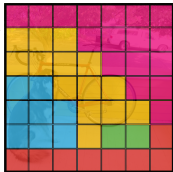


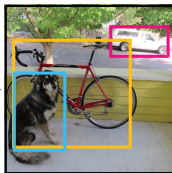
$S \times S$  grid on input



Bounding boxes + confidence



Class probability map



Final detections