnetic exposure?

To make this research possible, an existing planning tool is extended which gives insight in user and base station distributions. The tool also calculates information about path loss between radiators, power usage of the different electrical devices and which base station serves which user. In other words, the tool describes a fully configured UABS based access network. In this way, all needed parameters will be known.

1.3 Outline

This section briefly describes the structure of this document. Related research to the subject is discussed in chapter 2, where the State of the Art explains electromagnetic exposure and its absorption into the body. Also the used technology such as type of antennae, type of base station and which infrastructure will be examined. The chapter also discusses why this master dissertation differs from other research documents. Thereafter, chapter 4 talks about the different scenarios that will be investigated. Each scenario has different restrictions and consists of various configurations where different parameters will be evaluated. Eventually, the methodology is covered in chapter 3, where the calculations and implementation of the different aspects discussed in the State of the Art are presented. Chapter 5 shows the results of this implementation for the scenarios described in chapter 4. Finally, a conclusion and its results is formed in chapter 6 including future research trends.

2

State of the Art

This chapter gives an overview of related research that has been done in the field of work and aims to familiarize the reader with the subject. First, an overview of the legislation related to electromagnetic exposure and specific absorption rate is given after which the related work about electromagnetic exposure is discussed. The second section describes how UAV-networks are designed and how they can be optimized. Finally, the used technologies are summed up including the type of drone, the characteristics of the cellular network and the type of antennae that are often used for this type of applications.

2.1 Electromagnetic Exposure

2.1.1 Electromagnetic Field Radiation

People in wireless telecommunication networks are exposed to far-field electromagnetic radiation originating from base stations and other User Equipment (UE). Network planners need to make sure that the electromagnetic fields (expressed in V/m) do not exceed location dependent limitations enforced by the government. These limits are location dependent. The European Union (EU) recommends the guidelines as defined by the International Commission on Non-Ionizing Radiation Protection (ICNIRP) which limit electromagnetic exposure to 61 V/m. Each Euro-

pean country needs to decide for themselves which limitations to enforce. Belgium for example delegated this responsibility to Flanders, Brussels and Wallonia [?]. In order to have a comparable scenario, this study will be focused in the city center of Ghent. Therefore, the standards will be defined by the Flemish government, which state that in the 2.6 GHz frequency band, an individual antenna cannot exceed 4.5 V/m and the cumulative sum of all fixed sources has its maximum at 31 V/m [?, ?].

2.1.2 Specific Absorption Rate

The Specific Absorption Rate (SAR) represents the rate at which electromagnetic energy is absorbed by human tissue with the thermal effect as its most important health consequence. The volume of this tissue is typically 1 g (SAR_{1g}) or 10 g (SAR_{10g}). SAR values can be categorized based on the covered area. As an example, the whole body SAR (SAR^{wb}) is defined as the average radiation over the entire body while localized SAR-values only cover a certain part of the human body like the head. The ICNIRP has concluded that the threshold effect for SAR_{10g}^{wb} is at 4 W/kg meaning that any higher absorption rate would overwhelm the thermoregulatory capacity of the human body [?, ?]. Whole body SAR-values between 1 and 4 W/kg increase the temperature of the human body less than 1°C, which is proven not to be harmful for a healthy human being [?, ?]. Thereafter, a safety factor of 50 for the public [?] is used to tackle unknown variables like experimental errors, increased sensitivity for certain population groups and so on. The EU follows the recommendation from the ICNIRP [?] and suggests a whole body SAR_{10g} of 0.08 W/kg and 2 W/kg for localized SAR_{10g} at head and torso area [?, ?]. The first metric is applicable for UE and the second one for transmission towers [?]. Belgium follows this recommendation [?, ?]. The Federal Communications Commission (FCC) of the United States of America (USA) follows the recommendations of the Institute of Electrical and Electronics Engineers (IEEE) Std C95.1-1999 [?, ?] that defines regulations based on 1 g tissue. The SAR_{1g}^{wb} is therefore defined at 1.6 W/kg despite the fact that this value has been reviewed and changed by the IEEE to 8 W/kg in Std C95.1-2005 [?]. An overview is given in table 2.1.

Description	Value	Units
Max SAR_{10g}^{wb} (defined by ICNIRP)	4	W/kg
Max SAR_{10g}^{wb} for transmission towers (defined by the Belgian government)	0.08	W/kg
Max SAR_{10g} for UE at head area (defined by the Belgian government)	2	W/kg
Max SAR_{1g} for UE at head area (defined by the FCC)	1.6	W/kg

Table 2.1: Overview of the different SAR limitations.

The actual maximum SAR-value of a phone is usually much lower. As an illustration, the iPhone 11 pro has a maximum SAR_{10g}^{head} of 0.99 W/kg [?] and a Samsung Galaxy S20 5G a SAR_{10g}^{head} of 0.376 W/Kg [?].

2.1.3 Related Work

The goal of this master dissertation is the investigation of electromagnetic exposure considering all sources. Four types of sources are considered: the user's own phone, the base station that is serving this user, all devices from other users in the network and all other active base stations that are not serving this user. This electromagnetic radiation is thereafter absorbed by the human body and will be expressed in SAR-values. Any other type or source of electromagnetic radiation like bluetooth, WiFi or backhaul connections will not be considered.

Several papers calculate exposure originating from certain sources, but very limited research has been done covering the whole picture. Plets et al. addresses in [?] the problem that electromagnetic exposure is often a neglected factor when designing a network. Therefore, they propose a heuristic indoor network planner aiming to optimize exposure and coverage in a WiFi network. They conclude that higher allowed exposure limits and more separation between the user and the access point have positive influence on the throughput. The authors of [?] used this knowledge to investigate electromagnetic exposure originating from base stations in a more outdoor environment and propose a capacity based deployment tool capable of optimizing towards electromagnetic exposure and power consumption in order to support future green networks. Plets et al. later extended their indoor network planner in [?] and [?] so that also uplink (UL) traffic from the user's device will be calculated. They did not only consider the electromagnetic radiation for Universal Mobile Telecommunications System (UMTS) and WiFi but also how much is absorbed by the body, which will be expressed as specific absorption rates. Since the authors only cover voice calls, uplink SAR is expressed in localized SAR values while the downlink traffic is expressed in whole body SAR. With the advent of 5G, paper [?] has been published, describing a guideline on how the total exposure of in a hypothetical 5G network has to be modelled and applies it to various scenarios. They discuss how localized SAR values are achieved from different sources including all mobile phones and all base stations. They conclude that the user's own device is the most important contributor to the total localized SAR. The exposure for unconnected users is mainly originating from bystanders instead of base stations. The exposure from these bystanders will be four times higher than from base stations. The authors also conclude that reducing the cell size has a positive influence on the exposure of active users by a factor 2 to 10. In short, they state that a network with a lower path loss, smaller cells and additional indoor coverage, helps to reduce total exposure. Finally, Plets et al. published in [?] how to minimize UL and downlink (DL) exposure dose for an indoor environment. They describe how both UL and DL traffic can be converted in whole body SAR values making it possible to achieve an overall picture. They conclude that a dose reduction of 75% can be achieved by increasing number of base stations and decreasing transmission power. Further, their optimization algorithm is able to reduce downlink doses for WiFi with more than 95%. The reduction for UMTS will vary between 73% and 83% and the dose reductions for

Long-Term Evolution (LTE) will be at least 80%. Thanks to power control, UMTS and LTE require an almost continuous uplink usage in order to see a significant effect by the optimization algorithm.

Research about SAR-values have not only been done in function of an entire network. Also various papers exist considering other scenarios. In this way, Mahfouz et al. performs an analysis on the total SAR from a mobile phone considering the fact that the device contains multiple antennae. They concluded that the localized SAR for the different configurations never exceeds the limit defined by the ICNIRP [?]. The authors of [?] performed a research on the SAR-values for the head area when the mobile phone is positioned in the near-field and far-field and concluded that a difference in SAR-values was measured between both scenarios. In [?] are the standardization efforts discussed to predict localized and whole body SAR of users in and around the car when an antenna is attached to the outside of the car. Piuzzi et al. investigates in [?] the SAR of numeric models. The model of the children is achieved by anatomically downscaling the adult. The results show that the whole body SAR is higher for the children and therefore conclude that while the SAR measured for an adult might comply with restrictions enforced by the government, it is not necessarily the case for children. In [?] is the problem raised that developing a numeric model, often used for SAR analysis, is a timely and costly process. Therefore, an equation is proposed to estimate whole body SAR when using a half-wave dipole. Further, it is important to note that UE is not necessarily a mobile phone. For example, the authors of [?] investigated the exposure of a user to a nearby smart metre and concluded that SAR was well below the guideline restrictions. As last, the authors from [?] explained the duality between UE and base stations and concluded that the exposure from UE will decrease when the received signal improves. They also noticed that the exposure from UABSSs in a Global System for Mobile Communications (GSM) network is below than from UE. However, this is not always the case. An UMTS network will, thanks to power control, drastically reduce the exposure from UE and will therefore sometimes even be equal to radiation from the base station.

In a realistic network, some users are calling while others are using other types of telecommunication services like browsing the web. Therefore, all absorbed electromagnetic exposure should be expressed in whole body SAR while still covering all sources.

2.2 Optimized UAV-aided networks

A UAV knows several applications. It was originally mainly used to support the military for surveillance and remote attacks without endangering pilots [?]. However, UAVs have recently become more accessible by the general public due to decreasing costs. This allowed UAVs to be researched for various applications.

When attaching an antenna to a UAV, it can be used as a gateway for cellular communication for UE on the ground. Such a flying base station will be called a UABS. This has several advantages like mobility and rapid deployment which is ideal for emergency situations or temporary events. Thanks to this mobility, UABSs can easily be repositioned to satisfy certain requirements. A UAV-aided network also brings some challenges with it like the limited weight of the payload and sparse power supply.

Kawamoto et al. introduced in [?] a WiFi network with the support of UAVs while considering resource allocation and antenna directivity. Gangula et al. illustrates in [?] how UAVs can be used as a relay for LTE. If a terrestrial base station is in non line of sight (NLoS) with a user, a UABS can be used as a relay. Zeng et al. proposes in [?] a tutorial in 5G-and-beyond wireless systems where challenges like energy consumption, mobility and antenna direction are discussed. Deruyck et al. designed in [?] a capacity based deployment tool for UAV-aided emergency networks for large-scale disaster scenarios where an ideal flying height of 100 m is suggested. This was expanded in [?] with a performance evaluation of the direct-link backhaul of this tool where a slightly lower flying height of 80 metres is recommended.

These UAV-aided networks can be optimized towards certain goals. Mozaffari et al. provides in [?] guidelines on how to optimize and analyse UAVs equipped for wireless communication equipment. Issues like deployment, performance and power consumption are addressed. A research area that has been excessively studied is the location solutions optimization problem. For instance, [?] provides an algorithm that minimizes latency, [?, ?] minimizes interference between UABS and [?] minimizes the distance between UABS and UE. Other papers investigate trajectory optimization like in [?, ?]. Further, [?, ?] discuss several implementation approaches on how optimization algorithms should be tackled by discussing options like heuristic algorithms, exact algorithms and machine learning.

Optimizing the network towards electromagnetic exposure is rather limited. For a terrestrial network, using traditional base stations, Deruyck et al. discusses in [?] how the network can be optimized towards either a minimal exposure or minimal power consumption of the entire network. However, to the best of the author knowledge, no research has been done where a UABS-network has been optimized towards electromagnetic exposure.

2.3 Technologies

2.3.1 Type of Drone

The type of UAV will have a major impact on the network performance. Two types of drones are considered in [?]: an off-the-shelf drone affordable by the general public and a more ro-

bust one. The results in [?] show that the second type will require less drones to cover the same number of users and will last longer in the air. The research in this paper will therefore be done with the usage of the second type. A technical overview of this drone is given in table 2.2.

Parameter	Value	Units
Carrier power	13.0	A
Average carrier speed	12.0	m/s
Average carrier power usage	17.33	Ah
Carrier battery voltage	22.2	V

Table 2.2: Specifications of the used drone.

2.3.2 Long Term Evolution

The tool makes use of LTE, by the general public better known as 4G. LTE allows better UL and DL data speeds compared to its predecessors and is based on an all IP architecture. This technology can cover macrocells supporting cell sizes ranging from 5 km up to 100 km. Macrocell antennae are usually used by transmission towers along highways or on top of buildings. LTE supports however also smaller cells like femtocells covering only a few hundred meters. These femtocell antennae are therefore more portable, require less energy and will not require a telecommunication operator because of their simplicity [?]. Femtocell base stations are therefore used by the deployment tool. Further, LTE also supports both Frequency Division Duplex (FDD) and Time Division Duplex (TDD).

FDD makes simultaneous UL and DL traffic possible by assigning different frequencies within the same frequency range to both data streams. A small guard band is used between the UL and DL direction in order to prevent interference. An illustration is given in fig 2.1.

TDD allows UL and DL traffic by splitting the time domain. Meaning that both traffic directions use the same frequency and therefore alternately (in time) use the same frequency. A small time interval is used to prevent interference in case of a slightly bad timed synchronization as illustrated in fig. 2.2

Since it is assumed in this master dissertation that the user is continuously exposed without interruption, FDD will be used throughout this document.

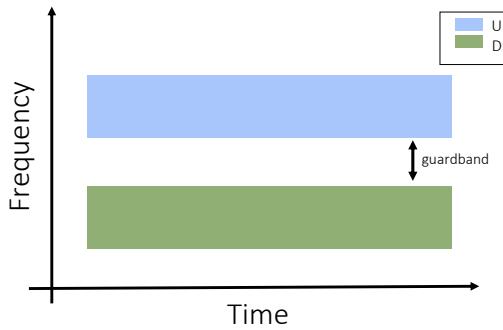


Figure 2.1: Resource allocation scheme for FDD.

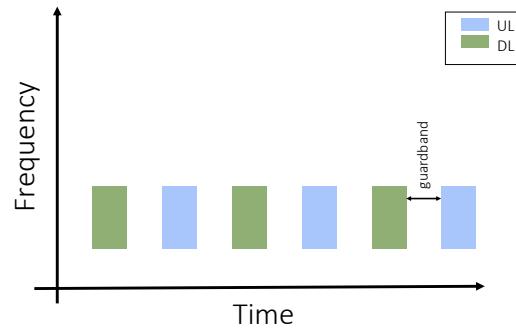


Figure 2.2: Resource allocation scheme for TDD.

2.3.3 Type of Antennae

The onboard antenna of the UAV will act as the gateway between the UE and the backhaul network. However, determining which antenna to use and how to position it, can be challenging.

Attaching an antenna to a UAV brings some additional challenges with it as explained by Rizwan et al. in [?]. Namely, the structure of the UAV can influence the radiation pattern. This can either have a constructive or destructive impact and depends on the relative position between the UAV and the antenna. When the antenna is too close to the UAV, the UAV can behave as a parasitic radiator, also emitting radiation. When using a directional antenna, the influence of the UAV will be much less but still existing, even when the UAV is not positioned in the direction of the mean beam. [?] suggest that this side-effect can be reduced by introducing a little offset between the antenna and the UAV. Another challenge that comes with attaching an antenna to a UAV is the need for 3D modelling of radiation patterns. In traditional terrestrial networks, the waves mainly propagated horizontally. When using UAVs, waves will have to travel rather downwards causing 2D antenna modelling to become insufficient. A 3D-model which accounts for both elevation and azimuth directivity will be required [?].

The easiest radiation pattern is a hypothetical equivalent isotropic radiator which radiates equally in all directions. Antennae that radiate equal quantities for a certain plane are called omnidirectional antennae [?] and several types exist. Attaching a conventional dipole antenna array might be low-cost, yet they are too high in profile and weight [?]. The authors of [?] and [?] both propose a broadband monopole blade antenna for UAV applications but this type suffers from a large surface which is a big disadvantage for the limited space available on the used UAVs in 2.3.1. [?, ?] propose a broadband blade dipole antenna which is much smaller. Their wing-shaped design allows good aerodynamics when flying. [?] proposes an alternative to blade antennae by presenting a wideband low profile monopole. The radiation pattern behaves

similar to a traditional monopole but has a reduced height.

Another type of antennae are directional antennae that take advantage of throughput, lower interference and battery life [?]. This is done by focussing the electromagnetic energy there where it is needed. One type of directional antennae that has been investigated excessively for UAV-usage are microstrip antennae since they provide several advantages compared to traditional antennae [?, ?]. Microstrip antennae are lightweight, low in cost and thin causing them to be more aerodynamic which is a useful feature since the antennae will be attached to UAVs. Zeng et al. proposes in [?] the use of such an antenna in a sunflower-shaped array configuration. Also the authors from [?] attach star-shaped millimetre wave antennae to the wings of a UAV and [?] uses circular patch antennae in a circular array configuration for communication between UAVs.

A basic microstrip antenna like the one presented in figure 2.3 consists of a ground plane and a radiating patch, both separated by a dielectric substrate. Several variations exist like microstrip patch antennae, microstrip slot antennae and printed dipole antennae which all have similar characteristics [?, ?]. They are all thin, support dual frequency operation and they all have the disadvantage that they will transmit at frequencies outside the aimed band. This is also known as spurious radiation. The microstrip patch and slot antenna support both linear and circular polarization while the printed dipole only supports linear polarization. Further, the fabrication of a microstrip patch antenna is considered to be the easiest of the considered patch antennae [?].

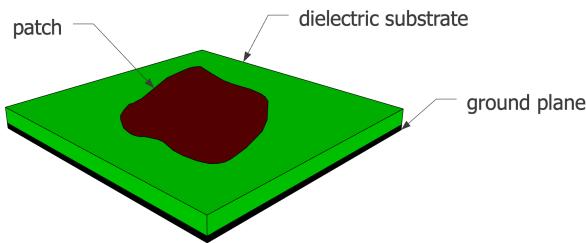


Figure 2.3: General design of a microstrip antenna.

The microstrip antenna requires besides the groundplane, dielectric substrate and the radiation patch also a feed line. Several feeding techniques exist of which the most popular are: coaxial probe feeding, microstrip line and aperture coupling.

A first feeding method is the usage of a coaxial cable where the outer conductor is attached to the ground plane and the inner conductor to the radiations patch. Modelling is however difficult, especially for thick substrates as will be used in this master dissertation. A second option is the usage of a microstrip line. This type of feeding is much easier to model since the microstrip line can be seen as en extension of the radiating patch. A disadvantage is the increased spurious radiation which limits bandwidth. A third is proximity coupling which has the largest bandwidth

and low spurious radiation. It consists however of two dielectric substrates causing the overall thickness of the antenna to increase as well as its fabrication difficulty [?].

The increasing usage of the microstrip patch antennae can be explained by its easy fabrication and lightweightness and therefore knows a widespread application in the military, global positioning systems, telemedicine, WiMAX applications and so on. The authors of [?] also state that some of the disadvantages like lower gain and power handling can be solved by using an array configuration.

The radiating patch is usually made of a thin layer of either gold or copper [?, ?] and can have any form. However, shapes other than circles or rectangles would require large numerical computation [?]. Thus, a simple rectangular shape will be used. Further, also the dielectric constant of the substrate is important. It typically varies between 2.2 and 12. Finding a good dielectric depends on how the antenna will be used. A lower dielectric constant with a thick substrate will result in better performance, better efficiency and larger bandwidths [?]. On the other hand, a larger dielectric constant reduces the dimensions of the antenna [?] which is also useful when attaching the antenna to a limited surface. Glass as a dielectric substrate with a constant of 4.4 will be used.

Figure 2.4 shows a microstrip patch antenna constructed out of an aluminium patch and a teflon substrate. The microstrip patch antenna is pointing towards the ground since the UAV will be flying above the user.

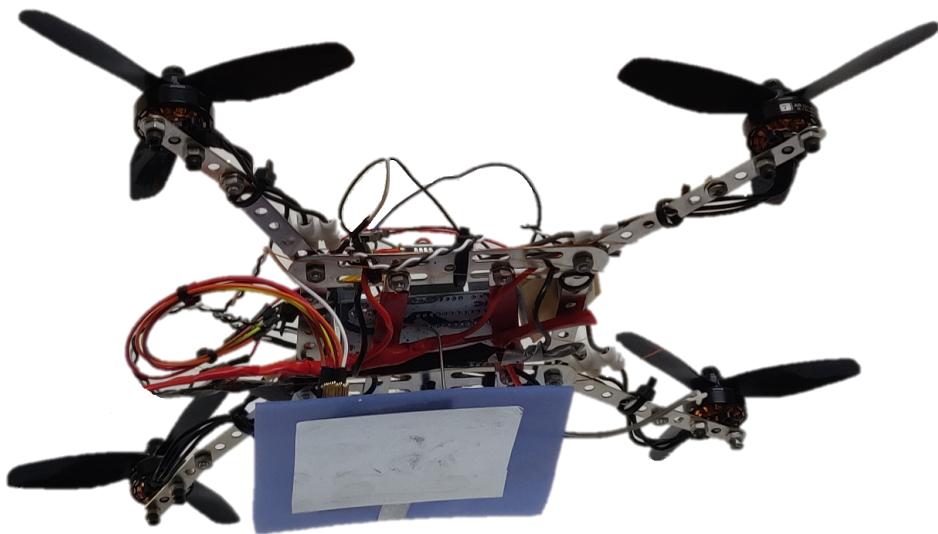


Figure 2.4: Image of a microstrip patch antenna attached to the bottom of a UAV.

2.4 Summary

In this chapter, related papers are discussed that perform research in the same field as well as the restrictions and guidelines by different organizations. First, legislations about electromagnetic exposure and specific absorption rates are discussed followed by giving an overview of related work. The whole body SAR from transmission towers in Belgium is limited to $0.08W/kg$. It turns out a lot of research has been performed about electromagnetic exposure but calculating whole body SAR considering all UE and all base stations is rather scarce. Secondly, related work about UAV-aided networks is presented. Various optimization strategies have been proposed in the past, including optimizing terrestrial networks towards electromagnetic radiation and power consumption. To the best of the author's knowledge, exposure and power consumption optimized for a UAV-aided networks remains unknown.

3

Methodology

The content of this chapter gives an answer to which steps that have to be taken to be able to answer the research questions. The first section explains how electromagnetic radiation is calculated for each source and how to convert these values to specific absorption rates. The second section gives a detailed overview of how a microstrip patch antenna can be designed and how its radiation pattern is achieved. The third section discusses how the network can be optimized towards either electromagnetic exposure or power consumption. The final section explains how these algorithms are implemented and how to further improve performance.

3.1 Electromagnetic Exposure

3.1.1 Calculation of the Total Specific Absorption Rate

The total whole body SAR ($SAR_{10g}^{wb,total}$) (expressed in W/kg) of a user can be calculated by a simple sum of individual SAR values from the different sources. Formula 3.1 was originally described in [?]. This formula assumes that the users are holding their device next to their ear and therefore investigates localized SAR for head and torso area. However for this case, this would result into incorrect conclusions since the position of the device relative to the user is unknown. The position of the phone can be next to the head but also in front of the user. The

induced electromagnetic radiation will therefore be expressed in function of the entire body.

$$SAR_{10g}^{wb,total} = SAR_{10g}^{wb,myUE} + SAR_{10g}^{wb,myUABS} + SAR_{10g}^{wb,otherUE} + SAR_{10g}^{wb,otherUABSs} \quad (3.1)$$

The first parameter, $SAR_{10g}^{wb,myUE}$, indicates the absorbed electromagnetic radiation by the whole body originating from the user's own device. Despite that the UL radiation is destined for the serving UABS, a portion of that radiation is directly absorbed by its user, due to the omnidirectional nature of the mobile's antenna. The second parameter, $SAR_{10g}^{wb,myUABS}$, represents the DL radiation caused by the UABS that is serving the user. As the third parameter, we have the $SAR_{10g}^{wb,otherUE}$ which is radiation caused by other people's devices. The radiation of these devices is once again destined for a specific UABS but again, a portion of that UL radiation will also be absorbed by our user. Finally, $SAR_{10g}^{wb,otherUABSs}$ represents the DL radiation by the other UABSs to which our user is exposed to but not served by. An illustration is given in figure 3.1. We can only speak in terms of SAR when the electromagnetic radiation is absorbed by the user. This last step is however not shown in the illustration.

The electromagnetic exposure to which people are exposed can be categorized in two groups. One of them is near-field radiation which is caused by the user's own device which is indicated with the green arrow in figure 3.1 and will be discussed in 3.1.3. The other arrows are a form of far-field radiation and will be explained in section 3.1.2. Examples of these types of radiators are UE which belong to other people and UABSs.

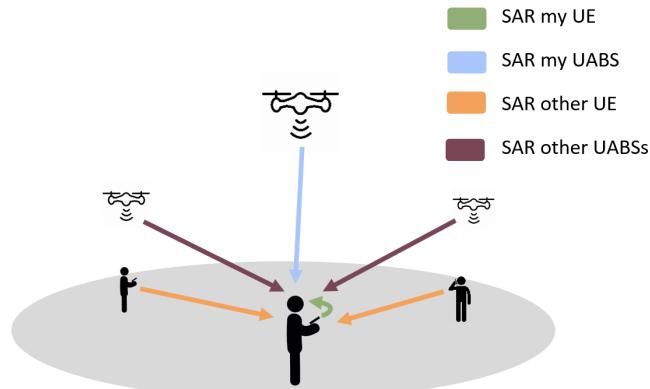


Figure 3.1: Illustration of the radiation affecting the average user (here shown in the center) by different types of sources.

3.1.2 Electromagnetic Exposure Caused by Far-Field Radiation

Electromagnetic Radiation from a Single Source

To determine the total exposure of a single human being or even of the entire network, the electric-field \vec{E} from a single radiator i should be calculated. The formula to determine this electromagnetic value E (expressed in V/m) for a specific location u is given in equation 3.2.

$$E_i(u)[V/m] = 10^{\frac{RRP(u)[dBm] - 43.15 + 20 \cdot \log(f[MHz]) - PL(u)[dB]}{20}} \quad (3.2)$$

Real radiation power and EIRP. In formula 3.2, as it was described in [?, ?], RRP was defined as equivalent isotropic radiation power (EIRP). EIRP is the radiation generated by an equivalent isotropic radiator which is a theoretical source of electromagnetic waves that radiate with the same intensity in all directions. The formula to find this EIRP value (in dBm) is described in 3.3 where P_{tx} stands for the input power of the antenna, G_t for the gain of the transmitter and L_t being its feeder loss.

$$EIRP[dBm] = P_{tx}[dBm] + G_t[dBi] - L_t[dB] \quad (3.3)$$

This formula, which is constructed out of different gains and losses, misses a factor when accounting for real life radiation patterns. Formula 3.2 solves this by using RRP instead of EIRP and can be defined as follows:

$$RRP(u)[dBm] = EIRP[dBm] - \text{attenuation}(u)[dB] \quad (3.4)$$

The attenuation for a user u is given based on the angle between the main beam and the user. More details on how this can be implemented are described where the radiation patters of antennae are explained. When assuming that $\text{attenuation}(u)$ returns positive values, the attenuation can simply be subtracted from the EIRP-value.

frequency The used frequency in the formula above is denoted as f and is expressed in MHz. Since LTE is used, this value will be 2600 MHz.

path loss At last, formula 3.2 requires the path loss PL . In order to calculate this, an appropriate propagation model —of which several exist— is required . The Walfish-Ikegami model is used since it performs well for femtocell networks in urban areas [?]. The model makes a distinction between whether a free line of sight (LoS) between the user and the base station exists or not. The mathematical representation is given in the formulas below and is based on [?, ?].

The formula for LoS situation is rather simple.

$$L_p = 42.6 + 20 \cdot \log(f[\text{MHz}]) + 26 \cdot \log(d[\text{km}]) \quad (3.5)$$

where f is the used frequency and d the distance between the two radiators. The formula for NLoS is more complex and translates as follows:

$$L_p = \begin{cases} L_0[\text{dB}] + L_{rts}[\text{dB}] + L_{msd}[\text{dB}] & \text{if } L_{rts}[\text{dB}] + L_{msd}[\text{dB}] > 0[\text{dB}] \\ L_0[\text{dB}] & \text{if } L_{rts}[\text{dB}] + L_{msd}[\text{dB}] \leq 0[\text{dB}] \end{cases} \quad (3.6)$$

with L_0 the path loss in free space, L_{rts} the roof-top-to-street diffraction and scatter loss. Further, L_{msd} stands for he multi-screen diffraction loss. The free space loss L_0 can be calculated as follows:

$$L_0 = 32.4 + 20 \cdot \log(f[\text{MHz}]) + 20 \cdot \log(d[\text{km}]) \quad (3.7)$$

where f is the used frequency in MHz and d the radio-path length. The second term in equation 3.6 is the roof-top-to-street diffraction and scatter loss calculated with the following formulas.

$$L_{rts} = -16.9 - 10 \log(w) + 10 \cdot \log(f[\text{MHz}]) + 20 \cdot (h_{roof}[\text{m}] - h_{rx}[\text{m}]) + L_{orientation} \quad (3.8)$$

with w representing the width of the roads and $h_{roof} - h_{rx}$ the difference in height between the receiver and the roof. $L_{orientation}$ depends on the orientation of the road and can be calculated as follows:

$$L_{orientation} = \begin{cases} -10 + 0.354 \cdot \phi[\text{deg}] & \text{if } 0^\circ \leq \phi < 35^\circ \\ 2.5 + 0.075 \cdot (\phi[\text{deg}] - 35) & \text{if } 35^\circ \leq \phi < 55^\circ \\ 4.0 - 0.114 \cdot (\phi[\text{deg}] - 55) & \text{if } 55^\circ \leq \phi \leq 90^\circ \end{cases} \quad (3.9)$$

where ϕ is the angle of incidence relative to the direction of the street. The final parameter required by equation 3.6 is the multi-screen diffraction loss and can be defined as follows:

$$L_{msd} = L_{bsh} + k_a + k_d \cdot \log(d) + k_f \cdot \log(f) - 9 \cdot \log(b) \quad (3.10)$$

L_{bsh} and k_a quantify the increase of path loss caused by obstructing buildings. This is especially the case for lower positioned base stations. b is the distance between buildings along the path where the signal travels. The factors k_f and k_d control the dependence of L_{msd} as a function

of radio frequency and distance, respectively. L_{bsh} and k_a can be calculated with respectively equations 3.11 and 3.12 and k_f and k_d respectively with equations 3.13 and 3.14.

$$L_{bsh} = \begin{cases} -18 \log(1 + \Delta h_{Base}) & \text{if } h_{Base} > h_{Roof} \\ 0 & \text{if } h_{Base} \leq h_{Roof} \end{cases} \quad (3.11)$$

$$K_a = \begin{cases} 54 & \text{if } h_{Base} > h_{Roof} \\ 54 - 0.8 \cdot (h_{tx}[m] - h_{rooF}[m]) & \text{if } d \geq 0.5 \text{ km and } h_{Base} \leq h_{Roof} \\ 54 - 0.8 \cdot \frac{(h_{tx}[m] - h_{rooF}[m])}{0.5} & \text{if } d < 0.5 \text{ km and } h_{Base} \leq h_{Roof} \end{cases} \quad (3.12)$$

$$k_d = \begin{cases} 18 & \text{if } h_{Base} > h_{Roof} \\ 18 - 15 * \left(\frac{(h_{tx}[m] - h_{rooF}[m])}{h_{rooF}[m] - h_{rx}} \right) & \text{if } h_{Base} > h_{Roof} \end{cases} \quad (3.13)$$

$$K_f = -4 + \begin{cases} 0.7 \left(\frac{f[MHz]}{925} - 1 \right) & \text{for medium sized and suburban areas} \\ 1.5 \left(\frac{f[MHz]}{925} - 1 \right) & \text{for metropolitan centres} \end{cases} \quad (3.14)$$

Combining Exposure

The total electromagnetic exposure E_{tot} for a given location originating from different sources can be calculated with formula 3.15 (in V/m). E_i stands for the electromagnetic exposure from source i and n stands for all far-field radiators of a certain category; they can either be UABSs or UE from other people. E_{tot} will be calculated for each location where a user is positioned.

$$E_{tot}[V/m] = \sqrt{\sum_{i=1}^n (E_i[V/m])^2} \quad (3.15)$$

Converting Far-Field Electromagnetic Exposure to SAR_{10g}^{wb}

Formula 3.1 expects that the radiation from each far-field source is expressed in $SAR_{10g}^{wb,myUABS}$, $SAR_{10g}^{wb,otherUE}$ and $SAR_{10g}^{wb,otherUABSs}$. The calculation for all these values is in fact identical since the only difference is the source. Physically seen, they all are whole body SAR values induced by far-field radiation ($SAR_{10g}^{ff,wb}$).

The electromagnetic radiation needs to be converted into $SAR_{10g}^{ff,wb}$. The conversion factor is based on Duke from the Virtual Family. Duke is a 34-year old male with a weight of 72 kg, a height of 1.74 m and body mass index of 23.1 kg/m [?]. Research shows that the conversion factor for WiFi is $0.0028 \frac{W/kg}{W/m^2}$. Since WiFi works at a frequency of 2400 MHz which is very close

to LTE, at 2600 MHz, it is assumed in [?] that this value is also applicable for LTE. The constant in equation 3.17 converts the power flux density S (in units $\frac{W}{m^2}$) to the required $SAR_{10g}^{ff,wb}$. To make this possible, the electromagnetic radiation from formula 3.15 (expressed in V/m) should first be converted to the power flux density with formula 3.16 before formula 3.17 can be applied.

$$S[W/m^2] = \frac{(E_{tot}[V/m])^2}{337} \quad (3.16)$$

$$SAR_{10g}^{wb,ff}[W/kg] = S[W/m^2] * 0.0028 \left[\frac{W/kg}{W/m^2} \right] \quad (3.17)$$

3.1.3 Electromagnetic Exposure Caused by Near-Field Radiation

Up till now, only sources that cause far-field radiation have been considered. However, when a user is operating his device, a part of the UL radiation will enter his body despite the fact that the data traffic is destined for the serving UABS. This device is very close to the user and the emitted radiation is therefore considered to be near-field radiation.

Localized Specific Absorption Rate

When assuming that all users hold their device next to their ear, a localized SAR-value for the head SAR_{10g}^{head} can be calculated. Various governments have defined different legislations. The European Union uses the directions of the IEC who define in IEC:62209-2 a maximum for a 10g tissue SAR_{10g}^{head} at 2 W/kg [?]. The FCC limits the maximum in the United States for a 1g tissue SAR_{1g}^{head} at 1.6 W/kg [?]. Most countries, including Belgium, enforce the 10g model and this will, therefore, be the point of reference for this master dissertation. The SAR_{10g}^{head} values are phone dependent. The values reported by mobile manufacturers are worst-case scenarios meaning that the values are measured when the phone is transmitting at maximum power. This is an understandable decision but will not result in a realistic scenario since modern cellular networks use power control mechanisms to prevent unnecessary high radiation of a nearby device. UE will therefore never use more energy than required to maintain a connection. To compensate for this overestimation, the actual SAR_{10g}^{head} of each user will be predicted. These will, however, remain an estimation since the position of the phone relative to the head differs from user to user. For example, by holding the phone differently, a hand can absorb more or less electromagnetic radiation. The SAR values will also depend on the age of the user, especially children who experience on average higher exposure in the brain regions because of different anatomical proportions [?, ?].

$$SAR_{10g}[W/kg] = \frac{P_{tx}[W]}{P_{tx}^{max}[W]} * SAR_{10g}^{max}[W/kg] \quad (3.18)$$

Equation 3.18 will be used to predict the actual SAR_{10g}^{head} of a certain user with P_{Tx}^{max} being the maximum transmission power for a phone which is in LTE and UMTS 23 dBm [?, ?]. The actual transmitted power (P_{tx}) is calculated with equation 3.19 where P_{sens} stands for the receiver sensitivity and PL the path loss between sender and receiver.

$$P_{tx} = P_{sens}[W] + PL[dB] \quad (3.19)$$

Despite the legal SAR_{10g}^{max} for Belgium is set to 2 W/kg, the actual SAR_{10g}^{max} value is usually lower and different for each mobile device. An average is calculated based on 3516 different phones from various brands using a German database [?]. An overview can be found in fig. 3.2. When the phone is positioned at the ear, an average SAR_{10g}^{max} of 0.7 W/kg is found with a standard deviation of 0.25 W/kg which are very similar results as in ref. [?]. The median of 0.67 W/kg is used as SAR_{10g}^{max} in formula 3.18.

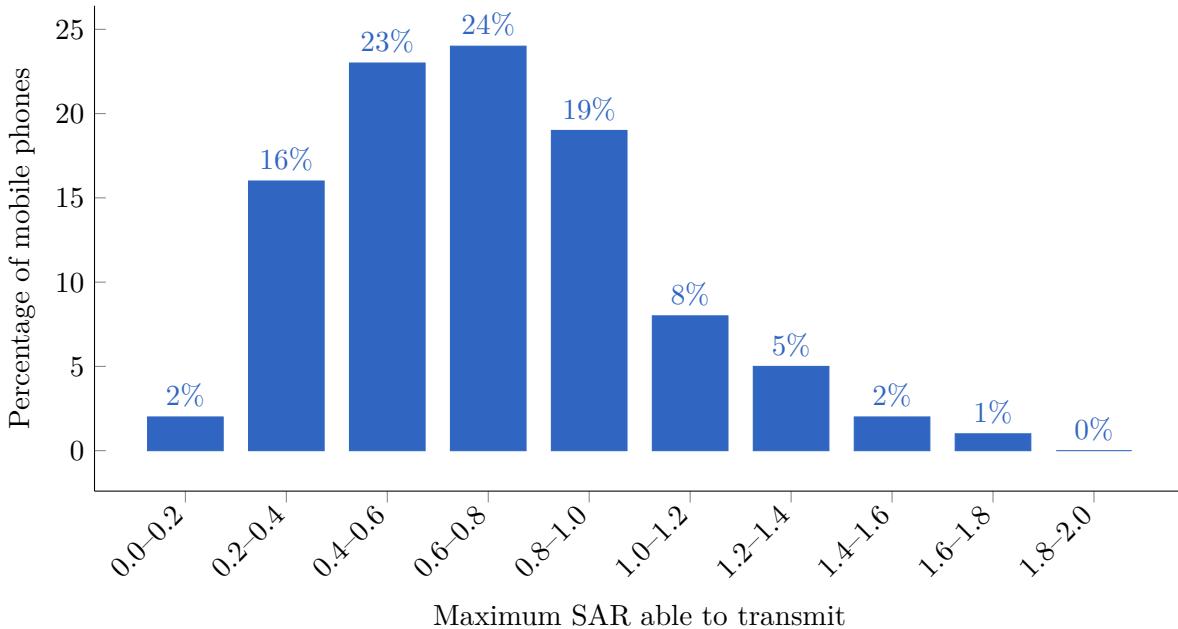


Figure 3.2: Distribution of how many phones belong to a certain SAR interval. Upper boundary not included.

Whole Body Specific Absorption Rate

The position of the phone relative to the user's body is however unknown. Some users will be calling and therefore probably holding their phone next to their ear while others are using other services like browsing the web. This would result in different types of localized values. To be able to give an average SAR based on all active users, the whole body SAR will be used. For this reason formula 3.1 expects that the specific absorption rate is expressed for the entire

body instead of localized SAR_{10g}^{head} . The conversion factors for Duke from the Virtual Family will be used again as it was already the case in 3.1.2. The constant to convert UL exposure to $SAR_{10g}^{wb,myUE}$ for WiFi is defined to be $0.0070 \frac{W/kg}{W}$ [?] which leads to eq. 3.20.

$$SAR_{10g}^{wb,myUE} \left[\frac{W}{kg} \right] = 0.0070 \left[\frac{W/kg}{W} \right] * P_{tx}^{UE}[W] \quad (3.20)$$

The power of the UE can be calculated using equation 3.21 [?].

$$P_{tx}^{UE} = \min \{ P_{max}[dBm], P_{pusch}[dBm] + \alpha * PL[dB] + 10\log(M) + \sigma \} \quad (3.21)$$

P_{max} is the maximum allowed transmission power by UE for LTE, defined at 23 dBm. However, this is the worst case and the actual used power is usually much lower thanks to power control. P_{pusch} is the required received power at the UABS and will be advertised by the base station over the Physical Uplink Shared Channel (PUSCH). This research will use a P_{pusch} of -120 dBm. α is the path loss compensation factor where α must equal {0,0.4,0.5,0.6,0.7,0.8,0.9,1}. An α set to zero indicates there is no path loss compensation [?, ?]. For this document, full path loss compensation will be used with an α equal to one. For the 20-MHz channel used in this paper, M will be set to 100; indicating the number of used resource blocks by PUSCH [?]. Finally, we have σ as the correction factor and is set to zero. Other possible values are {-1, 0, 1, 3} [?, ?]. The presented values can be found in the overview given in table 4.1.

3.2 Microstrip Patch Antenna

3.2.1 Design of a Microstrip Patch Antenna

A microstrip patch antenna is chosen because it allows easy production but more important, it has a low weight and has a thin profile causing it to be very aerodynamic which is useful when attaching it to a drone [?].

The dimensions of the antenna depend on the frequency it is operating at and the characteristics of the used substrate. The antenna will be radiating at a center frequency f_0 of 2.6 GHz. Each substrate has a dielectric constant ϵ_r representing the permittivity of the substrate that depends on the used material. Substrates with a high dielectric constant and low height reduce the dimensions of the antenna while a lower dielectric constant with a high height improves antenna performance [?, ?]. In this document, a substrate like glass is chosen because of the higher dielectric constant of $\epsilon_r = 4.4$ compared to materials like Teflon with only a dielectric constant of $\epsilon_r = 2.2$ [?]. Doing this in combination with an antenna height of 2.87 mm will decrease the

dimensions of the entire antenna surface. This comes in handy since drones only have limited space available.

Description	Symbol	Value
Center frequency	f_0	2600 MHz
Dielectric constant	ϵ_r	4.4
Height of the substrate	h	0.00287 m

Table 3.1: Overview of the configuration parameters.

The dimensions of the radiating patch can be calculated with the formulas from [?] and [?] using the defined values from table 3.1. In that way, the width of the patch W_p is calculated using formula 3.22.

$$W_p[m] = \frac{C[m/s]}{2 * f_0[Hz]} * \sqrt{\frac{\epsilon_r + 1}{2}} \quad (3.22)$$

With C being the speed of light, f_0 the center frequency of 2600 MHz and a dielectric constant ϵ_r of 4.4, the width of the patch becomes 35.09 mm.

In order to find the length of the radiating patch, some other values need to be determined first. Formula 3.23 will calculate the effective dielectric constant (ϵ_{ref}).

$$\epsilon_{ref} = \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{2} * \left(1 + 12 * \frac{h[m]}{W_p[m]}\right)^{-\frac{1}{2}} \quad (3.23)$$

This formula requires the width found in the previous formula along with the dielectric constant and substrate height from table 3.1. This will result in a ϵ_{ref} of 3.91.

$$L_{eff}[m] = \frac{C[m/s]}{2 * f_0[Hz]} * \sqrt{\epsilon_{ref}} \quad (3.24)$$

Now formula 3.24 can be used to calculate the effective length (L_{eff}), resulting in 29.16 mm.

$$\Delta L[m] = 0.412 * h * \frac{(\epsilon_{ref} + 0.3) \left(\frac{W_p[m]}{h[m]} + 0.264 \right)}{(\epsilon_{ref} - 0.258) \left(\frac{W_p[m]}{h[m]} + 0.8 \right)} \quad (3.25)$$

Eventually, the length extension is found with formula 3.25 by substituting the values from above. Doing so determines that the ΔL equals 1.3071 mm.

Finally, the length of the patch can be calculated using the expression 3.26

$$L_p[m] = L_{eff}[m] - 2 * \Delta L[m] \quad (3.26)$$

The length L_p results in 26.55 mm.

The dimensions of the radiation patch are now known. The only remaining questions are the dimensions of the ground plane and dielectric substrate to which the radiation patch is attached. The transmission line model is in fact only applicable for an infinite ground plane but it has been proven that similar results can be achieved if the ground plane's dimensions are bigger than the patch by approximately 6 times the height of the dielectric substrate [?, ?].

$$L_g[m] = 6 * h[m] + L_p[m] \quad (3.27)$$

$$W_g[m] = 6 * h[m] + W_p[m] \quad (3.28)$$

Therefore, the length of the ground plane L_g should be at least 0.0438 m and the width W_g at least 0.0524 m. A schematic overview of how the antenna will look like is given in figure 3.3.

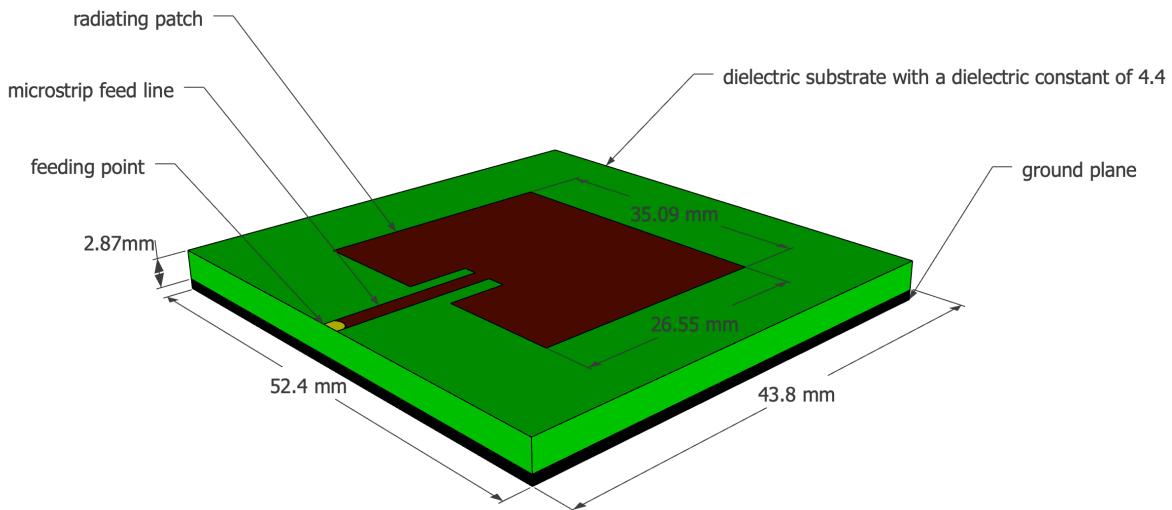


Figure 3.3: Design of the microstrip patch antenna.

3.2.2 Radiation Pattern

Matlab is able to generate the radiation pattern for this microstrip patch antenna. The code in listing 1 starts by defining the dielectric substrate which will be glass with a dielectric constant of 4.4 and a height of 0.00287 m. Thereafter, the microstrip patch antenna is generated with the `width` and `length` being the dimensions of the radiation patch and the `GroundPlaneLength` and `GroundPlaneWidth` the dimensions of the ground plane and dielectric substrate. The `FeedOffset` is the relative offset from the center where the radio frequency power is fed to

the radiating patch which will here be at the edge. This is in figure 3.3 indicated with a yellow dot. At last, the `dielectric`-object is substituted into the `patchMicrostripInsetfed`-object.

Generating the pattern is done with the `pattern`-command. The first value is the `patchMicrostripInsetfed`-object followed by the frequency at which the antenna will be operating. Optionally, an azimuth value can be parsed like in line 7 and 8 where 90 and 0 relatively stand for the H-plane and E-plane.

```

1 d = dielectric("Name",'glass',"Thickness",0.00287,"EpsilonR",4.4)
2 p = patchMicrostripInsetfed("Width",0.0351,"Length",0.02655,
3 "GroundPlaneLength",0.0438,"GroundPlaneWidth",0.0524,
4 "FeedOffset",[-0.021885 0],"Substrate",d)
5
6 pattern(p,2.6e9, "CoordinateSystem", 'polar', "Normalize",true)
7 pattern(p,2.6e9, 90, 0:10:360,
8 "CoordinateSystem", 'polar', "Normalize",true)
9 pattern(p,2.6e9, 0, 0:10:360,
10 "CoordinateSystem", 'polar', "Normalize",true)
```

Listing 1: Matlab code to generate the radiation patterns for the microstrip patch antenna.

Running the configuration from listing 1 will generate the radiation pattern from figure 3.4. When running the same configuration for a slightly bigger square ground plane with an edge of 0.060 m, the radiation pattern from 3.5 is achieved. Both radiation patterns show an aperture angle of approximately 90°. It becomes clear that the radiation pattern from figure 3.4 has a higher attenuation in the direction it is not facing compared to the radiation pattern of figure 3.5. If it is assumed that drones fly lower than some users are positioned in some buildings, the pattern of 3.5 would be a better approach. However, for the continuation of this master dissertation, the radiation pattern from figure 3.4 will be used since this antenna is the smallest and therefore most suitable to attach to the limited space available under a drone. A more extensive comparison between different radiation patterns is out of the scope of this master dissertation. A data sheet of the exact values from both radiation patterns can be found in appendix A.

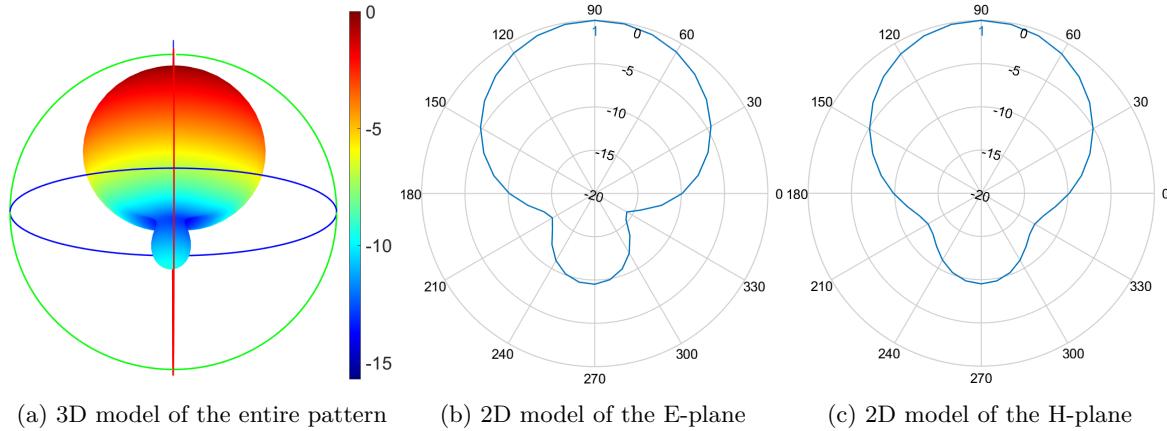


Figure 3.4: Radiation pattern 1 (in dBi) with the configuration as described above.

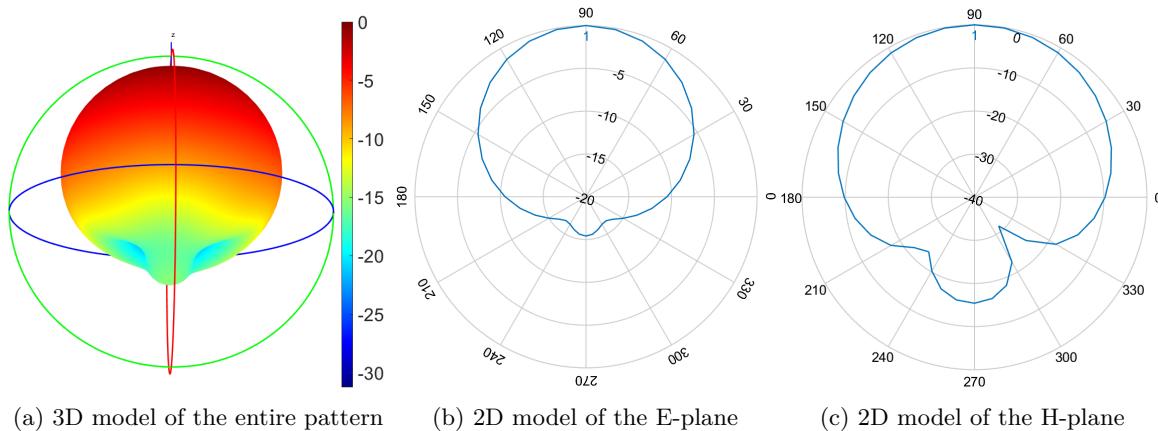


Figure 3.5: Radiation pattern 2 (in dBi) which is generated with a groundplane of 0.06m by 0.06m.

3.3 Optimizing the Network

UAVs can remain in the air for only a limited time, which is certainly the case when also an antenna needs to be connected to the battery of his carrier. It is therefore interesting to not only consider electromagnetic exposure of the user but also the power consumption that comes with it. However, an increasing transmission power of an antenna comes with an increasing electromagnetic exposure, this is not the case considering both values for an entire network. In fact, the authors from [?] prove that both become inversely equivalent.

The reason the network behaves like this is because it is often cheaper to increase the exposure of an already active base station than activating a new one. As an example, imagine there is a new user who can either be covered by activating a nearby base station or by an already

active base station a little further away. When this user is in a power consumption optimized network, the already active base station will increase its power level because that will be cheaper than activating a new base station. Users close by will thus experience a higher electromagnetic exposure. On the other hand, if the user would have been in an exposure optimized network, the nearby base station which was offline would be activated at a lower power level. So the electromagnetic exposure will also be lower but by activating a new base station, the overall power consumption increases.

This results in conflicting requirements. An optimization strategy that optimizes towards either electromagnetic exposure or total power consumption is given in 3.29 and is based on the fitness function described in [?].

$$f = w * \left(1 - \frac{E_m}{E_{max}}\right) + (1 - w) * \left(1 - \frac{P}{P_{max}}\right) * 100 \quad (3.29)$$

Formula 3.29 returns a fitness value which represents the performance of the entire network. Users are connected to different UABSs and each time a fitness value is calculated. The user will eventually be connected to the drone that results in the highest fitness value. This is repeated for each user. This process is explained in detail in section 3.4.1. w is the importance factor of electromagnetic exposure ranging from 0 to 1, boundaries included. A w set to zero means that electromagnetic exposure is not important. Such a network will therefore be called a PwrC Opt. Likewise, a w set to one means that minimizing exposure is top priority and will result in an exposure optimized network (Exp Opt). P_{max} is the power consumption of all UABSs, both active and inactive, when radiating at the highest possible level while P is the effective power used by the current designed network. This will be the power required for the flying drones themselves and their antenna. E_m will be the weighted exposure of the average user for the current designed network and E_{max} the weighted average of electromagnetic exposure when all antennae are at their highest power level.

When optimizing the network, it is not only important to consider the average exposure of all users, but also to limit high extremes [?]. In formula 3.30 a weighted average of exposure will be found by not only considering the median but also the 95 percentile of all users' DL exposure. Since both values are considered to have equal importance, the weight factors w_1 and w_2 will both have an equal importance of 50%.

$$E_m = \frac{w_1 * E_{50} + w_2 * E_{95}}{w_1 + w_2} \quad (3.30)$$

3.4 Simulation Tool

3.4.1 Implementation of the Deployment Tool

Main Algorithm

Calculating electromagnetic exposure requires knowledge about the area. For instance, the position of UABSs needs to be known but also other variables like the used transmission power and the distances between antennae.

The WAVES research group at Ghent University has developed a capacity based deployment tool for disaster scenarios with the aid of UAVs [?]. The idea of this UAV-aided emergency network is that in case of a disaster, the existing terrestrial network might be damaged and will not be able to handle all users who are trying to reconnect to the backbone network. The tool makes a fast deployable network possible by attaching femtocells to UAVs, so-called UABSs. The tool will orchestrate the UABSs over the disaster area by describing a fully configured network. This tool is thus a suitable starting point and works as follows:

The deployment tool will try to calculate the optimal placement for each UABS and requires therefore a description of the area where the UAV-aided network needs to be deployed. This is done with the use of so-called shape files. These files contain three dimensional descriptions of the buildings present in the area and are key values in approaching results as realistic as possible. Furthermore, the tool also requires a configuration file containing technical specifications of the type of UABS that is being used. The tool will thereafter randomly distribute users over the area and assigns a certain bitrate to them (figure 3.6). If a user is indoor, the height of the user will be estimated at half the height of the building. The height UE itself will be 1.5 metres above the floor.



Figure 3.6: Example of how users are randomly distributed over the city centre of Ghent.

In a second phase, the optimal position for each UABS is calculated. This is done by trying to locate a UABS above each active user. Two options are possible. If a fixed flying height is defined, a UABS is placed above each user at the given height, unless a building is obstructing its location. Then, no base station will be located above that user. Alternatively to the fixed flying height, a flying margin can be defined which represents the distance between the outdoor user and the drone. If the user is inside, this margin will be measured between the drone and the rooftop of that building. The latter is only allowed if the suggested height remains below the given maximum allowed height.

Thereafter, the decision algorithm calculates which users should be connected to which UABSSs. These decisions are based on the specified optimization strategy. For this master dissertation, this will either be power consumption optimized or exposure optimized.

In the final state, unused UABSSs are removed and the capacity of the facility is checked. If the number of active drones would exceed this capacity, UABSSs will be sorted based on the number of users they cover. Thereafter, drones with too few users are removed so that all the active drones could be stored in the facility. The flowchart of the main algorithm is given in figure 3.7.

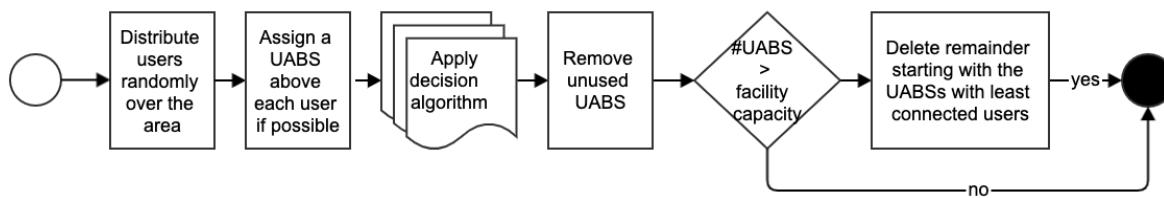
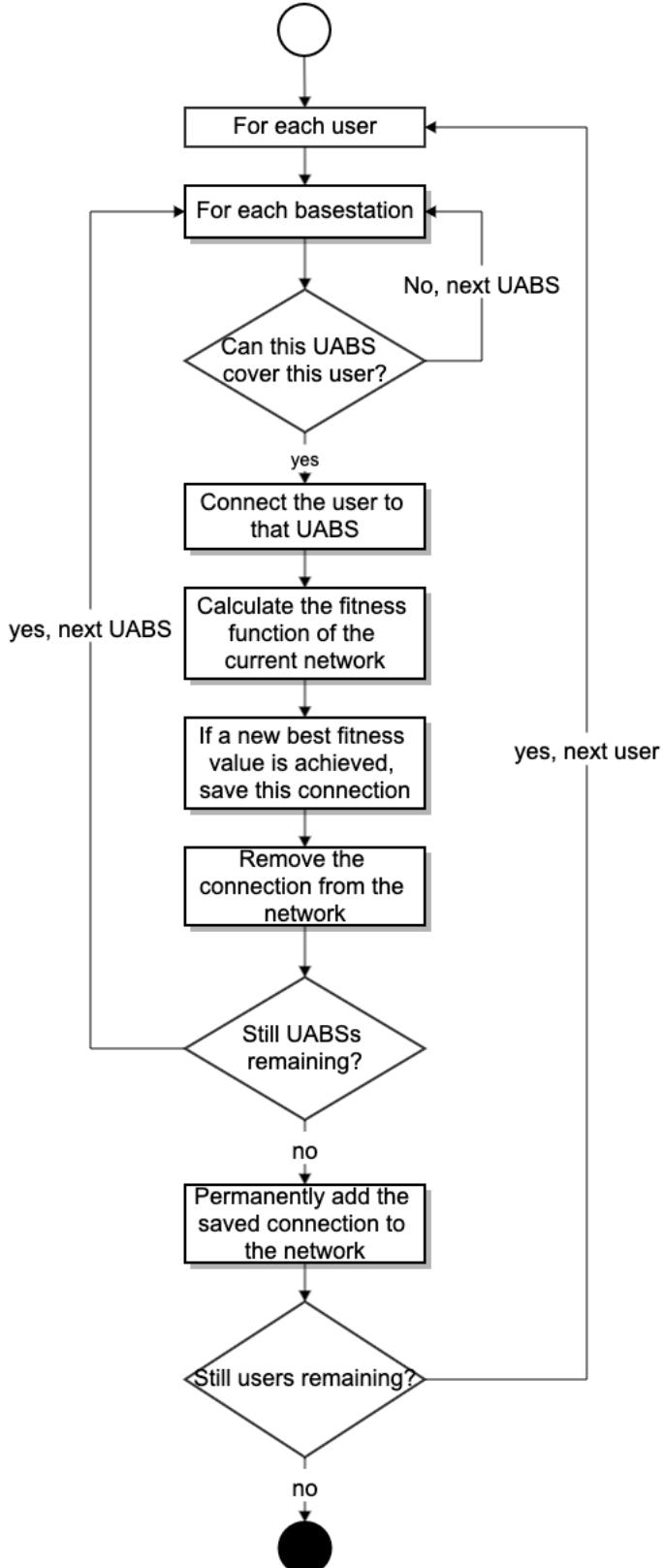


Figure 3.7: Flowchart of the main algorithm.

Decision Algorithm



Solving the network is done by the decision algorithm and starts by calculating the path loss between the different users and thereafter between users and UABSs. Thereafter, the tool iterates over each user and tries to connect that user to each UABS. This connection is not always possible. A UABS might be saturated with users and will not be able to cover yet another one or maybe the user is so far away that in order to cover that user, the UABS would have to exceed its maximum allowed input power. However, if a connection is possible, the user will be connected to that UABS and the fitness function from section 3.3 is applied. This is repeated for each UABS. Only the connection which results in the best fitness value for the entire network will be used. Doing so will make sure that, given the currently designed network, the user is optimized. In other words, each user is optimized and not the entire network. It is however assumed that the average network will be optimized as well. Thereafter, the tool shifts to the next user. When the last user has been processed, the network is fully designed for an unlimited number of drones and the result is returned to the main algorithm for further processing. The flowchart of this algorithm is given in figure 3.8.

Figure 3.8: Flowchart of the decision algorithm.

3.4.2 Implementation of the Radiation Pattern

Originally, the deployment tool did not consider attenuation. Therefore, the radiation from the antenna attached to the UAV was equal in each direction. Such a fictional antenna is called an equivalent isotropic radiator. Thus the tool has been extended in order to support several types of antennae by introducing new parameters like attenuation and direction. Doing so allows any type of antennae which is fully configurable in any given orientation. This configuration is done with the usage of an XML-file which will apply to all UABSs in the network. An equivalent isotropic radiator is still supported by returning a zero value when the attenuation is requested.

The orientation is done using two values called ‘downtilt’ and ‘north offset’. The first value defines the downtilt angle under which the antenna is pointing. A downtilt angle of zero degrees is perfectly horizontal and an antenna with a downtilt angle of 90° will be pointing straight to the ground. This parameter only supports positive values ranging from 0° to 360° (upper boundary not included). An antenna pointing to the sky would therefore require a value of 270°. The second value, the north offset, defines the azimuth orientation of the drone. The value given to this parameter indicates the offset between the north and the horizontal direction to which the antenna should be pointing at. The value once again ranges from 0° to 360° with the upper boundary not included. The angle is calculated in counterclockwise orientation. For instance, a north offset of 270° will let the UABS point to the east. An example is given in figure 3.9 where fig. 3.9.a shows a UAV that performs a horizontal movement with a north offset of 90°. The antenna attached to the UAV in fig. 3.9.b performs a downtilt movement of 90°.

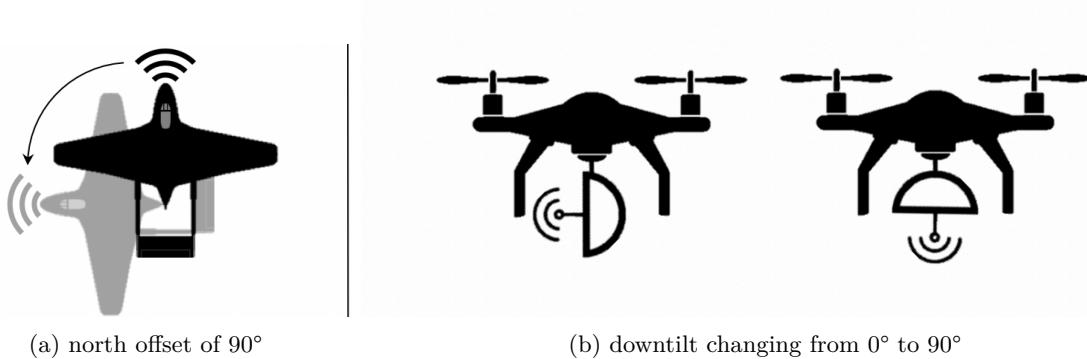


Figure 3.9: Illustration of the two possible movements. The UAV in fig. (a) is a top view while the UAV in fig. (b) is a side view.

Thereafter, the normalized radiation pattern is supplied to the tool, the actual pattern is three dimensional. To simplify this, slices perpendicular to the az-axis are extracted. These are indicated in figure 3.10 with azimuth cuts. With an angle of 90° four slices are achieved, each consisting out of elevation cuts. The intersection of an elevation and azimuth plane corresponds

with a certain attenuation which is fed to the tool. Figure 3.10 shows only 3 elevation planes. The radiation pattern used in the tool has an attenuation every 10° . In other words, a slice consists of 19 values ranging from 0° to 180° (boundaries included).

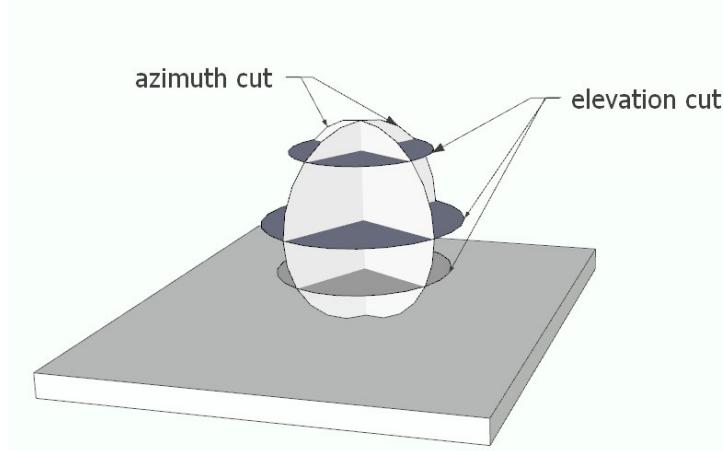


Figure 3.10: Schematic example of slices in a radiation pattern.

The number of required slices depends on the complexity of the radiation pattern. For symmetrical radiation patterns, like in figure 3.4 and 3.5, two azimuth cuts perpendicular to each other are definitely sufficient. This is also illustrated in figure 3.10 where two azimuth planes are shown and that, once cut, will result in four slices. However, this might not be the case for radiation patterns with a more complex structure containing several side lobes. To tackle this issue, more azimuth-slices can be defined for increased precision. Each slice should however contain an equal amount of elevation slices. A concrete example of a configuration file can be found in appendix B.

When the attenuation of a user from a certain UABS needs to be known, the elevation and azimuth angles between the user and the antenna's direction should be calculated. Figure 3.11 represents a radiation pattern with the black dot indicating the user whose attenuation needs to be calculated. The small black lines represent azimuth and elevation planes. The tool knows the exact attenuation only at the intersection of those lines. The chance that a user is positioned at such an intersection is very small. Therefore, the attenuation for the requested point has to be estimated using bilinear interpolation. First, the attenuation is estimated at the intersection of the red and orange line using linear interpolation on the horizontal axis with the known values at the end of the red line. The same is done for the orange-green intersection using the known values at the end of the green line. Finally, linear interpolation is applied to the y-axis for the black dot on the orange line using the estimated values at the end of the orange line.

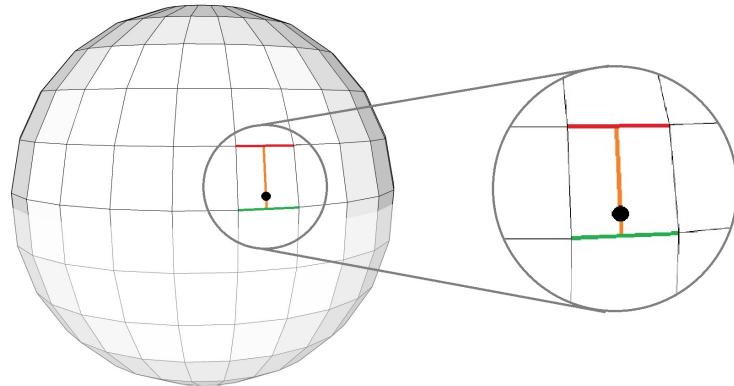


Figure 3.11: Schematic example of how bilinear interpolation works.

3.4.3 Performance Improvement

Calculating Path Loss

The path loss is required by several formulas. For instance, the formula that decides whether a UABS is feasible for a certain user makes use of this parameter but also the calculations for the downlink electromagnetic exposure require this value to be known. The formulas for the whole body SAR_{10g} require not only the path loss between the user and all UABSs but even the path loss between users themselves. These path loss calculations are based on the Walfish-Ikegami model that causes a high computational load. The calculation between two points is completely independent of any other calculation between any other points and is therefore a suitable candidate to multithread. The deployment tool creates two thread pools. The first pool creates a thread for each user where each thread calculates the path loss between the user assigned to him and all possible UABSs, causing a time complexity of n^2 . Each user stores all path losses between himself and any other UABS. This results therefore in a total space complexity of n^2 . When all users are finished, the thread pool is shut down and the second one is created for the same calculations but between users. The pool will, just like the previous, create threads for each user but there is an important difference. When a certain user calculates the path loss to another user, this path loss also applies for the other direction. The tool saves time by calculating the path loss only once and stores the path loss at both users. It is therefore sufficient that a given user only calculates path losses of users at his right side, since the other path losses will be calculated by the users on his left. This results in a time complexity of only $n(\frac{n}{2})$. When the last user finishes his thread, all users know the path loss of all other users causing a space complexity of $n(n - 1)$.

Limiting Antenna Searching

The user needs to be connected to the ‘best’ base station. To identify this best UABS, the user should be connected to each base station and the value of the fitness function presented in equation 3.29 has to be evaluated. The connection that resulted in the best fitness function will be added to the solution. This process is repeated for each user but can further be improved. A user will likely be connected to either the UABS directly above him or to a UABS in the direct neighbourhood. Time complexity can thus be improved by not considering drones outside a certain radius. An ideal data structure for neighbourhood-search with geographical coordinates is a KD-tree [?, ?]. This data structure is described by Bentley in [?] and is based on a binary tree, optimal for objects consisting out of multiple keys. Each node in this tree is associated with a certain dimension and will split the hyperplane over exact one dimension. In this case, the x and y coordinate will be used in a 2D-tree ($k=2$) like in figure 3.12.

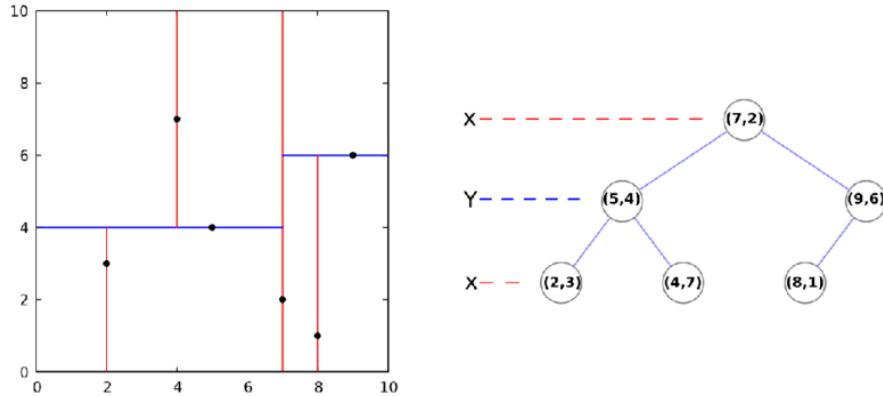


Figure 3.12: Example of a KD-tree in two dimensions.

The length of the connections is investigated to define a proper cut-off radius. The investigated network is a power consumption optimized network with an equivalent isotropic radiator because this configuration will result in the biggest cell sizes due to the absence of attenuation in the antenna. Figure 3.13 shows that for small networks with 50 users, 78% of the connections are less than 100 metres. The other 22% are situated between 100 and 400 metres and decrease logarithmically. For bigger networks with 600 users, 57% of the connections is less than 100 metres. The remaining 43% of the connections are situated between 100 and 500 metres. No significant percentage of connections longer than 500 metre were recorded for either cases. The percentage of connections less than 100 metres will even be higher when using exposure optimized networks and/or microstrip patch antennae. In this case the choice was made to only consider UABSs within a radius of half a kilometre which is believed to have a sufficient safety margin. The rare connections that would have exceeded this radius would not contribute much to the average values.

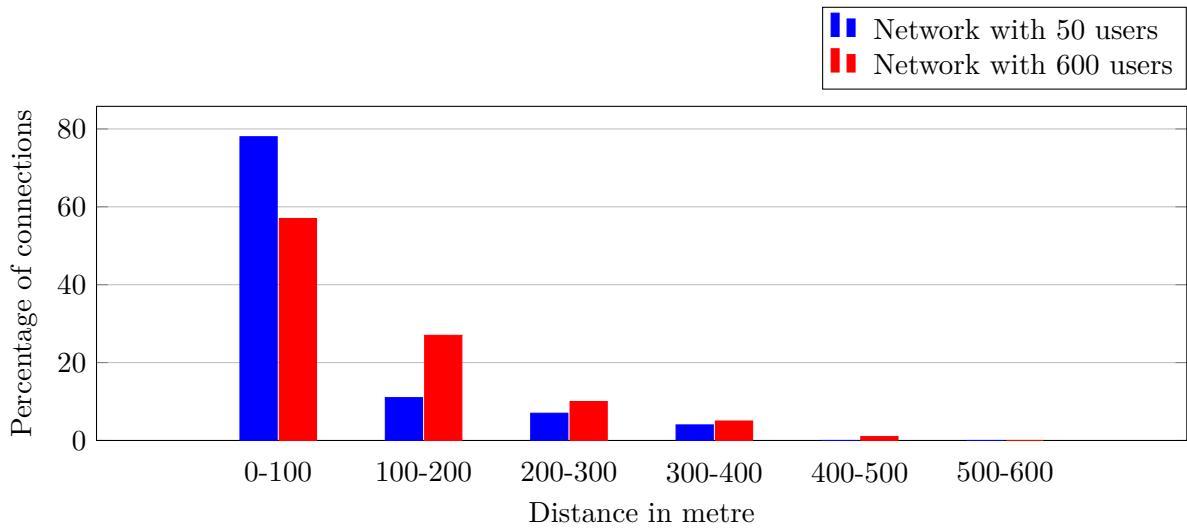


Figure 3.13: Distribution of how many connections belong to a certain interval of distance. Upper boundaries are not included.

3.5 Summary

This chapter discussed the different formulas that will be used by the tool and how to program or optimize some of the more complex problems like radiation patterns or path loss calculations.

First, the formulas about calculating the electromagnetic exposure from different sources and how they can be converted in SAR-values are presented. The electromagnetic field radiation in the far-field and near-field can be converted with the constants $0.0028 \frac{W/kg}{W/m^2}$ and $0.0070 \frac{W/kg}{W}$, respectively. Secondly, a proper microstrip patch antenna has been defined, optimized for the 2.6 GHz frequency band. The dimensions of the groundplane and glass substrate resulted in 52.4 mm by 43.8 mm and a height of 2.87 mm. The radiating patch itself has a width of 35.09 mm and a length of 26.55 mm. Thereafter, the radiation pattern of this antenna is achieved with the use of Matlab. Thirdly, a fitness function for the optimization strategy is introduced, explaining how this function will be able to optimize the network towards either electromagnetic exposure or network power consumption. Eventually, the implementation itself is tackled by discussing the main algorithm of the deployment tool and its embedded optimization algorithm. This is followed by an explanation on how a program can provide support for any possible radiation pattern. Finally, some improvements towards the general performance are discussed in order to reduce time complexity. The path loss calculations can be multithreaded, a proper data structure for neighbourhood search is introduced and non-essential computations are avoided by limiting the neighbourhood search to half a kilometre.

Once all these values and formulas have been implemented, the tool is ready to be applied to different scenarios which will be discussed in chapter 4.

4

Scenarios

The tool supports multiple configurations and the behaviour will be different for most of these configurations. Three main scenarios will be investigated, based on the network complexity. Within each Scenario, different parameters are evaluated. First, in Scenario I, only one user with one drone will be present in the network. Thereafter, in Scenario II, the network will be expanded for multiple users but with still only one drone available. Finally in Scenario III, the last restriction will be dropped, meaning that a network with multiple users and an unlimited number of UABSs is examined. It is important to note that all considered values are strictly limited to the mentioned sources in chapter 3 and thus only cover data traffic between UE and UABSs. Any other potential sources like backhaul links will not be covered.

Table 4.1 shows the default values that are always applicable unless mentioned otherwise. Firstly, the table shows the specifications for LTE operating at a frequency of 2.6 Ghz. The mentioned values are used for calculating the transmission power of UE as discussed in chapter 3: equation 3.21. Secondly, the details of the antenna used by the femtocell base station are presented. The antenna is attached under the UABS and will be pointing downwards. The antenna has a maximum transmission power of 33 dBm and a gain of 4 dBm. Two types of antennae are considered, which is either an equivalent isotropic radiator generating an EIRP or a microstrip patch antenna with a slightly more complex radiation pattern. The design of this radiation pattern is shown in chapter 3: fig. 3.4. By default, the UABSs will fly at a fixed altitude of 100 metres. Thirdly, the specifications of the carrying UAVs are summed up. The authors

from [?] investigated two types of UAVs for their UAV-aided emergency network and concluded that the more robust UAV outperformed the off-the-shelf UAV. The specifications of the more advanced UAV will be used in this master dissertation. Finally, the characteristics of the antenna belonging to UE are listed. The antenna will be located one and a half metre from the floor. Note that the floor does not necessarily mean the ground. For example, a user can be indoor at the third floor. The antenna will be an equivalent isotropic radiator. By default, 224 users with each one device will be distributed over the city centre of Ghent. This city planning map is given in figure 4.1



Figure 4.1: The red area covers the city centre of Ghent, Belgium.

Broadband cellular network	
Technology	LTE
Frequency	2.6 GHz
Power offset (P_{pusch})	-120 dBm
Path loss compensation (α)	1
Correction value	0 dBm
Number of used resource blocks	100
Femtocell antenna	
Maximum P_{tx}	33 dBm
Antenna direction	downwards (az: 0°; el: 90°)
Gain	4 dBm
Feeder loss	2 dBm
Implementation loss	0 dBm
Radiation pattern	EIRP or microstrip patch antenna
Flying altitude	100 m
UAV	
UAV power	13.0 A
Average UAV speed	12.0 m/s
Average UAV power usage	17.33 Ah
UAV battery voltage	22.2 V
Antenna UE	
Height	1.5m from the floor
Gain	0 dBm
Feeder loss	0 dBm
Radiation pattern	EIRP
Quantity in the network	224

Table 4.1: Overview of default configuration values.

4.1 Scenario I: A Single User

This first Scenario will investigate how SAR_{10g} and power consumption behave in an isolated environment meaning there is no influence from other base stations or other UE. The tool will provision one single drone and position it directly above the user. Figure 4.2 illustrates a possible network which satisfies the restrictions of Scenario I. In the middle is the average user drawn with above him the only available UABS. It is clear that the user is only exposed to his own device and the UABS above him.

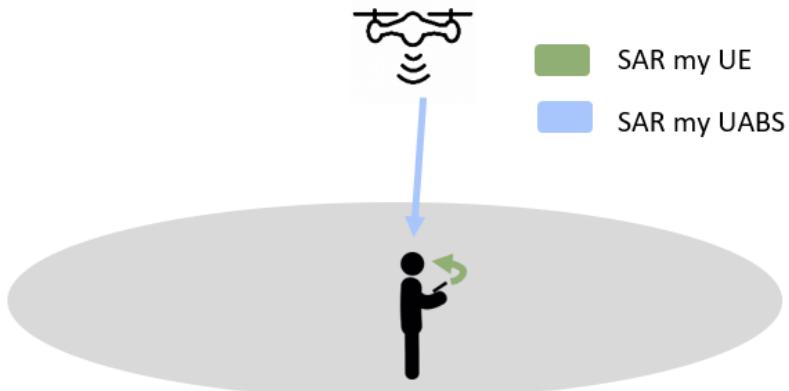


Figure 4.2: Illustration of an example network that satisfies the restrictions of Scenario I.

These results will however depend on the position of the user. If the randomly generated location of the user is indoor, the flying height of the drone might be obstructed by the building where the user resides, causing the user to become uncovered. If this is not the case, the expected altitude of the user is half of the height of the building meaning that the user would be closer to the UABS as if he would have been outdoors. Therefore, the user will be positioned outdoor while systematically increasing the flying height for more consistent results.

Another considered variable will be the transmission power of the antenna. LTE makes use of power control meaning that no more power will be used than strictly necessary. The actual transmission power therefore ranges between zero dBm and the maximum input power. This power is zero when either no user is present or the user is so far away that the actual transmitted power would exceed the maximum allowed transmission power. Increasing the maximum transmission power will not influence the actual power consumption or SAR_{10g} because of power control. However, the used transmission power of the UABS does influence power consumption and SAR_{10g} and its behaviour will be investigated at different flying heights.

This scenario investigates SAR_{10g} , power consumption and minimal transmission power for two different types of antennae: a fictional equivalent isotropic radiator and a realistic antenna as presented in table 4.2. The used optimization strategy is not important for this scenario. This is because the decision algorithm decides which user needs to be connected to which drone. Since only one UABS is available, both optimization strategies will behave identical.



Figure 4.3: Location of ‘Koningin Maria Hendrikaplein’ on the town planning map of Ghent

The user gets a fixed position. The exact location does not matter as long as it is outside. For this experiment is chosen for the ‘Koningin Maria Hendrikaplein’, a square just next to the train station of Ghent (fig. 4.3). Doing so will force the UE to always be at the same height of 1.5 metres. An overview of the simulation configuration scenarios is presented in table 4.3.

Input variables	Output variables
Type of antenna {EIRP, microstrip}	SAR_{10g} (W/kg)
Flying height [20m-200m]	Power consumption (W)
	Minimal P_{tx} (dBm)
	Electromagnetic field radiation (V/m)

Table 4.2: Evaluated parameters

Parameter	Value
X position user (longitude)	3.711198
Y position user (latitude)	51.036747
Shadow margin	-3.0398193
Number of users	1

Table 4.3: Restrictions

Note that there is no explicit restriction on the number of UAVs in table 4.3. The deployment tool initially places UABSs above each user and it is the optimization strategy that decides which of these potential positions will remain in the end solution. Since there is only one user, there can also be only one UAV.

4.2 Scenario II: Increasing Traffic with only one Drone available

This scenario investigates the same behaviour as the previous one. Still with only one drone but for a higher number of users. An illustration of a possible network is given in figure 4.4. The average user is drawn in the middle. The only available UABS covers him along with the person to the right. The two other users at the left side are uncovered and are therefore not emitting any radiation.

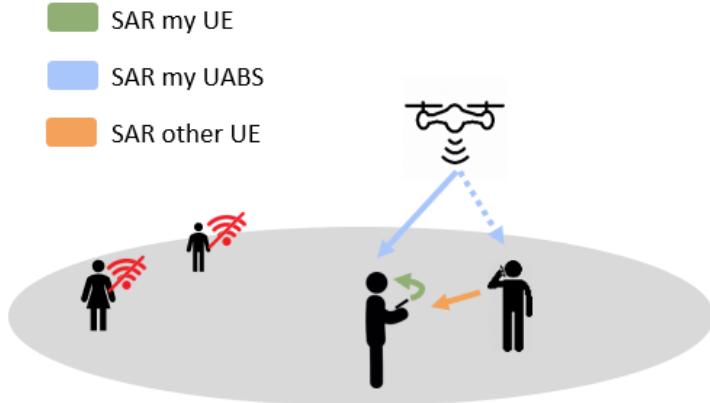


Figure 4.4: Illustration of an example network that satisfies the restrictions of Scenario II.

Two parameters will be investigated for this scenario. First, the flying height will be investigated for a fixed number of 224 users. This is the number of active users on an average day at 5 p.m. implying rush hour and therefore resulting in the highest number of simultaneous users for the day [?]. The other evaluated parameter is a variable number of users. When investigating this parameter, the flying height will be fixed to 100 m as recommended by [?]. An overview of the evaluated parameters is shown in table 4.4 To force the tool to only use one drone, a facility capacity is set to one indicating that there is only one spot available in the facility where the UABSSs are stored. The tool will still consider as much potential places as there are users in the network. But when the optimization algorithm is done, only one drone will remain. On overview of the restrictions is presented in figure 4.5.

For each parameter investigated, four configurations are possible because there are two antennae available (equivalent isotropic radiator and a microstrip antenna) which can both operate in a power consumption optimized network or an exposure optimized network. The SAR_{10g} , power consumption and user coverage will be investigated for all four configurations.

Input variables	Output variables
Type of antenna {EIRP, microstrip}	SAR_{10g} (W/kg)
Flying height [20m-200m]	Power consumption (W)
Number of users [50-600]	User coverage
Optimization strategy {Exp Opt, PwrC Opt}	Electromagnetic field radiation (V/m)

Table 4.4: Evaluated parameters

Parameter	Value
Capacity of the facility	1

Table 4.5: Restrictions

4.3 Scenario III: Increasing Traffic with an Undefined Amount of Drones

The third scenario has no restrictions. The tool can use as much UABSSs as desired while trying to maximize coverage. A UABSS will be considered above each user as was also the case in Scenario II. However, the last step where the capacity of the facility was checked and drones got eliminated, as discussed in chapter 3, is omitted here. It is expected that the optimization strategies will perform best for this scenario since the decision algorithm has been written with multiple drones in mind. An illustration is presented in figure 4.5 with the average user drawn in the middle. Most users are covered by the many UABSSs available. The average user will be exposed to all these UABSSs and to all the UE that belong to covered users.

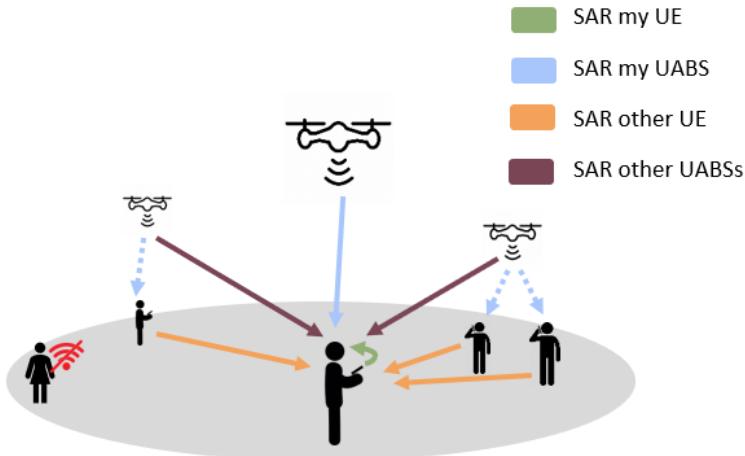


Figure 4.5: Illustration of an example network according to the description of Scenario III.

Again, two parameters will be evaluated: one with a fixed flying height of 100 m and a variable number of users and a second one with a variable flying height and a fixed number of 224 users. The influence that these input parameters have on the network will be based on the electromagnetic exposure, power consumption, number of drones required and user coverage. An overview of these parameters is given in table 4.6.

Input variables	Output variables
Type of antenna {EIRP, microstrip}	SAR_{10g} (W/kg)
Flying height [20-200]	Power consumption (W)
Number of users [50-600]	User coverage
Optimization strategy {Exp Opt, PwrC Opt}	Electromagnetic field radiation (V/m)

Table 4.6: Evaluated parameters

4.4 Overview of Configurations

Three different scenarios are considered. The first one with one user and one UABS. The second one has still only one UABS available but has much more users. The third one has an unlimited number of UABSs available in order to cover as much users as possible. All three scenarios evaluate the influence of a varying flying height while only the second and third one investigate different population sizes. Four possible configurations exist for each evaluated parameter within each scenario. The matrix in table 4.7 shows that two types of antennae are investigated and how the optimization strategy can operate towards two goals: exposure optimized and power consumption optimized.

		Optimization strategy	
		Exposure optimized	Power consumption optimized
Antenna type	Equivalent isotropic radiator	EIRP Exp Opt	EIRP PwrC Opt
	Microstrip patch antenna	Microstrip Exp Opt	Microstrip PwrC Opt

Table 4.7: Matrix with the four possible configurations

5

Results and Discussion

This chapter gives an overview of the achieved results from all considered scenarios. The two parameters, flying height and number of users, are evaluated by monitoring the power consumption, electromagnetic exposure and SAR-values. This is done for the two considered antennae who can both operate in two optimization strategies, making a total of four possible configurations. These configurations will be investigated in three different scenarios. The first section talks about Scenario I which is a small network with only one user and one UABS. In the following section, Scenario II is investigated where the network is expanded for a larger population but with still only one UABS available. The network in the last section investigates Scenario III which serves a large population with an unlimited number of UABSs.

The electromagnetic radiation and SAR are measured for the weighted average user. This means that equation 3.30 is used with both w_1 and w_2 set to 50%. Doing so will not only optimize the network towards the average user but also limit higher electromagnetic radiation. Each simulation is repeated 20 times. Therefore, the values for the weighted average user will be averaged over these 20 simulations.

Some interesting values are presented to give the reader an idea on how long these computations take. For example, the variable flying height in each scenario ranges from 20 m to 200 m in steps of 20 m resulting in a total of 200 simulations for one scenario. This results in more than 15 million 52 thousand path loss calculations. The evaluated parameter ‘number of users’

ranges from 50 to 600 in steps of 50, resulting in 240 simulations. Such one scenario takes 48 million 750 thousand path loss calculations. Remember that path loss calculations are done in the preparation phase and the network has not even been optimized at this point.

5.1 Scenario I: One User and One UAV

The network contains only one user in this scenario. This means that there is only one location possible for the UAV, being just above the user. This section will investigate minimal required transmission power and SAR values from different sources. Finally, also the power consumption of the entire network is measured. The “entire network” refers to all UABSs. For this scenario, the entire network will be constructed out of a single UABS.

5.1.1 The Influence of the Maximum Transmission Power

LTE makes use of power control meaning that no more power will be used than strictly necessary. The actual transmission power P_{tx} therefore ranges between zero dBm and the maximum allowed input power. P_{tx} is zero dBm when the UABS does not cover anybody. For instance when the flying height is too high and therefore also the path loss that comes with it, the maximum allowed P_{tx} is not enough to cover the distance. In such case, the UABS is shut down since it cannot meet the requirements. Increasing the maximum transmission power will not influence the actual used P_{tx} because the UABS will not use more than strictly required. It is therefore more useful to match the actual transmission power against a variable flying height.

Figure 5.1 shows a logarithmic relationship between P_{tx} and flying height. As already discussed in 4.1, the user is outdoor and just below the UABS. There is thus a free LoS between both radiators. It is clear from figure 5.1 that a discontinue step function is achieved. This is because multiple flying heights correspond to the same transmission power. When the flying height increases, so does the path loss. This causes the Signal to Noise Ratio (SNR) to drop under the required boundary. LTE tries to counteract this by increasing the power level. Each time the path loss becomes too high, the power level of the transmitter increases with one dBm. Doing so, increases the SNR allowing the user to properly receive and decode the signal again. After a jump in the step function, there is an overestimation meaning the P_{tx} increased more than necessary. So multiple flying heights correspond with the same P_{tx} . Further, dBm is also a logarithmic scale meaning that while 10 dBm equals 10 mW, 20 dBm equals 100 mW. This explains why the black lines become longer at higher flying altitudes. Each time the power level increases with one dBm, the overestimation becomes larger. If the tool would make use of a smaller step size, a more continuous logarithmic function would be achieved. This would however worsen the time complexity because it would take much more iterations before the power level

exceeds the path loss. The red line in figure 5.1 indicates the default maximum transmission power of 33 dBm used during simulations as defined in table 4.1. In a free LoS scenario with only one user, a UABS can fly up to 387 metres before losing connection.

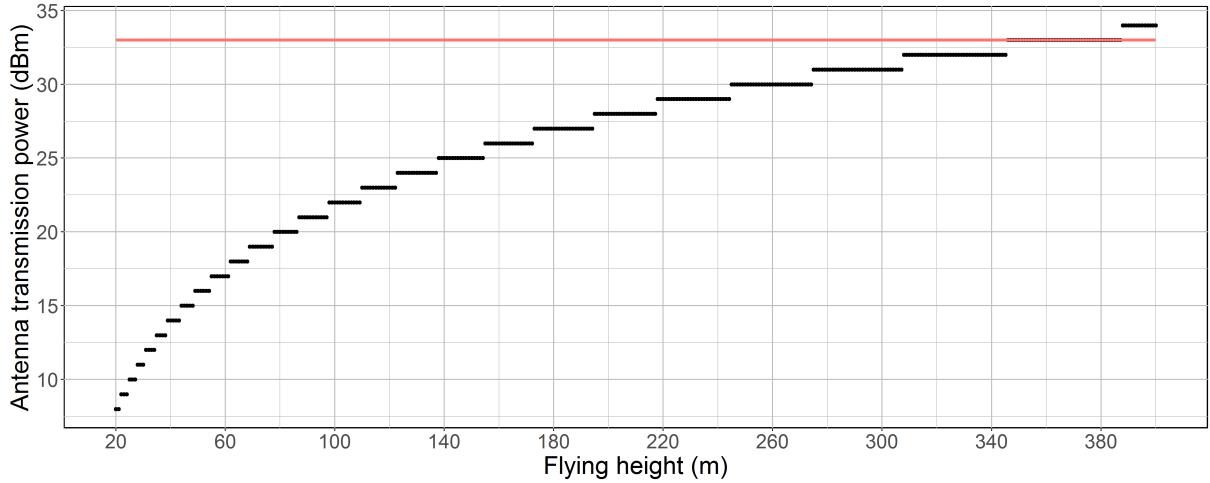


Figure 5.1: Minimal required transmission power by the antenna to reach the ground just below it. The red line shows the default maximum transmission power.

This scenario is investigated with a microstrip patch antenna using power consumption optimization. However, the chosen optimization strategy does not really matter as already explained in 4.1. This is because the decision algorithm decides which user needs to be connected to which UABS. Since only one UABS is available, both optimization strategies will behave identical. Further, also the used antenna will not make any difference despite the fact that a microstrip patch antenna has attenuation while an equivalent isotropic radiator does not. The user is namely positioned in the perfect center of the main beam where there is no attenuation experienced in either cases. So the results are applicable for the four possible cases from figure 4.7.

5.1.2 Influence of the Flying Height

This subsection investigates how the flying height of a UABS influences SAR_{10g} and power consumption. The SAR_{10g} , which is actually induced electromagnetic radiation into the user, is represented in figure 5.2 and shows that for a low flying UAV, DL radiation is the main source of electromagnetic exposure. This changes around an altitude of 80 metres where the UL radiation from the UE exceeds the DL radiation in order to still be able to reach the high flying UABSs.

SAR-values are caused by the transmitted power P_{tx} of the antenna. The P_{tx} in section 5.1.1 showed a discontinuous behaviour that sometimes radiates more than strictly necessary. This has thus a direct influence on the DL SAR; hence, the same discontinuous behaviour. The DL SAR can

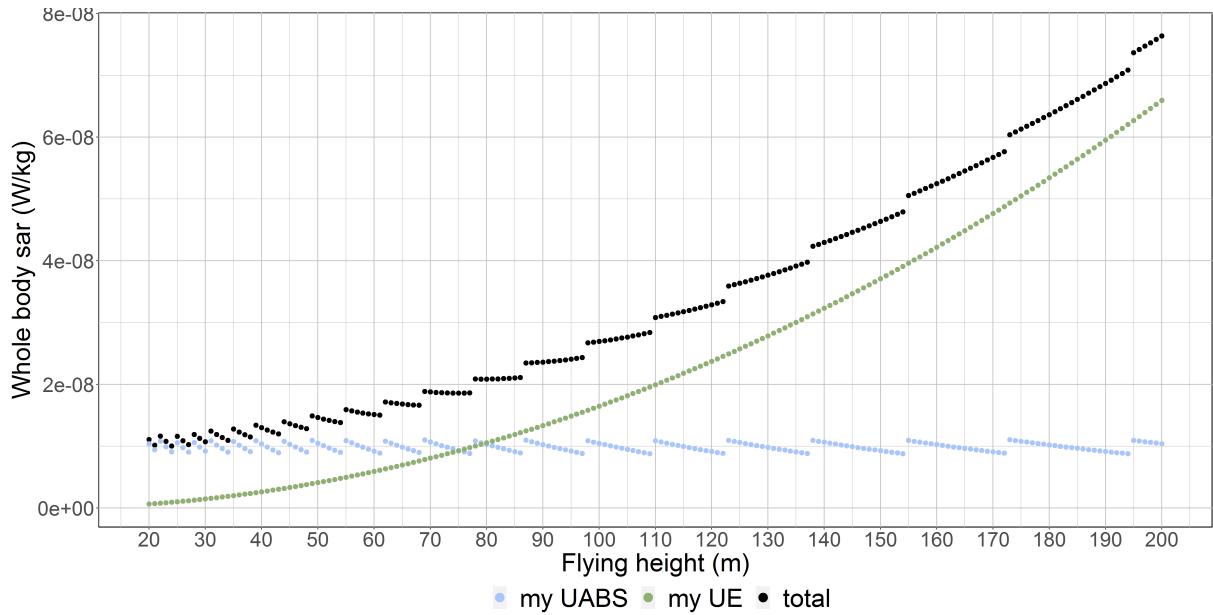


Figure 5.2: This figure shows how SAR values from different sources are influenced by different flying altitudes.

be simplified to a perfect constant line at 10 nW/kg . This constant behaviour can once again be explained with power control. When the UABS flies lower, there is less path loss and the UABS will therefore reduce the P_{tx} . We can therefore confirm that the electromagnetic exposure from the UABS is a constant fraction of power and distance. The electromagnetic radiation from the UE shows in figure 5.2 an exponential behaviour. The power used by the antenna is calculated with formula 3.21 and depends mainly on path loss. UE will, similar to UABSSs, radiate just enough so the SNR is high enough to be decoded by the receiver. The only difference with DL radiation is that the distance between the radiator and the user remains unchanged. Therefore, the UL electromagnetic radiation experienced by the user will increase when the flying altitude of the UABS increases. The UL radiation starts very low with only 1 nW/kg measured when the flying height is 20 metres. This increases fast to 66 nW/kg at 200 metres. Figure 5.2 does not show radiation from neighbours, because there are none present in this scenario. Finally, all these values are added up as explained in formula 3.1 resulting in the total SAR to which our user is exposed, represented by the black line in 5.2.

The power consumption of the entire network presented in figure 5.3 is here of course for the only UABS available. The energy is based on the transmission power of the antenna and the used battery by the UAV. Section 5.1.1 already explained the reason behind the stepped function. The transmission power is an important parameter when calculating the used power and is the cause that we see the same stepped behaviour in figure 5.3. All individual results (indicated with dots) can once again be simplified with a connected line that clearly shows an exponentially behaviour. The grey shadow behind the line represented the confidence interval.

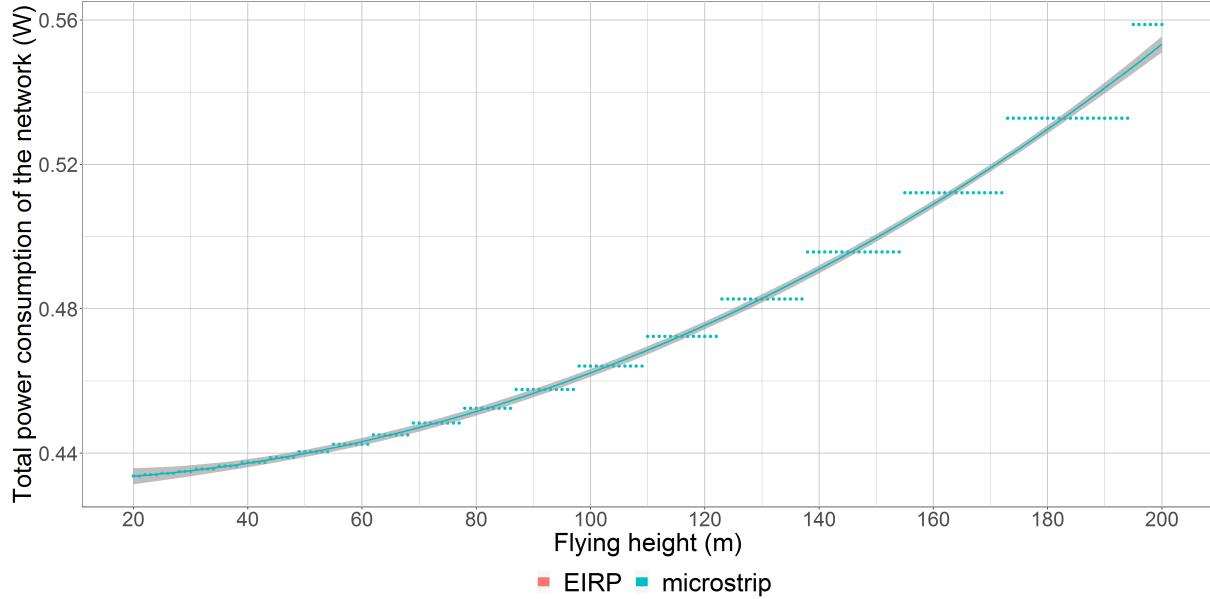


Figure 5.3: This figure shows the behaviour of the power consumption over the entire network at different flying heights. For this scenario, the power is used by only one UABS.

5.2 Scenario II: Increased Population

This scenario has just like the previous scenario only one UAV available. However, more users will be present in the network. First, a variable flying altitude is investigated for a fixed number of 224 users. Secondly, the flying height is set to 100 metres with a variable number of users. When designing the network, there will be as much possible UAV locations as there are users in the network and the tool will consider all of them. Only when the program is finished, one UAV will remain. Each considered input value will be averaged over 20 simulations.

5.2.1 Influence of the Flying Altitude

The first evaluated parameter of this scenario investigates how the network, consisting out of one UABS, behaves when applied on an ordinary day during rush hours. Different fixed flying heights are considered while 224 active users are distributed uniformly over the city centre of Ghent. as presented in the example of figure 5.4.

Figure 5.5 presents the average DL exposure and average total power consumption. The grey area indicates the confidence interval. A power consumption optimized network with an EIRP antenna (green) has the highest exposure during the entire experiment. At the default flying height of 100 metres, an electromagnetic field radiation of 10 mV/m is measured. This is logical when comparing to an EIRP antenna in an exposure optimized network (red) with only

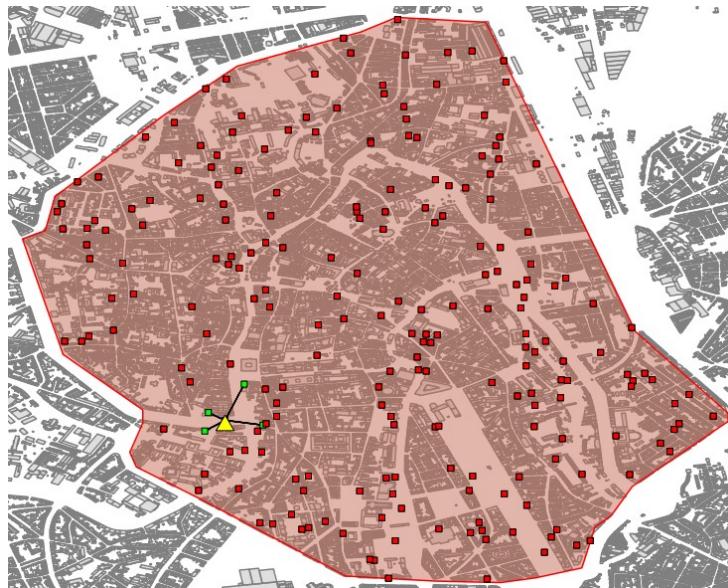


Figure 5.4: Example of an EIRP PwrC Opt network with only one UABS (yellow triangle). Only a very few users (green) are connected. All other users (red) remain uncovered.

8.5 mV/m . However, when looking at figure 5.5.b, the power consumption in a power consumption optimized network is not necessarily less than in an exposure optimized network. For example, an EIRP and microstrip antenna will require at the default flying height respectively 20 mW and 10 mW more in a power consumption optimized network than in an exposure optimized network. To understand this, the behaviour of the deployment tool needs to be understood first. A power consumption optimized network will result in a few high powered UABSSs because increasing the input power of an antenna costs less than activating a new UAV. Likewise, an exposure optimized network generates a lot of low powered UABSSs because the lower the power of the antenna, the lower the exposure. This has the consequence that the cover radius is less and therefore requires more UAVs which costs more energy. When only a limited amount of UABSSs are available, like only one in this scenario, the tool will only keep those UABSSs that cover the most users. Therefore, the power consumption in a power consumption optimized network is often higher.

Figure 5.5 further also shows how the electromagnetic radiation from the UABS starts decreasing again at high altitude. A microstrip PwrC Opt network is at his highest point around 162 metres and an EIRP PwrC Opt is at his highest at 195 metres. This decline starts later for exposure optimized networks and is situated outside the investigated flying range. The decreasing electromagnetic radiation at high flying altitudes is not caused by the obstructing buildings but by the distance in general.

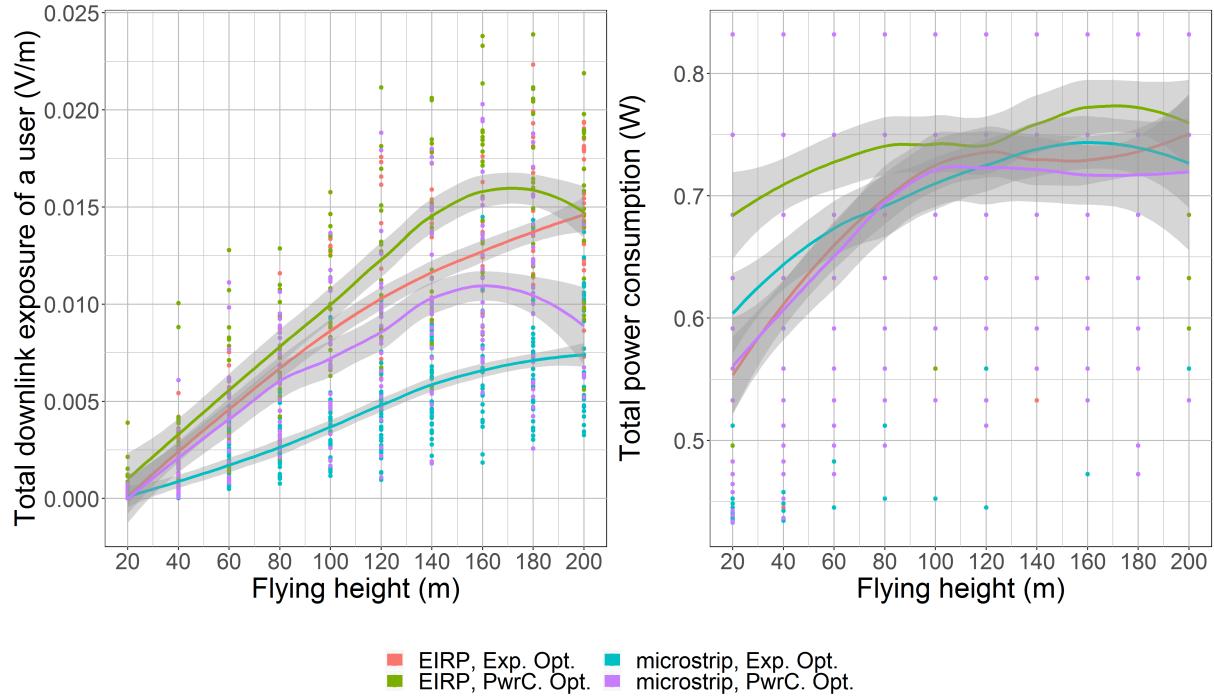


Figure 5.5: Fig. (a) show how the flying height influences the downlink electromagnetic radiation of the average user and fig. (b) the power consumption of the entire network for the only UABS available in the network.

The DL exposure in figure 5.5 increases along with the flying height. One might expect a more constant behaviour like it was the case in figure 5.2 of Scenario I. To understand this, the scenario has been reduced to only two users and is illustrated in figure 5.6. The two users, who will be referred to by ‘red’ and ‘blue’, are 90 metres separated from each other with a building between them. Scenario I already explained that the charts can be simplified and the blue line from fig. 5.7 remains in fact constant between zero and 130 metres. The chart shows that the UABS is positioned above the blue user. The red user is in NLoS as long as the UABS remains below 20 metres.

Once the UABS increases its flying altitude, the red user comes into LoS but still remains uncovered. This is because the tool initially locates a possible

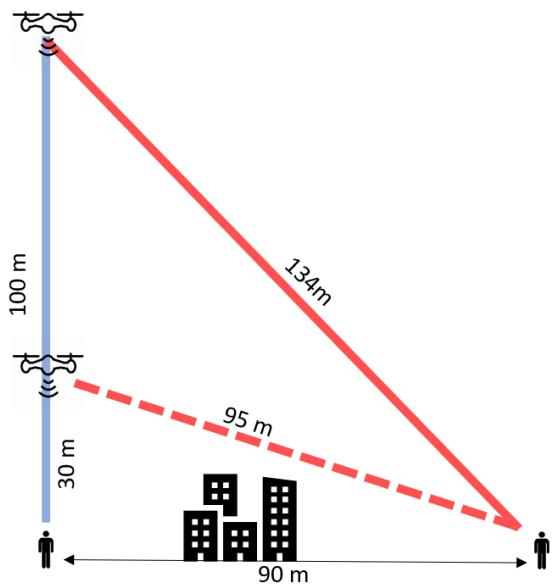


Figure 5.6: Schematic overview of Scenario II with only 2 users.

UABS above each user and thereafter performs the fitness function. The applied fitness function must have decided that it is better to connect each user to the UABS above him. In a final stage, the tool checks whether the number of online UAVs does not exceed the capacity of the facility which is here the case. The tool therefore deactivates one UABS causing the red user to be uncovered. One could argue that the red user should be connected to the online UAV who is only 90 metres away. This would however require the online UAV to increase its power consumption which would make the decisions made by the optimization strategy obsolete. When the UAV flies higher, the difference in distance between both users and the base station decreases. In other words, the Pythagorean theorem shows that when the flying height of the UABS increases, the distance to the blue user increases faster compared to the distance between that same UABS and the red user. This is also illustrated in figure 5.6. At 130 metres, the tool decides to connect both users to the same UABS. Therefore, it increases its power consumption whereby the red user would have the minimal required electromagnetic exposure. This has of course a negative influence on the blue user who is much more closer and experiences now a much higher exposure level in fig 5.7. Around 180 metres, the red and blue line switch because the UAV changes position. As explained before, the tool assigns two possible UAVs, one above each user. The tool must have decided that connecting both users to the other UAVs improves the fitness function of the entire network even though that difference might be very little. Finally, this brings us back to the weighted average exposure from figure 5.5 where 223 users will behave like the red user and only one user behaves like the blue one. The red line therefore dominates the average exposure in figure 5.5.

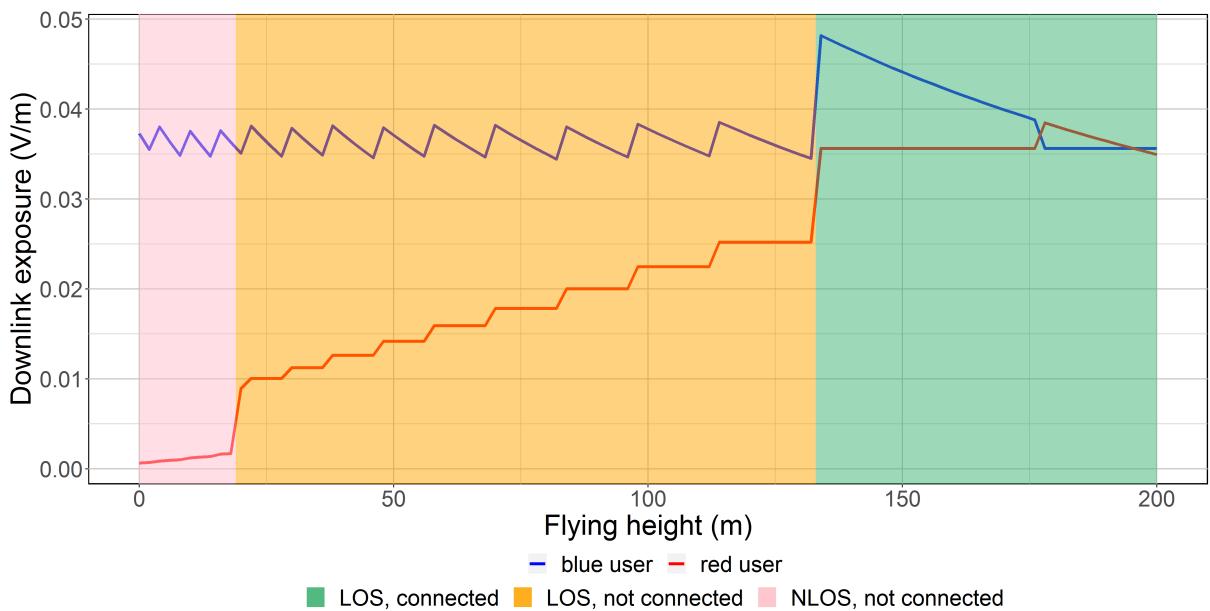


Figure 5.7: Scenario II with only 2 users. The coloured areas are only applicable for the red user. The blue user is connected during the entire time.

Figure 5.5 showed that the electromagnetic exposure of the average user increases along with the flying height which reflects itself on better coverage as visible in figure 5.8. Increasing the flying height from 20 to 100 metres improves the coverage between 1% and 2% for all four configurations. When replacing the fictional EIRP antenna by a microstrip patch antenna, the percentage of covered users drops for both optimization strategies less than 1%. The difference is caused by users who have a higher horizontal distance between themselves and the UABS. Microstrip patch antennae have a smaller aperture angle than an equivalent isotropic radiator and have therefore a smaller range. When a microstrip patch antenna is positioned higher, the range of the antenna increases since the angle between the user and the UABS's main lob decreases. The user will therefore experience less attenuation.

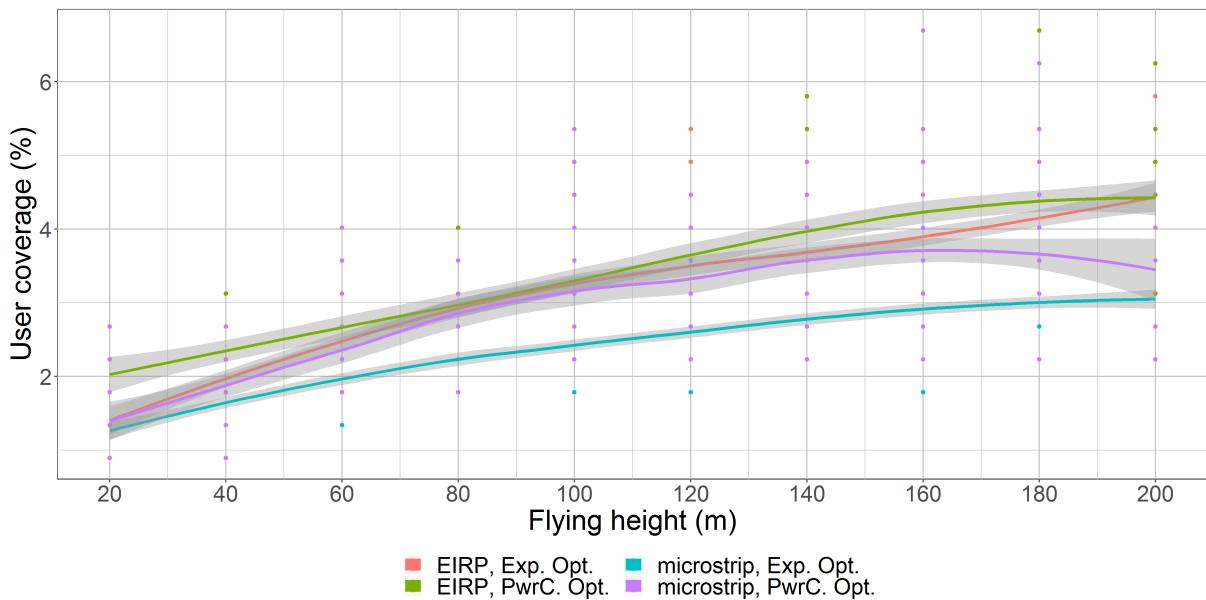


Figure 5.8: This graph shows the percentage of covered users for only one UABS at different flying heights.

Eventually, figure 5.9 shows the whole body SAR_{10g} for the weighted average user, deducted from all electromagnetic sources. This combines the exposure of the only UABS available in the network, the UL exposure from the user's own device and the exposure of the devices from all other covered users. When investigating the three different sources, we see that the SAR^{myUABS} shows the same curve as it did with the electromagnetic exposure in figure 5.5.a. This is normal behaviour considering that equation 3.17 is able of converting the DL exposure to SAR by simply multiplying with a constant. During the entire time is SAR^{myUABS} the most dominant factor followed by the near-field radiation from the user's own device. The far-field radiation from other UE barely has influence. As an illustration, when the UABS flies at 140 metres, the average user in an EIRP PwrC Opt network will experience around 2.1 nW/kg from the UABS and around 0.2 nW/kg from his own device. The exposure from other UE can be neglected with

0.03 pW/kg . A low but plausible value considering that most UE are not radiating anything since they are uncovered (hence the many red dots in fig. 5.4).

The weighted average SAR_{10g}^{ul} from the own device is zero in an exposure optimized network with a microstrip patch antenna which is even lower than the $SAR_{10g}^{neighbours}$. This is because the coverage in this scenario is so low that the weighted average only consists of uncovered users and the transmission power of an uncovered user is zero.

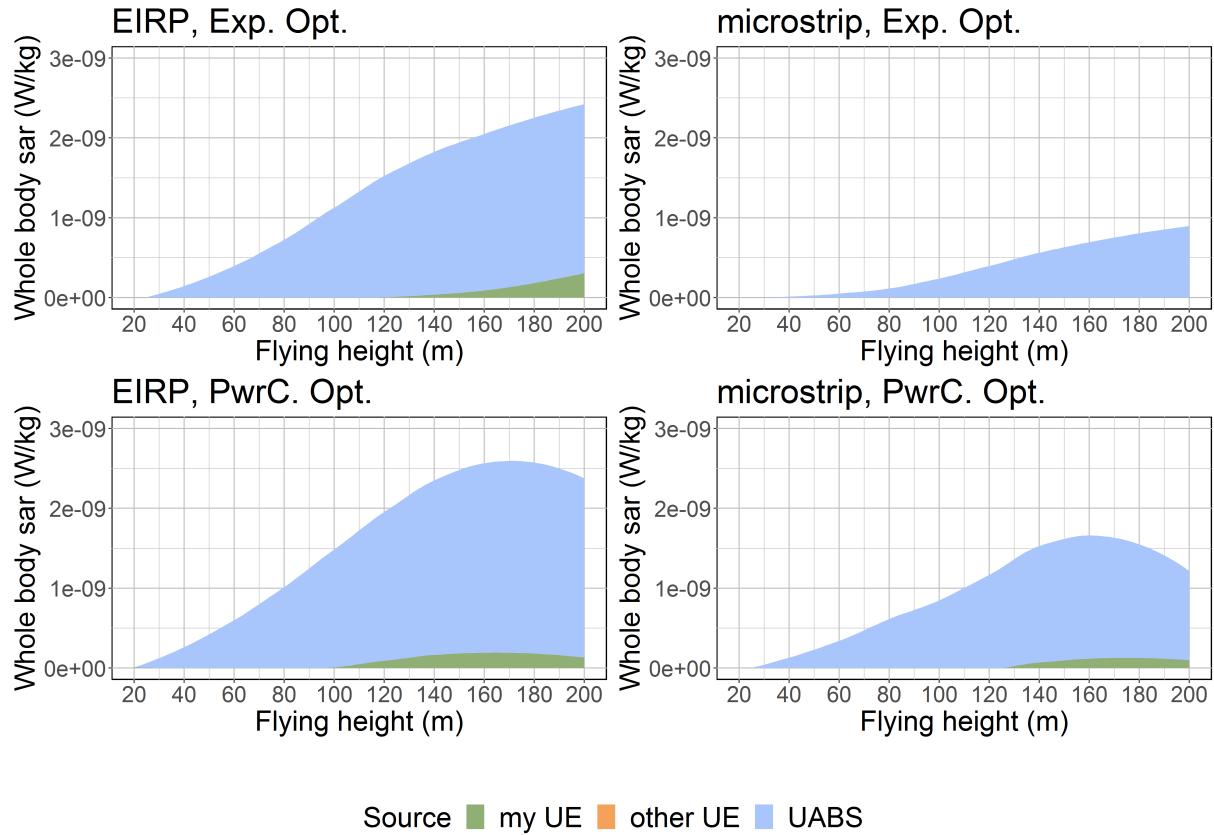


Figure 5.9: Each figure corresponds with a certain configuration and shows how the SAR from different sources are influenced by an increasing flying height.

5.2.2 Influence of the Number of Users

The number of covered users increases linearly compared to the number of users present in the network as shown in figure 5.10.b. It illustrates how an equivalent isotropic radiator is able to reach more users compared to a microstrip patch antenna. Just like an power consumption optimized network is able to reach more users than an exposure optimized network. For example, with 600 users, 5 to 7 additional people can be covered when replacing a microstrip patch antenna

with an equivalent isotropic radiator. An changing an exposure optimized network with an power consumption optimized network will cover one or two additional users.

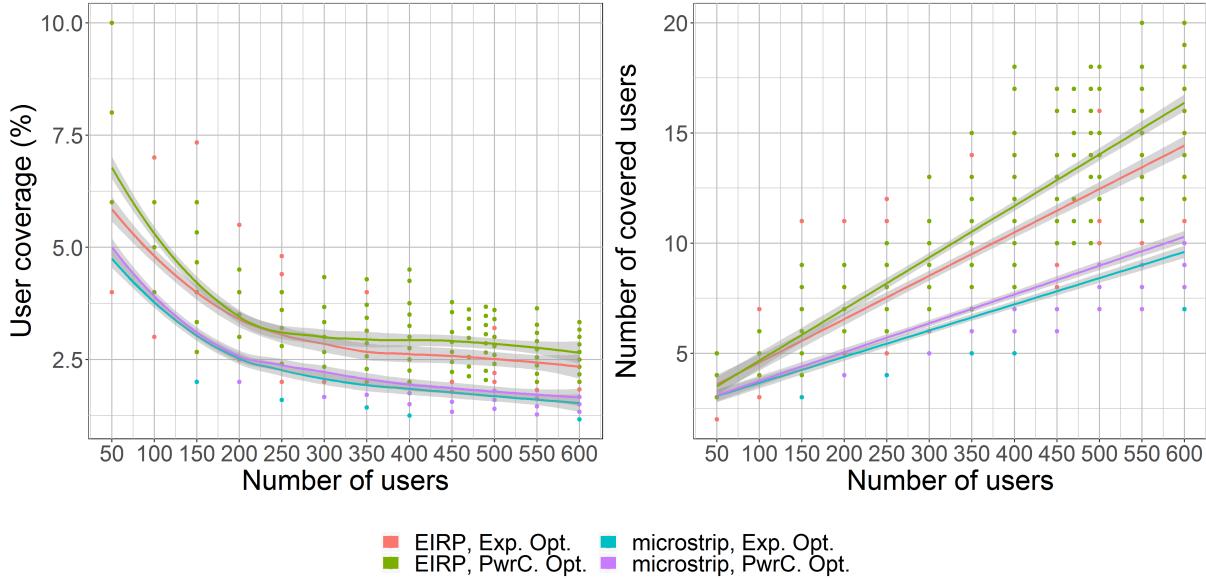


Figure 5.10: The influence of increasing traffic on the user coverage.

The linear regression lines from figure 5.10 can be predicted with the equations in 5.1.

$$\text{number of users} = \begin{cases} y = 0,0233x + 2,3553 & \text{if EIRP and PwrC Opt} \\ y = 0,0197x + 2,6144 & \text{if EIRP and Exp Opt} \\ y = 0,0131x + 2,4371 & \text{if microstrip and PwrC Opt} \\ y = 0,0119x + 2,4652 & \text{if microstrip and Exp Opt} \end{cases} \quad (5.1)$$

Figure 5.10.a shows the percentage of covered users that follow out of 5.10.b by taking the equations from 5.1 and dividing them by x . This results in a decreasing logarithmic behaviour because the regression lines from 5.10 have a slope of less than 0.5. This means that the percentage of covered users for a small populated network is more compared to the percentage of users in large populations. Figure 5.10 concludes that the increase in population causes a decrease in coverage since only one UABS is available. While an EIRP PwrC Opt network with only 50 users knows a 6.75% coverage, a network with 600 users has no more than 2.75% coverage.

Figure 5.11.a is influenced by 5.10.a. When less users are covered, the exposure of the average user will decrease as well. For example, in an EIRP PwrC Opt network, 50 users have a 6.75% coverage which corresponds with a weighted average exposure of 18 mV/m while 600 users with 2.75% coverage only have 9 mV/m . Further, figure 5.11.b is directly influence by figure 5.10.b. When the UABS has to cover more users, the probability that some of these users have a worse path loss is higher. The UABS solves this problem by increasing the power consumption. Increasing the population from 50 to 600 will require between 0.05 and 0.1 W more. For this scenario, no clear difference in power consumption exists between the four configurations.

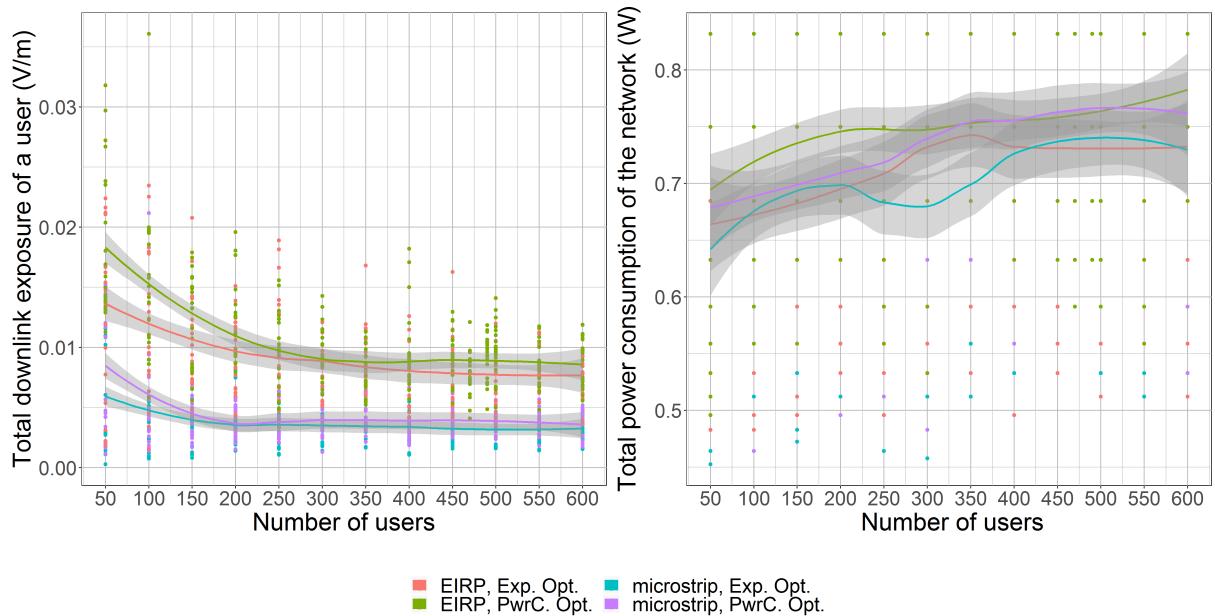


Figure 5.11: These two figures show how various sizes of population influence the downlink electromagnetic radiation of the average user (left) and power consumption of the entire network (rights) for one UABS available in the network.

Figure 5.12 investigates the assets of each source contributing to the total SAR. All four configurations show that base stations are the main source of electromagnetic radiation which remains almost constant. The equivalent isotropic radiator varies around 1 nW/kg for both optimizations and the microstrip antenna around 0.16 nW/kg . Figure 5.10 already showed that a sparsely populated network results in a higher coverage percentage which on his turn results in a higher SAR_{ownUE} . The SAR_{ownUE} for 50 users is for an equivalent isotropic radiator on average 1.7 nW/kg for both optimizations and the microstrip antenna around 0.4 nW/kg . The chart also proves once again that the far-field radiation from UE can be neglected. The SAR from neighbouring devices is not zero as it looks like in figure 5.12 but is just really low compared to the much higher SAR-values from other sources.

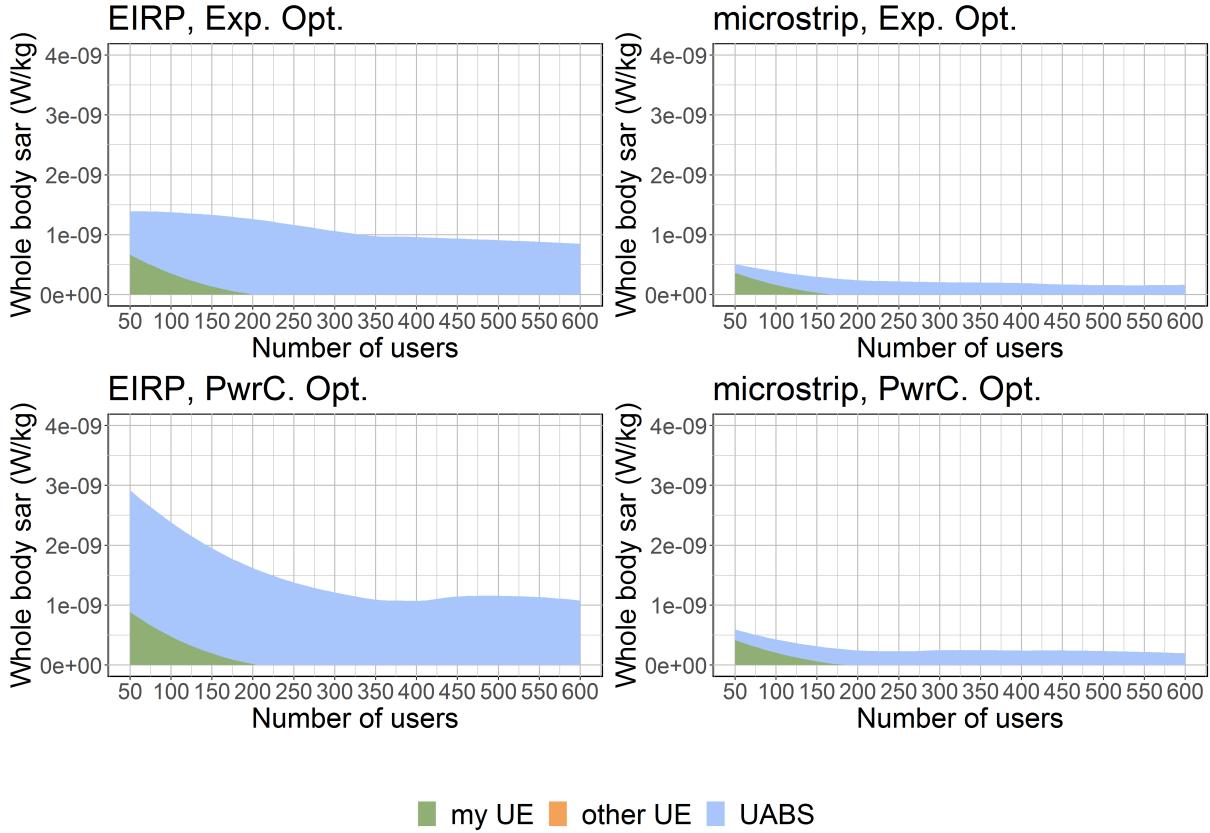


Figure 5.12: This figure shows how different sources are influenced by an increasing number of users.

While the population grows, more and more users become uncovered causing the average SAR to drop. However, this does not conclude that by increasing the population, the SAR of a user who is directly beneath a UABS would be less. To investigate this, a user is positioned in the middle of the city centre of Ghent and a UAV is positioned above him. Initially, only 49 people are active around him. The SAR of our central user is monitored while the population around him is growing. Figure 5.13 shows with the black lines which users are connected. Figure 5.13.a is for only 50 users and shows that only one user is connected besides our central user. Figure 5.13.b considers 600 users and shows much more connected users. Scenario I already showed that the SAR from the user's own device is only influenced by the flying height. The flying height for this experiment is fixed and the UL SAR from his device should therefore also be a constant. A hypothesis that is confirmed by figure 5.14.a where SAR^{myUE} is equal to $0.15 \mu W/kg$. The SAR from the UABS experiences a slight increase of $0.005 \mu W/kg$. When the population grows, more users become available and some will spawn near the central user. The UABS will likely decide to cover these users as well as visible in figure 5.13. These users might have a slightly worse path loss because of obstructing buildings or somewhat bigger distance.

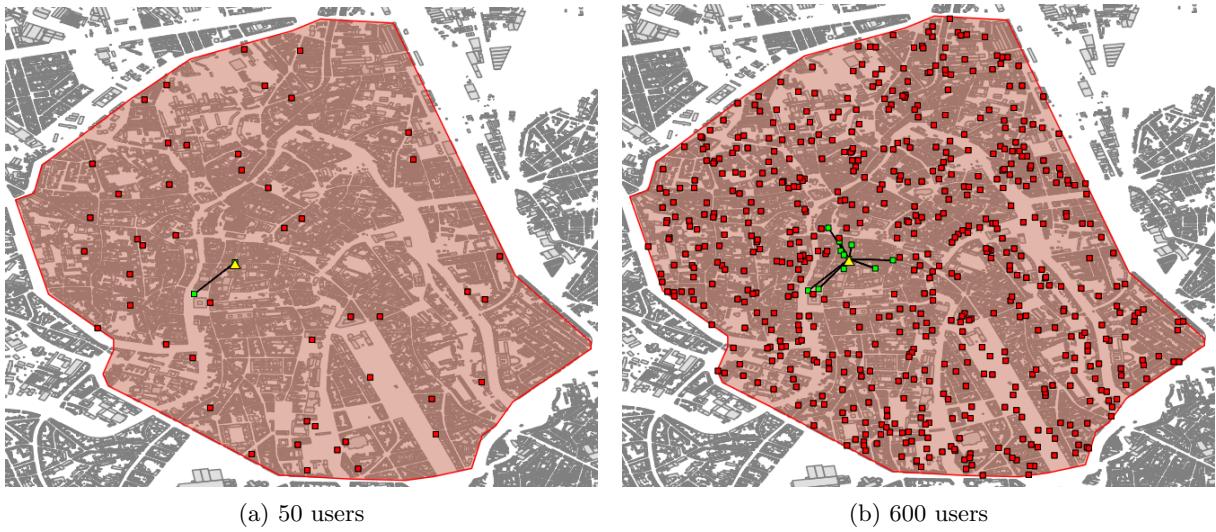


Figure 5.13: Overview of which users are connected to the UABS.

The UABS reacts to this by increasing his power consumption causing an increase in the DL SAR for the central user. The far-field radiation from UE is very low as mentioned before and therefore added separately in figure 5.14.b. It shows that the SAR from other UE increases from zero to 0.15 pW/kg . This is normal behaviour considering that around the central user more and more people become available of which some will be connected to the UABS and therefore also emitting radiation.

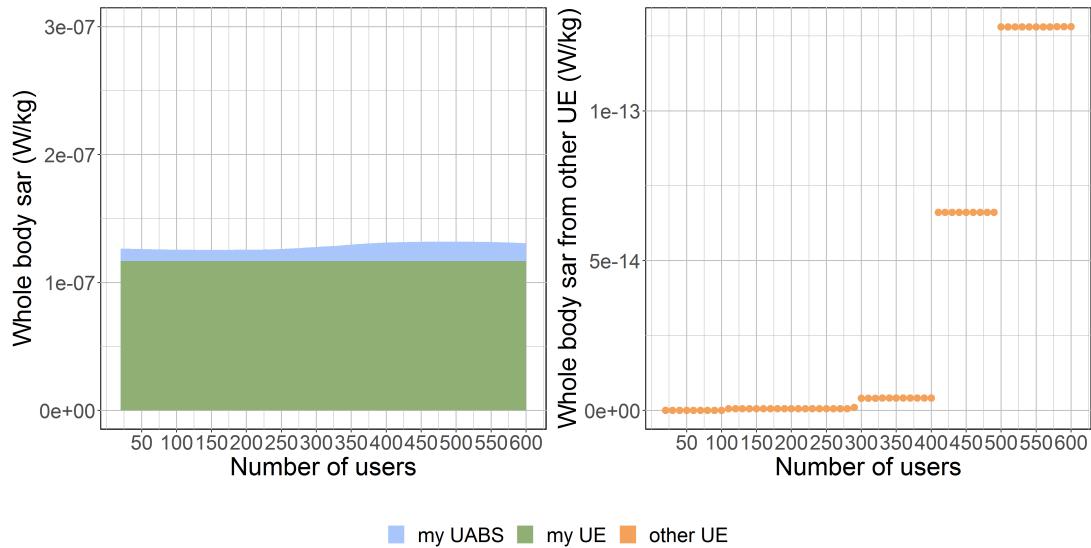


Figure 5.14: SAR-values for the user who is directly beneath the only UABS available.

5.3 Scenario III: Unlimited UAVs

This scenario, just like the previous one, has much more users in the network and investigates the same cases which include the variable flying height and the variable number of users. The only difference is that the restriction of only one UABS is dropped. An example is presented in figure 5.15.

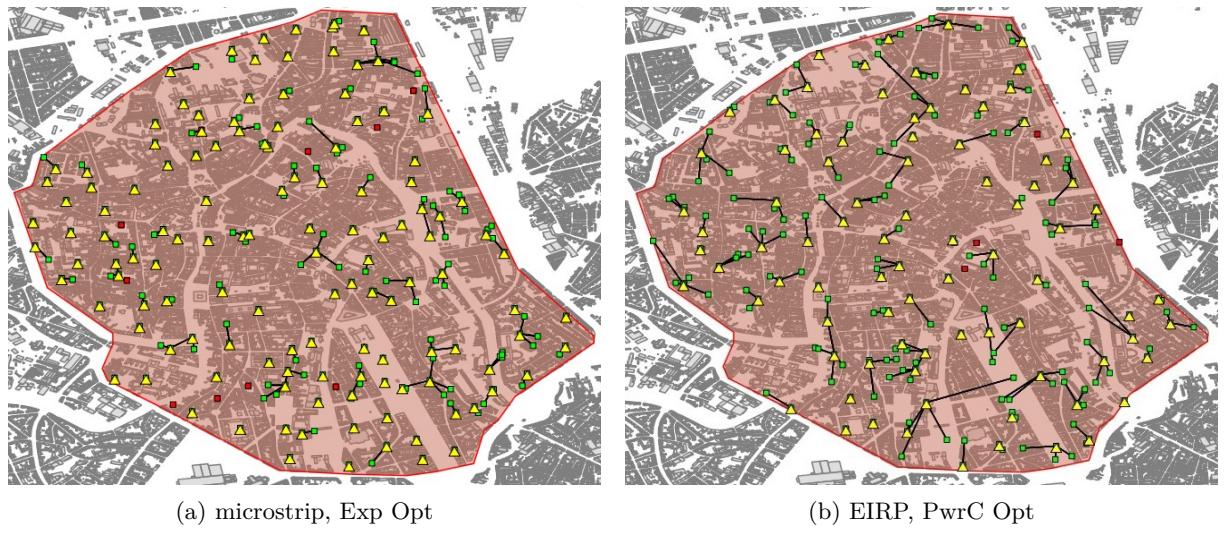


Figure 5.15: Example of two networks with users distributed over the area. Yellow triangles represent UABSs and are connected with black lines to users in green. Uncovered users are coloured in red.

5.3.1 Influence of the Flying Altitude

The first evaluated parameter of this scenario is the flying height with a fixed number of 224 users. Scenario II already explained that when only one UAV is available, a power consumption optimized network will not result in a low powered network. In this scenario, there is no limitation on the number of UAVs and the network remains thus unaltered after the decision algorithm is done. Figure 5.16 proves that the different optimization strategies work as intended. Power consumption optimized networks have indeed a lower power consumption but therefore result in higher electromagnetic radiation. On the other hand, an exposure optimized network will reduce the electromagnetic exposure by using more UAVs and thence also increases the network's power consumption. A behaviour that was also concluded in [?]. For example, when comparing both optimization strategies for the same equivalent isotropic radiator and the same default flying height, we see that the power consumption optimized network requires 51 W and therefore exposes its users to 15 mV/m. When optimizing towards electromagnetic radiation,

the exposure drops to 11.5 mV/m but at a cost of a higher power consumption of 54 W .

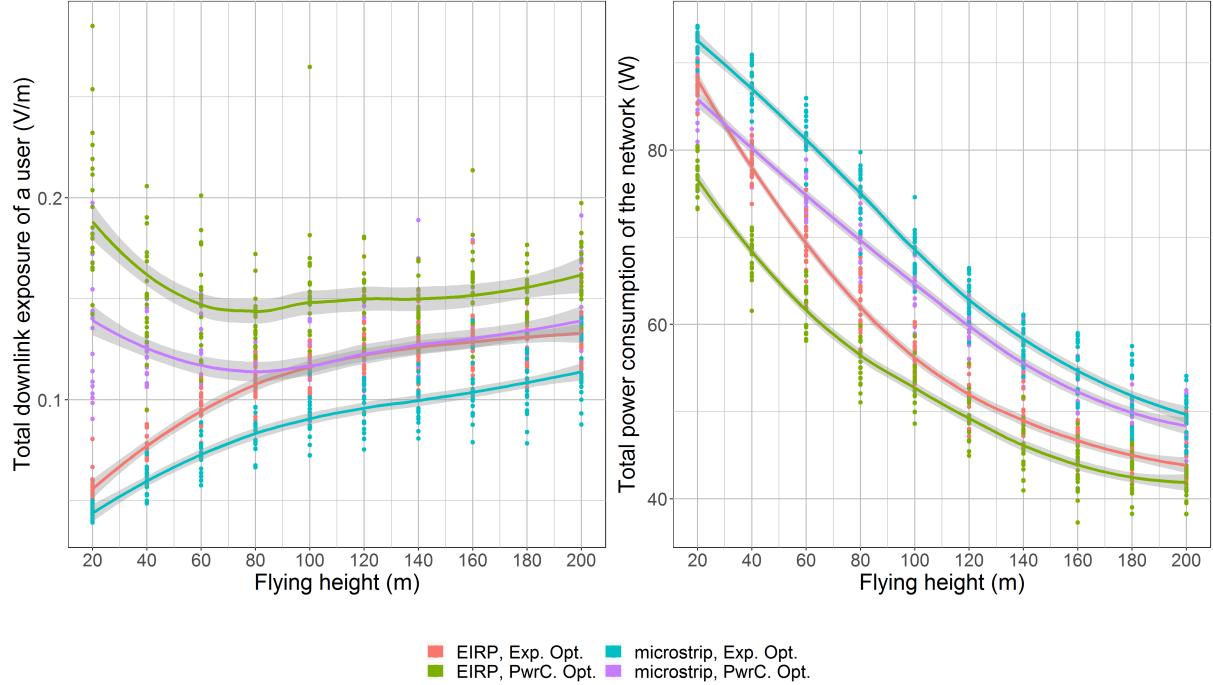


Figure 5.16: These two figures show how the flying height influences the downlink electromagnetic radiation of the average user (left) and power consumption of the entire network (right) for an unlimited number of drones.

Further, figure 5.16.a also shows that the exposure in an exposure optimized network increases logarithmically while in a power consumption optimized network the exposure has a concave relationship with the flying height, and has its lowest point at around 70 metres. Figure 5.17.a shows that the optimal coverage is achieved at a low flying height of 40 metres with around 99% coverage. However, there is a downside to this. Figure 5.17.b shows that the number of required UAVs increases when the flying altitude becomes lower; a behaviour which was also determined in [?]. For example, an microstrip Exp Opt network and an EIRP PwrC Opt network require respectively 84 and 64 UABSSs at a flying altitude of 200 m which increases respectively to 211 and 162 UABSSs at a much lower flying altitude of 20 m.

Scenario I already proved that for low altitude UAVs, the main source of electromagnetic radiation are UABSSs. This changed around 80 metres where UL electromagnetic radiation of the UE exceeds DL radiation in order to still be able to reach the high flying UABSSs. When looking at the individual sources of electromagnetic exposure presented in figure 5.18, we notice the same behaviour where the SAR from the own device indeed increases between 89 and 141 nW/kg by raising the flying altitude from 20 to 200 metres. However, a more logarithmic increase is shown

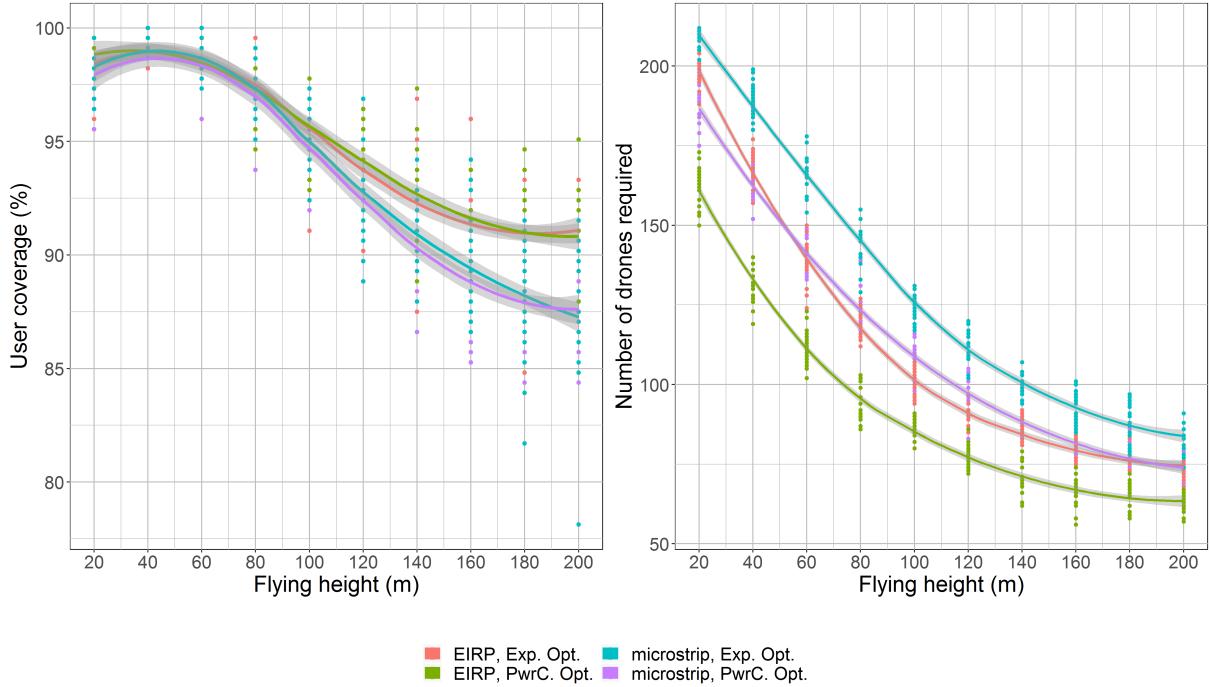


Figure 5.17: This graph shows how much UAVs are required at different flying heights while trying to achieve a 100% coverage.

despite the fact that figure 5.2 showed an exponential increase. This was however deducted with only one user present in the network as opposed to this scenario where 224 users are present. The electromagnetic radiation from the covered users will still behave like it did in Scenario I. Moreover, the SAR shown in figure 5.2 is averaged over covered and uncovered users. In conclusion, the average UL SAR in figure 5.2 will not increase as fast as it did in Scenario I (fig. 5.2).

We can see from figure 5.18 that once the flying altitude surpasses the NLoS of the buildings, around 70 to 80 metres, the SAR from the serving UABS remains more or less constant for all configurations. The SAR^{myUABS} varies for flying heights between 80 and 200 metres around 160 nW/kg for microstrip PwrC Opt networks and around 98 nW/kg for microstrip Exp Opt and EIRP PwrC Opt networks. An EIRP Exp Opt network is situated around 47 nW/kg .

When looking at the exposure from ‘other UABSs’, an increase in electromagnetic radiation at higher flying altitudes is noticed. The lower path loss from less obstructing buildings will be the reason. The figures from 5.18 clearly show that this increase in electromagnetic radiation will be less for a microstrip patch antenna. The reason behind this is that energy will be more focused towards the ground and there is less sideways radiation because of attenuation. The results show that by raising the flying altitude from 20 to 200 metres, the $SAR^{otherUABS}$ will

increase between 115 and 140 nW/kg for EIRP antennae and between 54 and 74 nW/kg for microstrip patch antennae.

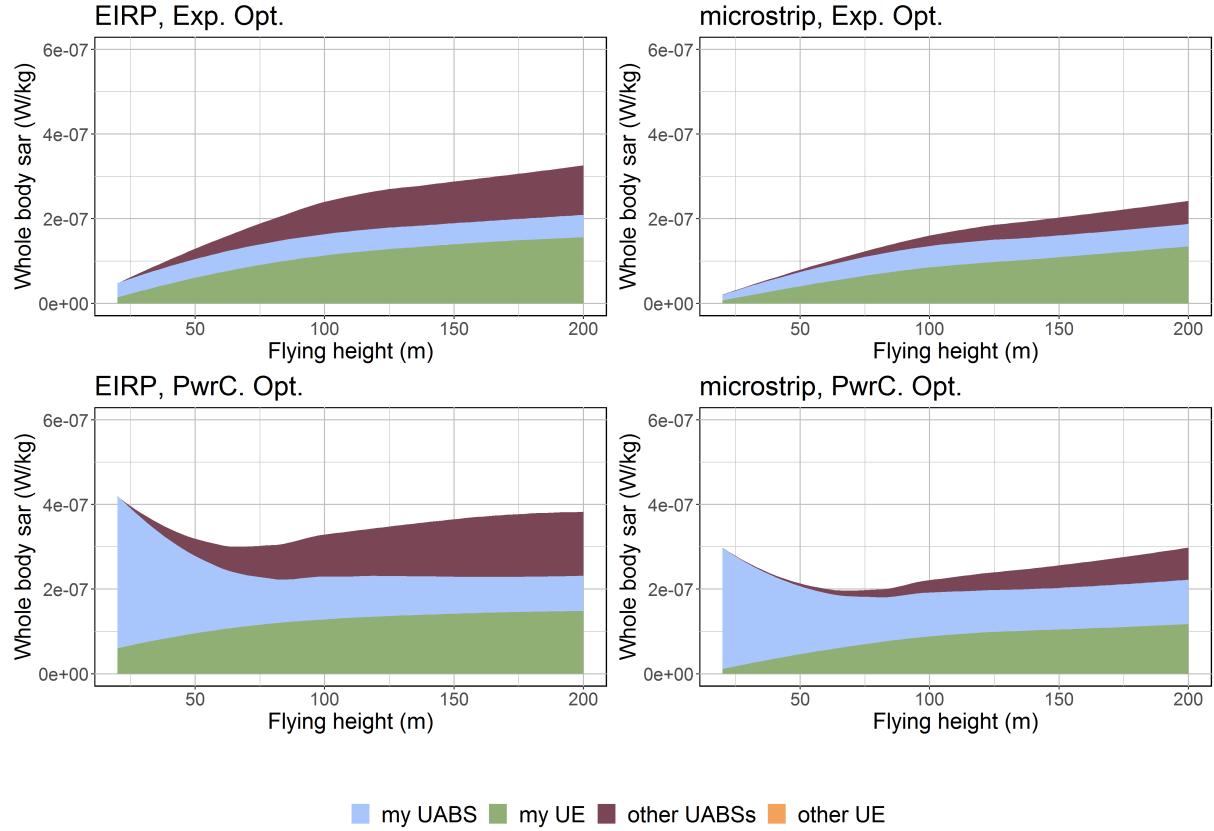


Figure 5.18: Each figure corresponds with a certain configuration and shows how the SAR from different sources are influenced by an increasing flying height.

5.3.2 Influence of the Number of Users

The second evaluated parameter of Scenario III is a variable number of users while the flying height is fixed to 100 metres. Figure 5.19.a shows how the tool tries to reach a 100% coverage. The percentage of covered users is slightly less for smaller networks. For only 50 users, an average coverage of around 93% is achieved while a network with 600 users has a coverage of around 97%. Figure 5.19.b shows how the tool requires more UAVs for these large populations. The difference in optimization strategy is very little for a small amount of people but increases very quickly. When the population increases from 50 to 600 users, 200 more UABSSs are required by a microstrip Exp Opt network around 130 more UABSSs for an EIRP Exp Opt network or a microstrip PwrC Opt network and 110 more UABSSs for an EIRP PwrC Opt network. This is an expected behaviour when looking at Scenario II where, with only one UABS available, the percentage of covered users decreases for these larger populations.

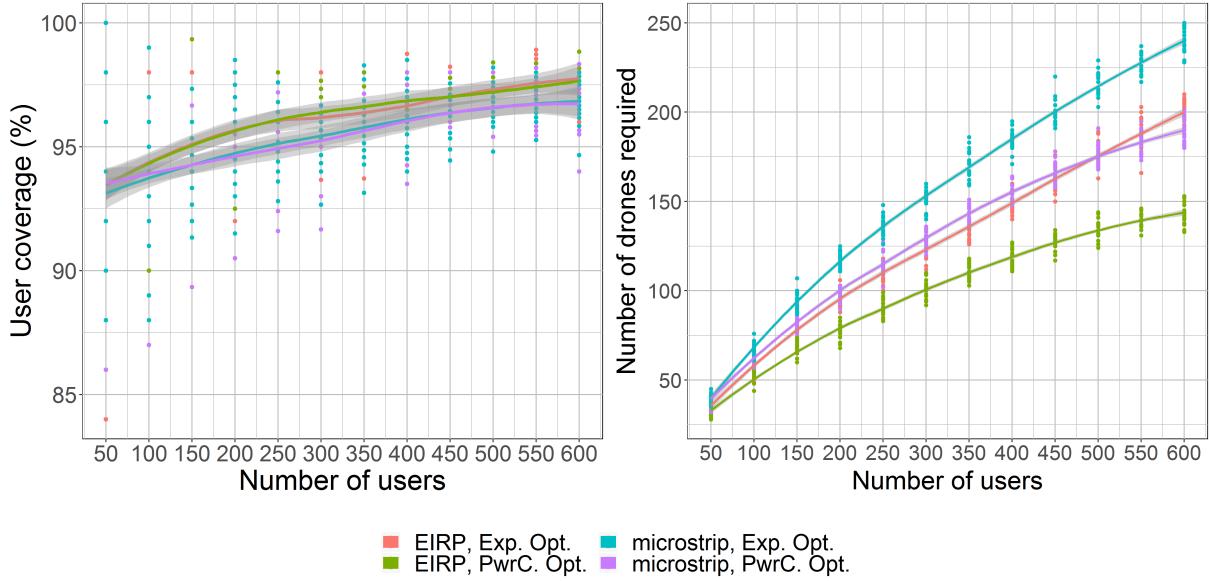


Figure 5.19: This graph shows how much UAVs are required for different flying heights while trying to achieve a 100% coverage.

Figure 5.20 shows that the electromagnetic radiation and power consumption increase for larger populations which is normal since more drones will be available. When the population increases from 50 to 600 users, the electromagnetic radiation increases between 80 and 130 mV/m depending on the configuration. The power consumption with 50 users is for all configurations around 20 W . Once the population is increased to 600 users, a microstrip Exp Opt network will require 130 W , a microstrip PwrC Opt network requires 117 W , EIRP Exp Opt networks require 107 W and EIRP PwrC Opt network requires 92 W .

The correct behaviour of the decision algorithm became already clear in the previous subsection 5.3.1 but is also confirmed here. When comparing both optimization strategies, a power consumption optimized network requires around 5 W less but exposes its users between 27 mV/m and 30 mV/m more than exposure optimized networks. Further, it is also noticed that equivalent isotropic radiators cause more electromagnetic radiation for less energy compared to microstrip patch antennae. When comparing the two types of antennae for a default number of 224 users, an equivalent isotropic radiator will expose the average user between 25 mV/m and 27 mV/m more while requiring around 12 W less than when the network would be using a microstrip patch antennae.

This means that Scenario III confirms that a power consumption optimized network indeed results in less UAVs and a lower power consumption for the entire network. At the same time, Scenario II showed that the active UABSS have a higher individual power consumption. We can therefore state that a power consumption optimized network will reduce its total power

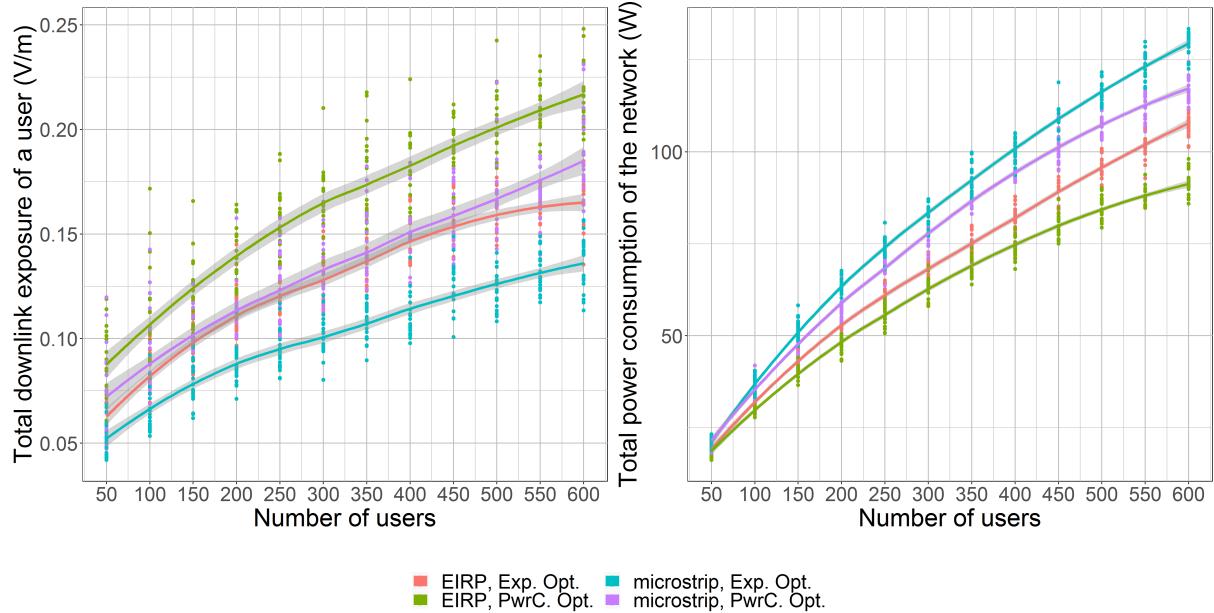


Figure 5.20: The influence of the population size on the downlink electromagnetic radiation (a) and power consumption (b).

consumption by using a few high powered UAVs. Likewise for an exposure optimized network, we can conclude that the network has indeed a lower electromagnetic exposure but the power consumption of the entire network is much higher. In Scenario II became already clear that the active UABSs have a low power consumption in order to guarantee a low electromagnetic exposure towards the users. We can conclude that an exposure optimized network will reduce the exposure of an individual by deploying several low powered UABSs.

Figure 5.21 shows how the SAR^{ownUE} remains almost constant which is normal since the flying height remains the same and will vary between $0.7 \mu W/kg$ and $1.2 \mu W/kg$. The SAR^{myUABS} barely increases in an exposure optimized network and is situated around $0.5 \mu W/kg$ for both antennae. The power consumption optimized network also starts around $0.5 \mu W/kg$ but increases when more users become online. A normal behaviour when considering that these UABSs try to cover much more users. Therefore, the SAR^{myUABS} with 600 users increases up to $2 \mu W/kg$ depends on the configuration. The SAR value that increases the most is $SAR^{otherUABS}$ which starts really low with less than $0.1 \mu W/kg$ for 50 users for all configurations. The SAR increases however very fast. The biggest increase is noticed in an EIRP PwrC Opt network where $3 \mu W/kg$ is measured for 600 users. The $SAR^{otherUE}$ increases the least for microstrip Exp Opt with only $1 \mu W/kg$ for 600 users.

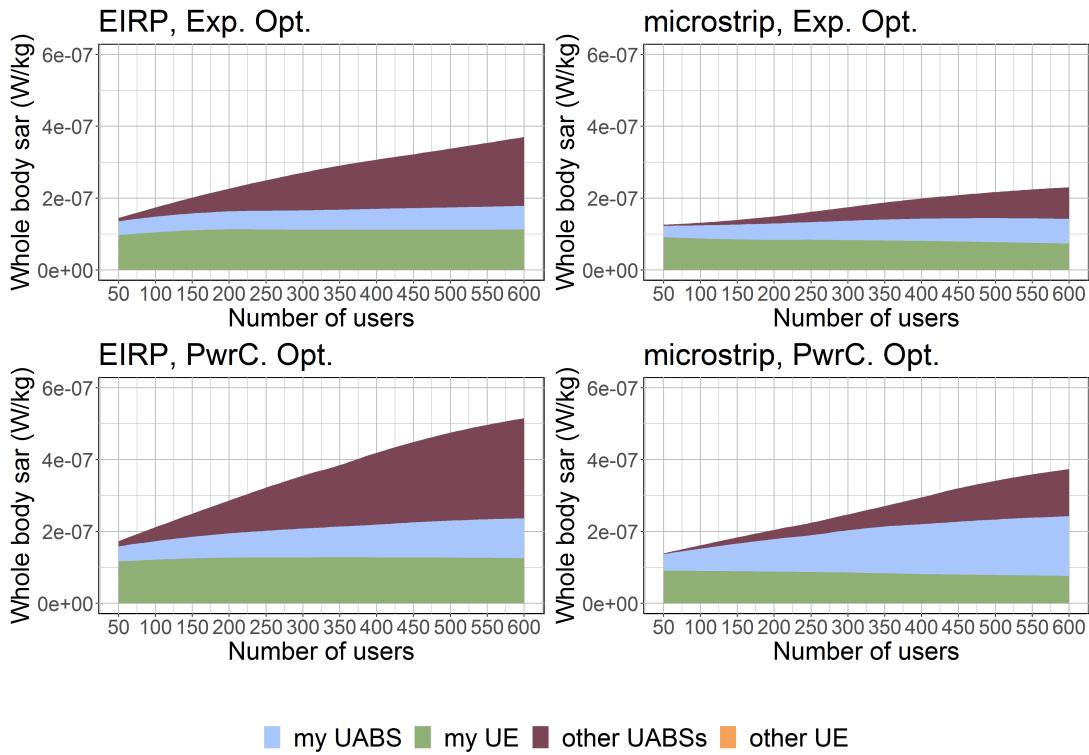


Figure 5.21: Each figure shows the SAR from different sources for an increasing population size.

5.4 Summary

This chapter discusses the achieved results when applying the tool to the different scenarios. Scenario I concludes that the required transmission power increases logarithmically with the flying height. The results show how the user's device is the main source of electromagnetic radiation for all flying heights above 80 metres and grows exponentially along with the flying height. On the other hand, the electromagnetic radiation from the UABS remains constant around 10 nW/kg . Scenario II shows that electromagnetic exposure drops when the population size increases or when the flying height decreases and a lower user exposure corresponds with lower coverage. Users that are covered are, just like in Scenario I, mainly exposed to their own device, followed by the UABS in second place. The results also show that the power consumption slightly increases when the UABS covers more users. The last scenario shows that less UABSS are required for higher flying altitudes and therefore result in a decreased power consumption. Exposure from the serving UABS remains almost constant above 80 metres while exposure from other UABSS and UE increases. Scenario III also shows that more UABSS are required for larger populations and therefore increase power consumption and electromagnetic exposure. Finally, the results also confirm that the optimization algorithm works as intended and is able to optimize towards either electromagnetic exposure or overall power consumption.

Scenario	Configuration	Network power consumption	Exposure	WB SAR
Scenario I	Exp Opt			
	PwrC Opt			
Scenario II	EIRP Exp Opt			
	EIRP PwrC Opt			
	microstrip Exp Opt			
	microstrip PwrC Opt			
Scenario III	EIRP Exp Opt			
	EIRP PwrC Opt			
	microstrip Exp Opt			
	microstrip PwrC Opt			

6

Conclusions

The following section presents the conclusion where the impact of the flying height and users population in a UAV-aided network is investigated by examining electromagnetic exposure and power consumption. Also, optimization techniques towards both evaluation parameters have been applied and two different antenna types have been considered. All conclusions are based on the default configuration with a flying height of 100 metres and 224 active users to cover. The other parameters are described in table 4.1.

6.1 Conclusion

Literature showed that a network can be optimized towards either the power consumption of the entire network or the electromagnetic exposure of the average user using a fitness function. This is because the power required to activate a new base station is much higher than for raising the electromagnetic radiation and therefore increasing its range [?]. The fitness function was originally applied for fixed transmission towers but can also be used for UABSs as this research shows. However, the fitness function should be used with care considering that UABSs can be placed anywhere as opposed to the transmission towers from [?] who have a predetermined position. For default networks, the electromagnetic field radiation from a power consumption optimized network can be reduced up to 23% for equivalent isotropic radiators and 30% for

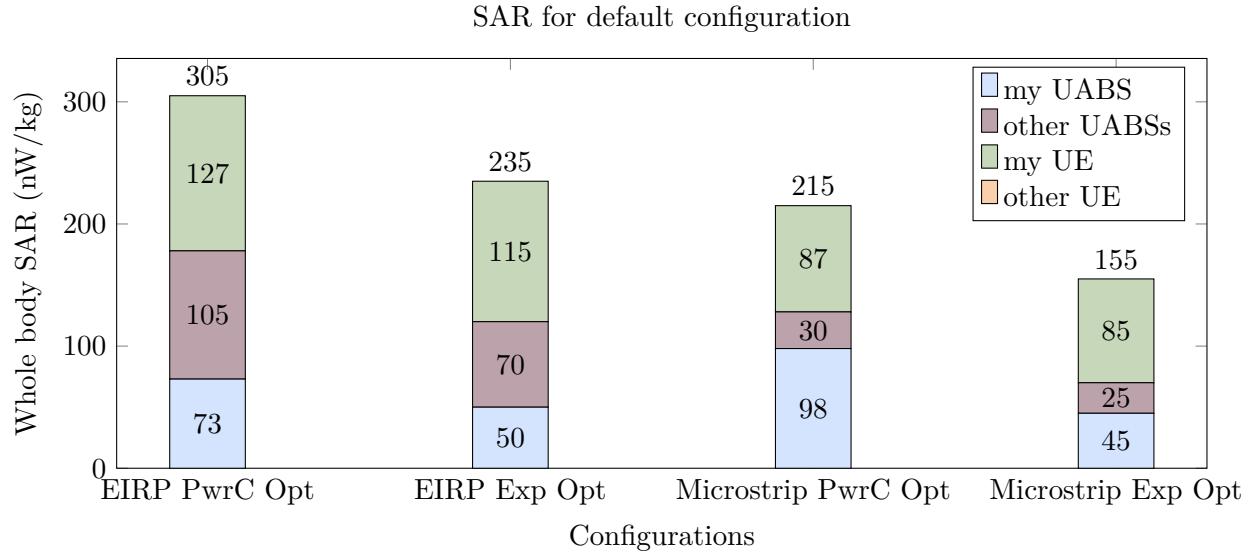


Figure 6.1: The contribution of each source towards the total SAR for each considered configuration. The values are achieved with default values.

microstrip patch antennae by optimizing towards electromagnetic exposure. Doing so, decreases the range of the UABS and much more UABSS will be needed. Therefore, exposure optimized networks will, on average, use 18 drones more than power consumption optimized networks and require therefore 5 W more energy. A power consumption optimized network on the other hand will try to limit the number of drones in order to save energy. So as a rule of thumb: an exposure optimized network will result in a lot of low powered devices (increasing the overall power consumption) while a power consumption optimized network results in a few high powered devices (increasing the exposure of the average user). The authors from [?] confirm this by stating that smaller cells will reduce electromagnetic radiation. If the goal is to remain in the air for a longer period of time, an exposure optimized network is recommended because the power consumption of an individual UABS is lower. On the other hand, a power consumption optimized network is cheaper because less drones are involved. Moreover, the results show that the electromagnetic radiation in a power consumption optimized network (with high powered UABSS) is far below the thresholds enforced by the Flemish government with more than a hundred thousandth of the maximal allowed whole body SAR.

A directional microstrip patch antenna is introduced because it gives several advantages compared to omnidirectional antennae. Directional antennae are able to focus their energy there where it is needed, namely towards the ground. Microstrip patch antennae further benefit from their thin and lightweight design. The performance of this directional microstrip patch antenna has been compared to a fictional equivalent isotropic radiator. This equivalent isotropic radiator has higher exposure and coverage for less power compared to a microstrip patch antenna. For a default network, a microstrip patch antenna can reduce between 30% and 34% electromagnetic

exposure from an equivalent isotropic radiator. Doing so will require around 24 drones extra and therefore increasing the power consumption with 11 W. The fact that an equivalent isotropic radiator has higher electromagnetic exposure for less power is due to the absence of attenuation and can hypothetically be compared to an antenna with a very big aperture angle. A microstrip patch antenna with a more limited aperture angle of 90° requires more resources but causes less sideways radiation. So the exposure from other UABSs will also be less.

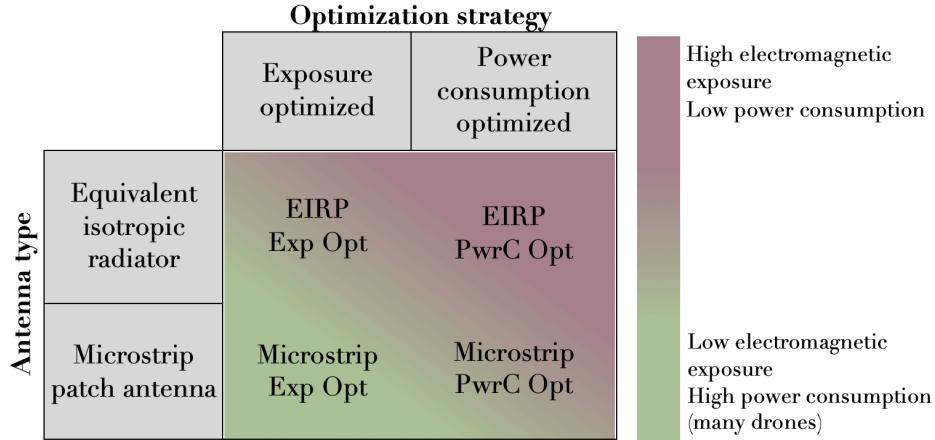


Figure 6.2: Matrix with the four possible configurations, colour-coded based on the results.

Figure 6.2 shows an overview based on the results from the two optimization strategies and the two types of antenna. Remarkable is that an EIRP exposure optimized network behaves very similar to a microstrip power consumption optimized network. Therefore, the microstrip patch antenna in a power consumption optimized network is recommended. The microstrip patch antenna will generate less electromagnetic radiation by design and the power consumption optimization reduces the number of required drones and power. A microstrip patch antenna with an aperture angle of 90° is considered as a good solution but if budget is more limited, an antenna with a larger aperture angle would further reduce cost without interfering with the Flemish legislation regarding electromagnetic exposure.

Figure 6.3 gives an overview of the contribution of SAR in percentage to the total exposure for a default network. The values have been averaged over all four considered configurations. The user's main source of exposure is clearly the user's own device which contributes 52% of the total experienced exposure. A conclusion that was also made by the authors of [?] where a 5G network is simulated and by the authors from [?] where a GSM and UMTS network is simulated. Further, in [?] is also concluded that, thanks to power control, the electromagnetic radiation from the mobile phone comes really close to the exposure from the UABS. Also this is confirmed by the results. Figure 6.3 shows that the electromagnetic exposure from all UABSs together covers the remaining 48% of which 15 % is from the serving UABS. The electromagnetic exposure from devices belonging to other people can be ignored compared to the much higher electromagnetic

exposure from the other sources and contributes only 0.0001%. It is important to notice that a rather low PUSCH value is used in equation 3.21 for determining the UL radiation and it is believed that a higher value will have a major effect on the SAR from the user's own device but also from neighbouring devices. Investigating this parameter is however out of scope and could be addressed in a future work.

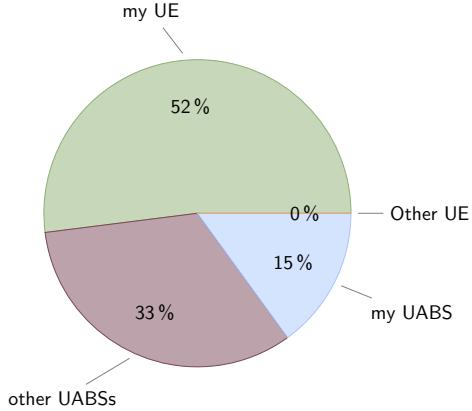


Figure 6.3: Contribution from each source towards the total SAR that is experienced by the weighted average user. The percentages are averaged over the four considered configurations.

As last, the results confirm that the flying height and population size have a major influence on electromagnetic exposure and power consumption. It becomes clear that more UABSs are required when the population size increases. This results in a higher power consumption and electromagnetic exposure. When the population increases from 50 to 600 users, the electromagnetic radiation increases between 80 and 130 mV/m depending on the configuration. The power consumption increases with 110 W for all configurations. The main source that is influenced by the number of users is the SAR from other UABSs with an increase between 1 and 3 $\mu W/kg$, depending on the configuration. Further, increasing the flying altitude has a positive influence on the number of required drones which on their turn have a positive influence on power consumption. Increasing the flying altitude from 20 m to 200 m, decreases the number of required drones around 59%. This decrease in number of UABSs was also concluded in [?]. Also authors from [?] made the conclusion that reduced path loss decreases electromagnetic exposure. The electromagnetic radiation from the UABSs remains more or less the same for flying altitudes between 80 and 200 metres. Most UABSs are in LoS and no more power will be used thanks to power control. However, the electromagnetic radiation from the user's own device does increase in order to reach the high flying drones. At around 80 metres, the exposure from the user's device surpasses the exposure from the serving UABS. When more UABSs are available in the network, electromagnetic exposure from other UABS will increase as well because more UABSs come into LoS. Raising the flying altitude from 20 to 200 m will increase the SAR from other UABSs between 46 and 49 times when using an EIRP antenna and between 70 and 85 times when using a microstrip patch antenna. It is therefore concluded that raising the flying height

has a positive influence on the number of UABSs but is not unlimited since the total SAR will increase as well. When also considering the results from [?] where a flying altitude of 80 metres is suggested for an optimal access and backhaul connectivity, a flying height of 80 metres is also here proposed for the city centre of Ghent.

6.2 Summary

The microstrip patch antenna with an aperture angle of 90° is a suitable starting point for an antenna. This directional antenna focusses electromagnetic radiation where it is needed. Unwanted sideways radiation is therefore reduced by design. The sufficiently large aperture angle covers enough users. The antenna is recommended to be deployed in a power consumption optimized network since less drones are required and therefore also less expensive. The optimal flying height for the city centre of Ghent is believed to be situated at 80 metres since lower flying heights require much more UABSs and higher flying heights have a negative influence on the electromagnetic exposure.

6.3 Future work

Despite the fact that many parameters have been examined, still some parameters require further investigations. The PUSCH value defines the minimal required signal strength received by the UABS and still needs to be evaluated for different values. Also, the exposure caused by backhaul links has not been evaluated yet.

The chosen microstrip patch antenna is solely based on literature and performing an excessive research to various types of radiation patterns is outside the scope of this master dissertation. It is expected that the radiation can further be improved by using microstrip patch antennae in more complex array-configurations.

The tool provides support for any possible radiation pattern and applies this to any UABS. However, despite some minor changes, each UABS can have its custom radiation pattern which makes 3D beamforming possible. Therefore, electromagnetic exposure can be determined for base stations where MiMo and massive MiMo are in use.

Also, the tool makes use of an exact algorithm. Despite the fact that several tactics have been introduced to improve performance, large populations still cause long runtimes. It might be useful to reduce the quality of the result in order to improve performance. Mozafari et al. discusses in [?] several other approaches besides exact algorithms like heuristic methods, machine learning and so on.

Appendices

A

Radiation Patterns: Datasheet

Table A.1 gives an overview of the attenuation in the E and H plane. The first radiation pattern has a square groundplane with an edge of 0.060 metre while the second pattern has more a rectangular shape with a width of 0.0524m and a length of 0.0438m. All other settings are equal as defined in 3.2.1

Table A.1: Overview of attenuation in dBm.

angle	pattern 1		pattern 2	
	E	H	E	H
0	0	0	0	0
10	-0,17	-0,14	-0.1561	-0.158
20	-0,67	-0,57	-0.5797	-0.6257
30	-1,48	-1,27	-1.263	-1.386
40	-2,57	-2,22	-2.193	-2.412
50	-3,90	-3,39	-3.357	-3.665
60	-5,40	-4,73	-4.741	-5.099
70	-7,09	-6,23	-6.337	-6.658
80	-8,82	-7,87	-8.136	-8.278
90	-10,54	-9,70	-10.11	-9.88
100	-12,20	-11,84	-12.14	-11.34
110	-13,73	-14,37	-13.81	-12.47
120	-15,04	-17,65	-14.42	-13.00
130	-16,01	-21,83	-13.72	-12.82
140	-16,47	-23,63	-12.41	-12.08
150	-16,42	-20,37	-11.15	-11.15
160	-16,05	-17,49	-10.21	-10.33
170	-15,69	-15,93	-9.683	-9.786
180	-15,54	-15,54	-9.596	-9.596
190	-15,69	-16,30	-9.963	-9.784
200	-16,05	-18,44	-10.79	-10.33
210	-16,42	-22,85	-12.07	-11.15
220	-16,47	-31,23	-13.71	-12.07
230	-16,00	-24,07	-15.25	-12.80
240	-15,03	-18,05	-15.65	-12.99
250	-13,72	-14,42	-14.3	-12.45
260	-12,20	-11,81	-12.11	-11.33
270	-10,54	-9,70	-9.882	-9.866
280	-8,82	-7,87	-7.859	-8.267
290	-7,09	-6,23	-6.069	-6.649
300	-5,40	-4,73	-4.502	-5.093
310	-3,90	-3,39	-3.154	-3.661
320	-2,57	-2,22	-2.029	-2.409
330	-1,48	-1,27	-1.138	-1.384
340	-0,67	-0,57	-0.4963	-0.6246
350	-0,17	-0,14	-1143	-0.1575

B

Radiation patterns: Example Configuration

In listing 2, a possible configuration for a radiation pattern is described. It is important to notice that this example configuration does not represent the used configuration in this master dissertation. The `radiationPattern`-tag consists of a `slices`-tag. This tag can contain as much slices as desired. In this example, 3 slices are defined indicated with the `attenuation`-tag. This tag contains a mandatory attribute `az` which defines the azimuth angle to which all underlying attenuation values belong. Inside the `attenuation`-tag, all attenuation values are written in a `value`-tag. Each `attenuation`-tag must contain an equal amount of `value`-tags.

The tool distributes all values equally over the 180° of that slice. In the example below, each `attenuation`-tag contains 10 values meaning that the exact attenuation is known every 20° .

The highlighted value of $-14, 42$ is therefore measured at an azimuth angle of 0° and an elevation angle of 120° (counterclockwise).

```

1 <radiationPattern>
2   <slices>
3     <attenuation az="0">
4       <value>0</value>
5       <value>-0.5797</value>
6       <value>-2.193</value>
7       <value>-4.741</value>
8       <value>-8.136</value>
9       <value>-12.14</value>
10      <value>-14.42</value>
11      <value>-12.41</value>
12      <value>-10.21</value>
13      <value>-9.596</value>
14    </attenuation>
15    <attenuation az="90">
16      <value>0</value>
17      <value>-0.6257</value>
18      <value>-2.412</value>
19      <value>-5.099</value>
20      <value>-8.278</value>
21      <value>-11.34</value>
22      <value>-13.00</value>
23      <value>-12.08</value>
24      <value>-10.33</value>
25      <value>-9.596</value>
26    </attenuation>
27    <attenuation az="180">
28      <value>0</value>
29      <value>-0.4963</value>
30      <value>-2.029</value>
31      <value>-4.502</value>
32      <value>-7.859</value>
33      <value>-12.11</value>
34      <value>-15.65</value>
35      <value>-13.71</value>
36      <value>-10.79</value>
37      <value>-9.596</value>
38    </attenuation>
39  </slices>
40 </radiationPattern>

```

Listing 2: Example configuration of a radiation pattern.