Modelação de Sistemas Físicos 2020 – 2021

Formulário:

$$v_x(t) = \frac{dx}{dt}$$

$$a_x(t) = \frac{dv_x}{dt} = \frac{d^2x}{dt^2}$$

$$v_x(t+\delta t) = v_x(t) + \frac{dv_x}{dt} \left[\delta t + \frac{1}{2} \frac{d^2 v_x}{dt^2} \right] \delta t^2 + \frac{1}{3!} \frac{d^3 v_x}{dt^3} \left[\delta t^3 + \sigma(\delta t^4) \right]$$

$$\vec{F} = m \vec{a}$$

$$W = \int_{C} \vec{F} \cdot d\vec{r} = \int_{t_{0}}^{t_{1}} \vec{F} \cdot \vec{v} \, dt = \frac{1}{2} m \, |\vec{v}_{1}|^{2} - \frac{1}{2} m \, |\vec{v}_{0}|^{2} \qquad \int_{C} \vec{F}^{(conservativa)} \cdot d\vec{r} = E_{p0} - E_{p1}$$

$$\int_{C} \vec{F}^{(conservativa)} \cdot d\vec{r} = E_{p0} - E_{p1}$$

$$\vec{F}_{res} = -m \, D |\vec{v}| \vec{v}$$

$$ec{F}_{res} = -rac{c_{res}}{2} A
ho_{ar} |ec{v}| ec{v} \qquad \left| ec{F}_{rol}
ight| = \mu \left| ec{N}
ight|$$

$$\left| \vec{F}_{rol} \right| = \mu \left| \vec{N} \right|$$

$$\vec{F}_{Magnus} = \frac{1}{2} A \, \rho_{ar} \, r \, \vec{\omega} \times \vec{v} \quad \vec{F}_{grav} = -G \frac{m \, M}{|\vec{r}|^2} \frac{\vec{r}}{|\vec{r}|} \qquad \qquad \vec{F}_{elástica} = -k \, \vec{r}$$

$$\vec{F}_{grav} = -G \frac{m M}{|\vec{r}|^2} \frac{\vec{r}}{|\vec{r}|}$$

$$\vec{F}_{el\acute{a}stica} = -k \ \vec{r}$$

$$\vec{F}_{elet} = -k_e \frac{q \, Q}{|\vec{r}|^2} \frac{\vec{r}}{|\vec{r}|}$$

$$\vec{F}_{elet} = q\vec{E}_{elet}$$

$$F_{x} = -\frac{dE_{p}}{dx}$$

$$E_p = m g y$$

$$E_p = \frac{1}{2} k x^2$$

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$$P_o = \vec{F} \cdot \vec{v}$$

$$\int_{t_0}^{t_1} \vec{F}(t) \ dt = \vec{p}_1 - \vec{p}_0$$

$$\sum \vec{F}^{ext} = \frac{d\vec{P}}{dt}$$

$$x(t) = A \cos(\omega t + \phi)$$

$$\omega = \sqrt{\frac{K}{M}}$$

$$\omega = \sqrt{\frac{K}{M}} \qquad \qquad E = \frac{1}{2}k A^2$$

$$E_p(x) = E_p(x_{min}) + \frac{dE_p}{dx}\Big|_{x_{min}} \delta x + \frac{1}{2} \frac{d^2 E_p}{dx^2}\Big|_{x_{min}} \delta x^2 + \frac{1}{3!} \frac{d^3 E_p}{dx^3}\Big|_{x_{min}} \delta x^3 + \sigma(\delta x^4)$$

$$x(t) = \frac{a_0}{2} + a_1 \cos(\omega t) + b_1 \sin(\omega t) + a_2 \cos(2\omega t) + b_2 \sin(2\omega t) + \cdots$$

$$a_n = \frac{2}{T} \int_t^{t+T} f(t) \cos(n\omega t) dt,$$

$$a_n = \frac{2}{T} \int_t^{t+T} f(t) \cos(n\omega t) \ dt, \qquad n = 0, 1, 2, \dots \qquad b_n = \frac{2}{T} \int_t^{t+T} f(t) \sin(n\omega t) \ dt, \qquad n = 1, 2, \dots$$

$$n=1, 2, \cdots$$

$$x(t) = A e^{-\frac{b}{2m}t} \cos(\omega t + \phi) \qquad \omega = \sqrt{\omega_0^2 - \left(\frac{b}{2m}\right)^2}$$

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$$A(\omega_f) = \frac{\frac{F_0}{m}}{\sqrt{\left(\omega_f^2 - \omega_0^2\right)^2 + \left(\frac{b\omega_f}{m}\right)^2}}$$

$$y(x,t) = A \operatorname{sen}(kx - \omega t + \phi)$$

Grandezas físicas e conversões:

Grandezas matemáticas e Transformações Trigonométricas:

$$e = 2,71828183 \qquad \pi = 3,14159265$$

$$sen (-x) = -sen (x) \qquad sen (\pi - x) = sen (x) \qquad sen \left(x \pm \frac{\pi}{2}\right) = \pm \cos(x)$$

$$cos(-x) = +\cos(x) \qquad cos \left(x \pm \frac{\pi}{2}\right) = \mp sen (x)$$

$$sen (x \pm y) = \sin x \cos y \pm \cos x \sin y \qquad cos (x \pm y) = \cos x \cos y \mp sen x \sin y$$

$$sin x \cos y = \frac{1}{2} \left[sen (x + y) + sen (x - y) \right]$$

$$cos x \sin y = \frac{1}{2} \left[sen (x + y) - sen (x - y) \right]$$

$$sin x \sin y = \frac{1}{2} \left[cos (x - y) - cos (x + y) \right]$$

$$cos x \cos y = \frac{1}{2} \left[cos (x - y) + cos (x + y) \right]$$

$$sen^2 x = \frac{1}{2} - \frac{1}{2} \cos 2x \qquad cos^2 x = \frac{1}{2} + \frac{1}{2} \cos 2x$$

$$sen x \pm sen y = 2 \cos \left(\frac{x + y}{2}\right) sen \left(\frac{x \pm y}{2}\right)$$

$$cos x - cos y = 2 sen \left(\frac{x + y}{2}\right) sen \left(\frac{x - y}{2}\right)$$