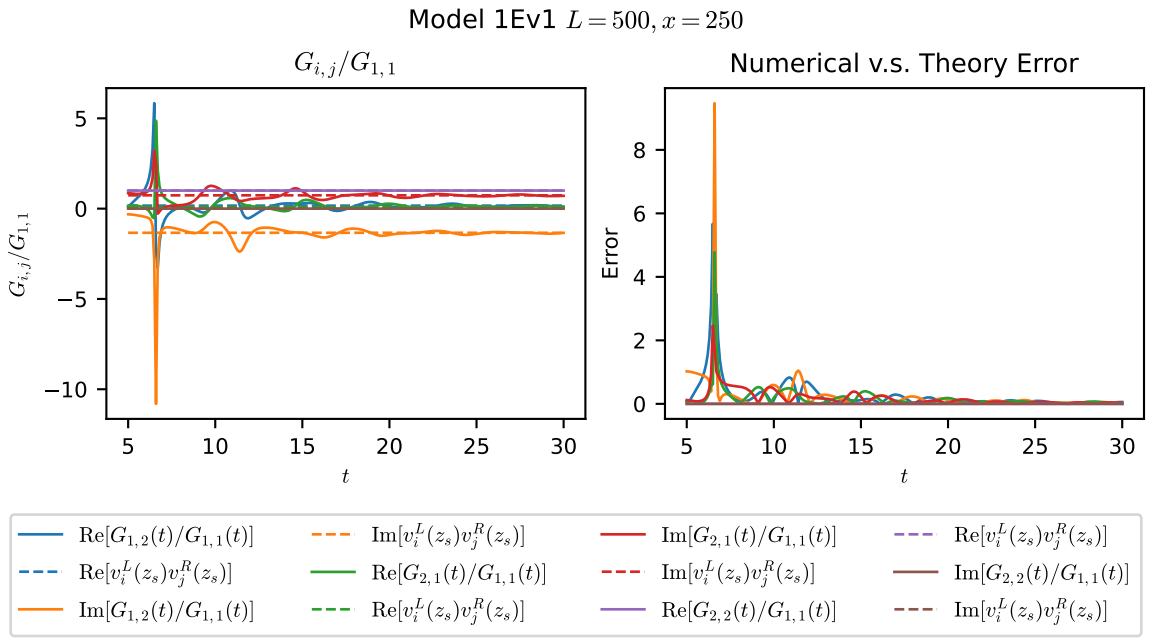
Model 1Ev1 $L = 500, x = 250$
$G_{i,j}/G_{1,1}$
$G_{i,j}/G_{1,1}$
t
Numerical v.s. Theory Error
Error
t
$\mathrm{Re}[G_{1,2}(t)/G_{1,1}(t)]$
$\mathrm{Re}[v_i^L(z_s)v_j^R(z_s)]$
$\mathrm{Im}[G_{1,2}(t)/G_{1,1}(t)]$
$\mathrm{Im}[v_i^L(z_s)v_j^R(z_s)]$
$\mathrm{Re}[G_{2,1}(t)/G_{1,1}(t)]$
$\mathrm{Re}[v_i^L(z_s)v_j^R(z_s)]$
$\mathrm{Im}[G_{2,1}(t)/G_{1,1}(t)]$
$\mathrm{Im}[v_i^L(z_s)v_j^R(z_s)]$
$\mathrm{Re}[G_{2,2}(t)/G_{1,1}(t)]$
$\mathrm{Re}[v_i^L(z_s)v_j^R(z_s)]$
$\mathrm{Im}[G_{2,2}(t)/G_{1,1}(t)]$
$\mathrm{Im}[v_i^L(z_s)v_j^R(z_s)]$