

view_frames Result

Recorded at time: 1046.821

map

Broadcaster: /rtabmap/rtabmap
Average rate: 20.225 Hz
Most recent transform: 1046.894 (-0.073 sec old)
Buffer length: 4.450 sec

odom

Broadcaster: /gazebo
Average rate: 10.297 Hz
Most recent transform: 1046.691 (0.130 sec old)
Buffer length: 4.273 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1046.821 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10.237 Hz
Most recent transform: 1046.740 (0.081 sec old)
Buffer length: 4.396 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10.237 Hz
Most recent transform: 1046.740 (0.081 sec old)
Buffer length: 4.396 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.237 Hz
Most recent transform: 1046.740 (0.081 sec old)
Buffer length: 4.396 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.237 Hz
Most recent transform: 1046.740 (0.081 sec old)
Buffer length: 4.396 sec

right_wheel