

# STAT 346/446 Lecture 6

## Principles of Data Reduction

CB Sections 6.1, 6.2, and DS Section 7.7

- 1 Sufficient Statistic
- 2 Minimal Sufficient Statistic
- 3 Ancillary Statistic
- 4 Complete Statistic

## Finding the "best" point estimator

- We have seen that the MLE of  $\sigma^2$  in  $N(\mu, \sigma^2)$  has a smaller MSE than the sample variance  $S^2$ .
- Could we find an estimator of  $\sigma^2$  that has the smallest possible MSE?
- Hard to answer in general, but if we restrict the space of estimators to e.g.
  - all unbiased estimators, or
  - all linear estimators, or
  - all linear and unbiased estimators

we can sometimes find the estimator with the smallest possible MSE in that space.

- UMVUE = Minimum Variance
- BLUE = Best Linear Unbiased Estimator

# Data reduction

- Want to use a sample  $X_1, X_2, \dots, X_n$  to infer about an unknown parameter  $\theta$ 
  - In practice: have data points  $x_1, x_2, \dots, x_n$
- A statistic  $T(X_1, X_2, \dots, X_n)$  is a method of summarizing the sample data
  - In practice:  $T(x_1, x_2, \dots, x_n)$
- Is there a statistic  $T(\cdot)$  (or statistics  $T_1(\cdot), \dots, T_k(\cdot)$ ) that gives the same amount of information about  $\theta$  as the sample  $X_1, X_2, \dots, X_n$  does?
  - Then we could store observed statistics only, instead of the whole dataset, i.e. get *data reduction*.
- Main use for STAT 346: Add tools to find UMVUEs (Section 7.3.3)

# Statistic as a partition of sample space

- A statistic  $T(X_1, X_2, \dots, X_n)$  can be thought of as a *partition* of the sample space  $\mathcal{X}$  of all possible outcomes for  $\mathbf{X} = (X_1, X_2, \dots, X_n)$

$$\mathcal{T}_{\mathbf{x} \in \mathcal{X}} \subset \mathcal{Y} \quad \mathcal{X} = \mathbb{R}^n$$

- Let

$$\mathcal{T} = \{t : t = T(x_1, x_2, \dots, x_n) \text{ for some } \mathbf{x} \in \mathcal{X}\}$$

- $\mathcal{T}$  contains all possible outcomes of  $T(X_1, X_2, \dots, X_n)$
- Often has lower dimension than  $\mathcal{X}$ 
  - E.g. if  $T(X_1, X_2, \dots, X_n) = \bar{X}$  then  $\mathcal{X} = \mathbb{R}^n$  and  $\mathcal{T} = \mathbb{R}$

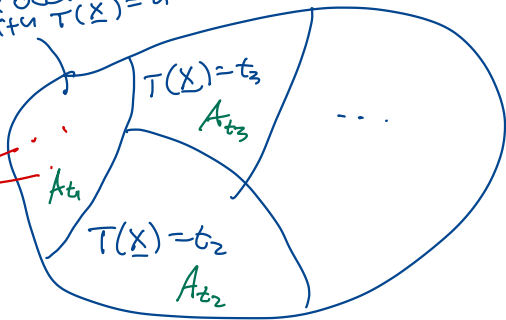
- Partition of  $\mathcal{X}$ :

$$A_t = \{\mathbf{x} : T(\mathbf{x}) = t\} \quad t \in \mathcal{T}$$

note: can have an uncountable index space

all vector  
with  $T(\underline{x}) = t_1$

all  
vectors  
in here  
have  
same  
sample  
mean



$X$  (e.g.  $\mathbb{R}^n$ )

$A_t, t \in \mathcal{T}$   
is a partition  
of  $X$

e.g. if  $T(\underline{x}) = \bar{x} \Rightarrow \mathcal{T} = \mathbb{R}$

$$\mathcal{T} = \{ t : T(\underline{x}) = t \text{ for some } \underline{x} \in X \}$$

# Sufficient data reduction

- A **sufficient statistic**  $T(\mathbf{X})$  for  $\theta$  (for a given distribution of  $\mathbf{X}$ ) is a statistic that contains (in some way) *all* the information about  $\theta$  in our sample  $X_1, X_2, \dots, X_n$

## Sufficiency Principle

If  $T(\mathbf{X})$  is a sufficient statistic for  $\theta$ , then any inference about  $\theta$  should depend on the sample  $\mathbf{X}$  *only* through the value  $T(\mathbf{X})$ .

- I.e. if  $\mathbf{x}_1$  and  $\mathbf{x}_2$  are two sample outcomes such that  $T(\mathbf{x}_1) = T(\mathbf{x}_2)$  then the inference about  $\theta$  should be the same whether  $\mathbf{X} = \mathbf{x}_1$  or  $\mathbf{X} = \mathbf{x}_2$  was observed.
- Can have more than one sufficient statistic for the same parameter

# Sufficient statistic

## Def: Sufficient Statistic

A statistic  $T(\mathbf{X})$  is a **sufficient statistic for  $\theta$**  if

$$f(\mathbf{x} \mid T(\mathbf{X}) = t) \quad \text{does not depend on } \theta$$

i.e. the conditional distribution of the sample  $\mathbf{X}$  given the value of  $T(\mathbf{X})$  does not depend on  $\theta$ .

- Conditional probability = change of sample space
  - $f(\mathbf{x} \mid T(\mathbf{X}) = t)$  has support inside  $A_t$
- A sufficient statistic does not have to be one dimensional

# Making sense of the definition of a Sufficient Statistic

**Example:**  $X_1, X_2, X_3$  i.i.d. Bernoulli( $\theta$ ) and  $T(\mathbf{X}) = X_1 + X_2 + X_3$

- The joint pdf:

$$f(\mathbf{x}) = \overbrace{\theta^{x_1}(1-\theta)^{1-x_1}}^{f(x_1)} \overbrace{\theta^{x_2}(1-\theta)^{1-x_2}}^{f(x_2)} \overbrace{\theta^{x_3}(1-\theta)^{1-x_3}}^{f(x_3)}$$

for  $x_1, x_2, x_3 \in \{0, 1\} \times \{0, 1\} \times \{0, 1\}$   $(x_1, x_2, x_3)$

- What is the distribution of  $(X_1, X_2, X_3)$  *given* that  $T(\mathbf{X}) = 2$ ?

i.e. what is  $f(\underline{x} | T(\underline{X})=2)$ ?

$$f(\underline{x} | T(\underline{X})=2) = \frac{P(\underline{X}=\underline{x}, T(\underline{X})=2)}{P(T(\underline{X})=2)}$$

Given that  $T(\underline{x})=2$  we know that the new sample space is  $A_2 = \{(1,1,0), (1,0,1), (0,1,1)\}$



Given that  $T(x)=2$  we know that the new sample space is  $A_2 = \{(1,1,0), (1,0,1), (0,1,1)\}$

$f(x)$	$x_1$	$x_2$	$x_3$	$T(x)$
$(1-\theta)^3$	0	0	0	0
$\theta(1-\theta)^2$	0	0	1	1
$\theta(1-\theta)^2$	0	1	0	1
$\theta(1-\theta)^2$	1	0	0	1
$\theta^2(1-\theta)$	0	1	1	2
$\theta^2(1-\theta)$	1	0	1	2
$\theta^2(1-\theta)$	1	1	0	2
$\theta^3$	1	1	1	3

$A_0$

$A_1$

$A_2$

$A_3$

$$f((0,1,1) | T(x)=2) = \frac{\theta^2(1-\theta)}{P(T(x)=2)}$$

= same  
for  $(1,0,1)$   
and  $(1,1,0)$

$\Rightarrow$  The three outcomes are equally likely, no matter what  $\theta$  is!

$\Rightarrow T(x) = x_1 + x_2 + x_3$   
is a suff. stat for  $\theta$ .

In general : The outcomes in  $A_t$  (the part of the sample space we are conditioning on) will not always be equally likely for a sufficient statistic

Point is: We can find the conditional probability of all outcomes in  $A_t$  without knowing the value of  $\theta$ .

↓

$f(\underline{x} | T(\underline{x}) = t)$  does not depend on  $\theta$ .

# Identifying a Sufficient statistic - Discrete case

- Let's take a closer look at  $f(\mathbf{x} \mid T(\mathbf{X}) = t)$  for discrete random samples:

$$f(\mathbf{x} \mid T(\mathbf{X}) = t) = P(\underline{X} = \underline{x} \mid T(\underline{X}) = t)$$

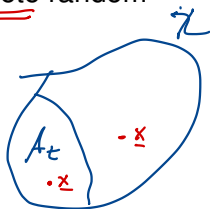
$$= \frac{P(\underline{X} = \underline{x}, T(\underline{X}) = t)}{P(T(\underline{X}) = t)}$$

$$= \frac{P(\underline{X} = \underline{x}, \underline{X} \in A_t)}{P(T(\underline{X}) = t)}$$

$$= \begin{cases} \frac{P(\underline{X} = \underline{x})}{P(T(\underline{X}) = t)} = \frac{f(\underline{x})}{f_T(t)} \\ 0 \end{cases}$$

$$\text{if } \underline{x} \in A_t$$

$$\text{if } \underline{x} \notin A_t$$



# Identifying a Sufficient statistic

## Theorem: Identifying a sufficient statistic

- Let  $p(\mathbf{x} \mid \theta)$  be the joint pmf or pdf of  $\mathbf{X} = (X_1, \dots, X_n)$  and
- Let  $q(t \mid \theta)$  be the pmf or pdf of a statistic  $T(\mathbf{X})$ .

If for every  $\mathbf{x} \in \mathcal{X}$  the ratio

*i.e does not depend  
on  $\theta$*

$$\frac{p(\mathbf{x} \mid \theta)}{q(T(\mathbf{x}) \mid \theta)}$$

is a constant as a function of  $\theta$ , then  $T(\mathbf{X})$  is a *sufficient statistic for  $\theta$*

- Need to find the pmf/pdf of  $T(\mathbf{X})$  (the sampling distribution) to use this result

# Example: Poisson

- Let  $X_1, X_2, \dots, X_n$  be a random sample from  $\text{Poisson}(\lambda)$ . Show that

$T(\mathbf{X}) = \sum_{i=1}^n X_i$  is a sufficient statistic for  $\lambda$ .

$$p(\underline{x} | \lambda) = \prod_{i=1}^n f(x_i | \lambda) = \prod_{i=1}^n \frac{e^{-\lambda} \lambda^{x_i}}{x_i!} = e^{-n\lambda} \lambda^{\sum_{i=1}^n x_i} \prod_{i=1}^n \frac{1}{x_i!}$$

= t

Also need the pmf of  $T(\underline{x}) = X_1 + X_2 + \dots + X_n$

Know that  $T(\underline{x}) \sim \text{Poisson}(n\lambda)$

$$\Rightarrow q(t | \lambda) = \frac{e^{-n\lambda} (n\lambda)^t}{t!} \quad \text{where } t = \sum_{i=1}^n x_i$$

$$\Rightarrow \frac{p(\underline{x} | \lambda)}{q(t | \lambda)} = \frac{e^{-n\lambda} \lambda^t \prod_{i=1}^n \frac{1}{x_i!}}{e^{-n\lambda} n^t \lambda^t \frac{1}{t!}} = \frac{t!}{n^t} \prod_{i=1}^n \frac{1}{x_i!}$$

= constant as a function of  $\lambda$

$\Rightarrow T(\underline{x}) = \sum_{i=1}^n X_i$  is a sufficient statistic for  $\lambda$ .

Example: Gamma<sup>1</sup>Exp(θ)  
"

- Let  $X_1, X_2, \dots, X_n$  be a random sample from  $\text{Gamma}(1, \theta)$ . Show that  $T(\mathbf{X}) = \sum_{i=1}^n X_i$  is a sufficient statistic for  $\theta$ .

$$p(\mathbf{x}|\theta) = \prod_{i=1}^n \frac{1}{\theta} e^{-x_i/\theta} = \theta^{-n} e^{-\frac{1}{\theta} \sum_{i=1}^n x_i} = \theta^{-n} e^{-t/\theta} \quad \text{where } t = \sum_{i=1}^n x_i$$

$$T = X_1 + X_2 + \dots + X_n \sim \text{Gamma}(n, \theta)$$

$$q(t|\theta) = \frac{1}{\Gamma(n)\theta^n} t^{n-1} e^{-t/\theta} \quad \text{where } t = \sum_{i=1}^n x_i$$

$$\Rightarrow \frac{p(\mathbf{x}|\theta)}{q(t|\theta)} = \frac{\theta^{-n} e^{-t/\theta}}{\frac{1}{(n-1)!} \theta^{-n} t^{n-1} e^{-t/\theta}} = \frac{(n-1)!}{t^{n-1}}$$

= a constant as a function of  $\theta$

$\Rightarrow T$  is a sufficient statistic for  $\theta$ .

<sup>1</sup> See book for Binomial and Normal

# More about sufficient statistics

- The original sample is it self a sufficient statistic

$$T(\underline{X}) = (X_1, X_2, \dots, X_n)$$

- The vector of the  $n$  *order* statistics

$$T(\mathbf{X}) = (X_{(1)}, X_{(2)}, \dots, X_{(n)})$$

is always a sufficient statistic for a random sample:

- Joint pdf/pmf of  $(X_{(1)}, X_{(2)}, \dots, X_{(n)})$  is

$$n! f(x_1) f(x_2) \cdots f(x_n) \quad \text{for } -\infty < x_1 < \cdots < x_n < \infty$$

so

$$\frac{p(\mathbf{x} | \theta)}{q(T(\mathbf{x}) | \theta)} = \frac{f(x_1) f(x_2) \cdots f(x_n)}{n! f(x_1) f(x_2) \cdots f(x_n)} = \frac{1}{n!}$$

- For some distributions the order statistics is as far as we can go with data reduction.

# Finding a sufficient statistic

- Finding  $q(T(\mathbf{x}) | \theta)$  can be difficult. There are ways around it!

## Factorization Theorem

Let  $f(\mathbf{x} | \theta)$  be the joint pmf or pdf of  $\mathbf{X} = (X_1, \dots, X_n)$ . A statistic  $T(\mathbf{X})$  is a *sufficient statistic for  $\theta$*  if and only if  $f(\mathbf{x} | \theta)$  can be written as

$$f(\mathbf{x} | \theta) = \underbrace{g(T(\mathbf{x}) | \theta)}_{\text{function of } \theta \text{ and } T(\mathbf{x})} \underbrace{h(\mathbf{x})}_{\text{function of } \mathbf{x} \text{ only, no } \theta}$$

function of  $\theta$  and  
of  $\mathbf{x}$  only through  
 $T(\mathbf{x})$   
i.e. could evaluate  
 $g(T(\mathbf{x}) | \theta)$  only knowing  $T(\mathbf{x})$



Poisson example:

$$f(\underline{x}|\lambda) = \underbrace{e^{-n\lambda} \lambda^{\sum_{i=1}^n x_i}}_{g(t|\lambda)} \cdot \underbrace{\prod_{i=1}^n \frac{1}{x_i!}}_{h(\underline{x})}$$

where  $t = \sum_{i=1}^n x_i$

set  $h(\underline{x}) = \prod_{i=1}^n \frac{1}{x_i!}$

and  $g(T(\underline{x})|\lambda) = e^{-n\lambda} \lambda^{T(\underline{x})}$

$\Rightarrow$  By the factorization theorem  
 $T(\underline{x})$  is a sufficient statistic  
for  $\lambda$

# Example: Normal distribution

- Let  $X_1, X_2, \dots, X_n$  be a random sample from  $N(\mu, \sigma^2)$ . Use the factorization theorem to show that the sample mean and sample variance are a sufficient statistic for  $(\mu, \sigma^2)$  (both unknown)

$$\begin{aligned}
 f(\underline{x} | \mu, \sigma^2) &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi} \sigma} \exp\left(-\frac{(x_i - \mu)^2}{2\sigma^2}\right) \\
 &= (2\pi)^{-n/2} \sigma^{-n} \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2\right) \\
 &\Rightarrow \underbrace{(2\pi)^{-n/2} \sigma^{-n}}_{h(\underline{x})} \underbrace{\exp\left(-\frac{1}{2\sigma^2} ((n-1)s^2 + n(\bar{x} - \mu)^2)\right)}_{g(\bar{x}, s^2 | \mu, \sigma^2)}
 \end{aligned}$$

$\Rightarrow$  by factorization theorem,  $\bar{x}$  and  $s^2$  are sufficient statistics for  $\mu$  and  $\sigma^2$ .

Good fact to know:  $\sum_{i=1}^n (x_i - \mu)^2 = (n-1)s^2 + n(\bar{x} - \mu)^2$

where  $\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$  and  $s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$

# Example: Uniform distribution

- Let  $X_1, X_2, \dots, X_n$  be a random sample from  $\text{Uniform}(0, \theta)$ . Use the factorization theorem to show that the  $n$ th order statistic  $X_{(n)}$  is a sufficient statistic for  $\theta$

$$f(x_i) = \frac{1}{\theta} I_{(0, \theta)}(x_i)$$

$$f(\underline{x} | \theta) = \prod_{i=1}^n \frac{1}{\theta} I_{(0, \theta)}(x_i)$$

$$= \theta^{-n} \underbrace{I_{(0, \theta)}(x_{(n)}) I_{(0, \theta)}(x_{(n)})}_{g(x_{(n)}, x_{(n)} | \theta)}$$

$\Rightarrow (x_{(n)}, x_{(n)})$  are suff.

$$= \theta^{-n} \underbrace{I_{(-\infty, \theta)}(x_{(n)})}_{g(x_{(n)} | \theta)} \underbrace{I_{(0, \infty)}(x_{(n)})}_{h(\underline{x})}$$

$x_{(n)}$  is a suff. stat for  $\theta$ .  
(=

# Sufficient statistics for exponential families

- Let  $X_1, X_2, \dots, X_n$  be a random sample from pdf or pmf of the form

$$f(x | \theta) = h(x)c(\theta) \exp \left( \sum_{j=1}^k w_j(\theta) t_j(x) \right)$$

- The statistic

$$T(\mathbf{X}) = \left( \sum_{i=1}^n t_1(X_i), \sum_{i=1}^n t_2(X_i), \dots, \sum_{i=1}^n t_k(X_i) \right)$$

is a sufficient statistic for  $\theta$

$$f(x | \theta) = h(x)c(\theta) \exp \left( \sum_{j=1}^k w_j(\theta) t_j(x) \right)$$

for each  $i$   
 $i=1, \dots, n$

$$f(x_i | \underline{\theta}) = h(x_i) c(\underline{\theta}) \exp \left( t_1(x_i) w_1(\underline{\theta}) + \dots + t_k(x_i) w_k(\underline{\theta}) \right)$$

joint pdf/pmf:

$$f(\underline{x} | \underline{\theta}) = \prod_{i=1}^n h(x_i) c(\underline{\theta}) \exp \left( t_1(x_i) w_1(\underline{\theta}) + \dots + t_k(x_i) w_k(\underline{\theta}) \right)$$

$$\begin{aligned}
 &= \left( \prod_{i=1}^n h(x_i) \right) * c(\underline{\theta})^n \\
 &\quad * \exp \left( w_1(\underline{\theta}) \sum_{i=1}^n t_1(x_i) + \dots + w_k(\underline{\theta}) \sum_{i=1}^n t_k(x_i) \right) \\
 &= g \left( \sum_{i=1}^n t_1(x_i), \dots, \sum_{i=1}^n t_k(x_i) \mid \underline{\theta} \right)
 \end{aligned}$$

$h(\underline{x})$  —

# Many sufficient statistics

- For many distributions there are many different sufficient statistics
- The whole sample  $T(\mathbf{X}) = (X_1, X_2, \dots, X_n)$  is a sufficient statistic
- The set of all order statistics  $T(\mathbf{X}) = (X_{(1)}, X_{(2)}, \dots, X_{(n)})$  is a sufficient statistic
- Any one-to-one function of a sufficient statistic is a sufficient statistic  
 say,  $T$  is sufficient, let  $C(T) = \omega \Rightarrow T = C^{-1}(\omega)$   
 one-to-one

$$f(\underline{x} | \theta) = h(\underline{x}) g(T | \theta) = h(\underline{x}) \underbrace{g(C^{-1}(\omega) | \theta)}_{\text{funct. of } \omega}$$

Can we find a sufficient statistics that gives us most "data reduction" possible?

# Minimal Sufficient Statistic

## Def: Minimal sufficient statistic

A sufficient statistic  $T(\mathbf{X})$  is called a **minimal sufficient statistic** if for any other sufficient statistic  $T^*(\mathbf{X})$ ,  $T(\mathbf{X})$  is a function of  $T^*(\mathbf{X})$ .

E.g.  $T^* = (X_{(1)}, \dots, X_{(n)})$  and  $T = \sum_{i=1}^n X_i$   
 then  $T = \sum_{i=1}^n X_{(i)}$  i.e.  $T$  is a function of  $T^*$

- Obtains the *coarsest* partition of the sample space as possible, without losing any information about the parameter  $\theta$



- Can still have many different minimal statistics  
 $\rightarrow$  one-to-one function

# Finding a Minimal Sufficient Statistic

## Theorem

Let  $f(\mathbf{x} \mid \theta)$  be the pmf or pdf of a sample  $\mathbf{X}$ . Suppose there exists a function  $T(\mathbf{X})$  such that:

- For every two outcomes  $\mathbf{x}$  and  $\mathbf{y}$  the ratio

$$\frac{f(\mathbf{x} \mid \theta)}{f(\mathbf{y} \mid \theta)} \quad *$$

any  $\mathbf{x}, \mathbf{y} \in \mathcal{X}$

is a constant as a function of  $\theta$  if and only if  $T(\mathbf{x}) = T(\mathbf{y})$

then  $T(\mathbf{X})$  is a minimal sufficient statistic

- ① If  $T(\mathbf{x}) = T(\mathbf{y})$  then  $*$  is a const. as a funct. of  $\theta$
- ② If  $*$  is a const. as a function of  $\theta \Rightarrow T(\mathbf{x}) = T(\mathbf{y})$



Example:  $X_1, \dots, X_n$  are iid Poisson ( $\lambda$ )

$$f(\underline{x} | \lambda) = \prod_{i=1}^n \frac{e^{-\lambda} \lambda^{x_i}}{x_i!} = e^{-n\lambda} \lambda^{n\bar{x}} \prod_{i=1}^n \frac{1}{x_i!}$$

$$* = \frac{f(\underline{x} | \lambda)}{f(\underline{y} | \lambda)} = \frac{e^{-n\lambda} \lambda^{n\bar{x}} \prod_{i=1}^n \frac{1}{x_i!}}{e^{-n\lambda} \lambda^{n\bar{y}} \prod_{i=1}^n \frac{1}{y_i!}}$$

$$= \lambda^{n(\bar{x} - \bar{y})} \prod_{i=1}^n \frac{1}{x_i} \bigg/ \prod_{i=1}^n \frac{1}{y_i}$$

$$\begin{array}{l} A \Rightarrow B \\ \text{equiv.:} \\ \neg B \Rightarrow \neg A \end{array}$$

1) If  $\bar{x} = \bar{y}$  then  $* = \prod_{i=1}^n \frac{1}{x_i} \bigg/ \prod_{i=1}^n \frac{1}{y_i} = \text{const. as a function of } \lambda$

2) If  $\bar{x} \neq \bar{y}$  then  $*$  does depend on  $\lambda$ .

$\Rightarrow T(\underline{x}) = \bar{X}$  is a minimal suff. statistic.

## Example: Normal distribution

$$\begin{aligned} n\bar{x}^2 - 2n\bar{x}\mu + n\mu^2 \\ n\bar{y}^2 - 2n\bar{y}\mu + n\mu^2 \end{aligned}$$

- Let  $X_1, X_2, \dots, X_n$  be a random sample from  $N(\mu, \sigma^2)$ , both  $\mu$  and  $\sigma^2$  are unknown. Find a minimal sufficient statistic for  $(\mu, \sigma^2)$ .

Recall:  $f(\underline{x} | \mu, \sigma^2) = (2\pi\sigma^2)^{-n/2} \exp\left(-\frac{1}{2\sigma^2} [(n-1)s^2 + n(\bar{x}-\mu)^2]\right)$

$$\frac{f(\underline{x} | \mu, \sigma^2)}{f(\underline{y} | \mu, \sigma^2)} = \frac{(2\pi\sigma^2)^{-n/2} \exp\left(-\frac{1}{2\sigma^2} [(n-1)s_x^2 + n(\bar{x}-\mu)^2]\right)}{(2\pi\sigma^2)^{-n/2} \exp\left(-\frac{1}{2\sigma^2} [(n-1)s_y^2 + n(\bar{y}-\mu)^2]\right)}$$

where  $s_x^2 = \frac{1}{n-1} \sum (x_i - \bar{x})^2$  and  $s_y^2 = \frac{1}{n-1} \sum (y_i - \bar{y})^2$

$$= \exp\left(-\frac{1}{2\sigma^2} [(n-1)(s_x^2 - s_y^2) + n(\bar{x}^2 - \bar{y}^2) - 2n\mu(\bar{x} - \bar{y})]\right)$$

= constant as a function of  $\mu$  and  $\sigma^2$

if and only if  $s_x^2 = s_y^2$  and  $\bar{x} = \bar{y}$

$\Rightarrow s^2$  and  $\bar{x}$  are minimal suff. stat.

# Ancillary statistic

will not use much

## Def: Ancillary statistic

A statistic  $S(\mathbf{X})$  is called an **ancillary statistic** if its distribution does not depend on the parameter  $\theta$ .

→ I.e. no information about  $\theta$  in  $S(\underline{X})$

- Kind of an opposite to a sufficient statistic
- There are a few examples of ancillary statistics actually providing information about a parameter when combined with a sufficient statistic.
  - See examples in the textbook
- But often sufficient and ancillary statistics are *statistically independent*
  - At least if the sufficient statistic is *complete*

# Examples of Ancillary Statistics

- Say  $X_1, X_2, \dots, X_n$  is a random sample from  $N(\mu, \sigma^2)$  where  $\sigma^2$  is known.   
 i.e.  $\mu$  is the parameter of interest
- We have seen that

$$\frac{(n-1)S^2}{\sigma^2} \sim \chi_{n-1}^2$$

OR:  $S^2 = \frac{\sigma^2}{n-1} W$  where  $W \sim \chi_{n-1}^2$   
 distr. of  $S^2$  does not depend on  $\mu \Rightarrow S^2$  is an ancillary statistic for  $\mu$ .

# Complete statistic

\*  $g(T)$  is an unbiased estimator of zero.

## Def: Complete statistic

Let  $f(t | \theta)$  be a family of pdfs or pmfs for a statistic  $T(\mathbf{X})$ . The family is called **complete** if the following holds: *any function  $g(t)$ :*

- If  $E(g(T)) = 0$  for all  $\theta$  then  $P(g(T) = 0) = 1$  for all  $\theta$

Also, the statistic  $T(\mathbf{X})$  is called a **complete statistic**

- Property of the family of distributions  $f(t | \theta)$  belongs to. *distr. of the statistic*
- Can be hard to verify sometimes
  - See examples 6.2.22 and 6.2.23 in the textbook

# Completeness of exponential families

## Theorem 6.2.25

Let  $X_1, X_2, \dots, X_n$  be a random sample from pdf or pmf of the form

$$f(x | \theta) = h(x)c(\theta) \exp \left( \sum_{j=1}^k w_j(\theta) t_j(x) \right)$$

The statistic

$$T(\mathbf{X}) = \left( \sum_{i=1}^n t_1(X_i), \sum_{i=1}^n t_2(X_i), \dots, \sum_{i=1}^n t_k(X_i) \right)$$

is complete if  $\{(w_1(\theta), \dots, w_k(\theta)) : \theta \in \Theta\}$  contains an open set in  $\mathbb{R}^k$

- The condition means: the theorem does not hold for *curved exponential families* like  $N(\theta, \theta^2)$

# Example

- Let  $X_1, \dots, X_n$  be a random sample from  $\text{Poisson}(\lambda)$ . Use theorem 6.2.25 to find a complete statistic.

pmf:  $f(x|\lambda) = \frac{e^{-\lambda} \lambda^x}{x!} = \frac{1}{x!} e^{-\lambda} e^{\ln \lambda^x}$

$$= \underbrace{\frac{1}{x!}}_{h(x)} \underbrace{e^{-\lambda}}_{c(\lambda)} \underbrace{e^{x \ln \lambda}}_{t(x)} \underbrace{\quad}_{w(\lambda)}$$

$\Rightarrow$  Exponential family

$\Rightarrow \sum_{i=1}^n t(x_i) = \sum_{i=1}^n X_i$  is a complete statistic.

# Theorem regarding complete statistics

## Basu's Theorem

If  $T(\mathbf{X})$  is a complete and minimal sufficient statistic, then  $T(\mathbf{X})$  is independent of every ancillary statistic.

*redundant condition*

E.g.  $\bar{X}$  is a complete and minimal sufficient statistic for  $\mu$ . (Given a random sample from  $N(\mu, \sigma^2)$ )  
 $S^2$  is ancillary for  $\mu \Rightarrow$  By Basu,  $\bar{X}$  and  $S^2$  are independent.

## Theorem 6.2.28

If a minimal sufficient statistic exists, then any complete statistic is also a minimal sufficient statistic

*complete  $\Rightarrow$  minimal suff.*  
 $\Downarrow$   
*strongest.*



## Summary

Let  $X_1, \dots, X_n$  be a random sample from  $f(x|\theta)$

Let  $T = T(\underline{X})$

How to show that  $T$  is: does not depend on  $\theta$

\* Sufficient?

①: Def:  $f(\underline{x} | T(\underline{x}) = t)$  is a constant as a func. of  $\theta$

②:  $\frac{f(\underline{x}|\theta)}{g(t|\theta)} \leftarrow \text{pdf/pdf of } T, t = T(\underline{x})$

easiest  $\rightarrow$  ③: Factorization Theorem:  
$$f(\underline{x}|\theta) = g(T(\underline{x})|\theta) h(\underline{x})$$

\* Minimal sufficient?

for any  $x, y \in \mathcal{X}$ :

$\frac{f(x|\theta)}{f(y|\theta)}$  a constant as a function of  $\theta$   
if and only if  $T(x) = T(y)$

\* Complete?

Exponential family.