Recorded at time: 1496193490.051 ur5/world Broadcaster: /rob\_st\_pub Average rate: 50.198 Hz Most recent transform: 1496193490.541 ( -0.490 sec old) Buffer length: 4.980 sec ur5/base\_link Broadcaster: /rob\_st\_pub Broadcaster: /rob\_st\_pub Average rate: 50.198 Hz Average rate: 41.869 Hz Most recent transform: 1496193490.035 ( 0.016 sec old) Most recent transform: 1496193490.541 ( -0.490 sec old) Buffer length: 4.968 sec Buffer length: 4.980 sec ur5/base ur5/shoulder\_link Broadcaster: /rob\_st\_pub Average rate: 41.869 Hz Most recent transform: 1496193490.035 ( 0.016 sec old) Buffer length: 4.968 sec ur5/upper\_arm\_link Broadcaster: /rob\_st\_pub Average rate: 41.869 Hz Most recent transform: 1496193490.035 ( 0.016 sec old) Buffer length: 4.968 sec ur5/forearm\_link Broadcaster: /rob\_st\_pub Average rate: 41.869 Hz Most recent transform: 1496193490.035 ( 0.016 sec old) Buffer length: 4.968 sec ur5/wrist\_1\_link Broadcaster: /rob\_st\_pub Average rate: 41.869 Hz Most recent transform: 1496193490.035 (0.016 sec old) Buffer length: 4.968 sec ur5/wrist\_2\_link Broadcaster: /rob\_st\_pub Average rate: 41.869 Hz Most recent transform: 1496193490.035 ( 0.016 sec old) Buffer length: 4.968 sec ur5/wrist\_3\_link Broadcaster: /rob\_st\_pub Broadcaster: /rob\_st\_pub Average rate: 50.198 Hz Average rate: 50.198 Hz Most recent transform: 1496193490.541 ( -0.490 sec old) Most recent transform: 1496193490.541 ( -0.490 sec old) Buffer length: 4.980 sec Buffer length: 4.980 sec ur5/ee\_link ur5/tool0 Broadcaster: /link1\_broadcaster Average rate: 10.191 Hz Most recent transform: 1496193490.070 ( -0.019 sec old) Buffer length: 4.906 sec gripper/world Broadcaster: /gripper/robot\_state\_publisher Average rate: 100.199 Hz Most recent transform: 1496193490.529 ( -0.478 sec old) Buffer length: 4.960 sec gripper/gripper\_root\_link Broadcaster: /gripper/robot\_state\_publisher Average rate: 100.199 Hz Most recent transform: 1496193490.529 ( -0.478 sec old) Buffer length: 4.960 sec gripper/robotiq\_85\_base\_link Broadcaster: /gripper/robot\_state\_publisher Broadcaster: /gripper/robot\_state\_publisher Broadcaster: /gripper/robot\_state\_publisher Broadcaster: /gripper/robot\_state\_publisher Average rate: 67.292 Hz Average rate: 67.292 Hz Average rate: 67.292 Hz Average rate: 67.292 Hz Most recent transform: 1496193490.026 ( 0.025 sec old) Buffer length: 4.949 sec Buffer length: 4.949 sec Buffer length: 4.949 sec Buffer length: 4.949 sec gripper/robotiq\_85\_left\_knuckle\_link gripper/robotiq\_85\_right\_knuckle\_link gripper/robotiq\_85\_left\_inner\_knuckle\_link gripper/robotiq\_85\_right\_inner\_knuckle\_link Broadcaster: /gripper/robot\_state\_publisher Broadcaster: /gripper/robot\_state\_publisher Broadcaster: /gripper/robot\_state\_publisher Broadcaster: /gripper/robot\_state\_publisher Average rate: 100.199 Hz Average rate: 100.199 Hz Average rate: 67.292 Hz Average rate: 67.292 Hz Most recent transform: 1496193490.529 ( -0.478 sec old) Most recent transform: 1496193490.529 ( -0.478 sec old) Most recent transform: 1496193490.026 ( 0.025 sec old) Most recent transform: 1496193490.026 ( 0.025 sec old) Buffer length: 4.960 sec Buffer length: 4.960 sec Buffer length: 4.949 sec Buffer length: 4.949 sec gripper/robotiq\_85\_left\_finger\_link gripper/robotiq\_85\_right\_finger\_tip\_link gripper/robotiq\_85\_right\_finger\_link gripper/robotiq\_85\_left\_finger\_tip\_link

view\_frames Result