THOMAS HUCKELL



OBJECTIVE

Recent Masters graduate in Mechanical Engineering with a research focus on legged robotics. Seeking to build industry experience and apply my knowledge of modeling and control of dynamic systems to start my career in robotics.

EDUCATION

Queen's University Sept 2019 - May 2022

MASc in Mechanical and Materials Engineering

Thesis: "Standing Balance of Legged Robots: Leveraging Reduced Order Models to Improve Balancing Performance"

- Proposed balancing model for legged robots that extends existing models to include additional balancing strategies
- Utilized model predictive control (MPC) and trajectory optimization to compare push recovery performance of the proposed balancing model against existing models
- Validated implementation of the MPC on a one-legged robot in a push recovery simulation in Simulink Simscape Multibody

Queen's University

Sept 2015 - April 2019

BASc in Mathematics and Engineering

- Dean's Scholar with First Class Honours
- Recipient of the R.H. Clark Applied Science Centennial Scholarship

EXPERIENCE

Mechanical Engineering Manager

April 2017 - May 2019

Queen's Mostly Autonomous Sailboat Team

- Led and oversaw the mechanical team of 10+ undergraduate students with the design and development of a sailboat to compete in the International Robotic Sailing Regatta
- Designed and constructed molds from CAD parts to fabricate sailboat's components from composite materials

AWARDS

RAIS 2021 Poster Competition

Oct 2021

• Winner of the robotics category with the poster "Improved Standing Balancing For Legged Robots With Unified Balancing Model"

Dean's Teaching Assistant Award

June 2021

Recognition of exemplary teaching during the 2020-2021 school year

SKILLS

Problem Solving - Leadership - Teamwork - Project Management - Communication

Software Fusion 360 - Solid Works - Simulink - Microsoft Office - Visual Studio Code

Technical Optimal control • Linear control • Modeling • Simulation • CAD

Rapid Prototyping 3D printing - Laser Cutting - CNC - Arduino

Programing MATLAB • C++ • Python • ROS

INTERESTS

Kayak Guide and Instructor (Paddle Canada certified) - Cycling - Camping - Golfing - Woodworking