CAB202 Exam Cheat Sheet

Downsides of C

- Compilation adds complexity
- Few data structures, small standard library
- Typically more code required for a given application
- Not memory-safe and only weakly-typed; easy to write buggy code (eg. buffer overflow)

Rational Operators

| Operator | Description | Example |
|----------|-------------|---------|
| == | Equal | 1 == 1 |
| != | Not Equal | 1!=0 |
| > | Greater | 3 > 2 |
| < | Less | 3 < 4 |

Common Problems

- Unlike other languages, C doesn't have Boolean data type.
- Any non-zero value is true, 0 is false
- Be sure to use == to test equality, = for assignment.
- Identation

Logical Expressions

| Operator | Description |
|----------|-------------|
| && | AND |
| | OR |
| & | BITWISE AND |
| | BITWISE OR |
| ^ | BITWISE XOR |
| &= | AND EQUAL |
| = | OR EQUAL |
| ^= | XOR EQUAL |

Break Statements

- Can stop a loop early by using the break statement

```
int i = 1000;
while ( i < 2000) {
// Stop when we find a multiple of 87
if ( i % 87 == 0) { break ; }
i ++;
}
printf ( " % d \ n " , i );</pre>
```

Loops

While loops are the simplest loop in C. If condition is true then the loop is executed over and over until it becomes false.

```
while ( condition ) {
// body of loop
}
```

Do...while loops are like while loops, but the condition is evaluated after the body so the body is always executed at least once.

```
do {
// body of loop
} while ( condition );
```

A "For" Loop is used to repeat a specific block of code a known number of times.

```
for ( start_statement ; condition ;
    end_statement ) {
    // body of loop
}
```

Assignments in conditions

Assignments are expressions, so we can get a condition to do double duty!

```
int i;
// Keep scanning as long as we get something
while ( r = scanf ("%d,%d",&i,&j) > 0) {
// process i , j , r
}
```

Strings

- In C, a string is array of char
- "A" is a **string** constant
- 'A' is a **char** constant
- Strings end with a **NULL** character
- String length must be specified to ensure it does not read/write beyon the end of the memory allocated

Arrays

Arrays can be used to store:

- Numbers in a Vector
- Records in a databse
- Characters in a string Initialisation:

We can also do multi-dimensional arrays which use more than one index:

```
// Store a matrix in a 2 d array
double matrix [3][3] = { { 1 , 0 , 0} ,
{ 0 , 1 , 0} ,
{ 0 , 0 , 1} };
// Store a b & w image
unsigned char picture [1920][1020];
```

Array variables are just pointers!

```
- int * pX = &x
in English means an integer pointer named 'pX'
   is set to the address of x
- int A[10]; int* p = A; p[0] = 0; makes
   variable p point to the first member of
   array A.
```

Pointers

Pointer Definition

A pointer is a variable that **stores the memory address of another variable as its value**. A pointer is created with the * operator.

scanf() and strings

```
// We must allocate some space for a string
char buffer [100]:
// scan in a string until the next whitespace
// Note : buffer is already a pointer ! No &
scanf ( " % s " , buffer );
// Scanf will happily write beyond the end of
    buffer .
```

Printing strings

```
// Use %s to print a string with printf ()
char * mystring = " Hello world ! " ;
printf ( " mystring = % s \ n " , mystring );
// Using a string variable as a format string :
char * myformat = " mystring = % s " ;
printf ( myformat , mystring );
// puts () prints the string followed by newline
puts ( " Mystring = " );
puts ( mystring );
```

rand()

The rand() function returns pseudorandom numbers between 0 and RAND_MAX:

rand() is called only once using a specified seed.

If no **seed** is specified then it will always be the **de**fault seed.

```
int r = rand (); // between 0 and RAND_MAX
int N = 100:
int s = rand () \% N // 0 <= s < N
```

By default rand() will always return the same sequence of numbers!. This is why we provide different seeds using srand()

srand()

- Provide seed using srand() before calling rand()
- If the seed changes on each run then we get a new sequence of numbers
- Common to use current time as a seed

Functions

Functions allow reusing same code in many places and on different data

```
int myfunction (int a , int b) {
return a + b ;
// Using a function
int x = myfunction (3, 5);
// myfunction can now be called anywhere in the
```

Functions can be passed like variables using pointers

```
int addInt(int n, int m) {
   return n+m;
//define a pointer to a function which receives
    2 ints and returns an int:
int (*functionPtr)(int.int);
//use as value
int sum = (*functionPtr)(2, 3); // sum == 5
//use as function
int add2to3(int (*functionPtr)(int, int)) {
   return (*functionPtr)(2, 3);
```

Pass by Reference Vs Value

| Pass By Value | Pass By Reference |
|-------------------------|-------------------------|
| Makes a copy of the | Address of the actual |
| actual param | param passed to func |
| Changes made inside | Changes made inside |
| function do not | function reflect |
| reflect original value | original value |
| Function gets a copy of | Function acesses the |
| the actual content | original variable's |
| | content |

The stack

A stack is a linear data structure in which insertions and deletions are allowed only at the end. called the top of the stack

```
// Space to store items
char stack [256];
// Stack starts at highest address and grows
    down!
char * stack_pointer = stack + 255;
// Puts the value x at the top of the stack
void push ( char x ) {
* stack_pointer = x ;
stack_pointer - -;
// Removes the last value by the function push
char pop () {
stack_pointer ++;
return * stack_pointer ;
```

Bitwise Operations

| Operator | Name | Operation |
|----------|-------------|------------------|
| ~ | bitwise NOT | 1 if 0, 0 if 1 |
| &= | bitwise AND | 1 if both are |
| | | 1, otherwise 0 |
| | bitwise OR | 0 if both 0, |
| | | otherwise 1 |
| ^ | bitwise XOR | 0 if the same, |
| | | 1 if different |
| << | Left shift | move all bits |
| | | left, fill right |
| | | with 0 |
| >> | Right shift | move all bits |
| | | right, fill left |
| | | with 0 |

OR and AND for any bit b

```
b | 1 == 1
b | 0 == b
b & 1 == b
b & 0 == 0
```

Bitwise Masks

```
Setting Bits:
x = 0b1010;
mask = 0b0011;
z = x | mask;
// z == 0b1011

Clearing Bits:
x = 0b1010;
mask = 0b0011;
z = x ^ mask;
// z == 0b1001

Testing Bits
x = 0b1010;
mask = 0b0011;
z = x & mask;
// z == 0 b0010
```

Micro-Controllers

Registers

Storage with 8 bits capacity

- Connected to **CPU** (accumulator)
- Operations on their content require ${\bf only}$ one instruction

— Data Direction Registers (DDRx)

Configured to specify which of the 8 bits is used for **output(1)** or **input(0)**

Data Register (PORTx)

Writes output data to port

Input Pins Address (PINx)

Reads input data from port

unsigned char temp; // temporary variable
temp = PINB; // read input

Serial Communications

Serial Vs Parallel

| Serial | Parallel |
|-----------------------|------------------------|
| One data bit is | Multiple data bits are |
| transceived at a time | transceived at a time |
| Slower | Faster |
| Less number of cables | Higher number of |
| required | cables required |

Synchronous Vs Asynchronous

| Synchronous | Asynchronous |
|------------------------|------------------------|
| Send & Receiver clocks | Not synchronised |
| synchronised | |
| Faster | Bytes are enclosed |
| | between start and stop |
| | bits |
| Example: Serial | Example: Universal |
| Peripheral Interface | Sync/ Async |
| (SPI) | Receiver/Transmitter |
| | (USART) |

USART

- 1) Asynchronous Normal Mode
- Data is transferred at the BAUD rate set in UBBR register
- Data is transmitted/received asynchronously, not using clock pulses.
- 2) Asynchronous Double Speed Mode
- Everything is like normal mode but doubled
- 3) Synchronous Mode
- Requires both data and a clock
- The data is transmitted at a fixed rate

To use must specify

- 1) Baud Rate
- 2) Number of data bits encoding a frame or char
- Usually 10: 1 start, 8 data, 1 stop.
- 3) The sense of the parity bit
- 4) Number of stop bits

Minimally you'll need:

- \bullet uart_init(ubrr) //Initialise the baud rate
- uart_putchar(unsigned char data)
- unsigned char c = uart_getchar(void)

Timers

- \bullet AVR timers run asynchronous to main AVR core
- Use clock pulse as parallel increment
- When timer reaches TOP value, reset to 0 (over-flowed)
- When overflowed, sends signal which can be used for interrupts

| Pin | Output Compare |
|--------|----------------|
| | ${f Register}$ |
| Pin 3 | OC2B |
| Pin 5 | OC0B |
| Pin 6 | OC0A |
| Pin 9 | OC1A |
| Pin 10 | OC1B |
| Pin 11 | OC2A |

ADC

ADC Defintion

Analog to Digital converters are used to create an **electric quantity**(Bit value) to vary directly like a **continuous variable** (temperature)

Registers Involved •

- 1. **ADMUX** used to select reference voltage source
- 2. **ADCSRx** used to tune aspects of the conversion(Auto-Trigger, Off/On, Interrupt Enable)

PWM

PWM Definition

It is a way of simulating an **analog signal** via a **digital pin**. It does this buy turning **off** and **on** at different **frequencies** to achieve desired effects

Registers Involved

1. \mathbf{TCCRx} - used to determine when to turn off and on