

Sistemas Distribuídos

Concurrency 1

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Summary

- Program vs. Process
 - Characterization of a multiprogrammed environment
- Processes vs. Threads
 - Characterization of a multithreaded environment
- Execution environment
- Threads in Java
- Suggested readings

Program vs. Process

Generally speaking, a *program* can be defined as a sequence of instructions which describes the execution of a certain task in a computer. However, for this task to be *in fact* carried out, the corresponding program must be executed.

A program execution is called a process.

Representing an activity that is taking place, a process is characterized by

- the *addressing space* the code and the current value of all its associated variables
- the *processor context* the current value of all the processor internal registers
- the *I/O context* all the data that are being transferred to the input and from the output devices
- the *state* of the execution.

Modeling the processes - 1

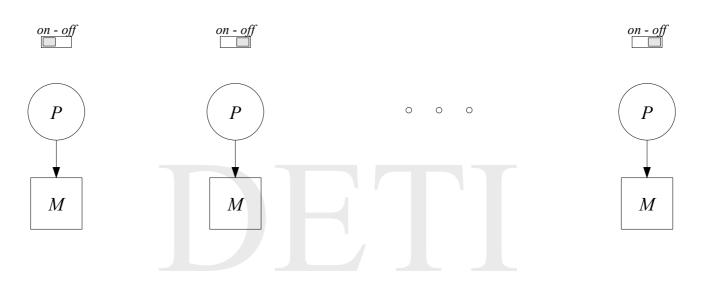
Multiprogramming, by creating an image of apparent simultaneity in the execution of different programs by the same processor, makes very difficult the perception of the activities that are taking place at the same time.

This image can be simplified if, instead of trying to follow the execution path undergone by the processor in its continuous meandering among processes, one supposes there are a set of virtual processors, one per process which concurrently coexists, and that the processes are run in parallel through the activation (*on*) and the deactivation (*off*) of the associated processors.

One further assumes in this model that

- process execution is not affected by the instant and the code location where the commutation takes place
- no restrictions are imposed to the total, or partial, execution time.

Modeling the processes - 2



- the *commutation* of the *process context* is simulated by the activation and the deactivation of the virtual processors and is controlled by its *state*
- in a *monoprocessor*, the number of active virtual processors at any given instant is one, at the maximum
- in a *multicore processor*, the number of active virtual processors at any given instant is equal to the number of processors in the core, at the maximum.

Process state diagram - 1

A process may be in different situations, called *states*, along its existence.

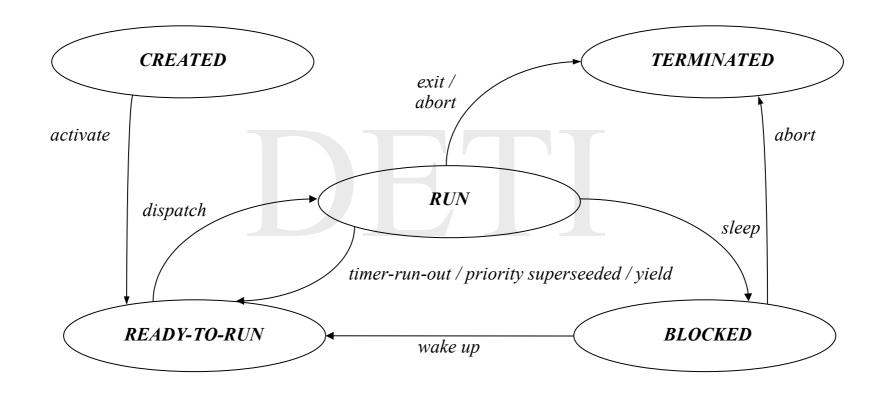
The most important states are the following

- run when it holds the processor and is, therefore, in execution
- ready-to-run when it waits for the assignment of the processor to start or resume execution
- *blocked* when it is prevented to proceed until an external event occurs (access to a resource, completion of an input/output operation, etc).

State transitions are usually triggered by an external source, the operating system, but may be triggered by the process itself in some instances.

The part of the operating system which deals with [process] state transitions is called the *scheduler* (*processor scheduler*, in this case), and forms an integral portion of its nucleus, the *kernel*, which is responsible for exception handling and for scheduling the assignment of the processor and all other system resources to the processes.

Process state diagram - 2



Process state diagram - 3

- activate a process is created and placed in the *ready-to-run queue* waiting to be scheduled for execution
- dispatch one of the processes of the ready-to-run queue is selected by the scheduler for execution
- timer-run-out the process in execution exhausted the slot of processor time which was assigned to it (preemptive scheduling)
- priority superseded the process in execution looses the processor because the ready-to-run queue now contains a process of higher priority that requires the processor (preemptive scheduling)
- *yield* the process releases voluntarily the processor to allow other processes to be executed (non-preemptive scheduling)
- sleep the process is prevented to proceed and must wait for an external event to occur
- wake up the external event the process was waiting for has occurred
- exit / abort the process has terminated / is forced to terminate its execution and waits for the resources that were assigned to it to be released

Processes vs. Threads - 1

The concept of *process* embodies the following properties

- resource ownership a private addressing space and a private set of communication channels with the input and output devices
- thread of execution a program counter which points to the instruction that must be executed next, a set of internal registers which contain the current values of the variables being processed and a stack which keeps the history of execution (a frame for each routine that was called and has not yet returned).

These properties, although taken together in a *process*, can be treated separately by the execution environment. When this happens, *processes* are envisaged as grouping a set of resources and *threads*, also known as *light weight processes*, represent runnable independent entities within the context of a single process.

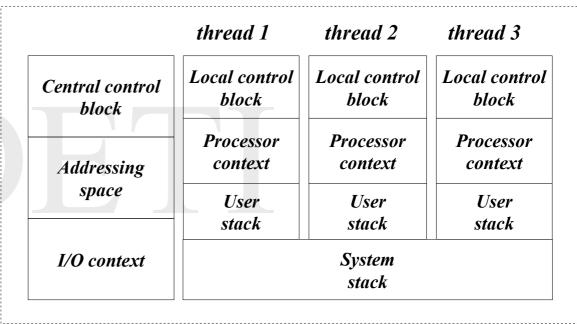
Multithreading, then, means an environment where it is possible to create multiple threads of execution within the same process.

Processes vs. Threads - 2

Control
block

Addressing
space
User
stack

I/O context
System
stack



Single threading

Multithreading

Advantages of a multithreaded environment

- greater simplicity in solution decomposition and greater modularity in its implementation – programs which involve multiple activities and service multiple requests are easier to design and implement in a concurrent perspective than in a pure sequential one
- better management of computer system resources sharing the addressing space and the I/O context among the *threads* of an application results in decreasing the complexity of managing main memory occupation and access to the input / output devices
- greater efficiency and speed of execution a solution decomposition based on threads, by opposition to one based on processes, requires less resources of the operating system, enabling that operations like process creation and termination and a context commutation to become less heavy and, thus, more efficient; furthermore, it becomes possible in symmetric multiprocessing to schedule for parallel execution multiple threads belonging to the same application, thus increasing the speed of execution

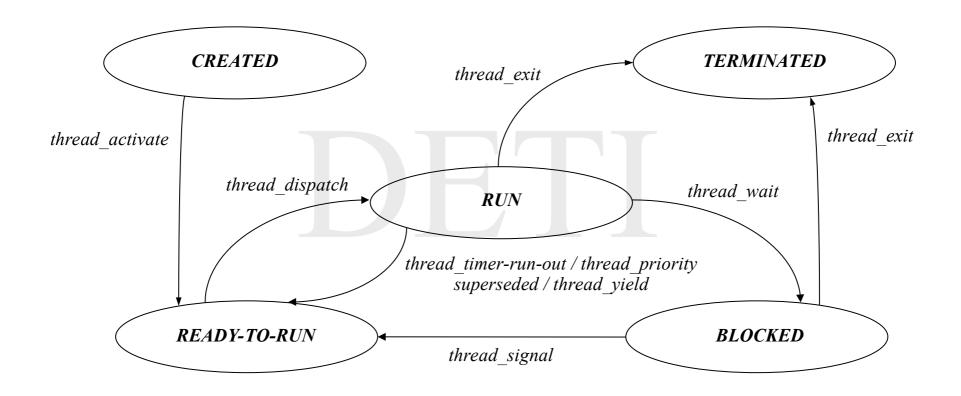
Organization of a multithreaded program - 1

Global data structure Function or procedure Common function implementing a specific activity or procedure Function or procedure Common function implementing a specific activity or procedure

Organization of a multithreaded program - 2

- each *thread* is typically associated with the execution of a *function or procedure implementing a specific activity*
- the *global data* structure forms an information sharing space, defined in terms of variables and communication channels with the input/output devices, to be accessed by the multiple *threads* that coexist at a given time for writing and for reading
- the *main program*, represented in the diagram by a *function or procedure imple-menting a specific activity*, constitutes the first *thread* to be created and, typically, the last *thread* to be concluded

Thread state diagram



Support to the implementation of a multithreaded environment

- *user level threads threads* are implemented by a specific library at user level which brings support to the creation, management and scheduling of *threads* without kernel interference; this generates a very versatile and portable, but inefficient, implementation since, as the kernel perceives only processes, when a particular *thread* invokes a blocking *system call*, all the process is blocked, even if there were *threads* ready to be run
- *kernel level threads threads* are implemented at kernel level by directly providing the operations for the creation, management and scheduling of *threads*; the implementation is operating system specific, but the blocking of a particular *thread* does not affect the dispatching of the remaining for execution and parallel execution in a multicore processor becomes possible

Execution environment - 1

Java virtual machine (JVM) constitutes the execution environment for a Java coded application. In principle, JVM runs on the top of the operating system of the hardware platform executing a Java program and establishes with it a very intimate connection. Access to information concerning the execution environment can be obtained through the invocation of methods on two reference data types of the Java base library, java.lang: Runtime and System.

Among the information that is provided, the following should be noticed

- number of processors and memory size available to run the code
- references to the streams associated with standard input, standard output and standard error devices
- access to a modifiable set of definitions, called *properties*, which characterize the execution environment
- read-only access to the definitions of the variables of the operating system user interface, the *shell*, where the java command was executed called in this context *environment*.

environment - 1

[ruib@ruib-laptop environment] \$ java CollectEnvironmentData

```
Characterization of Java Virtual Machine (JVM)
```

```
N. of available processors = 8
Size of dynamic memory presently free (in bytes) = 248250352
Size of total dynamic memory (in bytes) = 249561088
Maximum size of available main memory of the hardware platform where Java virtual machine is installed (in bytes) = 367840460
```

Properties of the execution environment

. . .

environment - 2

Variables of the execution environment

```
/opt/jdk1.8.0 241/bin:/opt/jdk1.8.0 241/jre/bin:/opt/mpich/bin:/home/
ruib/.local/bin:/home/ruib/bin:/usr/lib64/ccache:/usr/local/bin:/usr/bin:/
bin:/usr/local/sbin:/usr/sbin
LC MEASUREMENT = pt PT.UTF-8
LC COLLATE = pt PT.UTF-8
LOGNAME = ruih
                  /home/ruib/Teaching/SD/2020 2021/aulas
PWD
                                                                teóricas/exemplos
demonstrativos/threadBasics/environment
c=00;36:*.ogg=00;36:*.ra=00;36:*.wav=00;36:*.oga=00;36:*.opus=00;36:*.spx=00;36
:*.xspf=00;36:
XDG SESSION DESKTOP = KDE
SHI_{1}VI_{1} = 1
LC MONETARY = pt PT.UTF-8
DISPLAY = :0
LC NUMERIC = pt PT.UTF-8
HOME = /home/ruib
```

• • •

Execution environment - 2

The execution environment also allows running commands directly on the underlying operating system user interface. Two reference data types of the Java base library, java.lang, are instrumental to fulfill this purpose: ProcessBuilder and Process.

Each ProcessBuilder object manages process attributes such as the *shell* command to be executed and the setting of the working directory and of the streams associated with standard input, standard output and standard error devices. Multiple processes can be created in succession from the same object, thus sharing the same attribute configuration.

Each process that is created is an instance of the Process data type. Means are provided here to check if it is still running, wait for its termination, get its termination status, kill it and obtain references to the streams associated with its standard input, standard output and standard error devices.

runCommand

[ruib@ruib-laptop runCommand]\$ java ListWorkDir Listing current working directory

Being Java a concurrent programming language, *threads* are supported by the language itself. Conceptually, the creation of a *thread* presupposes two entities to exist in the Java virtual machine: an object representing an autonomous thread of execution, the *thread* itself, and a non-instantiated reference data type, or an object instantiated from it, which defines the method executed by the *thread*, its life cycle.

Java virtual machine manages the multithreaded environment according to the following rules

- every running program consists of at least one *thread* which is implicitly created when the virtual machine, after initializing the execution environment, calls the method main on the initial data type
- the remaining *threads* are explicitly created by the *thread* main, or by any *thread* created in succession from the *thread* main
- the program terminates when all the created *threads* have finished executing their associated method.

Java base library, java.lang, provides two reference data types, one using the constructor *interface* and the other using the constructor *class*, which are instrumental in building a *multithreaded* environment.

```
public interface Runnable
{
   public void run ();
}

public class Thread
{
      . . .
   public void run ()
   public void start ()
      . . .
}
```

Each autonomous thread of execution is an instantiation of the reference data type Thread. It defines two methods which are operationally relevant in this context

- run which is called when the *thread* is put into execution (started) and which represents its life cycle
- start which is called to *start* the *thread*.

It is not, however, strictly necessary to create new reference data types, derived from Thread and which override the method run, to ensure the execution of specific tasks. The same goal may alternatively be achieved by creating an independent reference data type which implements the interface Runnable and which, as a consequence, defines run.

The latter is usually reported as the preferred approach in Java related literature, but the former enables a Java solution to multiple inheritance which is quite useful in building servers that have a client service differentiation.

Thread creation (approach 1)

reference data type which defines the thread functionality

Thread creation (approach 2)

reference data type which defines the thread functionality

A *thread* has the following attributes

- name assigned name (by default, the execution environment generates a *string* of format Thread-#, where # is the creation number successively incremented from zero)
- internal identifier number of type long which unique and is kept unchanged during the thread lifetime
- *group* group the *thread* belongs to (all the *threads* of the same application belong by default to the same group, the group main)
- priority it may vary from 1 (MIN_PRIORITY) to 10 (MAX_PRIORITY), by default, the execution environment assigns the value of 5 (NORM_PRIORITY)
- state thread current state
 - -NEW (*CREATED*), after instantiation of a reference variable of data type Thread, or of a derived data type
 - -RUNNABLE (*READY-TO-RUN* or *RUN*), when waits for execution or is in execution
 - -BLOCKED, WAITING or TIME_WAITING (BLOCKED), when is blocked
 - -TERMINATED (*TERMINATED*), after termination.

threadInfo

[ruib@ruib-laptop threadInfo]\$ java CollectThreadData

Thread characterization

```
Name = main
Internal identifier = 1
Group = main
Priority = 5
Current state = RUNNABLE
```

Possible states:

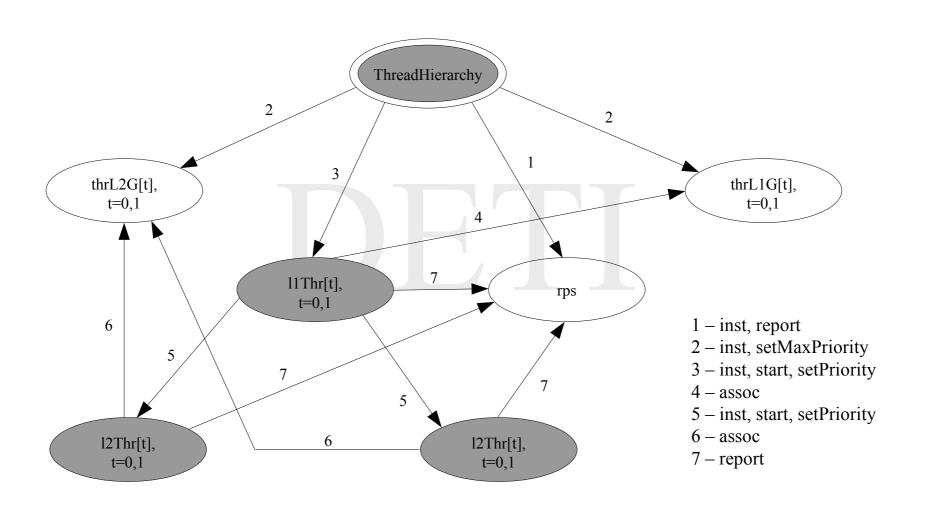
NEW
RUNNABLE
BLOCKED
WAITING
TIMED_WAITING
TERMINATED

The partition in different groups of the *threads* which are instantiated in succession, makes possible to organize in a hierarchical and functional fashion an application, as well as taking advantage of the Java specificities in the definition of common properties and in the interaction with them. Java base library, <code>java.lang</code>, provides the reference data type <code>ThreadGroup</code> to fulfill this purpose.

Thus, it turns out that it is possible

- to define at the very beginning the maximum priority and the property of being a *daemon* associated with a given group all the *threads* later instantiated, and belonging to this group, will keep these properties
- to send an interrupt to *all* the *threads* belonging to the same group in an unique operation, instead of doing it separately to each member of the group.

hierarchy - 1



hierarchy - 2

level 0

threadName: main

threadId: 1

threadPriority: 5

threadGroupName: main

threadParentGourpName: system

threadName: Thread_L1.1

threadId: 8 threadPriority: 9

threadGroupName: Thread_G1.1 threadParentGroupName: main

level 1

threadName: Thread_L1.2

threadId: 9

threadPriority: 8

threadGroupName: Thread_G1.2
threadParentGroupName: main

threadName: Thread_L1.1_L2.1

threadId: 11 threadPriority: 8

threadGrpName: Thread_G1.1_G2

threadPrtGrpName: Thread_G1.1

threadName: Thread_L1.1_L2.2

threadId: 12 threadPriority: 8

threadGrpName: Thread_G1.1_G2

 $thread Prt Grp Name: Thread_G1.1$

threadName: Thread_L1.2_L2.1

threadId: 13 threadPriority: 7

 $\it thread GrpName: Thread_G1.2_G2$

threadPGroupName: Thread G1.2

threadName: Thread L1.2 L2.2

threadId: 14 threadPriority: 7

threadGrpName: Thread_G1.2_G2
threadPGroupName: Thread G1.2

level 2

hierarchy - 3

Printed values

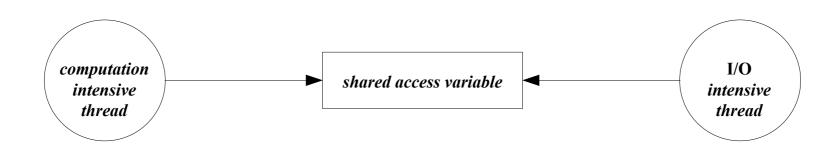
```
[ruib@ruib-laptop hierarchy 1]$ java ThreadHierarchy1
Number of level 1 threads? 2
Number of level 2 threads per level 1 threads? 2
Thread name: main
Thread id: 1
Thread priority: 5
Name of the thread group: main
Name of the parent group of the thread group: system
N. of active threads in the thread group: 1
Name of active threads in the thread group: main
N. of active subgroups in the thread group: 0
Thread name: Thread L1.1 L2.1
Thread id: 11
Thread priority: 8
Name of the thread group: Thread G1.1 G2
Name of the parent group of the thread group: Thread G1.1
N. of active threads in the thread group: 2
Name of active threads in the thread group: Thread L1.1 L2.1 -
N. of active subgroups in the thread group: 0
```

Java virtual machine supposes a policy of *non-preemptive scheduling* based on a system of static priorities with 10 levels

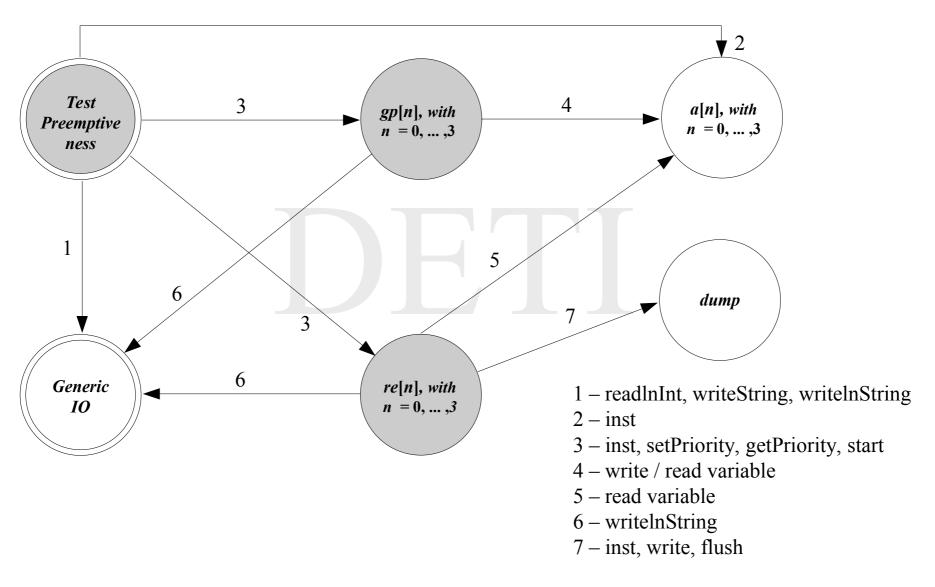
- the transitions between the state *RUN* and the state *READY-TO-RUN* are of type *thread_priority_superseded* and *thread_yield*
- the priority assigned to a *thread*, defined upon instantiation or modified before its creation, remains unaltered during its active life time.

Java virtual machine, however, does not enforce strictly the *scheduling* policy. The implementation has a lot of freedom on how it puts it to work. This is particularly true when Java virtual machine is run on the top of a general purpose multitasking operating system!

In Linux, for instance, Java threads are *kernel* level threads, taking advantage of *multicore* processors to enhance parallel execution, and the prevailing *scheduling* policy is the local one.



- there are four sets, consisting each of a computation intensive thread, an I/O intensive thread and a shared access variable
- the computation intensive thread successively increments by one the shared access variable 10 million times
- the I/O intensive thread successively reads and prints the shared access variable until its value reaches 10 million
- thread priorities can be changed and *yield* may be introduced after each increment operation of the computation intensive thread is performed
- the number of reads and prints carried out by the I/O intensive thread is used as a figure of merit to estimate the relative execution speed of both threads



Without thread yield

```
Priority level of computation intensive threads? 1
Priority level of I/O intensive threads? 10
Priority of computation intensive threads = 1
Priority of I/O intensive threads = 10
I have already started the I/O intensive threads!
I have already started the computation intensive threads!
I have finished my job!
N. of iterations in printing values of A = 59702
A = 10000000
N. of iterations in printing values of D = 123791
D = 10000000
N. of iterations in printing values of C = 111804
C = 10000000
N. of iterations in printing values of B = 102411
B = 10000000
```

Without thread yield

```
Priority level of computation intensive threads? 10

Priority level of I/O intensive threads? 1

Priority of computation intensive threads = 10

Priority of I/O intensive threads = 1

I have already started the I/O intensive threads!

I have already started the computation intensive threads!

I have finished my job!

N. of iterations in printing values of C = 62180

C = 10000000

B = 10000000

N. of iterations in printing values of B = 103934

N. of iterations in printing values of D = 91698

D = 10000000

A = 10000000

N. of iterations in printing values of A = 119485
```

With thread yield

```
Priority level of computation intensive threads? 1
Priority level of I/O intensive threads? 10
Priority of computation intensive threads = 1
Priority of I/O intensive threads = 10
I have already started the I/O intensive threads!
I have already started the computation intensive threads!
I have finished my job!
N. of iterations in printing values of C = 4834998
C = 10000000
N. of iterations in printing values of D = 5085208
D = 10000000
N. of iterations in printing values of A = 4931095
A = 10000000
N. of iterations in printing values of B = 5193997
B = 10000000
```

With thread yield

```
Priority level of computation intensive threads? 10

Priority level of I/O intensive threads? 1

Priority of computation intensive threads = 10

Priority of I/O intensive threads = 1

I have already started the I/O intensive threads!

I have already started the computation intensive threads!

I have finished my job!

N. of iterations in printing values of D = 5053297

D = 10000000

A = 10000000

N. of iterations in printing values of A = 5151587

N. of iterations in printing values of B = 5461388

B = 10000000

N. of iterations in printing values of C = 5392911

C = 10000000
```

One should notice that the field a of the reference data type Variable includes the modifier volatile. Its precise meaning is to inform the Java compiler that the *threads*, during their execution, must permanently observe a *consistent* value in the variable a.

Consistency means in this sense that access to the variable a should always take place in the exact manner prescribed by the code of each *thread*.

This information is crucial here because Java memory model allows the compiler, when generating the *bytecode* of a given reference data type, as well as Java virtual machine, when interpreting this *bytecode*, to perform code optimization which, being totally consistent in a *singlethreaded* environment, may produce a paradoxical execution in a *multithreaded* environment.

A Java *multithreaded* application ends in principle when all its constituent *threads* terminate. In complex applications, where the number of support *threads* is very large, dealing with exceptional situations that may require aborting the operations, can become rather strenuous and demand the introduction of specific code whose practical utility is questionable.

To simplify the problem, Java presents two alternatives

- calling the method void System.exit (int status) which forcibly terminates the Java virtual machine, returning the communicated status of operation
- turning the instantiated *threads*, directly or indirectly, created from the *thread* main into *daemons* the Java virtual machine terminates as soon as all the remaining *threads* have this property.

Nevertheless, the usual termination of a *multithreaded* application is done by making the first or principal *thread* waiting for the termination of all the *threads* that may have been created from it.

In Java, one has a similar situation. The reference data type Thread has a method called join which, as it is tradititional in concurrent programming, and in a object oriented perspective, blocks the calling *thread* until the referenced *thread* ends.

Suggested reading

- *Distributed Systems: Concepts and Design, 4th Edition, Coulouris*, Dollimore, Kindberg, Addison-Wesley
 - Chapter 6: Operating systems support
- Distributed Systems: Principles and Paradigms, 2nd Edition, Tanenbaum, van Steen, Pearson Education Inc.
 - Chapter 3: *Processes*
- *On-line* support documentation for Java program developing environment by Oracle (Java Platform Standard Edition 8)