DP-SPRT: Differentially Private Sequential Testing

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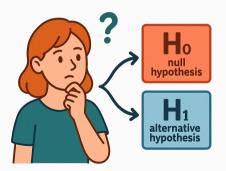


Sequential Hypothesis Testing

The Problem: We observe samples X_1, X_2, \ldots sequentially from distribution f_θ

Goal: Test $H_0: \theta = \theta_0$ vs $H_1: \theta = \theta_1$ with as few samples as possible

Constraints: False positive probability $\leq \alpha$, false negative probability $\leq \beta$

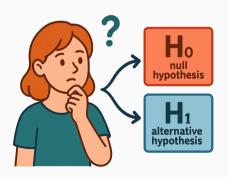


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When do we need to test?

- Clinical Trials
- A/B Testing
- Fraud Detection

In RL and Control:

- Model Validation
- Constraints Satisfaction

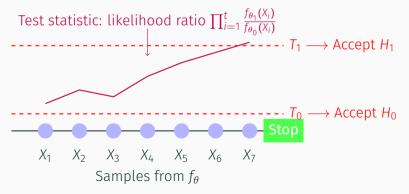
Sequential Probability Ratio Test

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Sequential Probability Ratio Test (SPRT) (Wald, 1945):



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Why Sequential?

- Efficiency: Stop as soon as you have enough evidence
- Optimality: SPRT minimizes expected sample size
- · Real-time: Make decisions as data arrives

The Privacy Problem: A Medical Trial

Scenario: Testing if new drug works better than placebo

 H_0 : Drug success rate = 30% (Same as placebo) vs H_1 : Drug success rate = 70%

Each patient outcome: $X_i \in \{0,1\}$ (failure/success)



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Question: What was patient 7's outcome? Success (1) or Failure (0)?

The stopping decision reveals patient 7 had a SUCCESS!

Privacy violation: Patient 7's medical outcome is leaked by our decision to stop

Privacy in Sequential Decisions



Clinical Trial

- Testing new drug vs placebo
- Stopping pattern reveals:
 - Treatment effectiveness
 - Patient responses



A/B Testing

- Users see different versions
- When we conclude reveals:
 - User behavior
 - Conversion rates



Fraud Detection

- Monitor transactions
- Alert timing reveals:
 - Transaction patterns
 - Detection methods

Core Problem: When we stop reveals what we observed

Differential Privacy

Neighboring Datasets: Two datasets D, D' are neighboring if they differ by exactly one record.

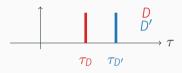
Differential Privacy (Dwork, Roth, et al., 2014): A randomized mechanism \mathcal{M} is DP if for any neigboring datasets D and D' and for any events S:

$$\begin{array}{ll} \varepsilon\text{-DP:} & \log\left(\frac{\mathbb{P}[\mathcal{M}(\mathcal{D})\in\mathcal{S}]}{\mathbb{P}[\mathcal{M}(\mathcal{D}')\in\mathcal{S}]}\right)\leq\varepsilon\\ \\ (\alpha,\varepsilon)\text{-R\'enyi DP:} & D_{\alpha}(\mathcal{M}(\mathcal{D})\|\mathcal{M}(\mathcal{D}'))\leq\varepsilon \end{array}$$

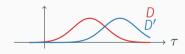
where D_{α} is the Rényi divergence of order $\alpha > 1$.

Stopping Time Distributions

Deterministic Algorithm



Private Algorithm



Privacy adds randomness to mask the stopping decision pattern

Our Method: DP-SPRT

DP-SPRT Algorithm (blue = privacy additions to SPRT):

Input: Hypotheses θ_0, θ_1 , error probabilities α, β , noise distributions $\mathcal{D}_Z, \mathcal{D}_Y$, correction function C(n,x), error allocation γ

- 1. Sample threshold noise $Z \sim \mathcal{D}_Z$
- 2. For $n = 1, 2, 3, \dots$ do
- 3. Sample query noise $Y_n \sim \mathcal{D}_Y$
- 4. Compute noisy average $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i + \frac{Y_n}{n}$
- 5. Compute noisy threshold $\hat{T}_0^n = \mu_0 + \frac{\text{KL}(\nu_{\theta_0}, \nu_{\theta_1}) \log(1/(\gamma\beta))/n}{\theta_1 \theta_0} C(n, (1 \gamma)\beta) \frac{Z}{n}$
- 6. Compute noisy threshold $\hat{T}_1^n = \mu_1 \frac{\text{KL}(\nu_{\theta_1}, \nu_{\theta_0}) \log(1/(\gamma \alpha))/n}{\theta_1 \theta_0} + C(n, (1 \gamma)\alpha) + \frac{Z}{n}$
- 7. If noisy average \bar{X}_n is below noisy threshold \hat{T}_0^n then Halt and accept \mathcal{H}_0
- 8. Else if noisy average \bar{X}_n is above noisy threshold \hat{T}_1^n then Halt and accept \mathcal{H}_1

DP-SPRT: Privacy

Table: Comparison of DP-SPRT instantiations

	Laplace Noise	Gaussian Noise
Noise distributions	$Y_n \sim \text{Lap}(4/arepsilon)$ $Z \sim \text{Lap}(2/arepsilon)$	$Y_n \sim \mathcal{N}(0, \sigma_Y^2)$ $Z \sim \mathcal{N}(0, \sigma_Z^2)$
Privacy guarantee	arepsilon-Differential Privacy	$(\alpha, \varepsilon(\alpha))$ -RDP
Correction function $C(n,x)$	$\frac{6\log(n^{s}\zeta(s)/x)}{n\varepsilon}$	$\frac{\sqrt{2(\sigma_Y^2 + \sigma_Z^2)\log(n^s\zeta(s)/2)}}{n}$

- Exact error control: $\mathbb{P}_{\theta_0}(\text{reject }H_0) \leq \alpha$, $\mathbb{P}_{\theta_1}(\text{accept }H_0) \leq \beta$
- Theoretical calibration: No empirical tuning required
- Privacy amplification: Enhanced with subsampling in high-privacy regimes

Near-Optimal Sample Complexity (DP-SPRT with Laplace noise)

Lower Bound (any ε -DP test):

$$\mathbb{E}[\tau] \ge \frac{\log(1/\beta)}{\min(\mathsf{KL}(\nu_{\theta_0}, \nu_{\theta_1}), \varepsilon \cdot \mathsf{TV}(\nu_{\theta_0}, \nu_{\theta_1}))} \tag{1}$$

Sample Complexity Upper Bound (Laplace Noise):

$$\mathbb{E}[\tau] \lesssim \max\left(\frac{\log(1/\beta)}{\mathsf{KL}(\nu_{\theta_0}, \nu_{\theta_1})}, \frac{(\theta_1 - \theta_0)\log(1/\beta)}{\varepsilon \cdot \mathsf{KL}(\nu_{\theta_0}, \nu_{\theta_1})}\right) \tag{2}$$

For Bernoulli distributions, we have

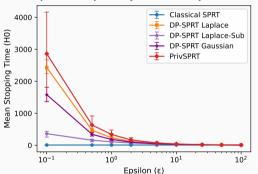
$$\frac{\mathsf{KL}(\nu_{\theta_0}, \nu_{\theta_1})}{\theta_1 - \theta_0} \xrightarrow[\theta_1 \to \theta_0]{\mathsf{TV}(\nu_{\theta_0}, \nu_{\theta_1})}$$

DP-SPRT with Laplace noise is near-optimal

Experimental Results: Performance Comparison

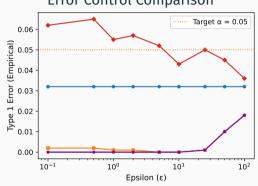
Setup: Bernoulli($p_0 = 0.3$) vs Bernoulli($p_1 = 0.7$), $\alpha = \beta = 0.05$, 1000 trials

Sample Complexity vs Privacy Level



On average, **DP-SPRT variants outperform** PrivSPRT (Zhang, Mei, and Cummings, 2022) across privacy levels

Error Control Comparison



All DP-SPRT variants guarantee error control, while PrivSPRT can violate error targets due to empirical tuning

Conclusion

Privacy:

- · Real-world applications **NEED** privacy (regulations, competition, ethics)
- · Sequential decisions leak sensitive information

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Our Contributions:

- First theoretically calibrated private sequential test with guaranteed error control
- 2. **Near-optimal sample complexity** matching lower bounds up to a constant in some regimes
- 3. Practical implementation with no empirical tuning required, low variance in stopping times, and subsampling amplification in high-privacy regimes

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References

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