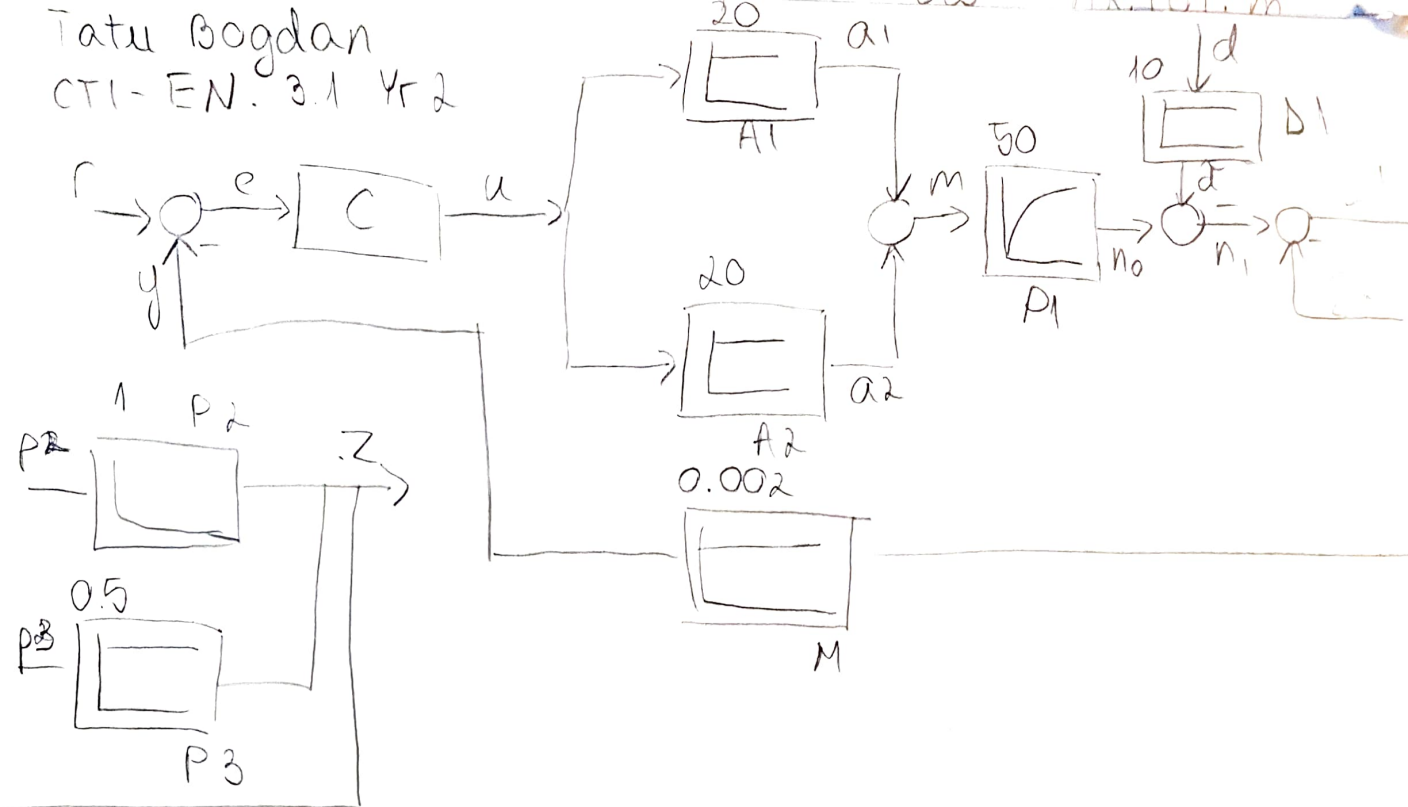


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CTI-EN. 3.1 Yr 2



$$C(s) = K_c \left(1 + \frac{1}{T_i s} \right) = K_c + \frac{K_c}{T_i s} = \frac{K_c (1 + T_i s)}{T_i s} \Rightarrow \text{PI controller}$$

$$1. H_{2r}(s) = \frac{z(s)}{r(s)} \Big|_{d(s)=0}$$

$$= H_c \cdot (H_{A1} + H_{A2}) \cdot H_{P1} \cdot \frac{H_{P2}}{1 + H_{P2} \cdot H_{P3}}$$

$$1 + H_c (H_{A1} + H_{A2}) \cdot H_{P1} \cdot \frac{H_{P2}}{1 + H_{P2} \cdot H_{P3}} \cdot H_M$$

$$= H_c (H_{A1} + H_{A2}) \cdot H_{P1} \cdot \frac{H_{P2}}{1 + H_{P2} \cdot H_{P3}}$$

$$\frac{1 + H_{P2} \cdot H_{P3} + H_c (H_{A1} + H_{A2}) \cdot H_{P1} \cdot H_{P2} \cdot H_M}{1 + H_{P2} \cdot H_{P3}}$$

$$= \frac{H_c (H_{A1} + H_{A2}) \cdot H_{P1} \cdot H_{P2}}{1 + H_{P2} \cdot H_{P3} + H_c (H_{A1} + H_{A2}) \cdot H_{P1} \cdot H_{P2} \cdot H_M}$$

$K_c > 0$

for H_{2d}

no

$$= \frac{K_c + K_c T_i \Delta}{T_i \Delta} \cdot (20 + 20) \cdot \frac{50}{2\Delta + 1} \cdot \frac{1}{\Delta}$$

$$1 + \frac{1}{\Delta} \cdot 0.5 + \frac{K_c + K_c T_i \Delta}{T_i \Delta} \cdot (20 + 20) \cdot \frac{50}{2\Delta + 1} \cdot \frac{1}{\Delta} \cdot 0.002$$

$$= \frac{(K_c + K_c \cdot T_i \Delta) \cdot 40 \cdot 50}{T_i \Delta \cdot (2\Delta + 1) \cdot \Delta}$$

$$1 + \frac{0.5}{\Delta} + \frac{(K_c + K_c T_i \Delta)(40) \cdot 50 \cdot 0.002}{T_i \Delta (2\Delta + 1) \cdot \Delta}$$

$$= \frac{K_c (1 + T_i \Delta) \cdot 2000}{T_i \Delta (2\Delta + 1) \cdot \Delta}$$

$$T_i \Delta (2\Delta + 1) \Delta + 0.5(2\Delta + 1) T_i \Delta + K_c (1 + T_i \Delta) \cdot 4$$

$$= \frac{K_c (1 + T_i \Delta) \cdot 2000}{2T_i \Delta^3 + T_i \Delta^2 + T_i \Delta^2 + 0.5T_i \Delta + 4K_c + 4K_c T_i \Delta}$$

for $K_c = 1$ and $T_i = 2.5$

$$\Rightarrow H_{2-r}(\Delta) = \frac{2000(2.5\Delta + 1)}{5\Delta^3 + 2.5\Delta^2 + 11.25\Delta + 4}$$

$$H_{2d}(\Delta) = -H_{D1} \cdot \frac{\frac{H_{P2}}{1 + H_{P3} H_{P2}}}{1 - \frac{H_{P2}}{1 + H_{P3} H_{P2}} \cdot H_M \cdot (-1) \cdot H_c \cdot (H_{A1} + H_{A2}) \cdot H_{P1}}$$

$$= -H_{D1} \cdot \frac{\frac{H_{P2}}{1 + H_{P2} \cdot H_{P3}}}{1 + H_{P2} H_{P3} + \frac{H_{P2} \cdot H_M \cdot H_c \cdot (H_{A1} + H_{A2}) \cdot H_{P1}}{1 + H_{P3} H_{P2}}}$$

$$= - \frac{H_{P2} \cdot H_{D1}}{1 + H_{P2} \cdot H_{P3} + H_{P2} \cdot H_M \cdot H_c \cdot (H_{A1} + H_{A2}) \cdot H_{P1}}$$

bottom is same as $H_{2r}(\Delta)$

$$= - \frac{\frac{1}{0.5\Delta} \cdot 10}{Ti\Delta^2(2\Delta+1) + 0.5Ti\Delta(2\Delta+1) + K_c(1+Ti\Delta) \cdot 4}$$

$$= - \frac{5Ti\Delta(2\Delta+1)}{Ti\Delta^2(2\Delta+1) + 0.5Ti\Delta(2\Delta+1) + K_c(1+Ti\Delta) \cdot 4}$$

$$= - \frac{10Ti\Delta^2 + 5Ti\Delta}{2Ti\Delta^3 + 2Ti\Delta^2 + 0.5Ti\Delta + 4K_c + 4K_cTi\Delta}$$

for $K_c = 1$ and $Ti = 2.5$

$$\Rightarrow H_{Z-d}(\Delta) = - \frac{12.5\Delta(2\Delta+1)}{5\Delta^3 + 5\Delta^2 + 11.25\Delta + 4}$$

$$3. H_2 - r(\Delta) = \frac{\dots}{5\Delta^3 + 5\Delta^2 + 11.25k_c\Delta + 4k_c} \quad k_c > 0$$

$$T_i = 2.5$$

$$\Delta(\Delta) = 5\Delta^3 + 5\Delta^2 + 11.25k_c\Delta + 4k_c \quad \text{same for } H_2d$$

$$> 0 \quad > 0 \quad > 0 \Rightarrow k_c > 0 \quad > 0 \Rightarrow k_c > 0$$

$$H_1 = \begin{pmatrix} 5 & 4k_c & 0 \\ 5 & 11.25k_c & 0 \\ 0 & 5 & 4k_c \end{pmatrix}$$

$$4. \det H_1 > 0 \Leftrightarrow 5 > 0 \quad \checkmark$$

$$\det H_2 > 0 \Leftrightarrow 36.25k_c > 0 \Leftrightarrow k_c > 0$$

$$\det H_3 > 0 \Leftrightarrow 4k_c \cdot \det H_2 > 0 \Leftrightarrow 4k_c^2 \cdot 36.25 > 0$$

$$\Leftrightarrow k_c^2 > 0 \Leftrightarrow |k_c| > 0 \Leftrightarrow k_c \in (-\infty, 0) \cup (0, \infty) \quad \Rightarrow k_c > 0$$

$$k_c > 0 \Rightarrow \text{system stable}$$

$$2. k_c = 1 \stackrel{3}{=} \text{system stable}$$

$$4. r_\infty = 5$$

$$d_\infty = 80$$

$$D1 \rightarrow P \stackrel{FVT}{=} \hat{d}_\infty = H_{D1}(0) \cdot d_\infty = 10 \cdot 80 = 800$$

$$H_c \rightarrow P1 \Rightarrow e_\infty = 0$$

$$c_\infty = r_\infty - y_\infty \Rightarrow y_\infty = e_\infty - r_\infty = 5$$

$$H_M \rightarrow P \stackrel{FVT}{=} y_\infty = H_M(0) \cdot z_\infty \Rightarrow z_\infty = \frac{y_\infty}{H_M(0)} = \frac{5}{0.002}$$

$$= 2500$$

$$H_{P3} \rightarrow P \stackrel{FVT}{=} p_{3\infty} = H_{P3}(0) \cdot z_\infty = 0.5 \cdot 2500 = 1250$$

$$H_{P2} \rightarrow 1 \Rightarrow p_{2\infty} = 0$$

$$p_{2\infty} = n'_{1\infty} - p_{3\infty} \Rightarrow n'_{1\infty} = p_{2\infty} + p_{3\infty} = 1250$$

$$n_{1\infty} = r_{0\infty} - \hat{d}_\infty \Rightarrow n_{0\infty} = n'_{1\infty} + \hat{d}_\infty = 2050$$

$$P1 \rightarrow PT1 \stackrel{FVT}{=} n_{\theta\infty} = H_{P1}(0) \cdot m_{\infty} \Rightarrow m_{\infty} = \frac{n_{\infty}}{H_{P1}(0)} = 41$$

$$m_{\infty} = a_{1\infty} + a_{2\infty}$$

$$A1, A2 \rightarrow P \stackrel{FVT}{=} a_{1\infty} = H_{A1}(0) \cdot u_{\infty} = 20u_{\infty}$$

$$a_{2\infty} = H_{A2}(0) \cdot u_{\infty} = 20u_{\infty}$$

$$\Rightarrow m_{\infty} = 40u_{\infty} \Rightarrow u_{\infty} = \frac{m_{\infty}}{40} = \frac{41}{40}$$

$$5. k_r = H_{zr}(0) = \frac{2000 k_c}{4k_c} = \frac{500 k_c}{k_c} = 500$$

$$k_d = H_{zd}(0) = 0$$

$$z_{\infty} = 500 r_{\infty} + 0 \cdot d_{\infty} = 2500 \checkmark$$

$$f = H_{zd} = 0$$

$$H_0(\Delta) = \frac{0.5}{\Delta} + \frac{k_c(1+2.5\Delta) \cdot 4}{2.5\Delta^2(2\Delta+1)}$$

= don't have time