

## MATHEMATICS FOR SIGNALS AND SYSTEMS

1. Let  $A \in \mathbb{R}^{n \times m}$  be a matrix with  $n$  rows and  $m$  columns whose entries are real numbers. We assume that  $n \geq m$  and that  $A$  has rank  $m$ .

We assume that we know the  $QR$ -decomposition of the matrix  $A$ , i.e. there exist two matrices  $Q \in \mathbb{R}^{n \times n}$  and  $R \in \mathbb{R}^{n \times m}$  such that  $A = QR$ ,  $Q$  is orthogonal ( $Q^T Q = I$  where  $I$  is the identity matrix), and  $R$  is an upper triangular matrix (the upper  $m \times m$  block of  $R$  is upper triangular and the rest of the entries of  $R$  are equal to zero). More precisely

$$R = \begin{pmatrix} r_{11} & r_{12} & r_{13} & \dots & r_{1m} \\ 0 & r_{22} & r_{23} & \ddots & \vdots \\ \vdots & \ddots & r_{33} & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & 0 & 0 & r_{mm} \\ 0 & \dots & \dots & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \dots & \dots & \dots & 0 \end{pmatrix}$$

In this problem the goal is to devise an algorithm to derive the  $QR$ -decomposition of the matrix  $\tilde{A} \in \mathbb{R}^{(n+1) \times m}$  obtained by adding a row to the matrix  $A$ . More precisely,

$$\tilde{A} = \begin{pmatrix} A_1 \\ z^T \\ A_2 \end{pmatrix} \quad \text{where} \quad A = \begin{pmatrix} A_1 \\ A_2 \end{pmatrix}$$

with  $A_1 \in \mathbb{R}^{n_1 \times m}$ ,  $A_2 \in \mathbb{R}^{n_2 \times m}$ ,  $n_1 + n_2 = n$ , and  $z \in \mathbb{R}^m$ .

- a) Let us also assume that

$$A = \begin{pmatrix} A_1 \\ A_2 \end{pmatrix} = \begin{pmatrix} Q_1 \\ Q_2 \end{pmatrix} R,$$

where  $Q_1$  and  $Q_2$  have the same number of rows as  $A_1$  and  $A_2$  respectively.

- i) Show that

$$\tilde{A} = \begin{pmatrix} \mathbf{0} & Q_1 \\ 1 & \mathbf{0}^T \\ \mathbf{0} & Q_2 \end{pmatrix} \begin{pmatrix} z^T \\ R \end{pmatrix}, \quad (1.1)$$

where  $\mathbf{0}$  represent zero vectors of the appropriate dimensions. [ 2 ]

- ii) Show that  $\hat{Q} = \begin{pmatrix} \mathbf{0} & Q_1 \\ 1 & \mathbf{0}^T \\ \mathbf{0} & Q_2 \end{pmatrix}$  is an orthogonal matrix. [ 3 ]

- iii) Is (1.1) a  $QR$  decomposition? Justify your answer. [ 2 ]

b) We define the matrix  $U_1$  as follows, for  $\theta \in \mathbb{R}$

$$U_1 = \begin{pmatrix} \cos(\theta) & -\sin(\theta) & 0 & \dots & 0 \\ \sin(\theta) & \cos(\theta) & 0 & \ddots & \vdots \\ 0 & 0 & 1 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

- i) Show that  $U_1$  is orthogonal. [ 1 ]
- ii) Find a value of  $\theta$  such that  $U_1^T \begin{pmatrix} z^T \\ R \end{pmatrix}$  has 0 in the entry on its second row and first column. [ 2 ]
- iii) More generally show that there is a sequence of orthogonal matrices  $U_1, \dots, U_m$  such that  $\tilde{R} = U_m^T \dots U_1^T \begin{pmatrix} z^T \\ R \end{pmatrix} \in \mathbb{R}^{(n+1) \times m}$  is upper triangular. [ 2 ]
- iv) Show that  $\tilde{Q} = \hat{Q}U_1 \dots U_m$  is an orthogonal matrix. [ 2 ]
- v) Describe an algorithm that updates the  $QR$  of a matrix if a row is added to it. [ 2 ]
- vi) Is the procedure described in b) v) more efficient than performing the  $QR$  decomposition of  $\tilde{A}$  from scratch, i.e. without relying on an update of the  $QR$  decomposition of  $A$ ? Justify your answer carefully. [ 4 ]

2. Define  $\|x\| = \sqrt{x^T x}$ .

a) Given a vector  $x$  and an orthogonal projection  $P$ , i.e.  $P^2 = P$  and  $P^T = P$ .

i) Show that  $Px$  and  $x - Px$  are orthogonal. [ 2 ]

ii) Show that  $\|x\|^2 = \|Px\|^2 + \|x - Px\|^2$ . [ 2 ]

b) Let  $U$  a subspace of  $\mathbb{R}^d$  of dimension  $k$  and let  $u_1, \dots, u_k$  an orthonormal basis of  $U$ , i.e.  $u_i^T u_i = 1$ , and for all  $i \neq j$   $u_i^T u_j = 0$ . Consider the matrix

$$P_U = \sum_{i=1}^k u_i u_i^T = u_1 u_1^T + u_2 u_2^T + \dots + u_k u_k^T$$

i) Show that  $P_U$  is an orthogonal projection and derive its range and null-space. [ 3 ]

ii) Let  $a_1, \dots, a_n$  be  $n$  vectors in  $\mathbb{R}^d$ . Show that

$$\sum_{j=1}^n \|P_U a_j\|^2 = \sum_{j=1}^n \sum_{i=1}^k (u_i^T a_j)^2.$$

*Hint: start by showing that for a given vector  $x \in \mathbb{R}^d$  we have that  $\|P_U x\|^2 = \sum_{i=1}^k (u_i^T x)^2$ .* [ 2 ]

c) We say that a subspace  $U$  of dimension  $k$  is the *best-fit  $k$ -dimensional subspace* if it maximizes the sum of the squared lengths of the orthogonal projections onto it, i.e. the subspace  $U$  such

$$\sum_{j=1}^n \|P_U a_j\|^2 = \max_{\substack{V \text{ subspace of } \mathbb{R}^d \\ \dim(V)=k}} \sum_{i=1}^n \|P_V a_i\|^2.$$

Using questions a.ii show that the subset  $U$  that maximize the sum of the squared lengths of the projections onto the subspace does also minimize the sum of squared distances to the subspace. [ 2 ]

d) Let  $A \in \mathbb{R}^{n \times n}$ . In what follows we will describe a procedure for deriving the singular vectors of  $A$ . Let  $a_1^T, \dots, a_n^T$  the vectors representing the rows of  $A$  ( $a_i^T$  being the  $i$ th row of  $A$ ).

i) Show that for any vector  $v \in \mathbb{R}^n$  we have

$$\sum_{i=1}^n (a_i^T v)^2 = \|Av\|^2. \quad [ 2 ]$$

ii) Let  $v_1 \in \mathbb{R}^n$  be such that  $Av_1 = \max_{\|v\|=1} \|Av\|$ . Using c and d.i, show that for all  $v \in \mathbb{R}^n$

$$\sum_{i=1}^n \|a_i - (v_1^T a_i)v\| \geq \sum_{i=1}^n \|a_i - (v_1^T a_i)v_1\|. \quad [ 2 ]$$

e) We now define a greedy procedure for deriving the singular vectors of  $A$ . Recall that

$$Av_1 = \max_{\|v\|=1} \|Av\|.$$

Let  $v_2 \in \mathbb{R}^n$  such that

$$Av_2 = \max_{\|v\|=1, v^T v_1=0} \|Av\|.$$

Similarly let  $v_3 \in \mathbb{R}^n$  such that

$$Av_3 = \max_{\|v\|=1, v^T v_1=0, v^T v_2=0} \|Av\|.$$

We stop the process when we found vectors  $v_1, v_2, \dots, v_r$  as singular vectors and

$$\max_{\|v\|=1, v^T v_1=0, \dots, v^T v_r=0} \|Av\| = 0.$$

Using an induction show that the subspace  $\text{Span}\{v_1, \dots, v_r\}$  spanned by  $\{v_1, \dots, v_r\}$  is the best-fit  $k$ -dimensional subspace for the vectors  $a_1, \dots, a_n$ . [ 5 ]

3. Let  $\mathbb{R}[X]$  be the vector space of polynomials with real coefficients, and  $\mathbb{R}_n[X]$  be the subspace of polynomials with degree smaller or equal to  $n$ . For  $P$  and  $Q$  in  $\mathbb{R}[X]$ , we define

$$\langle P, Q \rangle = \int_{-1}^1 P(x)Q(x) \frac{1}{\sqrt{1-x^2}} dx.$$

- a) Define  $T_k(x)$  the polynomials such that, for  $k \geq 1$  and  $\theta \in (0, \pi)$

$$T_k(\cos(\theta)) = \cos(k\theta), \quad T_0 = 1,$$

known as Chebyshev's polynomials.

- i) Give the expressions of  $T_1$ ,  $T_2$  and  $T_3$ . [ 3 ]  
 ii) Show that, for  $k \geq 1$ , we have

$$T_{k+1} = 2XT_k - T_{k-1}.$$

[ 3 ]

- iii) Using the change of variable  $\theta = \arccos(x)$ , compute  $\langle T_n, T_m \rangle$ , when  $n = m$  and  $n \neq m$ . [ 3 ]  
 iv) Derive an orthonormal basis for  $\mathbb{R}_3[X]$ . Justify your answer. [ 2 ]

- b) Consider the application on  $\mathbb{R}_n[X]$  defined by

$$D(P) = (1 - X^2)P'' - XP'$$

where  $P \in \mathbb{R}_n[X]$ ,  $P'$  and  $P''$  are its first and second derivatives respectively.

- i) Using that the fact that  $T_k(\cos(\theta)) = \cos(k\theta)$ , show that

$$-\cos(\theta)T'_k(\cos(\theta)) + \sin(\theta)^2 T''_k(\cos(\theta)) = -k^2 T_k(\cos(\theta)).$$

[ 3 ]

- ii) Show that  $D(T_k) = -k^2 T_k$ . [ 3 ]  
 iii) Derive the eigenvalues and eigenvectors of the transformation  $D$  on  $\mathbb{R}_n[X]$ . [ 3 ]