

Requirement					Possible points		
exercise 1	scale is given for drawings				3		
	Force 1 drawn to scale on 1st set of axes				2		
	Force 2 drawn to scale on 2nd set of axes				2		
	component table	Force 1	Arithmetic	setting up the Force equation correctly for Force 1	1		
				spiting \hat{r} into $\cos\theta\hat{x}+\sin\theta\hat{y}$	1		
				multiplying mass times acceleration	1		
				distributing (FOIL-ing) the force into the component vectors	2		
			units	using correct units for mass and accelaration	2		
				calculation finishes with units that have the correct order of magnitude	2		
				calculation leads to correct units for a force.	1		
				Force 1 x-component entered in table	3		
		Force 1 y-component entered in table	3				
		Force 2	Arithmetic	setting up the Force equation correctly for Force 1	1		
				spiting \hat{r} into $\cos\theta\hat{x}+\sin\theta\hat{y}$	1		
				multiplying mass times acceleration	1		
				distributing (FOIL-ing) the force into the component vectors	1		
			units	using correct units for mass and accelaration	2		
				calculation finishes with units that have the correct order of magnitude	2		
				calculation leads to correct units for a force.	2		
				Force 1 x-component entered in table	3		
			Force 1 y-component entered in table	3			
			x-components are summed correctly to yeild Resultant x-component				3
			y-components are summed correctly to yeild Resultant y-component				3
	F_R drawing		Force 2 has been drawn starting from the tip of Force 1 (or vice versa) on the lower set of axes and both are to scale.				3
		The Resultant force has been drawn from the origin of the lower axes to the tip of the sum of the component axes .				3	
	cTangent	the angle of the reultant vector from the x-axis has been found using the arctan function				2	
		the operand of arctan is set up as y-component over x-component				2	
		units have been included and canceled correctly				1	

Ar	the quadrant of the Resultant force has been accounted for and the actual angle of the resultant vector has been found		2	
	F _R calc	pythagorean theorem set up properly	5	
units have been calculated correctly		3		
Arithmetic has been performed correctly		5		
F _E calc	F=ma used properly	3		
	units have been calculated correctly	2		
	Arithmetic has been performed correctly	2		
% difs	the % difference has been found between the magnagues of the calculated and measured forces		7	
	difference in angle between the calculated and meaued angles is calculated		5	
subtotal			90	
scale is given for drawings			3	
Force 1 drawn to scale on 1st set of axes			2	
Force 2 drawn to scale on 2nd set of axes			2	
component table	Force 1	Arithmetic	seting up the Force equation correctly for Force 1	1
			spiting r-hat into cosθx-hat+sinθy-hat	1
			multiplying mass times acceleration	1
			distributing (FOIL-ing) the force into the component vectors	2
		units	using correct units for mass and accelaration	2
			calculation finishes with units that have the correct order of magnitude	2
			calculation leads to correct units for a force.	1
		Force 1 x-component entered in table		3
		Force 1 y-component entered in table		3
	Force 2	Arithmetic	seting up the Force equation correctly for Force 1	1
			spiting r-hat into cosθx-hat+sinθy-hat	1
			multiplying mass times acceleration	1
			distributing (FOIL-ing) the force into the component vectors	1
		units	using correct units for mass and accelaration	2
			calculation finishes with units that have the correct order of magnitude	2
			calculation leads to correct units for a force.	2
		Force 1 x-component entered in table		3
		Force 1 y-component entered in table		3

exercis			x-components are summed correctly to yeild Resultant x-component	3	
			y-components are summed correctly to yeild Resultant y-component	3	
	F _R drawing		Force 2 has been drawn starting from the tip of Force 1 (or vice versa) on the lower set of axes and both are to scale.	3	
			The Resultant force has been drawn from the origin of the lower axes to the tip of the sum of the component axes .	3	
	ArcTangent		the angle of the reultant vector from the x-axis has been found using the arctan function	2	
			the operand of arctan is set up as y-component over x-component	2	
			units have been included and canceled correctly	1	
			the quadrent of the Resultant force has been accounted for and the actual angle of the resultant vector has been found	2	
	F _R calc		pythagorean theorum set up properly	5	
			units have been calculated correctly	3	
			Arithmetic has been performed correctly	5	
	F _E calc		F=ma used properly	3	
			units have been calculated correctly	2	
			Arithmetic has been performed correctly	2	
	% difs		the % difference has been found between the magnagues of the calculated and measured forces	7	
			difference in angle between the calculated and meaured angles is calculated	5	
	subtotal			90	
			scale is given for drawings	3	
			Force 1 drawn to scale on 1st set of axes	2	
			Force 2 drawn to scale on 2nd set of axes	2	
		Force 1	Arithmetic	seting up the Force equation correctly for Force 1	1
				spiting r-hat into cosθx-hat+sinθy-hat	1
				multiplying mass times acceleration	1
				distributing (FOIL-ing) the force into the component vectors	2
			units	using correct units for mass and accelaration	2
				calculation finishes with units that have the correct order of magnitude	2
				calculation leads to correct units for a force.	1
				Force 1 x-component entered in table	3

exercise 3

component table	Force 2	Arithmetic	Force 1 y-component entered in table	3
			seting up the Force equation correctly for Force 1	1
			spiting r-hat into cosθx-hat+sinθy-hat	1
			multiplying mass times acceleration	1
			distributing (FOIL-ing) the force into the component vectors	1
		units	using correct units for mass and accelaration	2
			calculation finishes with units that have the correct order of magnitude	2
			calculation leads to correct units for a force.	2
		Force 2 x-component entered in table		3
		Force 2 y-component entered in table		3
	Force 3	Arithmetic	seting up the Force equation correctly for Force 1	1
			spiting r-hat into cosθx-hat+sinθy-hat	1
			multiplying mass times acceleration	1
			distributing (FOIL-ing) the force into the component vectors	1
		units	using correct units for mass and accelaration	2
			calculation finishes with units that have the correct order of magnitude	2
			calculation leads to correct units for a force.	2
		Force 3 x-component entered in table		3
		Force 3y-component entered in table		3
		x-components are summed correctly to yeild Resultant x-component		3
	y-components are summed correctly to yeild Resultant y-component		3	
F _R drawing	Force 2 has been drawn starting from the tip of Force 1 (or vice versa) on the lower set of axes and both are to scale.		3	
	The Resultant force has been drawn from the origin of the lower axes to the tip of the sum of the component axes .		3	
ArcTangent	the angle of the reultant vector from the x-axis has been found using the arctan function		2	
	the operand of arctan is set up as y-component over x-component		2	
	units have been included and canceled correctly		1	
	the quadrent of the Resultant force has been accounted for and the actual angle of the resultant vector has been found		2	
q calc	pythagorean theorem set up properly		5	
	units have been calculated correctly		3	

	F _f	Arithmetic has been performed correctly	5
	F _E calc	F=ma used properly	3
		units have been calculated correctly	2
		Arithmetic has been performed correctly	2
	% difs	the % difference has been found between the magnagues of the calculated and measured forces	7
		difference in angle between the calculated and meaured angles is calculated	5
	subtotal		106
total		286	