

## PERCEPTRON LEARNING CONVERGENCE THEOREM

Recall: Perceptron learning updates weights ONLY if:

$$y = f(\bar{x} \cdot \bar{w}) \neq t$$

if so, the update is:  $\bar{w}_{(NEW)} = \bar{w}_{(OLD)} + t\bar{x}$

### Perceptron Learning Convergence Theorem

"If there is a weight vector  $\bar{w}^*$ , such that  $f(\bar{x}(p) \cdot \bar{w}^*) = t(p)$  for all  $p$ , then, for any starting vector  $\bar{w}$ , the perceptron learning rule will converge to a weight vector (not necessarily  $\bar{w}^*$ ) that gives the correct response for all training patterns, and will do so in a FINITE number of steps."

Originally, the training set is composed of:

$$F^+ = \{x(p) / t(p) = +1\}$$

$U$

$$F^- = \{x(p) / t(p) = -1\}$$

NOTE THAT FINDING A WEIGHT VECTOR FOR THIS TRAINING SET (SOLUTION) IS THE SAME AS FINDING ONE FOR:

$$F^+ \cup -F^- = F$$

where:  $-F^- = \{-x(p) / t(p) = -1\}$

BUT NOW ALL THE TARGETS WILL BE +1

So, let's consider the process of perceptron training for such modified training set:

Let's consider ONLY pattern presentations that REQUIRE a weight upgrade, in a sequence, starting with  $\bar{x}(0)$ , which fails to satisfy the target with weights  $w(0)$

$$\bar{x}(0) \cdot \bar{w}(0) \leq 0 \rightarrow y = -1 \Rightarrow y \neq 1 = t$$

MODIFICATION:

$$\bar{w}(1) = \bar{w}(0) + \bar{x}(0)$$

NOTE: We will assume  $\theta = 0$ ,  $\alpha = 1$  for simplicity

then: this set of weights eventually fails:

$$\bar{x}(1) \cdot \bar{w}(1) \leq 0$$

MODIFICATION:

$$\bar{w}(2) = \bar{w}(1) + \bar{x}(1)$$

and so on.

IN GENERAL:  $\bar{x}(k-1) \cdot \bar{w}(k-1) \leq 0$

causes the modification:

$$\bar{w}(k) = \bar{w}(k-1) + \bar{x}(k-1)$$

the whole CHAIN OF CHANGES, FROM  $w(0)$  IS:

$$\bar{w}(k) = \underbrace{\bar{w}(0)}_{w(1)} + \underbrace{\bar{x}(0) + \bar{x}(1) + \dots + \bar{x}(k-1)}_{w(2) \dots} \quad \text{[a]}$$

WE WANT TO SHOW THAT  $k$  CANNOT BE ARBITRARILY LARGE

• ASSUME  $\bar{w}^*$  EXISTS, such that  $\bar{x} \cdot \bar{w}^* > 0$

• Now find the minimum:  $\forall x \in F$

$$m = \min \{ \bar{x} \cdot \bar{w}^* \} \quad \left( \begin{array}{l} \text{pattern } \bar{x} \text{ that has} \\ \text{the smallest projection} \\ \text{on } \bar{w}^* \end{array} \right)$$

from [a]:

$$\bar{w}(k) \cdot \bar{w}^* = [\bar{w}(0) + \bar{x}(0) + \dots + \bar{x}(k-1)] \cdot \bar{w}^*$$

$$\Rightarrow \bar{w}(k) \cdot \bar{w}^* = \bar{w}(0) \cdot \bar{w}^* + \underbrace{\bar{x}(0) \cdot \bar{w}^* + \dots + \bar{x}(k-1) \cdot \bar{w}^*}_{k \text{ terms}}$$

then:

$$\bar{w}(k) \cdot \bar{w}^* \geq \bar{w}(0) \cdot \bar{w}^* + k m \quad \text{[b]}$$

because  $m$  is smaller or equal to any of the  $k$  terms in the sum.

Recall the

Cauchy-Schwarz Inequality:

$$(\bar{a} \cdot \bar{b})^2 \leq |\bar{a}|^2 |\bar{b}|^2$$

or

$$|\bar{a}|^2 \geq \frac{(\bar{a} \cdot \bar{b})^2}{|\bar{b}|^2} \quad \left( \text{if } |\bar{b}|^2 \neq 0 \right)$$

In this context:

$$|w(k)|^2 \geq \frac{(w(k) \cdot w^*)^2}{|w^*|^2} \quad \text{if } |w^*|^2 \neq 0 \quad (\text{ok})$$

substituting, from

$$\text{[b]}: \quad |w(k)|^2 \geq \frac{(w(0) \cdot w^* + k m)^2}{|w^*|^2} \quad \text{[A]}$$

Now, consider the general UPDATE RULE:

$$\bar{w}(k) = \bar{w}(k-1) + \bar{x}(k-1) \quad \text{[c]} \quad \text{[d]}$$

when  $\bar{x}(k-1) \cdot \bar{w}(k-1) \leq 0$

Performing the inner product of each side of [c] with itself, and preserving the equality:

$$|\bar{w}(k)|^2 = |\bar{w}(k-1)|^2 + 2 \bar{x}(k-1) \cdot \bar{w}(k-1) + |\bar{x}(k-1)|^2$$

then, because of [d]:

$$|w(k)|^2 \leq |w(k-1)|^2 + |\bar{x}(k-1)|^2 \quad \text{[e]}$$

Let's assign:  $M = \max \{ |\bar{x}|^2 \}$ .  
 then, in:

$$\begin{aligned}
 |\bar{w}(k)|^2 &\leq |\bar{w}(k-1)|^2 + |\bar{x}(k-1)|^2 \\
 &\leq \underbrace{|\bar{w}(k-2)|^2 + |\bar{x}(k-2)|^2}_{\text{A}} + |\bar{x}(k-1)|^2 \\
 &\leq \underbrace{|\bar{w}(k-3)|^2 + |\bar{x}(k-3)|^2}_{\text{A}} + \underbrace{|\bar{x}(k-2)|^2}_{\text{A}} + \underbrace{|\bar{x}(k-1)|^2}_{\text{A}} \\
 &\vdots \\
 |\bar{w}(k)|^2 &\leq |\bar{w}(0)|^2 + |\bar{x}(0)|^2 + |\bar{x}(1)|^2 + \dots + |\bar{x}(k-1)|^2 \\
 \Rightarrow |\bar{w}(k)|^2 &\leq |\bar{w}(0)|^2 + kM \quad \begin{array}{l} \text{k terms} \\ \text{because} \\ M \geq |\bar{x}(i)|^2 \\ \text{for any } i \end{array} \quad \text{B}
 \end{aligned}$$

Now: Combining A and B

$$\frac{(w(0) \cdot w^* + km)^2}{|w^*|^2} \leq |\bar{w}(k)|^2 \leq |w(0)|^2 + kM$$

→ Assume for simplicity that  $\bar{w}(0) = \bar{0}$ :

$$\Rightarrow \frac{(km)^2}{|w^*|^2} \leq kM$$

$$\Rightarrow \boxed{k \leq \frac{M |w^*|^2}{m^2}} \quad \begin{array}{l} k \text{ has an} \\ \text{upper bound!} \\ k \text{ is not} \\ \text{infinite!} \end{array}$$

If we assume that the (hypothetic)  
 Solution vector  $w^*$  is of unit norm:  
 $|w^*|^2 = 1$

then:  $k \leq \frac{M}{m^2}$

then the maximum number of effective  
 updates is  $M/m^2$

Since  $w^*$  (and  $m$ ) are not known, the  
 above result cannot be used to  
 predict the length of training.