Resumo ASE

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Type of Data Transfer

- Data Transfer is where you move data from internal components of the microcontroller itself, such as, moving data from registers of the CPU into or from the memory or peripherals.
- Besides you can transfer data between components without CPU interaction as long as the data bus is free.
- There are 3 type of data transfer essentially:
    1. Polling
    2. Interruptions
    3. DMA (Direct Access Memory)

Polling

- The CPU takes initiative, where it starts and controls the data transfer.
- In polling, the CPU actively check the status of a task or peripheral to see if the expecting data is ready to be transferred. However while it's waiting for the peripheral to be ready, it will steal clock cycles where it could be used for execution of instructions.
- **Advantages**:
    - Simple, to implement it, we use continuously loops, checking a flag or register in the peripheral to see if it has data available.
- **Disadvantages**:
    - Can be inefficient for slow peripherals or frequent data transfers

- The processor wastes time constantly checking the peripheral, even if no data is ready. -> High Overhead

Interruptions

- In interruptions when the peripheral is ready to transfer data it will signal the CPU with a flag informing that the data in the peripheral is available.
- When the flag for interruptions in the CPU is signaled, it will abandon temporarily the execution of the program and execute the code that the interrupt handler is pointing to.
- The data transfer is made by the CPU but the busy waiting disappears, once it only occurs when the peripheral is ready.
- **Advantages:**
  - The CPU only spends time handling data transfer when necessary, improving overall performance.
- **Disadvantages**
  - Might introduce slight delays in handling the interrupt compared to polling continuously.

DMA (Direct Memory Access)

References

1. https://docs.espressif.com/projects/esp-idf/en/stable/esp32c3/get-started/index.html

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- **Hardware timers** are the physical timer circuits on the ESP32C3 chip.
- **Software (ESP-IDF libraries)** allows you to interact with these hardware timers and define their behavior.
- **Counter:** This is indeed a core component. Both GPTs and the ESP Timer have a counter register. This register is what actually increments or decrements based on the timer configuration.

    - In the ESP32C3, GPTs are 54-bit counters, while the ESP Timer is a 64-bit counter.
- **Pre-scaler (GPTs only):** GPTs have an additional register called the pre-scaler. This allows you to divide the clock signal feeding the timer, effectively slowing down the counter's increment/decrement rate. The ESP Timer doesn't have a pre-scaler.
- **Compare Register:** This register is present in both GPTs and the ESP Timer. You can set a value in this register. When the counter reaches the value in the compare register, an event occurs (like an interrupt). This allows you to generate periodic events based on the timer.
- **Auto-reload:** Both GPTs and the ESP Timer offer auto-reload functionality. When enabled, upon reaching the compare register value, the counter automatically resets to zero and starts counting again. This is essential for creating periodic signals or tasks.