

# Quantum Mechanics Notes

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These are my notes following graduate-level quantum mechanics coursework. The main sources are:

- J. J. Sakurai and J. Napolitano, *Modern Quantum Mechanics*, 3rd ed. (2021).
- R. Shankar, *Principles of quantum mechanics*, 2nd ed. (1994).
- S. Todadri, [Quantum Theory I \(MIT OCW, 2017\)](#).
- L. D. Landau and E. M. Lifshitz, *Quantum Mechanics: Non-Relativistic Theory*, 3rd ed. (1977).

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# 1. Fundamental Concepts

## 1.1 Vector Spaces and Hilbert Spaces

### 1.1.1 Inner Product Spaces

Recall that a **vector space**  $(V, +, \cdot, \mathbb{F})$  is an Abelian group with respect to addition equipped with a scalar multiplication operation  $\cdot : \mathbb{F} \times V \rightarrow V$ . Scalar multiplication obeys properties

$$\begin{aligned}\alpha(\beta v) &= (\alpha\beta)v, \\ \alpha(v + w) &= \alpha v + \alpha w, \\ (\alpha + \beta)v &= \alpha v + \beta v, \\ 1_{\mathbb{F}} \cdot v &= v,\end{aligned}$$

for  $\alpha, \beta \in \mathbb{F}$  and  $v, w \in V$  with  $1_{\mathbb{F}}$  the multiplicative identity of  $\mathbb{F}$ . Unless specified otherwise, we will be working exclusively in the case where our field is of the complex numbers, that is,  $\mathbb{F} = \mathbb{C}$ . A routine example of a vector space is  $\mathbb{C}^n$  itself.

We can upgrade a vector space to an **inner product space** by introducing an operation

$$\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{C}$$

with properties for  $u, v \in V$  and  $\alpha \in \mathbb{C}$ ,

$$\begin{aligned}\langle u, v \rangle &= \langle v, u \rangle^*, \\ \langle u, v + \alpha w \rangle &= \langle u, v \rangle + \alpha \langle u, w \rangle, \\ u \neq 0 &\implies \langle u, u \rangle > 0.\end{aligned}$$

That is, the inner product is an operation that is (up to complex conjugation) symmetric, linear in its second argument, and is positive definite. An important property is that

$$\langle \alpha u, v \rangle = \langle v, \alpha u \rangle^* = (\alpha \langle v, u \rangle)^* = \alpha^* \langle u, v \rangle.$$

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**Example 1.1.** Examples of inner product spaces.

- Let  $V = \mathbb{C}^n$  and attach  $\langle u, v \rangle = \sum_i u_i^* v_i$ .
- A more interesting example is allowing  $V = L^2$ :<sup>1</sup> The set of square-integrable functions on some fixed domain  $U$ ,

$$\int_U dx |f(x)|^2 < \infty.$$

Its inner product is given by

$$\langle f, g \rangle = \int_U dx f^*(x)g(x).$$

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<sup>1</sup>More rigorously, we take this set to be square integrable function equivalence classes where  $f \sim g$  iff  $f = g$  *almost everywhere*. We will see this to be necessary so that the distance between two functions is zero iff those two functions are the same.

### 1.1.2 Hilbert Spaces

We may interpret any inner product space as a metric space by defining a norm

$$\|u\| := \sqrt{\langle u, u \rangle}.$$

This gives us a distance function  $d(u, v) := \|u - v\|$ . A metric space is said to be **complete** if every Cauchy sequence converges: Intuitively this means there are no “holes” between values in the vector space. A **Hilbert space** is a vector space whose induced metric is complete.

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**Example 1.2.** Complete and incomplete metrics.

- $\mathbb{Q}^n$  (over the field  $\mathbb{Q}$ ) provides a simple example of a vector space whose induced metric is incomplete. This is because Cauchy sequence may approach arbitrarily close to an irrational number without actually converging to it, making  $\mathbb{Q}^n$  not a Hilbert space.
  - $\mathbb{C}^n$  and  $L^2$  both are Hilbert spaces — ones we will be using frequently.
- 

### 1.1.3 Dual Spaces and Dirac Notation

Given a vector space  $V$ , we may define its **dual space**  $V^*$  as the set of continuous linear forms

$$f : V \rightarrow \mathbb{C}.$$

If  $V$  is an inner product space, then we may correspond any vector  $v \in V$  with a natural dual vector as the map  $w \mapsto \langle v, w \rangle$ . Dirac defined a simple notation to represent vectors and dual vectors for use in quantum mechanics, dubbed “bra-ket” notation. A vector  $v \in V$  is denoted  $|v\rangle$  and its corresponding dual vector is denoted  $\langle v|$ . By the definition of dual vector, this means applying  $\langle v|$  to a vector  $|w\rangle$  gives:

$$\langle v|(|w\rangle) = \langle v, w \rangle,$$

the inner product of  $|v\rangle$  and  $|w\rangle$ . This motivates the notation

$$\langle v|w\rangle := \langle v|(|w\rangle) = \langle v, w \rangle.$$

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**Example 1.3.** Interpretation of dual vectors.

- In the case  $V = \mathbb{C}^n$ , we see that  $|v\rangle$  corresponds to a column vector,

$$|v\rangle = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix},$$

while  $\langle v|$  corresponds to a row vector,

$$\langle v| = [v_1^* \quad v_2^* \quad \cdots \quad v_n^*].$$

In this case, it is easy to see that  $\langle v|w\rangle = \langle v, w\rangle$ .

- If  $V = L^2$ , then  $|f\rangle$  corresponds to a square integrable function while  $\langle f|$  is an operator on another function  $|g\rangle$  that integrates  $f^*g$  over the domain.

## 1.2 Linear Operators

A linear operator  $T : V \rightarrow V$  is a function such that

$$T|v + \alpha w\rangle = T|v\rangle + \alpha T|w\rangle.$$

This map induces a dual operator  $T^* : V^* \rightarrow V^*$  that maps  $\langle \phi| \in V^*$  as

$$\langle \phi| \mapsto \langle \phi|T.$$

This gives the conjugate-linearity of  $T$  on dual vectors,

$$\langle v + \alpha w|T = \langle v|T + \alpha^* \langle w|T.$$

**Example 1.4.** Let  $\{|e_j\rangle\}$  be the standard basis of  $\mathbb{C}^n$ , then we may represent a linear operator  $T$  by an  $n \times n$  matrix. Its elements are found by considering how  $T$  acts on the standard basis:

$$\langle e_i|T|e_j\rangle = T_{ij}.$$

In fact, if  $V$  is any finite-dimensional vector space with  $\dim V = n$  then a matrix representation of a linear operator  $T$  in basis  $\{|b_j\rangle\}$  is

$$T_{ij} = \langle b_i|T|b_j\rangle.$$

### 1.2.1 Adjoint of an Operator

The **adjoint**  $T^\dagger : V \rightarrow V$ , if exists, of an operator  $T$  is defined such that

$$\langle v|Tw\rangle = \langle T^\dagger v|w\rangle.$$

It turns out that such an operator  $T^\dagger$  exists and is unique for all operators we will be considering.<sup>2</sup> Thus we formulate how  $T$  transforms bras and kets as

$$\begin{aligned} T|v\rangle &= |Tv\rangle, \\ \langle v|T &= \langle T^\dagger v|. \end{aligned}$$

<sup>2</sup>Turns out that if  $V$  is a Hilbert space, then  $T^\dagger$  always exists uniquely according to the [Riesz representation theorem](#).

An operator  $T$  is said to be **Hermitian** if  $\langle v|Tw\rangle = \langle Tv|w\rangle$  for all  $v, w \in V$ .<sup>3</sup>

Some useful properties of the adjoint are

$$\begin{aligned} A^\dagger + B^\dagger &= (A + B)^\dagger, \\ (AB)^\dagger &= B^\dagger A^\dagger, \\ (A^\dagger)^\dagger &= A. \end{aligned} \tag{1}$$

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**Example 1.5.** In  $\mathbb{C}^n$ , if we represent an operator as a matrix, then its adjoint is just the conjugate transpose of that matrix.

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### 1.2.2 The Eigenvalue Problem

Recall the eigenvalue problem, where we want to find eigenvalues  $v$  and  $|v\rangle$  such that

$$A|v\rangle = v|v\rangle.$$

The dual of this equation is given as

$$\langle v|A^\dagger = v^*\langle v|.$$

As in the above, we will often abuse notation by using the same symbol for an eigenvalue and its eigenvector. This technically is ill-defined since anytime  $|v\rangle$  is a solution, then any vector in the span of  $|v\rangle$  will also be a solution. This can be fixed by taking a convention to always normalize  $|v\rangle$ , but that doesn't solve the problem when  $v$  has a degeneracy greater than 1 (that is, when there exists multiple linearly independent eigenvectors for a given eigenvalue).

**Theorem 1.6.** *If  $A$  is a Hermitian operator, then its eigenvalues are real and its eigenvectors corresponding to different eigenvalues are orthogonal.*

*Proof.* Let  $|v\rangle, |w\rangle$  be eigenvectors of  $A$  with corresponding eigenvalues  $v$  and  $w$ . Then,

$$v\langle v|v\rangle = \langle v|Av\rangle = \langle Av|v\rangle = v^*\langle v|v\rangle,$$

so  $v \in \mathbb{R}$ . In addition if  $v \neq w$ ,

$$w\langle w|v\rangle = \langle Aw|v\rangle = \langle w|Av\rangle = v\langle w|v\rangle,$$

so  $\langle w|v\rangle = 0$ , showing orthogonality. □

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<sup>3</sup>It turns out that being self-adjoint and Hermitian are not always the same if you allow  $T$  to be an unbounded linear operator, but this is a common abuse of terminology.

Many important operators in quantum mechanics are Hermitian. If  $V$  is finite dimensional, the space decomposes as the direct sum,

$$V = \bigoplus_{\alpha} V_{\alpha},$$

where  $V_{\alpha} = \{|x\rangle \neq 0 : A|x\rangle = \alpha|x\rangle\}$  is the eigenspace for eigenvalue  $\alpha$ , whose dimension defines the degeneracy of  $\alpha$ . By Theorem 1.6 these eigenspaces are mutually orthogonal, and choosing orthonormal bases in each  $V_{\alpha}$  yields an orthonormal eigenbasis for  $V$ .

For now, we will consider the case where  $V$  is finite-dimensional. Consider a Hermitian  $A$  with eigenbasis  $|a_i\rangle$ . We may write any vector  $|\alpha\rangle$  as

$$|\alpha\rangle = \sum_i c_i |a_i\rangle.$$

By multiplying both sides by  $\langle a_i|$ , we see that  $c_i = \langle a_i|\alpha\rangle$ , so

$$|\alpha\rangle = \sum_i |a_i\rangle \langle a_i|\alpha\rangle,$$

which gives identity

$$1 = \sum_i |a_i\rangle \langle a_i|. \quad (2)$$

Intuitively,  $|a_i\rangle \langle a_i|$  is a projection operator that projects any state onto basis vector  $a_i$ , so the identity is the result of projecting onto each basis vector and summing—this leads to no change as expected.

In none of this discussion did we *require* that  $V$  is finite-dimensional or even of countable dimension. Let us have a continuous spectrum of eigenvectors  $|x\rangle$  as in

$$A|x\rangle = x|x\rangle.$$

The orthonormality condition is given by  $\langle y|x\rangle = \delta(y-x)$  for two eigenvectors  $|x\rangle$  and  $|y\rangle$ . Then any arbitrary vector may be represented by

$$|\alpha\rangle = \int dx \langle x|\alpha\rangle |x\rangle,$$

and we may recover the useful property

$$1 = \int dx |x\rangle \langle x|.$$

One may have noticed that  $\delta(y-x) \notin \mathbb{C}$  if  $x = y$ , so this inner product cannot be well-defined between these eigenvectors  $|x\rangle$  and  $|y\rangle$ . This means that operating using  $|x\rangle$  seems ill-defined as an eigenbasis for the Hilbert space. Strictly speaking, it in fact does not form a basis for any Hilbert space and will instead serve as a convenient tool that physicists

use for calculations.<sup>4</sup> That is, we may recognize any vector  $|\psi\rangle$  in our Hilbert space  $V$  as a continuous combination of such “eigenvectors”  $|x\rangle$ ,

$$|\psi\rangle = \int dx \psi(x)|x\rangle,$$

but we should not ever view these  $|x\rangle$  as members of our Hilbert space themselves. As a result, we will often adopt the notation  $\psi(x) = \langle x|\psi\rangle$  to emphasize that  $x$  acts only as a parameterization of vectors.

### 1.2.3 Change of Basis

Let  $V$  be finite-dimensional. If  $A$  is Hermitian, then we’ve already shown that we can form a basis from eigenvectors of  $A$ . This is to say that  $A$  is *diagonalized* under this basis. That is, if we can perform a change of basis using

$$U = [|a_1\rangle \cdots |a_n\rangle]$$

by the transformation  $A \rightarrow U^{-1}AU$ . Now, since the base vectors  $\{|a_i\rangle\}$  are orthonormal,  $U$  is actually **unitary**, which means that

$$UU^\dagger = U^\dagger U = 1.$$

Thus our change of basis transformation can be written as

$$A \rightarrow U^\dagger AU. \tag{3}$$

Now if  $A$  was the matrix used to form these eigenvectors then

$$\langle e_j|U^\dagger AU|e_i\rangle = \langle a_j|A|a_i\rangle = a_i\delta_{ij},$$

so it is diagonal under this basis.

**Theorem 1.7.** *Let  $\{|a_i\rangle\}$  and  $\{|b_i\rangle\}$  both be orthonormal bases. Then there exists a unitary operator  $U$  that can transform between these. The form of  $U$  is*

$$U = \sum_i |b_i\rangle\langle a_i|.$$

*Proof.* The  $U$  shown is unitary since

$$U^\dagger U = \sum_{k,l} |a_k\rangle\langle b_k|b_l\rangle\langle a_l| = \sum_k |a_k\rangle\langle a_k| = 1,$$

where we have used the fact that  $|\alpha\rangle\langle\beta|^\dagger = |\beta\rangle\langle\alpha|$ . Now, clearly  $U$  transforms us from  $\{|a_i\rangle\}$  to  $\{|b_i\rangle\}$ :

$$U|a_k\rangle = \sum_i |b_i\rangle\langle a_i|a_k\rangle = |b_k\rangle.$$

□

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<sup>4</sup>There do, however, exist formalisms to include distributions like the delta function within an extension of a Hilbert space. Such a space is called a *rigged Hilbert space*.



Thus any set of eigenvectors can be transformed to any other set of eigenvectors. In fact, it turns out that such a unitary change of basis does not even alter eigenvalues: Suppose  $A$  and  $B$  are Hermitian with eigenbases  $\{a_i\}$  and  $\{b_i\}$  related by a unitary transformation  $U$ . Then we have

$$UAU^\dagger|b_i\rangle = UAU^\dagger U|a_i\rangle = UA|a_i\rangle = a_i U|a_i\rangle = a_i|b_i\rangle.$$

That is  $UAU^\dagger$  shares eigenvalues with  $A$ .

**Remark:**

It turns out that quite a lot of interesting cases are such that  $B = UAU^\dagger$ . Consider for example spin angular momentum  $S_x$  and  $S_z$ . They share eigenvalues  $\pm\hbar/2$  and turn out to be related by a unitary rotation operator.

We may also consider change of bases in the continuous case. Suppose we have two continuous spectra  $\{|x\rangle\}$  and  $\{|y\rangle\}$ . Then

$$|\psi\rangle = \int dx \psi(x)|x\rangle = \int dy \tilde{\psi}(y)|y\rangle,$$

where  $\tilde{\psi}(y) = \langle y|\psi\rangle$ . If we know  $\langle x|y\rangle$  (recall, here  $|x\rangle$  and  $|y\rangle$  are understood to be drawn for different bases), then we may arrive at a change-of-basis using

$$\begin{aligned}\psi(x) &= \int dy \tilde{\psi}(y)\langle x|y\rangle, \\ \tilde{\psi}(y) &= \int dx \psi(x)\langle y|x\rangle.\end{aligned}\tag{4}$$

**Example 1.8.** Consider two continuous spectra on Hilbert space  $L^2$ :  $\{|x\rangle\}$  and  $\{|p\rangle\}$ . These will later correspond to position and momentum states. Their parameterizations  $\psi(x) = \langle x|\psi\rangle$  and  $\tilde{\psi}(p) = \langle p|\psi\rangle$  of a state  $\psi \in L^2$  are called *wavefunctions*. It will turn out that

$$\langle x|p\rangle = \frac{1}{\sqrt{2\pi\hbar}}e^{ixp/\hbar},$$

so the position-space wavefunctions and momentum-space wavefunctions are related by Equation 4 as

$$\begin{aligned}\psi(x) &= \frac{1}{\sqrt{2\pi\hbar}} \int dp \tilde{\psi}(p)e^{ixp/\hbar}, \\ \tilde{\psi}(p) &= \frac{1}{\sqrt{2\pi\hbar}} \int dx \psi(x)e^{-ixp/\hbar}.\end{aligned}$$

That is, these wavefunctions are related by the Fourier transform, so position-space and momentum-space are Fourier duals of each other.

### 1.2.4 Commuting Operators

Two operators  $A$  and  $B$  commute if  $AB = BA$ . To encode this information, we define the **commutator**

$$[A, B] := AB - BA.$$

We also define the **anti-commutator**

$$\{A, B\} := AB + BA.$$

Then operators  $A$  and  $B$  commute iff  $[A, B] = 0$ . We should state a few useful properties of the commutator:

$$\begin{aligned} [A, B] &= -[B, A], \\ [A + \alpha B, C] &= [A, C] + \alpha[B, C], \\ [A, BC] &= [A, B]C + B[A, C], \\ [A, [B, C]] + [B, [C, A]] + [C, [A, B]] &= 0, \\ [A, B]^\dagger &= [B^\dagger, A^\dagger]. \end{aligned} \tag{5}$$

**Theorem 1.9.** *If  $A$  and  $B$  are Hermitian and commute then  $B$  is block diagonal in the eigenbasis of  $A$ .*

*Proof.* We have,

$$0 = \langle a_i | [A, B] | a_j \rangle = (a_i - a_j) \langle a_i | B | a_j \rangle,$$

so if  $a_i \neq a_j$  then  $\langle a_i | B | a_j \rangle = 0$ . If  $a_i = a_j$  then we may have an eigenspace of dimension  $d$  corresponding to this eigenvalue. We cannot guarantee these are diagonal for  $B$ , but this guarantees block diagonality.  $\square$

From Theorem 1.9, if  $A$  is non-degenerate we have that the eigenvectors of  $A$  are also eigenvectors of  $B$ :

$$\begin{aligned} B|a_i\rangle &= \sum_{j,k} |a_j\rangle \langle a_j|B|a_k\rangle \langle a_k|a_i\rangle \\ &= \sum_j |a_j\rangle \langle a_j|B|a_i\rangle \\ &= \langle a_i|B|a_i\rangle |a_i\rangle, \end{aligned}$$

so  $|a_i\rangle$  is an eigenvector of  $B$  with eigenvalue  $\langle a_i|B|a_i\rangle$ . In fact, this remains true even in the presence of degeneracy, but to do this we must diagonalize  $B$  which amounts to starting with the block-diagonal form that Theorem 1.9 provides and diagonalizing each block matrix. Since  $A$  is diagonal in its own basis, it is possible to diagonalize the block matrices within  $B$  without affecting  $A$ .

### 1.2.5 Functions of Operators

Recall that if  $A$  is Hermitian, then

$$A = \sum_i a_i |a_i\rangle \langle a_i|,$$

or in continuous case,

$$A = \int da a |a\rangle\langle a|.$$

Let  $f : \mathbb{R} \rightarrow \mathbb{R}$  be defined for the set of eigenvalues of any operator  $A$ . Then we define

$$f(A) := \sum_i f(a_i) |a_i\rangle\langle a_i|,$$

and in continuous case

$$f(A) := \int da f(a) |a\rangle\langle a|.$$

**Example 1.10.** Examples of using functions of operators.

- Recall that if  $A$  can be diagonalized as  $A = U^{-1}DU$  with  $D = \text{diag}(a_i)$  and  $U = [u_i]$ , then

$$A^n = U^{-1}D^nU.$$

This means  $A^n$  has eigenvalues  $a_i^n$ . Our definition of functions on operators with  $f(\cdot) = (\cdot)^n$  agrees here.

- If  $f$  has Taylor series

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(0)}{k!} x^k,$$

then our definition provides

$$f(A) = \sum_i \sum_{k=0}^{\infty} \frac{f^{(k)}(0)}{k!} a_i^k |a_i\rangle\langle a_i| = \sum_{k=0}^{\infty} \frac{f^{(k)}(0)}{k!} A^k.$$

## 1.3 Position and Momentum

## 1.4 Wavefunctions

## 2. Quantum Dynamics

### 2.1 Schrödinger Picture

### 2.2 Heisenberg Picture

### 2.3 Free Particle

### 2.4 Harmonic Oscillator

### 2.5 Path Integral Formulation

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## 4. Symmetry

## 5. Approximation Methods

### 5.1 Time-independent Perturbation Theory

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### 5.5 The Adiabatic Approximation and Berry's Phase

### 5.6 Time-Dependent Perturbation Theory

## 6. Identical Particles



## 7. Scattering Theory

## 8. Scattering Theory

## 9. Relativistic Quantum Mechanics