

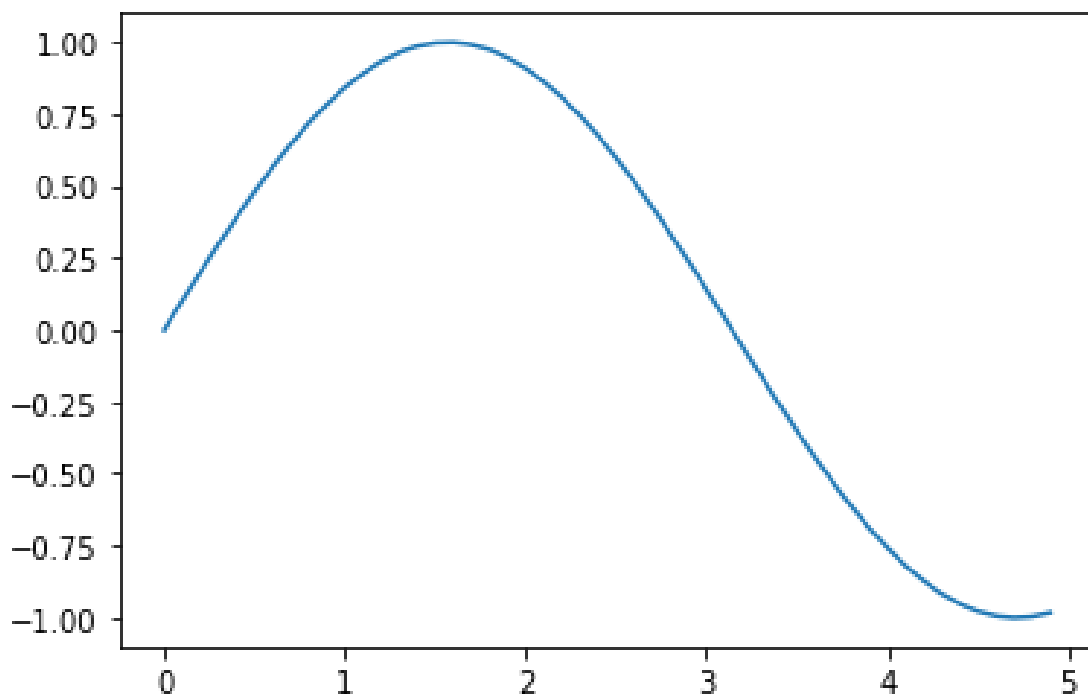
# Contents

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```
1 import numpy as np
2 import matplotlib
3 #matplotlib.use('Agg')
4 import matplotlib.pyplot as plt
5
6 x = np.arange(0, 5, 0.1)
7 y = np.sin(x)
8 fig, ax = plt.subplots()
9 ax.plot(x, y)
10 plt.savefig("fffffffffff")
```

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<matplotlib.lines.Line2D at 0x7feba26633d0>



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```
1 import matplotlib, numpy
2 #matplotlib.use('Agg')
3 import matplotlib.pyplot as plt
4 fig=plt.figure(figsize=(4,2))
5 x=numpy.linspace(-15,15)
6 plt.plot(numpy.sin(x)/x)
7 #fig.tight_layout()
8 plt.savefig('images/python-matplot-fig.png')
9 #return 'images/python-matplot-fig.png' # return filename to org-mode
```

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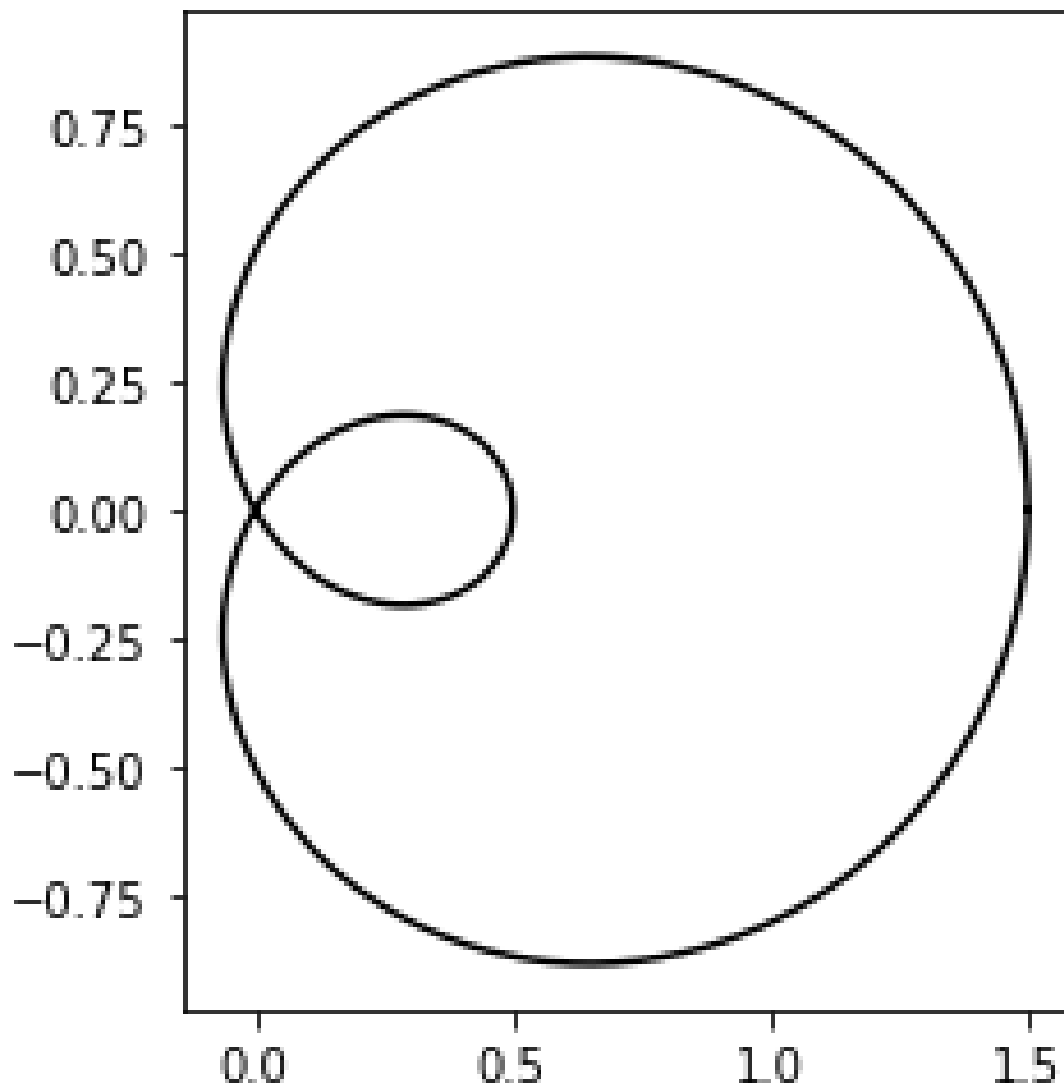
```
1 import numpy as np
2
3 import matplotlib.pyplot as plt
4 from matplotlib.path import Path
5 from matplotlib.patches import PathPatch
6
7 N = 400
8 t = np.linspace(0, 2 * np.pi, N)
```

```

9  r = 0.5 + np.cos(t)
10 x, y = r * np.cos(t), r * np.sin(t)
11
12 fig, ax = plt.subplots()
13 ax.plot(x, y, "k")
14 ax.set(aspect=1)

```

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```

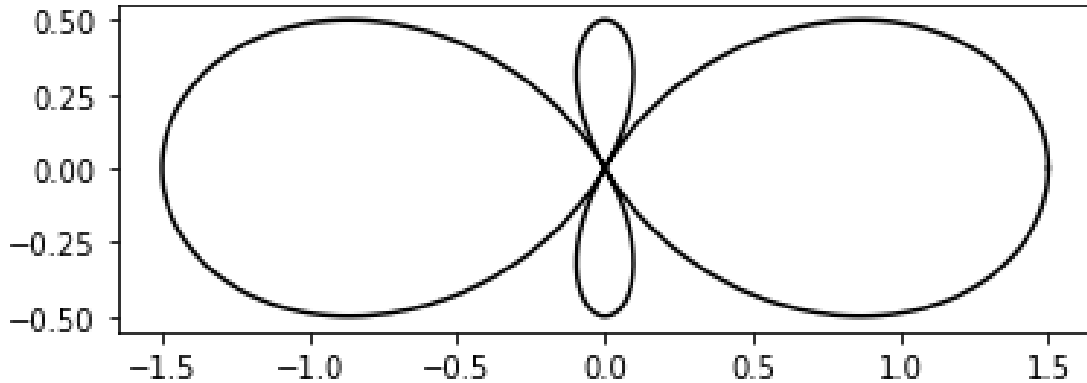
1  import numpy as np
2
3  import matplotlib.pyplot as plt
4  from matplotlib.path import Path
5  from matplotlib.patches import PathPatch
6
7  N = 400
8  t = np.linspace(0, 2 * np.pi, N)
9  r = 0.5 + np.cos(2*t)
10 x, y = r * np.cos(t), r * np.sin(t)

```

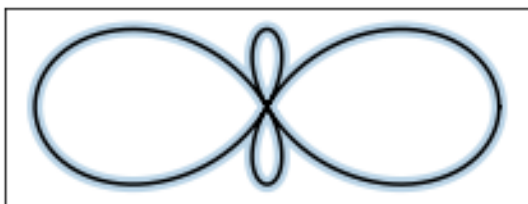
```

11
12 fig, ax = plt.subplots()
13 ax.plot(x, y, "k")
14 ax.set(aspect=1)
15
16 def draw_error_band(ax, x, y, err, **kwargs):
17     # Calculate normals via centered finite differences (except the first point
18     # which uses a forward difference and the last point which uses a backward
19     # difference).
20     dx = np.concatenate([[x[1] - x[0]], x[2:] - x[:-2], [x[-1] - x[-2]]])
21     dy = np.concatenate([[y[1] - y[0]], y[2:] - y[:-2], [y[-1] - y[-2]]])
22     l = np.hypot(dx, dy)
23     nx = dy / l
24     ny = -dx / l
25
26     # end points of errors
27     xp = x + nx * err
28     yp = y + ny * err
29     xn = x - nx * err
30     yn = y - ny * err
31
32     vertices = np.block([[xp, xn[:-1]],
33                          [yp, yn[:-1]]]).T
34     codes = np.full(len(vertices), Path.LINETO)
35     codes[0] = codes[len(xp)] = Path.MOVETO
36     path = Path(vertices, codes)
37     ax.add_patch(PathPatch(path, **kwargs))
38
39
40 axes = (plt.figure(constrained_layout=True)
41         .subplots(1, 2, sharex=True, sharey=True))
42 errs = [
43     (axes[0], "constant error", 0.05),
44     (axes[1], "variable error", 0.05 * np.sin(2 * t) ** 2 + 0.04),
45 ]
46 for i, (ax, title, err) in enumerate(errs):
47     ax.set(title=title, aspect=1, xticks=[], yticks=[])
48     ax.plot(x, y, "k")
49     draw_error_band(ax, x, y, err=err,
50                     facecolor=f"C{i}", edgecolor="none", alpha=.3)
51
52 plt.show()

```



constant error



variable error

