

Introduction to Algorithm design and analysis

Example: sorting problem.

Input: a sequence of n number $\langle a_1, a_2, \dots, a_n \rangle$

Output: a permutation (reordering) $\langle a_1', a_2', \dots, a_n' \rangle$
such that $a_1' \leq a_2' \leq \dots \leq a_n'$.

Different sorting algorithms:

Insertion sort and Mergesort.

Efficiency comparison of two algorithms

- Suppose $n=10^6$ numbers:
 - Insertion sort: $c_1 n^2$
 - Merge sort: $c_2 n (\lg n)$
 - Best programmer ($c_1=2$), machine language, one billion/second computer A.
 - Bad programmer ($c_2=50$), high-language, ten million/second computer B.
 - $2 (10^6)^2$ instructions/ 10^9 instructions per second = 2000 seconds.
 - $50 (10^6 \lg 10^6)$ instructions/ 10^7 instructions per second ≈ 100 seconds.
 - Thus, merge sort on B is 20 times faster than insertion sort on A!
 - If sorting ten million numbers, 2.3 days VS. 20 minutes.
- Conclusions:
 - Algorithms for solving the same problem can differ dramatically in their efficiency.
 - much more significant than the differences due to hardware and software.

Algorithm Design and Analysis

- Design an algorithm
 - Prove the algorithm is correct.
 - Loop invariant.
 - Recursive function.
 - Formal (mathematical) proof.
- Analyze the algorithm
 - Time
 - Worse case, best case, average case.
 - For some algorithms, worst case occurs often, average case is often roughly as bad as the worst case. So generally, worse case running time.
 - Space
- Sequential and parallel algorithms
 - Random-Access-Model (RAM)
 - Parallel multi-processor access model: *PRAM*

Insertion Sort Algorithm (cont.)

INSERTION-SORT(A)

1. **for** $j = 2$ to $\text{length}[A]$
2. **do** $key \leftarrow A[j]$
3. //insert $A[j]$ to sorted sequence $A[1..j-1]$
4. $i \leftarrow j-1$
5. **while** $i > 0$ and $A[i] > key$
6. **do** $A[i+1] \leftarrow A[i]$ //move $A[i]$ one position right
7. $i \leftarrow i-1$
8. $A[i+1] \leftarrow key$

Correctness of Insertion Sort Algorithm

- Loop invariant
 - At the start of each iteration of the for loop, the subarray $A[1..j-1]$ contains original $A[1..j-1]$ but in sorted order.
- Proof:
 - Initialization : $j=2$, $A[1..j-1]=A[1..1]=A[1]$, sorted.
 - Maintenance: each iteration maintains loop invariant.
 - Termination: $j=n+1$, so $A[1..j-1]=A[1..n]$ in sorted order.

Analysis of Insertion Sort

INSERTION-SORT(A)		<i>cost</i>	<i>times</i>
1.	for $j = 2$ to $\text{length}[A]$	c_1	n
2.	do $\text{key} \leftarrow A[j]$	c_2	$n-1$
3.	//insert $A[j]$ to sorted sequence $A[1..j-1]$	0	$n-1$
4.	$i \leftarrow j-1$	c_4	$n-1$
5.	while $i > 0$ and $A[i] > \text{key}$	c_5	$\sum_{j=2}^n t_j$
6.	do $A[i+1] \leftarrow A[i]$	c_6	$\sum_{j=2}^n (t_j - 1)$
7.	$i \leftarrow i-1$	c_7	$\sum_{j=2}^n (t_j - 1)$
8.	$A[i+1] \leftarrow \text{key}$	c_8	$n-1$

(t_j is the number of times the while loop test in line 5 is executed for that value of j)

The total time cost $T(n)$ = sum of *cost* \times *times* in each line

$$= c_1 n + c_2(n-1) + c_4(n-1) + c_5 \sum_{j=2}^n t_j + c_6 \sum_{j=2}^n (t_j - 1) + c_7 \sum_{j=2}^n (t_j - 1) + c_8(n-1)$$

Analysis of Insertion Sort (cont.)

- Best case cost: already ordered numbers
 - $t_j=1$, and line 6 and 7 will be executed 0 times
 - $T(n) = c_1n + c_2(n-1) + c_4(n-1) + c_5(n-1) + c_8(n-1)$
 $= (c_1 + c_2 + c_4 + c_5 + c_8)n - (c_2 + c_4 + c_5 + c_8) = cn + c'$
- Worst case cost: reverse ordered numbers
 - $t_j=j$,
 - SO $\sum_{j=2}^n t_j = \sum_{j=2}^n j = n(n+1)/2 - 1$, and $\sum_{j=2}^n (t_j - 1) = \sum_{j=2}^n (j - 1) = n(n-1)/2$,
and
 - $T(n) = c_1n + c_2(n-1) + c_4(n-1) + c_5(n(n+1)/2 - 1) + c_6(n(n-1)/2 - 1) + c_7(n(n-1)/2) + c_8(n-1)$
 $= ((c_5 + c_6 + c_7)/2)n^2 + (c_1 + c_2 + c_4 + c_5/2 - c_6/2 - c_7/2 + c_8)n - (c_2 + c_4 + c_5 + c_8) = an^2 + bn + c$
- Average case cost: random numbers
 - in average, $t_j = j/2$. $T(n)$ will still be in the order of n^2 , same as the worst case.

Merge Sort—divide-and-conquer

- **Divide:** divide the n -element sequence into two subproblems of $n/2$ elements each.
- **Conquer:** sort the two subsequences recursively using merge sort. If the length of a sequence is 1, do nothing since it is already in order.
- **Combine:** merge the two sorted subsequences to produce the sorted answer.

Merge Sort –merge function

- Merge is the key operation in merge sort.
- Suppose the (sub)sequence(s) are stored in the array A . moreover, $A[p..q]$ and $A[q+1..r]$ are two sorted subsequences.
- $\text{MERGE}(A, p, q, r)$ will merge the two subsequences into sorted sequence $A[p..r]$
 - $\text{MERGE}(A, p, q, r)$ takes $\Theta(r-p+1)$.

MERGE-SORT(A, p, r)

1. **if** $p < r$
2. **then** $q \leftarrow \lfloor (p+r)/2 \rfloor$
3. MERGE-SORT(A, p, q)
4. MERGE-SORT($A, q+1, r$)
5. MERGE(A, p, q, r)

Call to MERGE-SORT($A, 1, n$) (suppose $n = \text{length}(A)$)

Analysis of Divide-and-Conquer

- Described by recursive equation
- Suppose $T(n)$ is the running time on a problem of size n .
- $$T(n) = \begin{cases} \Theta(1) & \text{if } n \leq n_c \\ aT(n/b) + D(n) + C(n) & \text{if } n > n_c \end{cases}$$

Where a : number of subproblems

n/b : size of each subproblem

$D(n)$: cost of divide operation

$C(n)$: cost of combination operation

Analysis of MERGE-SORT

- **Divide:** $D(n) = \Theta(1)$
- **Conquer:** $a=2, b=2$, so $2T(n/2)$
- **Combine:** $C(n) = \Theta(n)$
- $T(n) = \begin{cases} \Theta(1) & \text{if } n=1 \\ 2T(n/2) + \Theta(n) & \text{if } n>1 \end{cases}$
- $T(n) = \begin{cases} c & \text{if } n=1 \\ 2T(n/2) + cn & \text{if } n>1 \end{cases}$

Compute $T(n)$ by Recursive Tree

- The recursive equation can be solved by recursive tree.
- $T(n) = 2T(n/2) + cn$, ([See its Recursive Tree](#)).
- $\lg n + 1$ levels, cn at each level, thus
- Total cost for merge sort is
 - $T(n) = cn \lg n + cn = \Theta(n \lg n)$.
 - Question: best, worst, average?
- In contrast, insertion sort is
 - $T(n) = \Theta(n^2)$.

Recursion tree of $T(n)=2T(n/2)+cn$

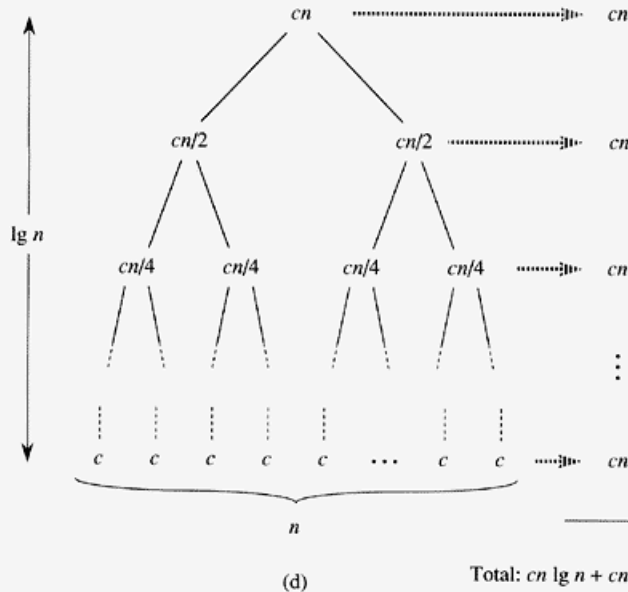
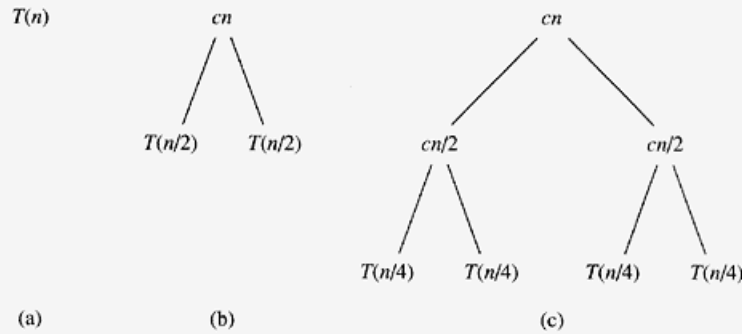
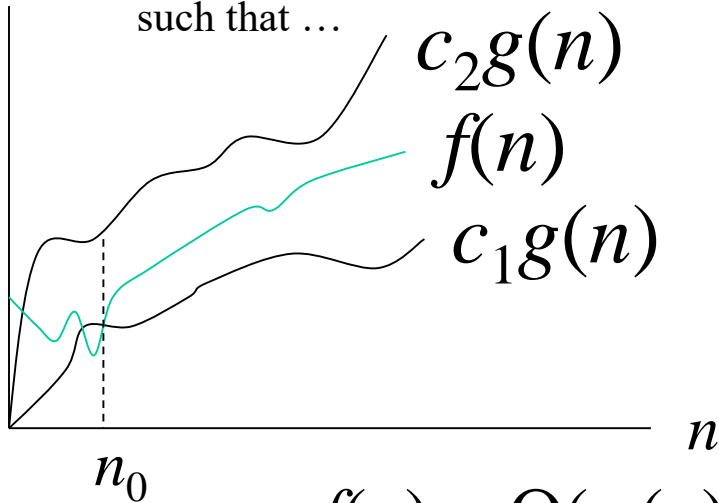


Figure 2.5 The construction of a recursion tree for the recurrence $T(n) = 2T(n/2) + cn$. Part (a) shows $T(n)$, which is progressively expanded in (b)–(d) to form the recursion tree. The fully expanded tree in part (d) has $\lg n + 1$ levels (i.e., it has height $\lg n$, as indicated), and each level contributes a total cost of cn . The total cost, therefore, is $cn \lg n + cn$, which is $\Theta(n \lg n)$.

Order of growth

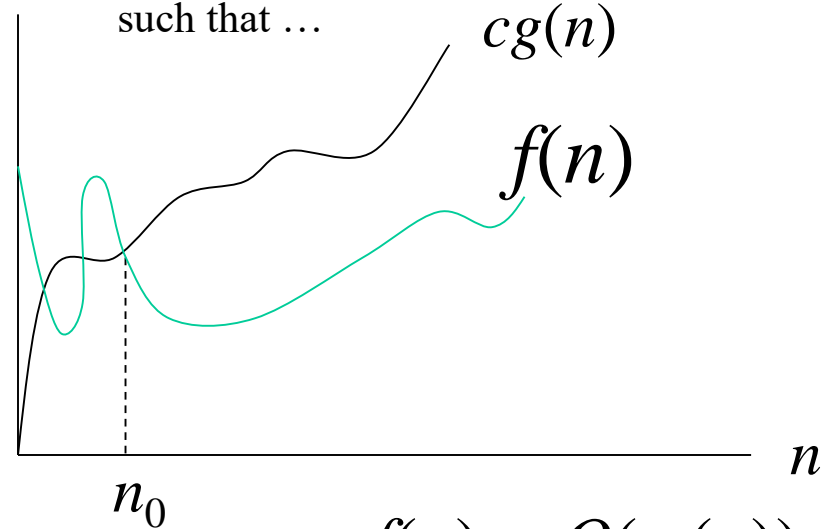
- Lower order item(s) are ignored, just keep the highest order item.
- The constant coefficient(s) are ignored.
- The rate of growth, or the order of growth, possesses the highest significance.
- Use $\Theta(n^2)$ to represent the worst case running time for insertion sort.
- Typical order of growth: $\Theta(1)$, $\Theta(\lg n)$, $\Theta(\sqrt{n})$, $\Theta(n)$, $\Theta(n \lg n)$, $\Theta(n^2)$, $\Theta(n^3)$, $\Theta(2^n)$, $\Theta(n!)$
- Asymptotic notations: Θ , O , Ω , o , ω .

There exist positive constants c_1 and c_2 such that there is a positive constant n_0 such that ...



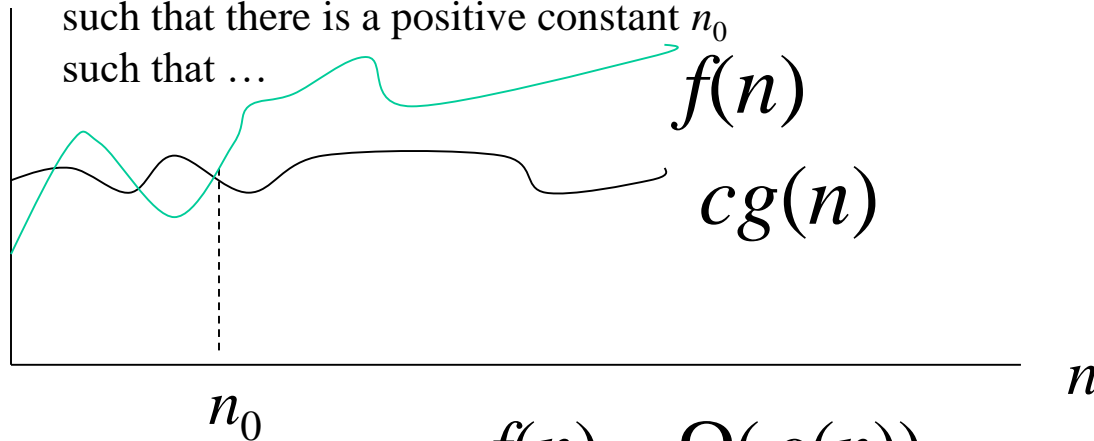
$$f(n) = \Theta(g(n))$$

There exist positive constants c such that there is a positive constant n_0 such that ...



$$f(n) = O(g(n))$$

There exist positive constants c such that there is a positive constant n_0 such that ...



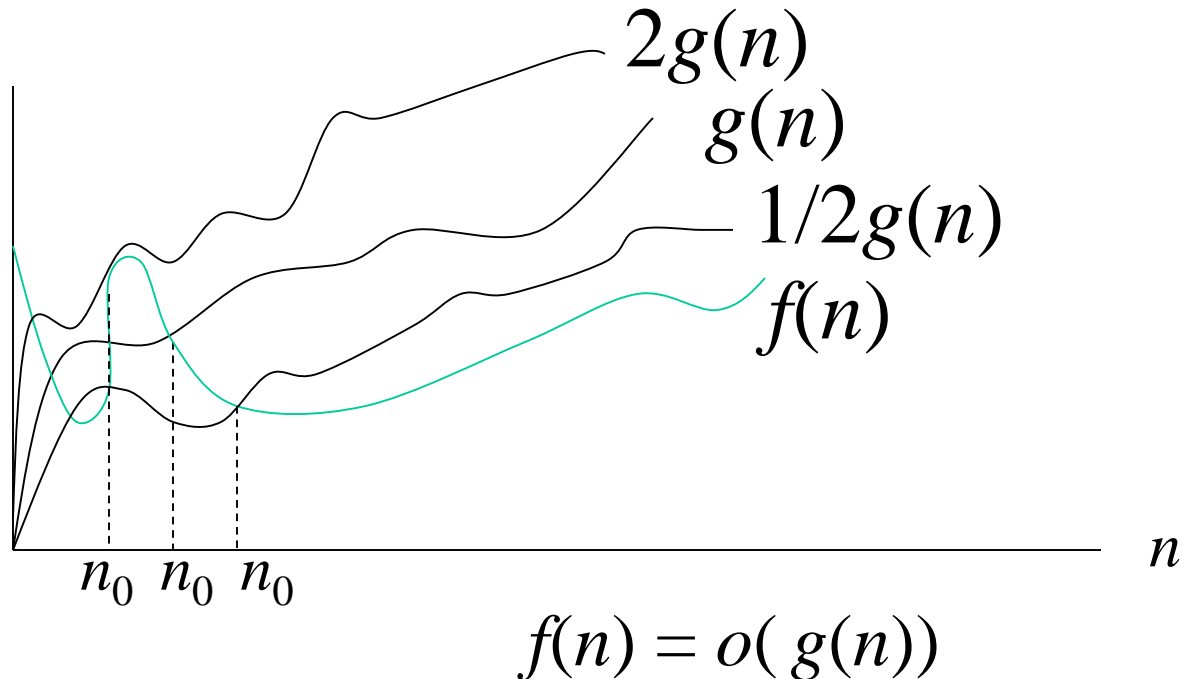
$$f(n) = \Omega(g(n))$$

Prove $f(n)=an^2+bn+c=\Theta(n^2)$

- a, b, c are constants and $a>0$.
- Find c_1 , and c_2 (and n_0) such that
 - $c_1n^2 \leq f(n) \leq c_2n^2$ for all $n \geq n_0$.
- It turns out: $c_1=a/4$, $c_2=7a/4$ and
 - $n_0 = 2 \cdot \max(|b|/a, \sqrt{|c|/a})$
- Here we also can see that lower terms and constant coefficient can be ignored.
- How about $f(n)=an^3+bn^2+cn+d$?

o -notation

- For a given function $g(n)$,
 - $o(g(n)) = \{f(n) : \text{for any positive constant } c, \text{ there exists a positive } n_0 \text{ such that } 0 \leq f(n) \leq cg(n) \text{ for all } n \geq n_0\}$
 - Write $f(n) \in o(g(n))$, or simply $f(n) = o(g(n))$.



Notes on o -notation

- O -notation may or may not be asymptotically tight for upper bound.
 - $2n^2 = O(n^2)$ is tight, but $2n = O(n^2)$ is not tight.
- o -notation is used to denote an upper bound that **is not tight**.
 - $2n = o(n^2)$, but $2n^2 \neq o(n^2)$.
- Difference: for **some** positive constant c in O -notation, but **all** positive constants c in o -notation.
- In o -notation, $f(n)$ becomes insignificant relative to $g(n)$ as n approaches infinitely: i.e.,
 - $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$.

ω -notation

- For a given function $g(n)$,
 - $\omega(g(n)) = \{f(n) : \text{for any positive constant } c, \text{ there exists a positive } n_0 \text{ such that } 0 \leq cg(n) \leq f(n) \text{ for all } n \geq n_0\}$
 - Write $f(n) \in \omega(g(n))$, or simply $f(n) = \omega(g(n))$.
- ω -notation, similar to o -notation, denotes lower bound that **is not asymptotically tight**.
 - $n^2/2 = \omega(n)$, but $n^2/2 \neq \omega(n^2)$
- $f(n) = \omega(g(n))$ if and only if $g(n) = o(f(n))$.
- $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = \infty$

Techniques for Algorithm Design and Analysis

- Data structure: the way to store and organize data.
 - Disjoint sets
 - Balanced search trees (red-black tree, AVL tree, 2-3 tree).
- Design techniques:
 - divide-and-conquer, dynamic programming, prune-and-search, lazy evaluation, linear programming, ...
- Analysis techniques:
 - Analysis: recurrence, decision tree, adversary argument, amortized analysis,...

NP-complete problem

- Hard problem:
 - Most problems discussed are efficient (poly time)
 - An interesting set of hard problems: NP-complete.
- Why interesting:
 - Not known whether efficient algorithms exist for them.
 - If exist for one, then exist for all.
 - A small change may cause big change.
- Why important:
 - Arise surprisingly often in real world.
 - Not waste time on trying to find an efficient algorithm to get best solution, instead find approximate or near-optimal solution.
- Example: traveling-salesman problem.