

# Thomas Mousseau

21 rue de Franchimont, J7B 1W4

[linkedin.com/in/thomas-mousseau](https://www.linkedin.com/in/thomas-mousseau)

SOFTWAREENGINEERING

(514)-601-6377

[thom.mousseau@gmail.com](mailto:thom.mousseau@gmail.com)

[github.com/ThomasMousseau](https://github.com/ThomasMousseau)

## EDUCATION

---

### **POLYTECHNIQUE MONTRÉAL, 4th year student**

*Bachelor in Software Engineering (B. Eng.) with AI specialization*

**September 2021 – May 2025**

(Montréal, Canada)

### **CEGEP LIONEL-GROULX**

*Diplômes d'études collégiales in Computer Science and Mathematics*

**September 2019 – May 2021**

(Montréal, Canada)

## WORK EXPERIENCES

---

### **CLINIA, Machine Learning Engineer Intern, R&D Team**

**May 2024 - August 2024**

- Optimized embedder models, in a RAG context, by modifying their architecture
- Designed and developed a benchmarking project for multiple NLP models
- Utilized and contributed to NVIDIA Triton Inference Server and TensorRT repositories

### **DESJARDINS, DevOps Software Engineering Intern, Escouade Stagiaire**

**May 2023 - August 2023**

- Conceived and deployed microservices modules and their pipelines for multiple environments
- Implemented infrastructures for CI/CD tasks automation

### **GROUP TMX, DevOps Software Engineering Intern, DevOps Tools**

**May 2022 - August 2022**

- Developed and supported Linux servers and workstations using RedHat satellite.
- Deployed, improved and maintained Kubernetes clusters using AWS, Docker and Rancher.

## PROJECTS / ACTIVITIES

---

### **ELECTRIC FSAE OF POLYTECHNIQUE, Python, C++ and ROS2**

**September 2023 - To this day**

- Technical Lead of the Driverless team
- Led cross-functional teams to integrate systems and improve vehicle performance
- Designed and implemented the perception pipeline with cameras (Stereolab ZED X) and LiDAR (HESAI-AT128)
- Developed SLAM and path planning systems
- Built Model Predictive Controller (MPC) and sensors fusion using extended kalman-filter
- Created and optimized the telemetry system and a PID controller for traction and launch control
- Implemented a State of Charge (SoC) algorithm based on custom discharging cell models

### **HACKATHONS, Machine Learning & Web Development**

**2019 - To this day**

- Won 2 Machine Learning Hackathons and participated in 3 more

## SKILLS

---

- **Programming/scripting languages:** Python, Rust, C++, Terraform, Bash
- **Hard skills:** PyTorch, ML, RL, NLP, CV, JAX, Infrastructures, ROS, Embedded systems, AWS, NVIDIA ecosystem
- **Soft skills:** Passionate, Communication, Collaboration, Resourcefulness, Self-motivated
- **Certifications:** English certification C-2 from Boston EF Learning Center
- **Languages:** French (native), English (fluent)