

# Gyeongsu (Bob) Cho

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## Education

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**Ulsan National Institute of Science and Technology (UNIST)** 2022 – Present  
Integrated M.S.–Ph.D., Artificial Intelligence  
Research focus: 3D/4D vision, generative models, 3D content creation

**Chung-Ang University (CAU)** 2018 – 2021  
Bachelor of Engineering, Mechanical Engineering (Early Graduation)

## Research Interests

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3D/4D reconstruction of animals and humans, generative model, Gaussian splatting, video understanding.

## Publications

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### Journal Articles

- [J1]. A paper on "Reference-Guided Video Anomaly Detection for Display Inspection", submitted to *TCSVT*.
- [J2]. **DogRecon: Canine Prior-Guided Animatable 3D Gaussian Dog Reconstruction From a Single Image**  
Gyeongsu Cho, C. Kang, D. Soon, K. Joo. *International Journal of Computer Vision (IJCV)*, 2025.

### Conference Papers

- [C1]. A paper on "4D Animal Mesh Reconstruction", submitted to *CVPR*
- [C2]. **Pose-Diverse Multi-View Virtual Try-on from a Single Frontal Image**  
S. Han\*, M. Chung\*, Gyeongsu Cho, K. Joo, T. Kim. *WACV*, 2026.
- [C3]. **Avatar++: Fast and Pose-Controllable 3D Human Avatar Generation from a Single Image**  
S. Han\*, M. Chung\*, Gyeongsu Cho, K. Joo, T. Kim. *ICCV 2025*, Wild3D Workshop.
- [C4]. **Canine Prior-Guided Animatable 3D Gaussian Dog Reconstruction From a Single Image**  
Gyeongsu Cho, C. Kang, D. Soon, K. Joo. *CVPR 2024, Computer Vision for Animals Workshop (Oral)*.
- [C5]. **SlaBins: Fisheye Depth Estimation using Slanted Bins on Road Environments**  
J. Lee, Gyeongsu Cho\*, J. Park\*, K. Kim\*, S. Lee\*, J. H. Kim, S.-G. Jeong, K. Joo. *ICCV*, 2023.

## Research & Industry Experience

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**Graduate Researcher, UNIST – 3D/4D Vision & Graphics** 2022 – Present

- Lead author of **DogRecon (IJCV 2025)** and **4D Animal Reconstruction** on single-image 3D Gaussian dog reconstruction and 4D animal motion from monocular videos.
- Develop synthetic video pipelines, SMAL-based animal models, and PyTorch3D-based renderers for large-scale training and evaluation.
- Explore generative pipelines that lift text/video outputs into animatable 3D/4D representations.

**Research Collaboration with Samsung Electronics – Video Anomaly Detection** 2024 – 2025

- Co-develop a video anomaly detection framework for industrial display inspection, using real manufacturing data.
- Contributed to dataset design, model architecture, and experiments for a **TCSVT** submission.

**Startup Project – Real-Time 3D Human Pose Estimation (KIC & GWU Program)** 2024

- Built a **3-camera real-time 3D human pose estimation system** with smoothing algorithms for stable motion analysis in gyms.
- Designed the system as an AI-based personal training assistant to support.
- Selected for a Korean government startup support program and a 3-week entrepreneurship program at **George Washington University**.

- Conducted 50+ interviews with fitness and healthcare professionals across major U.S. cities and refined a US-market-focused business model; ranked **1st in track**.

### Teaching & Mentoring

- Teaching Assistant: Linear Algebra (CAU), Computer Graphics (UNIST), Introduction to AI Programming 2 (UNIST).
- Tutor for a Hyundai Motor Company internal data/AI program (Python, data analysis).

### Grants & Awards

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**AI Tech Open Workshop – Creative Project UNIST (Startup Track, 1st Place)** 2025

- Project: *Lightweight camera system and inference for 3D animal model reconstruction*.
- Awarded **30,000,000 KRW (20,000 USD)**; funding allocated as research budget for continued 3D animal reconstruction work.

### Patents

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- **Method and apparatus for reconstructing a 3D dog Gaussian model from a single image**  
Korean Patent Application 10-2025-0107831 (2025-08-05); PCT Application PCT/KR2025/019381.
- **Method and apparatus for generating a depth map of an image**  
Korean Patent Application 10-2023-0125078, with 42dot.

### Reference

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**Prof. Kyungdon Joo**, Professor, UNIST

Relationship: M.S & Ph.D. advisor

E-mail: kyungdon@unist.ac.kr

**Dr. Hezhen Hu**, Postdoctoral fellow, UT Austin

Relationship: Collaborator

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