Polar Decomposition

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2. Prove that the singular values of A are the eigenvalues of H.

We know that any matrix $A \in \mathbb{C}^{m \times n}$, $m \geq n$ has a thin singular value decomposition $A = P\Sigma Q^*$ where $P \in \mathbb{C}^{m \times n}$ has orthogonal columns, $Q \in \mathbb{C}^{n \times n}$ is unitary, and $\Sigma \in \mathbb{C}^{n \times n}$ is diagonal with $\Sigma = \operatorname{diag}(\sigma_1, \ldots, \sigma_r)$ where $\operatorname{rank}(A) = r$ and $\sigma_1 \geq \ldots \geq \sigma_r \geq 0$, the singular values of A. Thus we can write

$$A = (PQ^*)(Q\Sigma Q^*) =: UH \tag{1}$$

where U and H satisfy the properties of a polar decomposition.

In particular we have $H = Q\Sigma Q^*$ where Σ is diagonal and Q is orthogonal. Thus the diagonal values of Σ are the eigenvalues of H, which are the singular values of A.

3. Prove that A is normal $(A^*A = AA^*)$ iff U and H commute.

We first suppose that U and H commute. Note that for the product HU to be well defined, we must have m=n which implies $U \in \mathbb{C}$ is unitary. Since A=UH=HU we get the following,

$$A^*A = (UH)^*(UH) = H^*(U^*U)H = H^2$$
(2)

$$AA^* = (HU)(HU)^* = H(UU^*)H^* = H^2$$
(3)

so A is normal.

Now suppose A is normal. Since $A^*A \in \mathbb{C}^{n \times n}$ and $AA^* \in \mathbb{C}^{m \times m}$, A normal requires m = n. Using the singular value decomposition of A, we have

$$AA^* = P\Sigma Q^* Q\Sigma P^* = P\Sigma^2 P^* \tag{4}$$

where $\Sigma^2 = \operatorname{diag}(\sigma_1^2, \dots, \sigma_r^2)$. Equating

4. Verify the formula

$$U = \frac{2}{\pi} A \int_{0}^{\infty} (t^{2}I - A^{*}A)^{-1} dt$$

for full rank A by using the singular value decomposition (SVD) of A to diagonalize the formula.

- 5. Derive Newton's method for computing U by considering equations (X + E) * (X + E) = I, where E is a "small perturbation". (Newton's method is $X_{k+1} = (X_k + X_k^{-*})/2, X_0 = A$)
- 6. Prove that Newton's method converges, and at a quadratic rate, by using the SVD of A.
- 7. Use the SVD to analyze the convergence of the Newton-Schulz iteration for computing U:

$$X_{k+1} = \frac{1}{2}X_k(3I - X_k^*X_k), X_0 = A$$

8. Evaluate the operation count for one step of Newton's method and one step of the Newton-Schulz iteration (taking account of symmetry). Ignoring operation counts, how much faster does matrix multiplication have to be than matrix inversion for Newton-Schulz to be faster than Newton (assuming both take the same number of iterations)?