

# Synchronous Computations

## Motivation

- ▶ Sometimes, we need threads to synchronize repeatedly with each other
- ▶ We can use a *barrier* to do so

- ▶ C# provides a Barrier class

- ▶ Initialize:

```
1 Barrier B = new Barrier( count, (b) => { ... } );
```

- ▶ The  $\lambda$  function will be executed when the final thread hits the barrier
- ▶ It's passed the barrier itself as an argument
- ▶ The threads don't resume until the  $\lambda$  function returns

- ▶ Signal:

B.SignalAndWait();

- ▶ You may not call this from the  $\lambda$  function! (Doesn't make sense anyway)

# Pitfall

- ▶ All threads need to use the *same* barrier object. Bad:

```
1 new Thread( () => {  
2     Barrier B = new Barrier(3, (b)=>{} );  
3     ...stuff...  
4     B.SignalAndWait();  
5 }).Start();  
6  
7 new Thread( () => {  
8     Barrier B = new Barrier(3, (b)=>{} );  
9     ...stuff...  
10    B.SignalAndWait();  
11 }).Start();  
12  
13 new Thread( () => {  
14     Barrier B = new Barrier(3, (b)=>{} );  
15     ...stuff...  
16     B.SignalAndWait();  
17 }).Start();
```

## Better

```
1  Barrier B = new Barrier(3, (b)=>{} );
2  new Thread( () => {
3      ...stuff...
4      B.SignalAndWait();
5  }).Start();
6
7  new Thread( () => {
8      ...stuff...
9      B.SignalAndWait();
10 }).Start();
11
12 new Thread( () => {
13     ...stuff...
14     B.SignalAndWait();
15 }).Start();
```

## Usage

- ▶ When is something like this useful?
- ▶ Consider the *merge sort* algorithm
  - ▶ Input: An array A of N elements
  - ▶ Create a temporary array B of N elements
  - ▶ Look at adjacent pairs of elements in A. Store them in the correct (sorted) order to corresponding slots in B
    - ▶ Ex: Compare A[0] and A[1]. If A[0] is smaller: Store A[0] to B[0].
    - ▶ Else, store A[1] to B[0]
    - ▶ Then store the other element to B[1]
- ▶ Do the same thing for A[2]/A[3], A[4]/A[5], etc.
- ▶ When we're done, B[0...1] is a sorted two-element array, as is B[2...3], B[4...5], etc.

## Sorting

- ▶ Next, consider adjacent two-element arrays  $B[0...1]$ ,  $B[2...3]$
- ▶ Sort these elements and store them back to  $A[0...3]$ 
  - ▶ Look at  $B[0]$  and  $B[2]$ . Take smallest element, store to  $A[0]$
  - ▶ "Salami slicing" algorithm: Repeat until all 4 elements stored
- ▶ When we're done, we have a bunch of 4 element sorted subarrays in  $A$

## Sorting

- ▶ Now, take adjacent pairs of 4-element arrays and salami-slice them again
- ▶ This will give a bunch of sorted 8-element arrays
- ▶ Repeat until we're all done



## Example

- ▶ Suppose A is this:  
3, 1, 4, 1, 5, 9, 2, 6, 5, 3, 5, 8, 9, 7, 9, 3
- ▶ Pass 1: Sort pairs of 1-element subarrays to 2-element subarrays  
1,3, 1,4, 5,9, 2,6, 3,5, 5,8, 7,9, 3,9
- ▶ Pass 2: Sort adjacent 2-element subarrays to 4-element subarrays  
1,1,3,4, 2,5,6,9, 3,5,5,8, 3,7,9,9
- ▶ Pass 3: Sort adjacent 4-element subarrays to 8-element subarrays  
1,1,2,3,4,5,6,9, 3,3,5,5,7,8,9,9
- ▶ Pass 4: Merge these two 8-element subarrays  
1,1,2,3,3,3,4,5,5,5,6,7,8,9,9,9

# Time

- ▶ How much time does this take?
  - ▶ Each time we do a round of merging, we're looking at all  $n$  elements of  $A$
  - ▶ Each time we merge, we're doubling the number of elements in each subarray and thus halving the number of subarrays
  - ▶  $n$  subarrays at first, then  $n/2$ , then  $n/4$ , then  $n/8$ , ...
  - ▶ Denominator is  $2^0$ , then  $2^1$ , then  $2^2$ , ...
- ▶ When does denominator ==  $n$ ?
  - ▶ When  $2^i == n$
- ▶ What is  $i$ ? Take  $\lg$  of both sides:  $i = \lg n$
- ▶ So  $\lg n$  iterations, each one of time  $n$ , so  $O(n \lg n)$  time

## Example

- ▶ Example implementation: [mergeSort.cs](#)

## Parallelization

- ▶ We can do the merges in parallel
- ▶ But: We must stop after each "turn of the crank" so that each round is fully done before we move on to another round
- ▶ Note that (for an array of  $n$  elements), we can have  $n/2$  threads active (max) on the first iteration, but then  $n/4$  and then  $n/8$  and then  $n/16$ , ...
- ▶ Amount of available parallelism goes down as we progress!

## Code

- ▶ Example implementation: [mergeSortParallel.cs](#)

# Assignment

- ▶ Implement parallel blur
  - ▶ Your program should take a three command line arguments (via Main's `args[]` array): The name of an image file, the number of worker threads, and the number of rounds of blurring to perform
  - ▶ Load the image and perform the specified number of 5x5 box blurs of the image
  - ▶ Output the results to the file "out.png"
  - ▶ Do the blurring concurrently and correctly
  - ▶ Output the total time required to the console

## Code

### ► To load an image:

```
1 using System;
2 using System.Drawing;
3 using System.Drawing.Imaging;
4 using System.Runtime.InteropServices;
5 ...
6 Bitmap img = (Bitmap) Image.FromFile(filename);
```

## Code

- ▶ To convert an image to a byte array so it can be examined:

```
1 var bdata = img.LockBits(new Rectangle(0,0,img.Width,img.Height),  
    ImageLockMode.ReadWrite, PixelFormat.Format24bppRgb );  
2 byte[] pix = new byte[bdata.Stride*bdata.Height];  
3 Marshal.Copy(bdata.Scan0, pix, 0, pix.Length );
```

- ▶ The pix array will have the image data in BGR order, one row after another
- ▶ Each row is Stride bytes long



## Code

► To save a modified copy of the image:

```
1 Marshal.Copy(pix, 0, bdata.Scan0, pix.Length );  
2 img.UnlockBits(bdata);  
3 img.Save("out.png");
```

## References

- ▶ <http://www.vcskicks.com/image-to-byte.php>

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