

## Introduction to Machine Learning

BIAS AND VARIANCE ANALYSIS

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## 1 Analytical derivations

1. We have the expected generalization error of the k-Nearest Neighbours algorithm:

$$E_{LS}\{E_{y|\mathbf{x}}\{(y-\hat{y}(\mathbf{x};LS,k))^2\}\}$$

We can substitude y by  $f(\mathbf{x}) + \epsilon$  and expand the square in the expected squared error written as

$$E_{y|\mathbf{x}}\{(y-\hat{y}(\mathbf{x};LS,k))^2\}$$

to obtain:

$$E_{y|\mathbf{x}}\{(f(\mathbf{x}) - \hat{y}(\mathbf{x}; LS, k))^2 + 2\epsilon(f(\mathbf{x}) - \hat{y}(\mathbf{x}; LS, k)) + \epsilon^2\}$$

Since  $E[\epsilon] = 0$  and  $\epsilon$  is independent of f(x) and  $\hat{y}(\mathbf{x}; LS, k)$  the cross-term vanishes and the formula becomes:

$$E_{y|\mathbf{x}}\{(y - \hat{y}(\mathbf{x}; LS, k))^2\} = (f(\mathbf{x}) - \hat{y}(\mathbf{x}; LS, k))^2 + E[\epsilon^2]$$

Since  $\epsilon \sim \mathcal{N}(0, \sigma^2)$ , we have  $E[\epsilon^2] = \sigma^2$  it can be written as:

$$(f(\mathbf{x}) - \hat{y}(\mathbf{x}; LS, k))^2 + \sigma^2$$

We can rewrite  $\hat{y}(\mathbf{x}; LS, k)$  as the average of the function values at the k-nearest neighbors:

$$\hat{y}(\mathbf{x}; LS, k) = \frac{1}{k} \sum_{l=1}^{k} y_{(l)}$$

where  $y_{(l)} = f(\mathbf{x}_{(l)}) + \epsilon$  (with  $\epsilon \sim \mathcal{N}(0, \sigma^2)$ ). Therefore it can be written as:

$$\hat{y}(\mathbf{x}; LS, k) = \frac{1}{k} \sum_{l=1}^{k} f(\mathbf{x}_{(l)}) + \epsilon = \frac{1}{k} \sum_{l=1}^{k} f(\mathbf{x}_{(l)}) + \frac{1}{k} \sum_{l=1}^{k} \epsilon$$

The expected squared error can be decomposed as follows:

$$\sigma^2 + \left(f(\mathbf{x}) - \frac{1}{k} \sum_{l=1}^k f(\mathbf{x}_{(l)})\right)^2 + 2\left(f(\mathbf{x}) - \frac{1}{k} \sum_{l=1}^k f(\mathbf{x}_{(l)})\right) \left(\frac{1}{k} \sum_{l=1}^k \epsilon\right) + \left(\frac{1}{k} \sum_{l=1}^k \epsilon\right)^2$$

Since  $\epsilon$  is an independent random variable with a mean of zero, the cross-term has an expectation of zero. We can write the expected generalization error as:

$$E_{LS}\{E_{y|\mathbf{x}}\{(y-\hat{y}(\mathbf{x};LS,k))^{2}\}\} = E_{LS}(\sigma^{2}) + E_{LS}\left[\left(f(\mathbf{x}) - \frac{1}{k}\sum_{l=1}^{k}f(\mathbf{x}_{(l)})\right)^{2}\right] + E_{LS}\left[\left(\frac{1}{k}\sum_{l=1}^{k}\epsilon\right)^{2}\right]$$

The expectation of a constant is the constant itself and the expectation of the third term

$$E_{LS}\left[\left(\frac{1}{k}\sum_{l=1}^{k}\epsilon\right)^{2}\right] = \frac{\sigma^{2}}{k}$$

because  $Var(\epsilon) = \sigma^2$ .

Since **x** is fixed, the second term is also fixed. Taking the expectation  $E_{LS}$  over this term has no effect.

Therefore we can conclude that

$$E_{LS}\{E_{y|\mathbf{x}}\{(y-\hat{y}(\mathbf{x};LS,k))^2\}\} = \sigma^2 + \left[f(\mathbf{x}) - \frac{1}{k} \sum_{l=1}^{k} f(\mathbf{x}_{(l)})\right]^2 + \frac{\sigma^2}{k}$$

The first term represents the noise, the second the bias, and the third the variance.

2. We know that  $f(x) = x^2$ . Since we have to evaluate the bias and variance at x = 0 we know that f(x) = 0.

The bias can be written as:

bias = 
$$\left(\frac{1}{k} \sum_{l=1}^{k} (x_{(l)})^2\right)^2$$

Since the training inputs are symmetrically distributed around x = 0 on a uniform grid in [-1,+1], the k-neighbors of x = 0 include the point x = 0, k' positive points, and k' negative points. We have that

$$\sum_{l=1}^{k} (x_{(l)})^2 = 2\sum_{l=1}^{k'} \left(\frac{i}{N'}\right)^2 = \frac{2}{(N')^2} \sum_{l=1}^{k'} i^2$$

We can use the formula to write the sum as a function of k':

$$\frac{2}{(N')^2} \sum_{l=1}^{k'} i^2 = \frac{2}{(N')^2} \frac{k'(k'+1)(2k'+1)}{6}$$

The result must be expressed as a function of k and N, we can replace k' and N' with the relation  $k' = \frac{k-1}{2}$  and  $N' = \frac{N-1}{2}$ :

$$\frac{2}{\frac{(N-1)^2}{4}} \frac{\binom{(k-1)}{2}(\frac{k-1}{2}+1)(k-1+1)}{6} = \frac{4k(k-1)(\frac{k-1}{2}+1)}{3(N-1)^2}$$

The bias can be written as a function of k and N:

bias = 
$$\left(\frac{1}{k} \frac{4k(k-1)(\frac{k-1}{2}+1)}{3(N-1)^2}\right)^2 = \left(\frac{4(k-1)(\frac{k-1}{2}+1)}{3(N-1)^2}\right)^2$$

The variance is already expressed as a function of  $\sigma$  and k:

variance = 
$$\frac{\sigma^2}{k}$$

- 3. k appears in the formula of the variance and it is obvious that a greater k leads to a smaller variance. But increasing k may lead to an increase of the biais because we would consider more distant points which reduce the flexibility of the model.
  - Increasing the size N of the learning sample generally leads to a denser distribution, therefore with the same k and  $\sigma$ , the k-nearest neighbors around x will be closer to x and we can expect that they better represent the local behavior of f(x). We can say that larger N leads to smaller bias. If we consider the problem explain in 2, we can see that the size N is in the bias formula and increasing N reduces the bias.

N has no direct impact on the variance but we can note that a larger N allows a larger k which leads to a lower variance.

- A greater  $\sigma$  means more noise and as we may expect it increases the variance but does not impact the biais.
- 4. As suggested we'll compute the minimum by running actual experiments. We have to minimize this function:

$$f(k) = \frac{4}{3(N-1)^2} \left( \frac{(k-1)^2}{2} + (k-1) \right)^2 + \frac{\sigma^2}{k}$$

By testing every possible value of k such that k = 2k' + 1 with  $0 \le k' \le \frac{N-1}{2}$  for each combination of N and  $\sigma$  we have the following results:

	$\sigma = 0$	$\sigma = 0.1$	$\sigma = 0.2$
N=25	1	1	1
N = 50	1	1	3

Table 1: Table of  $k^*$  considering only odd values for k

The cells represent the  $k^*$  for each combination.

If we can still consider even values for k with the formula obtained considering only odd values of k we would have:

	$\sigma = 0$	$\sigma = 0.1$	$\sigma = 0.2$
N = 25	1	1	2
N = 50	1	2	2

Table 2: Table of  $k^*$  considering every value for k

5. Increasing the size of N or  $\sigma$  tends to increase the value of  $k^*$ . If  $\sigma = 0$  then modifying N won't change  $k^*$  because the best value would always be to consider only one element.

## 2 Empirical analysis

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- 2.
- 3.
- 4.
- 5.