UNIVERSITÀ DI TRENTO

Formal Method Mod. 2 (Model Checking)
Laboratory 11

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Timed systems

Real time systems

- ▶ Correctness depends not only on the logical result but also on the time required to compute it.
- ▶ Common in safety-critical domains like: defense, transportation, health-care, space and avionics.

Timed Transition System (TTS)
transitions are either discrete
or time-elapses,
all clocks increase of the same
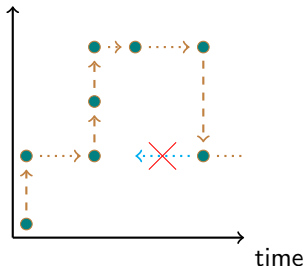amount in time-elapses.
Model checking for TTS is **undecidable**.

Timed Automata (TA)
decidable restriction of TTS,
finite time abstraction:
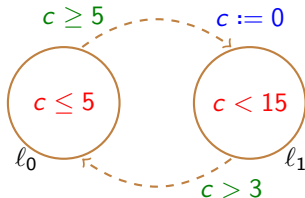clocks compared only to constants.

discrete

time

Timed systems: representation

Timed Automata (TA)

Explicit graph representation of discrete states (nodes) and transitions (edges).
Symbolic representation of temporal aspects via (convex) constraints (location invariants, transition guards and resets).

Symbolic TTS

Logical formulae represent sets of states: $p := \{s \mid s \models p)\}$.
Transition system symbolically represented by formula $\varphi(X, X')$.
There is a discrete transition from s_0 to s_1 iff $s_0(X), s_1(X') \models \varphi(X, X')$.

$I = \ell_0 \rightarrow c \leq 5 \quad \wedge$

$I = \ell_1 \rightarrow c < 15 \quad \wedge$

$(I = \ell_1 \wedge I' = \ell_0) \rightarrow c > 3 \quad \wedge$

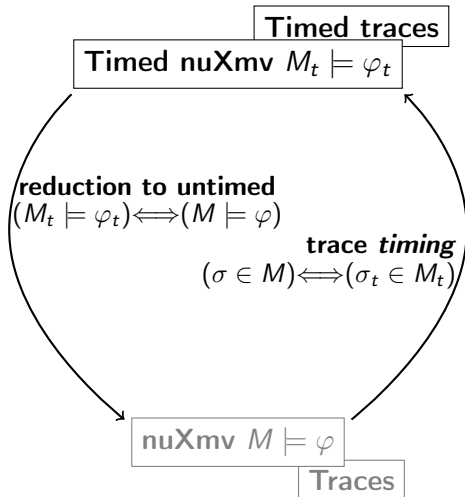$(I = \ell_0 \wedge I' = \ell_1) \rightarrow (c \geq 5 \wedge c' = 0)$

Timed traces

Timed nuXmv $M_t \models \varphi_t$

reduction to untimed
$(M_t \models \varphi_t) \Longleftrightarrow (M \models \varphi)$

trace *timing*
$(\sigma \in M) \Longleftrightarrow (\sigma_t \in M_t)$

nuXmv $M \models \varphi$

Traces

Timed nuXmv: input language [1/4]

Overview

- ▶ Must start with `@TIME_DOMAIN continuous;`
- ▶ Symbolic description of infinite transition system using: `INIT`, `INVAR` and `TRANS` to specify initial, invariant and transition conditions.
- ▶ Model described as a synchronous composition of `MODULE` instances.
- ▶ Clock variables,
- ▶ `time`: built-in clock variable,
- ▶ convex invariants over clocks,
- ▶ `URGENT`: forbid time elapse.

Timed nuXmv adds

- ▶ `clock` variable type, all `clocks` increase of the same amount during timed transitions;
- ▶ `time`: built-in `clock`, can be used only in comparisons with constants;
- ▶ `noncontinuous` type modifier: symbol can change its assignment during timed transitions;
- ▶ `URGENT`: freeze time: when one of the `URGENT` conditions is satisfied only discrete transitions are allowed;
- ▶ $MTL_{0,\infty}$ specifications, by "extending" LTL;

Timed nuXmv: input language [3/4]

Timed nuXmv updates

- ▶ `TRANS` constrain the discrete behaviour only,
- ▶ `INVAR`: `clocks` allowed in invariants with shape:
  `no_clock_expr -> convex_clock_expr;`
- ▶ LTL operators: X, Y, U, S,
- ▶ Bounded LTL operators.

Timed nuXmv: input language [4/4]

Specification

▶ Different operators to refer to the *discrete* next and *timed* next: X, X~; symmetrically for the past: Y, Y~.

▶ Time interval semantic to handle open intervals: a predicate p might hold in an interval $(a, b]$ for $a, b \in \mathbb{R}$.

▶ Operators to retrieve value of expression the next/last time an expression will hold/held: time_until, time_since, @F~ and @O~.

Timed nuXmv: untiming

Timed to untimed model

- `clock` symbols and `time`: variables of type `real`.

- δ: continuous positive variable, prescribes the amount of time elapse for every transition.

- ι: prescribes the alternation of singular [·] and open $(-)$ time intervals.
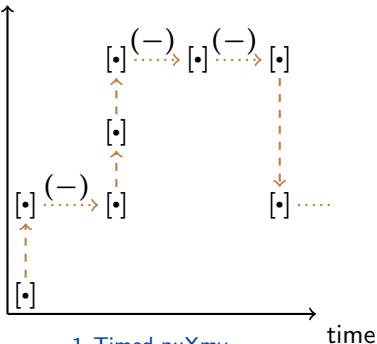
Properties rewriting

MTL *fragment*

$$F_{[0,5]}\ p$$

↓ rewrite

LTL *timed*

$$((\neg pUp) \land time\_until(p) \leq 5) \lor$$
$$((\neg pU\tilde{X}p) \land time\_until(p) < 5)$$

↓ untime

LTL *untimed*

$$((\neg pUp) \land (time@\tilde{F}p) - time \leq 5) \lor$$
$$((\neg pU((\neg\iota \land p) \lor X(\neg\iota \land p))) \land (time@\tilde{F}p) - time < 5)$$

Outline

Timed and infinite traces

From untimed model execution to timed trace.

Issue

nuXmv traces must have shape: $\alpha\beta^\omega$,
α and β sequences of states.
Complete for finite state systems.
TTS: time monotonically increasing,
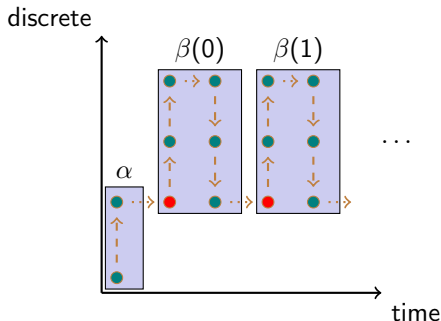infinite state system, **undecidable**.
Identify traces expressible as: $\alpha\beta(i)^\omega$.
Same problem can be found in
infinite state transition systems.

Solution

Value assigned to variables at state
s is function of the previous
configuration assignments.
e.g. $next(time) := time + \delta$

Three main operations on traces: **simulation**, **execution** and **completion**.

Simulation

Build a possible execution of the model. The trace can be built automatically by the system or the user can choose each state from the list of possible ones.
Exploit SMT-solver to perform a discrete transition or time-elapse to obtain next configuration.

Timed and infinite traces: operations

Execution

Check if a trace belongs to the language of the model.
Exploit SMT-solver to prove that **for all** possible iterations all
prescribed transition can be performed.

Completion

A partial trace is completed so that it belongs to the model
language.
Sound and complete technique requires to check if there **exists** a
possible completion so that the completed trace belongs to the
model language: quantifier alternation ($\exists\forall$).
Adopt sound but incomplete approach.

- ▶ `./nuXmv -time -int`: start nuXmv interactively and enable commands for timed models.
- ▶ `go_time`: process the model.
- ▶ `write_untimed_model`: dump SMV model corresponding to the input timed system.

▶ timed_check_invar: check invariants.

▶ timed_check_ltlspec: check LTL.

Mostly the same command line options of the corresponding commands for untimed models.

- ▶ `timed_pick_state`: pick initial state.
- ▶ `timed_simulate`: simulate the model starting from a given state.
- ▶ `execute_traces`: re-execute stored traces.
- ▶ `execute_partial_traces`: try to complete stored traces.

Semantics of temporal operators

Formally nuXmv uses a super-dense weakly-monotonic time model $T \subset \mathbb{N} \times \mathbb{R}_0^+$.

A time point is a pair $\langle i, r \rangle$ where $i \in \mathbb{N}$ "counts the discrete steps" and $r \in \mathbb{R}_0^+$ is the time.

We say that $\langle i, r \rangle < \langle i', r' \rangle$ iff $i < i'$ or $i = i'$ and $r < r'$.

2. Timed and infinite traces

Semantics of temporal operators

$\sigma, t \models \phi$ is defined recursively on the structure of ϕ:
usual definition for predicates, conjunction and negation.

$\sigma, t \models \phi_1 U \phi_2$ iff there exists $t' \geq t, \sigma, t' \models \phi_2$ and
   for all $t'', t \leq t'' < t', \sigma, t'' \models \phi_1$

$\sigma, t \models \phi_1 S \phi_2$ iff there exists $t' \leq t, \sigma, t' \models \phi_2$ and
   for all $t'', t' < t'' \leq t, \sigma, t'' \models \phi_1$

$\sigma, t \models X \phi$ iff there exists $t' > t, \sigma, t' \models \phi$ and
   there exists no $t'', t < t'' < t'$

$\sigma, t \models \tilde{X} \phi$ iff for all $t' > t$, there exists $t'', t < t'' < t', \sigma, t'' \models \phi$

$\sigma, t \models Y \phi$ iff $t > 0$ and there exists $t' < t, \sigma, t' \models \phi$ and
   there exists no $t'', t' < t'' < t$

$\sigma, t \models \tilde{Y} \phi$ iff $t > 0$ and for all $t' < t$,
   there exists $t'', t' < t'' < t, \sigma, t'' \models \phi$

Let k, $k1$ and $k2$ be some constant real values such that $0 \leq k \leq k1 < k2$ and let b a boolean symbol.
The following properties true or false?

- $\tilde{Y}\top$

LTL- MTL properties [1/2]

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Let k, $k1$ and $k2$ be some constant real values such that $0 \leq k \leq k1 < k2$ and let b a boolean symbol.
The following properties true or false?

- $\tilde{Y}\top$: false in the initial state.
- $(\neg Xb) \rightarrow (X\neg b)$

Let k, $k1$ and $k2$ be some constant real values such that $0 \leq k \leq k1 < k2$ and let b a boolean symbol.
The following properties true or false?

- ▶ $\tilde{Y}\top$: false in the initial state.
- ▶ $(\neg Xb) \rightarrow (X\neg b)$: false, the first one holds in every time elapse, the second one holds only in discrete steps where $\neg b$ holds in the next state.
- ▶ $(\neg \tilde{X}\ b) \rightarrow (\tilde{X}\neg b)$

2. Timed and infinite traces

LTL- MTL properties [1/2]

Let k, $k1$ and $k2$ be some constant real values such that $0 \leq k \leq k1 < k2$ and let b a boolean symbol.
The following properties true or false?

- $\tilde{Y}\top$: false in the initial state.
- $(\neg Xb) \to (X\neg b)$: false, the first one holds in every time elapse, the second one holds only in discrete steps where $\neg b$ holds in the next state.
- $(\neg \tilde{X}\ b) \to (\tilde{X}\neg b)$: false, as above but for time elapses.
- $(X\neg b) \to (\neg Xb)$

Let k, $k1$ and $k2$ be some constant real values such that $0 \leq k \leq k1 < k2$ and let b a boolean symbol.
The following properties true or false?

▶ $\tilde{Y}\top$: false in the initial state.

▶ $(\neg Xb) \rightarrow (X\neg b)$: false, the first one holds in every time elapse, the second one holds only in discrete steps where $\neg b$ holds in the next state.

▶ $(\neg \tilde{X} b) \rightarrow (\tilde{X}\neg b)$: false, as above but for time elapses.

▶ $(X\neg b) \rightarrow (\neg Xb)$: true, the first one holds iff there is a discrete step and $\neg b$ holds in the next state, hence Xb is false.

▶ $(\tilde{X}\neg b) \rightarrow (\neg \tilde{X} b)$

LTL- MTL properties [1/2]

Let k, $k1$ and $k2$ be some constant real values such that $0 \leq k \leq k1 < k2$ and let b a boolean symbol.
The following properties true or false?

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- $(X\neg b) \rightarrow (\neg Xb)$: true, the first one holds iff there is a discrete step and $\neg b$ holds in the next state, hence Xb is false.
- $(\tilde{X}\neg b) \rightarrow (\neg \tilde{X} b)$: true, as above but for time elapses.
- $(G\tilde{X}\top) \rightarrow ((Gb) \vee (G\neg b))$

2. Timed and infinite traces

Let k, $k1$ and $k2$ be some constant real values such that $0 \leq k \leq k1 < k2$ and let b a boolean symbol.
The following properties true or false?

- $\tilde{Y}\top$: false in the initial state.
- $(\neg Xb) \rightarrow (X\neg b)$: false, the first one holds in every time elapse, the second one holds only in discrete steps where $\neg b$ holds in the next state.
- $(\neg \tilde{X} b) \rightarrow (\tilde{X}\neg b)$: false, as above but for time elapses.
- $(X\neg b) \rightarrow (\neg Xb)$: true, the first one holds iff there is a discrete step and $\neg b$ holds in the next state, hence Xb is false.
- $(\tilde{X}\neg b) \rightarrow (\neg \tilde{X} b)$: true, as above but for time elapses.
- $(G\tilde{X}\top) \rightarrow ((Gb) \vee (G\neg b))$: true, the first part implies that we never perform a discrete transition and the truth value of b can only change in discrete transitions.
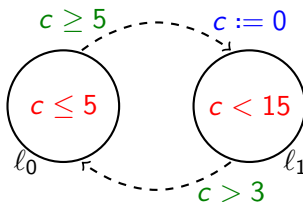
See files in examples.

Outline

Simple timed automaton

Write the SMV model corresponding to the timed automaton in the figure.

Properties

▶ from location ℓ_0 we always reach ℓ_1 within 5 time units;

▶ if we are in ℓ_1 then for the next 3 time units we remain in ℓ_1;

▶ if just arrived in ℓ_1 then for the next 3 time units we remain in ℓ_1.

Timed thermostat

- a thermostat has 2 states: *on* and *off*;
    - if the temperature is below 18 degrees the thermostat switches *on*.
    - if the temperature is above 18 degrees the thermostat switches *off*.
- Every time the thermostat misure the temperature in the room, the temperature increases (if *on*) or decreases (if *off*) by *dt* (with respect to the previous check);
- the thermostat measures the temperature at most ($<$) every *max_dt* time units.
- the temperature initially is in $[18 - max\_dt; 18 + max\_dt]$.

Verify that the temperature is always in
$[18 - 2max\_dt; 18 + 2max\_dt]$

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Try to encode the timed automata shown in the theoretical slide
about timed automata.

3. Exercises