Data Structures and Algorithms ¹

BITS-Pilani K. K. Birla Goa Campus

¹Material for the presentation taken from Cormen, Leiserson, Rivest and Stein, *Introduction to Algorithms, Fourth Edition*;

Course plan

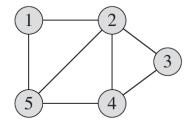
► Ch. 20, 21, 22.3 (Graph Algorithms)

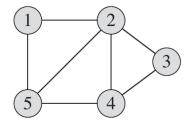
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- ► Ch. 20, 21, 22.3 (Graph Algorithms)
- ▶ Ch. 12, 13 (Binary Search Tree and Red-Black Tree)

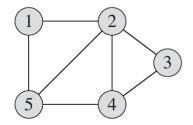
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- ► Ch. 20, 21, 22.3 (Graph Algorithms)
- ► Ch. 12, 13 (Binary Search Tree and Red-Black Tree)
- ► Ch. 11 (Hash Tables)





Graphs are mathematical structures consisting of vertices and edges.

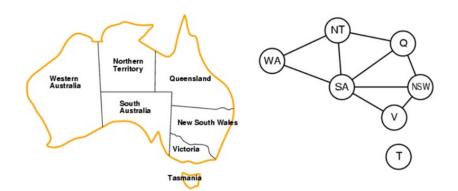


- Graphs are mathematical structures consisting of vertices and edges.
- ▶ The input to the graph algorithms will be a graph represented as G = (V, E).

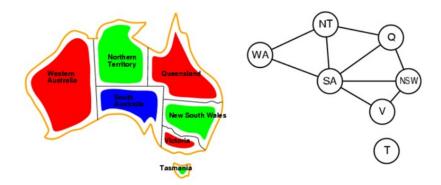
Map coloring problem



Vertex coloring problem



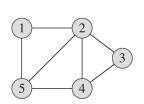
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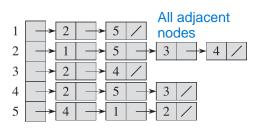


► Ch. 20: Elementary Graph Algorithms

Ch. 20: Elementary Graph Algorithms
 Breadth-first search, Depth-first search, Topological sort

Adjacency-list representation of undirected graphs





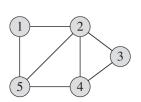
► Suppose we sum the lengths of all the adjacency lists of an undirected graph. What will be the sum?

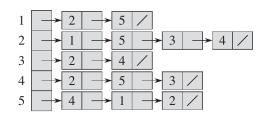
► Suppose we sum the lengths of all the adjacency lists of an undirected graph. What will be the sum?

- (i) V (ii) E (iii) V^2 (iv) VE
- (v) None of the above

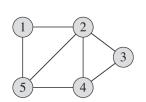
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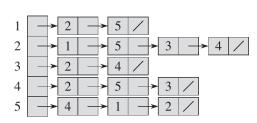
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Adjacency-matrix representation of undirected graphs

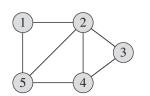


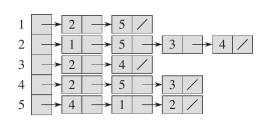


| | 1 | 2 | 3 | 4 | 5 |
|---|---|------------------|---|---|---|
| 1 | 0 | 1 | 0 | 0 | 1 |
| 2 | 1 | 0 | 1 | 1 | 1 |
| 3 | 0 | 1 | 0 | 1 | 0 |
| 4 | 0 | 1 | 1 | 0 | 1 |
| 5 | 1 | 1 0 1 1 | 0 | 1 | 0 |

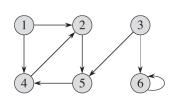
1 if adjacent

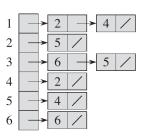
▶ Will the Adjacency-matrix for an undirected graph be symmetric? Yes



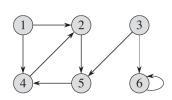


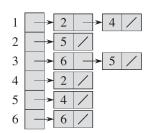
| | 1 | 2 | 3 | 4 | 5 |
|---|---|---|---|-----------------------|---|
| 1 | 0 | 1 | 0 | 0 | 1 |
| 2 | 1 | 0 | 1 | 1 | 1 |
| 3 | 0 | 1 | 0 | 1 | 0 |
| 4 | 0 | 1 | 1 | 0 | 1 |
| 5 | 1 | 1 | 0 | 0 1 1 0 1 | 0 |





adjacency only 1-way not 2-way





| | 1 | 2 | 3 | 4 | 5 | 6 |
|---|---|---|---|-----------------------|---|---|
| 1 | 0 | 1 | 0 | 1 | 0 | 0 |
| 2 | 0 | 0 | 0 | 0 | 1 | 0 |
| 3 | 0 | 0 | 0 | 0 | 1 | 1 |
| 4 | 0 | 1 | 0 | 0 | 0 | 0 |
| 5 | 0 | 0 | 0 | 1 | 0 | 0 |
| 6 | 0 | 0 | 0 | 1 0 0 0 1 | 0 | 1 |

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- ▶ Dense graphs: |E| is close to $|V|^2$.

Graph Representation: Weighted graphs

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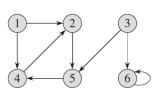
Weight function $w: E \to \mathbb{R}$.

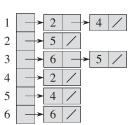
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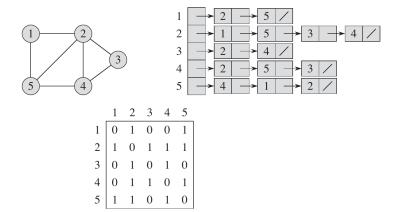


| | $\overline{}$ | | | | | |
|---|---------------|---|---|---|---|----------------------------|
| | 1 | 2 | 3 | 4 | 5 | 6 |
| 1 | 0 | 1 | 0 | 1 | 0 | 0 |
| 2 | 0 | 0 | 0 | 0 | 1 | 0 |
| 3 | 0 | 0 | 0 | 0 | 1 | 1 |
| 4 | 0 | 1 | 0 | 0 | 0 | 0 |
| 5 | 0 | 0 | 0 | 1 | 0 | 0 |
| 6 | 0 | 0 | 0 | 0 | 0 | 0 0 1 0 0 1 |

https://algorithmtutor.com/images/graph_representation_weighted.png

Graph Representation

Can we have an edge which is a self-loop in an undirected graph?



Graph Representation

Adjacency-list representation requires $\Theta(V+E)$ memory compared to $\Theta(V^2)$ memory for Adjacency matrix.

Graph Representation

- Adjacency-list representation requires $\Theta(V+E)$ memory compared to $\Theta(V^2)$ memory for Adjacency matrix.
- Suppose we wish to check whether a given edge (u, v) is present in a graph G(V, E). Which representation will take more time to check this? Adjacency-list or adjacency-matrix?

Matrix will be O(2*V), List will be O(V+E*), where E* would be number of edges for that vertex, ie, degree of that vertex.

Directed graph can double time but pretty much same complexity.

Breadth-first search algorithm

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- ▶ Also, we have an attributes *d* (distance) and *color* for each node.

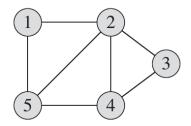
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- Operation of Breadth-first search (P. 557)

Breadth-first search algorithm

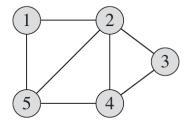
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- Operation of Breadth-first search (P. 557)
- Breadth-first search pseudocode (P.556)

Breadth-first search: Undirected graph



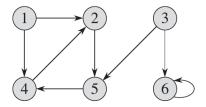
- ➤ Suppose we do a Breadth-first search starting from node 5. Which of the following orders of node visits is not possible under Breadth-first search?
- a. 5,4,1,2,3
- **b**. 5,1,2,4,3
- c. 5,1,2,3,4 c, since 4 is at less dist than 3

Breadth-first search: Undirected graph



▶ If we start from node 5, what will be the distance of node 3 found by the Breadth-first search?

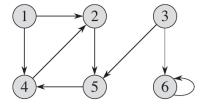
Breadth-first search: Directed graph



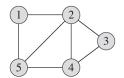
- ➤ Suppose we do a Breadth-first search starting from node 1. Which of the following orders of node visits is not possible under Breadth-first search?
- a. 1,2,4,5,3,6
- b. 1,2,5,4
- c. 1,2,4,5

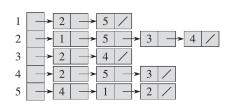
Only c is possible

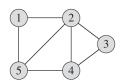
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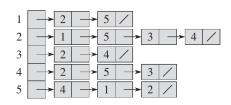


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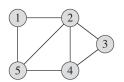


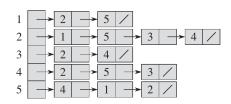




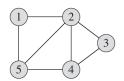


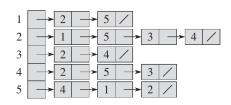
► Running time of BFS is



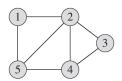


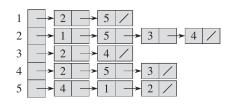
▶ Running time of BFS is O(V + E).



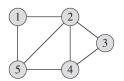


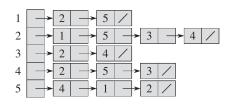
▶ Running time of BFS is O(V + E). (Aggregate analysis)





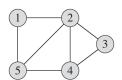
- ▶ Running time of BFS is O(V + E). (Aggregate analysis)
- ▶ Why is it called Breadth-first search?

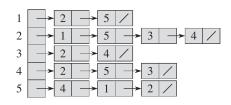




- Running time of BFS is O(V + E). (Aggregate analysis)
- Why is it called Breadth-first search?
- ▶ When the BFS algorithm terminates, the attribute *v.d* contains the shortest path (minimum number of edges) from node *s* to *v*.

Predecessor attribute π





The attribute π stores the parent (predecessor) of each node in the breadth-first tree. We can use π attributes to find the shortest path from s to any vertex v.

Q. What will be the running time of BFS if we represent its input graph by an adjacency matrix and modify the algorithm to handle this form of graph input?

▶ Predecessor subgraph $G_{\pi} = (V_{\pi}, E_{\pi})$:

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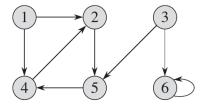
 $E_{\pi} = \{ (v.\pi, v) : v \in V_{\pi} - \{ s \} \}$

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Predecessor subgraph obtained after breadth-first search is called a breadth-first tree.



Suppose we do a Breadth-first search starting from node 1. Find the Breadth-First tree $G_{\pi} = (V_{\pi}, E_{\pi})$ obtained?

Tree consists of parts of graph reachable from given node

Shortest path in a maze

$$\mathsf{maze} = \left[\begin{array}{ccccccc} S & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 0 & E \end{array} \right]$$

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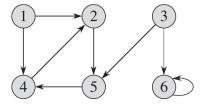
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- Discovered and finished timestamps.

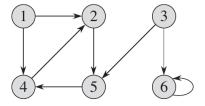
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- Discovered and finished timestamps.
- ▶ DFS pseudocode (p. 565)

Depth-first search: Directed graph



➤ Suppose that the first node to be discovered is 3. What are the possible finish timestamps for node 4?

Depth-first search: Directed graph



- ► Suppose that the first node to be discovered is 3. What are the possible finish timestamps for node 4?
- ▶ Which node remains white when node 3 is finished?

► Tree - connected acyclic graph

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- ▶ DFS helps us generate a depth-first forest G_{π} .

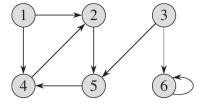
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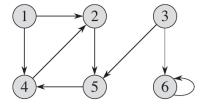
Forest is set of trees obtained on performing DFS from various initial nodes

Depth-first Tree



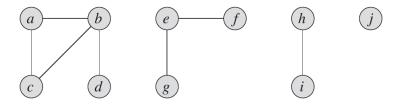
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Depth-first Tree



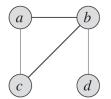
- ▶ DFS helps us generate a depth-first forest G_{π} .
- Suppose that the first node to be discovered is 3. What will the depth-first forest G_{π} look like?

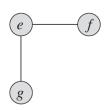
Depth-first Forest



Consider the undirected graph shown above.

Depth-first Forest





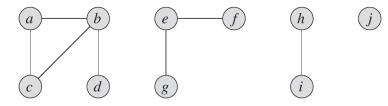




► Consider the undirected graph shown above.

$$|V| = 10, |E| = 7.$$

Depth-first Forest



- Consider the undirected graph shown above.
 - |V| = 10, |E| = 7.
- ▶ How many trees will the Depth-first forest G_{π} contain?

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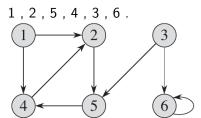
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1,2,5,4,3,6.
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▶ What will be a back edge in the above graph?

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- Back edge is an edge from a descendent node to a parent node during a DFS.
- Suppose we discover the nodes in the following order:

1, 2, 5, 4, 3, 6.

- ▶ What will be a back edge in the above graph? 4,2 is back edge
- Back edge helps us detect a cycle in a graph.

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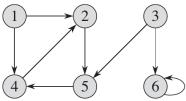
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- ► **Tree edge** if *v* is WHITE.
- How can we detect a Back edge using the COLOR attribute?

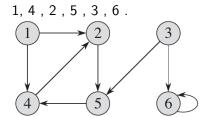
- During DFS of a directed graph, suppose we reach v by following adj[u]
- ▶ That is, we reach v by following the directed edge (u, v).
- Tree edge if v is WHITE.
- How can we detect a Back edge using the COLOR attribute?
- **▶ Back edge** if *v* is GRAY.

▶ Suppose we discover the nodes in the following order:

1, 4 , 2 , 5 , 3 , 6 .

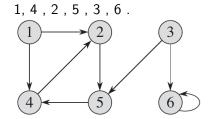


Suppose we discover the nodes in the following order:



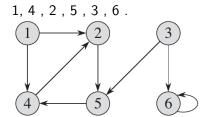
► How can we detect a Forward edge using the *COLOR* attribute?

Suppose we discover the nodes in the following order:



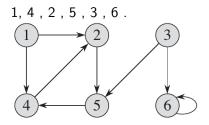
- ► How can we detect a Forward edge using the *COLOR* attribute?
- ▶ **Forward edge** if *v* is BLACK (not a sufficient condition).

Suppose we discover the nodes in the following order:



- ► How can we detect a Forward edge using the *COLOR* attribute?
- ▶ **Forward edge** if *v* is BLACK (not a sufficient condition).
- ► All the remaining edges are Cross edges.

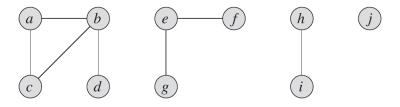
Suppose we discover the nodes in the following order:



colour implemented by map or hash table

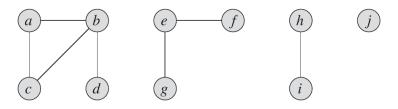
- How can we detect a Forward edge using the COLOR attribute?
- **Forward edge** if v is BLACK (not a sufficient condition).
- All the remaining edges are Cross edges.
- ► **Cross edge** : if *v* is BLACK.

Connected components of an undirected graph



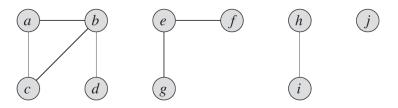
▶ Subgraph of a graph *G* is another graph formed from a subset of the vertices and edges of *G*.

Connected components of an undirected graph



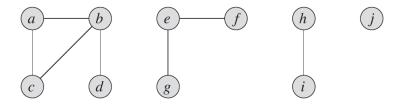
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Connected components of an undirected graph



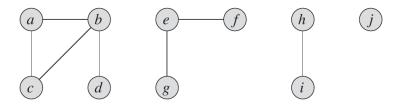
- ▶ Subgraph of a graph *G* is another graph formed from a subset of the vertices and edges of *G*.
- ► The vertex subset must include all endpoints of the edge subset, but may also include additional vertices.
- Connected component is a connected subgraph that is not part of any larger connected subgraph.

Counting the connected components



How many connected components are there in the above graph?

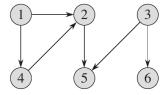
Counting the connected components



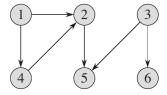
- How many connected components are there in the above graph?
- Can we modify the DFS algorithm to count the number of connected components?

➤ A directed graph without any back edge is called a Directed acyclic graph (DAG).

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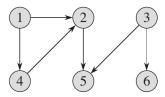


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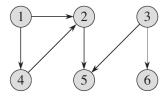


▶ Topological sort gives us a linear ordering of vertices such that if there is a directed edge (u, v), then u comes before v in the linear ordering.

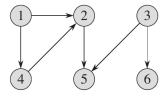
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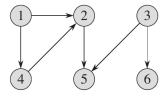
- ▶ Topological sort gives us a linear ordering of vertices such that if there is a directed edge (u, v), then u comes before v in the linear ordering.
- Which of the following is a topological sort?
- a. 1, 4, 2, 5, 3, 6
- b. 1, 4, 2, 3, 5, 6



- ▶ Which of the following is a topological sort?
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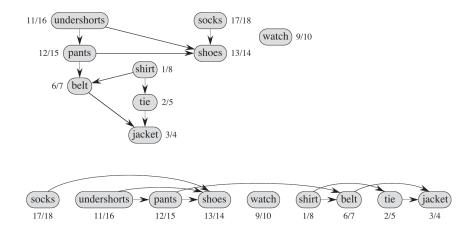


- Which of the following is a topological sort?
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- b. 1, 4, 2, 3, 5, 6
- Can we have another topological sort for the same graph?



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- a. 1, 4, 2, 5, 3, 6
- b. 1, 4, 2, 3, 5, 6
- Can we have another topological sort for the same graph?
- c. 3, 6, 1, 4, 2, 5

Topological sort example

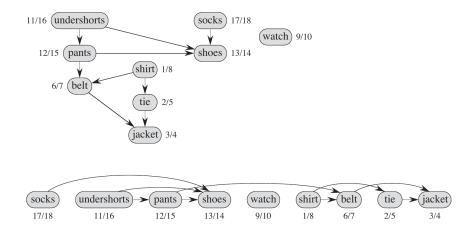


Topological sort pseudocode

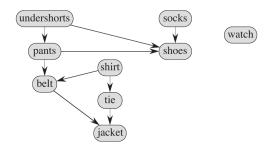
TOPOLOGICAL-SORT(G)

- 1 call DFS(G) to compute finishing times ν . f for each vertex ν
- 2 as each vertex is finished, insert it onto the front of a linked list
- 3 **return** the linked list of vertices

Topological sort example

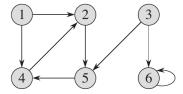


Topological sort example 2

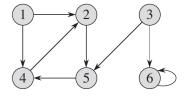


Let us say we consider nodes in the following order: Belt, Shoes, Shirt, Undershorts, Watch, Socks

▶ Topological sorting should fail if we detect a back edge.



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Why does topological sort algorithm work?

Applications of DFS and Topological sort

Operating system deadlock detection

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- Course schedule problem

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