view_frames Result Recorded at time: 1431702478.313 camera_link Broadcaster: /static_tf_publisher_2 Broadcaster: /static_tf_publisher_1 Average rate: 33.413 Hz Average rate: 33.417 Hz Most recent transform: 1431702478.335 (-0.022 sec old) Most recent transform: 1431702478.338 (-0.026 sec old) Buffer length: 4.968 sec Buffer length: 4.968 sec camera_rgb_frame camera_depth_frame Broadcaster: /static_tf_publisher_4 Broadcaster: /static_tf_publisher_3 Average rate: 33.400 Hz Average rate: 33.411 Hz Most recent transform: 1431702478.337 (-0.025 sec old) Most recent transform: 1431702478.335 (-0.023 sec old) Buffer length: 4.968 sec Buffer length: 4.970 sec camera rgb optical frame camera_depth_optical_frame Broadcaster: /ur5_with_asus_calibration Average rate: 5.106 Hz Most recent transform: 1431702478.151 (0.162 sec old) Buffer length: 4.701 sec shelf Broadcaster: /ur5_with_asus_calibration Average rate: 5.106 Hz Most recent transform: 1431702478.151 (0.162 sec old) Buffer length: 4.701 sec world Broadcaster: /robot_state_publisher Average rate: 50.208 Hz Most recent transform: 1431702478.808 (-0.495 sec old) Buffer length: 4.959 sec base_link Broadcaster: /robot_state_publisher Average rate: 31.413 Hz Most recent transform: 1431702478.307 (0.006 sec old) Buffer length: 4.966 sec shoulder_link Broadcaster: /robot_state_publisher Average rate: 31.413 Hz Most recent transform: 1431702478.307 (0.006 sec old) Buffer length: 4.966 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 31.413 Hz Most recent transform: 1431702478.307 (0.006 sec old) Buffer length: 4.966 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 31.413 Hz Most recent transform: 1431702478.307 (0.006 sec old) Buffer length: 4.966 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 31.413 Hz Most recent transform: 1431702478.307 (0.006 sec old) Buffer length: 4.966 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 31.413 Hz Most recent transform: 1431702478.307 (0.006 sec old) Buffer length: 4.966 sec wrist_3_link Broadcaster: /robot_state_publisher Average rate: 50.208 Hz Most recent transform: 1431702478.808 (-0.495 sec old) Buffer length: 4.959 sec ee_link