

- 1.) Write a function that takes in a string and prints "hello" + "name":  
# insert code underneath
- 2.) How many IR sensors does Zumi have ?
  - A.) 2
  - B.) 4
  - C.) 6
  - D.) 8
- 3.) A front IR sensor reading of 0 means:
  - A.) An object is directly in front of Zumi
  - B.) Zumi has detected nothing in front of it
  - C.) Zumi is near an object
  - D.) Zumi is just starting to detect an object
- 4.) Fill in the blank (choose the best answer):  
We manipulate \_\_\_\_\_ in order to get Zumi to move.
  - A.) Distance
  - B.) Time
  - C.) Power
- 5.) What is the command to collect IR sensor data readings ?
  - A.) Zumi.get\_sensor\_data()
  - B.) Zumi.IR()
  - C.) Zumi.sensor\_readings()
  - D.) Zumi.get\_all\_IR\_data()
- 6.) Why is the Zumi.go\_straight command preferred over the Zumi.forward() ?
- 7.) What goes in the first argument to the Zumi.forward( A, B, C ) function ? The first argument would be where the A letter is.
  - A.) Time
  - B.) Power
  - C.) Distance
- 8.) True/False. Zumi.go\_straight() function only works when called inside of a loop with lower speed values ?