

Q1: We have 8 red balls and 8 blue balls. We store them in two urns. In urn1, we have 2 red balls and 6 blue balls. In urn2, we have 2 blue balls and 6 red balls. We pick urn1 with probability 0.75. We pick a ball from one of the two urns, and it's red. Determine the probabilities:

a) $P(R|Urn1), P(R|Urn2)$.

b) $P(Urn1|R), P(Urn2|R)$.

c) $P(R)$: Total probability of picking a red ball.

(25) Marks

$$a) P(R|Urn1) = \frac{2}{2+6} = \boxed{\frac{1}{4}}$$

$$P(R|Urn2) = \frac{6}{2+6} = \boxed{\frac{3}{4}}$$



$$P[Urn1] = 0.75 = \frac{3}{4}$$

$$P[Urn2] = 0.25 = \frac{1}{4}$$

b) $P(Urn1|R)$: using bayes' rule

$$P(Urn1|R) = \frac{P(R|Urn1) \cdot P(Urn1)}{P(R)} = \frac{\frac{1}{4} \cdot \frac{3}{4}}{\frac{3}{8}} = \frac{\frac{3}{16}}{\frac{3}{8}} = \boxed{\frac{1}{2}}$$

$P(R) \leftarrow \text{found in c}$

again using bayes' rule:

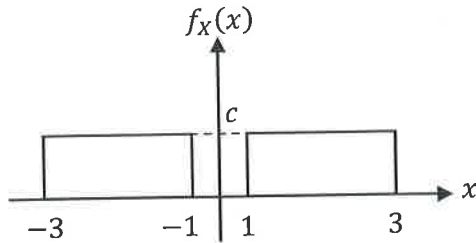
$$P(Urn2|R) = \frac{P(R|Urn2) \cdot P(Urn2)}{P(R)} = \frac{\frac{3}{4} \cdot \frac{1}{4}}{\frac{3}{8}} = \frac{\frac{3}{16}}{\frac{3}{8}} = \boxed{\frac{1}{2}}$$

$P(R) \leftarrow \text{found in c}$

c) $P(R) = P(R|Urn1) + P(R|Urn2) = P(R|Urn1)P(Urn1) + P(R|Urn2)P(Urn2)$

$$= \frac{1}{4} \cdot \frac{3}{4} + \frac{3}{4} \cdot \frac{1}{4} = \frac{6}{16} = \frac{3}{8}$$

Q2: Given the pdf



- a) Determine c .
b) Calculate $E[x]$

(25) Marks

a) In order to find c , we need the CDF $= F_X$ to be 1

$$P(X < \infty) = \int_{-\infty}^{\infty} f_X(x) dx = \int_{-3}^{-1} c dx + \int_{1}^3 c dx = c x \Big|_{-3}^{-1} + c x \Big|_1^3 \quad \text{as } x \rightarrow \infty$$

$$= c \cdot 2 + c \cdot 2 = c \cdot 4$$

$$\int_{-\infty}^{\infty} f_X(x) dx = 4c = 1 \Rightarrow \boxed{c = \frac{1}{4}}$$

$$b) E[x] = \int_{-\infty}^{\infty} x f_X(x) dx = \int_{-3}^{-1} c x dx + \int_{1}^3 c x dx$$

$$= c \frac{x^2}{2} \Big|_{-3}^{-1} + c \frac{x^2}{2} \Big|_1^3 = \frac{c}{2} (1 - 9) + \frac{c}{2} (9 - 1)$$

$$= 0$$

$$E[X] = 0$$

Q3: We observe the following data corresponding to different classes:

Class 1:	10	11	12
Class 2:	5	7	6

Prior probabilities of the above two classes are equal.

- Construct a Gaussian based generative method for the above two classes.
- Given the observation $x=9$. Estimate its class.

(25) Marks

$P_1(x) \equiv P(X|Y=1) \Leftarrow$ for class 1 let Y be a r.v. s.t. $Y=1 \Rightarrow$ class 1
 $P_2(x) \equiv P(X|Y=2) \Leftarrow$ for class 2 $Y=2 \Rightarrow$ class 2

for class 1

$$\hat{\mu}_1 = \frac{10+11+12}{3} = 11, \quad \hat{\sigma}_1^2 = \frac{1}{3-1} \left[(10-11)^2 + (11-11)^2 + (12-11)^2 \right]$$

$$= \frac{1}{2} [1 + 0 + 1] = 1$$

for class 2

$$\hat{\mu}_2 = \frac{5+7+6}{3} = 6, \quad \hat{\sigma}_2^2 = \frac{1}{3-1} \left[(5-6)^2 + (7-6)^2 + (6-6)^2 \right] = 1$$

$$P_1(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(x-11)^2\right), \quad P_2(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(x-6)^2\right)$$

$$P(Y=1|X) = \pi_1 \cdot P_1(x) \quad \text{not important} \rightarrow P(x) \quad \text{or } 0.5 P_1(x), \quad P(Y=2|X) = \pi_2 P_2(x) \quad \text{or } 0.5 P_2(x)$$

$$y_{\text{est}} = \arg \max_i (\pi_i P_i(x)) = 0.5 P_2(x) = 0.072$$

$$b) \quad x=9, \quad P(Y=1|X=9) = 0.5 P_1(X=9) = 0.5 \cdot \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(9-11)^2\right)$$

$$P(Y=2|X=9) = 0.5 P_2(X=9) = 0.5 \cdot \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(9-6)^2\right)$$

$P(Y=1|X=9) > P(Y=2|X=9) \Rightarrow$ class estimate is Class 1

Q4: Consider a classification problem with two variables. In Figure 1 we show two positive “+” and two negative “-” examples.

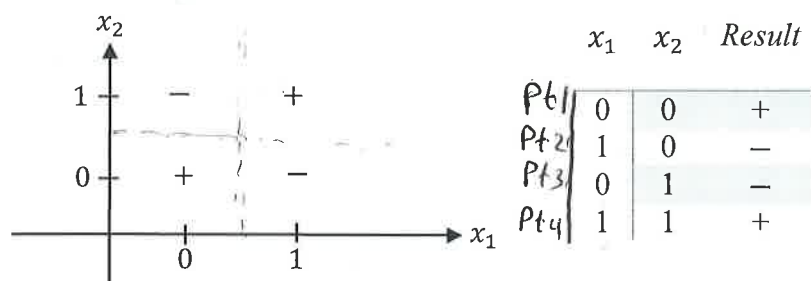
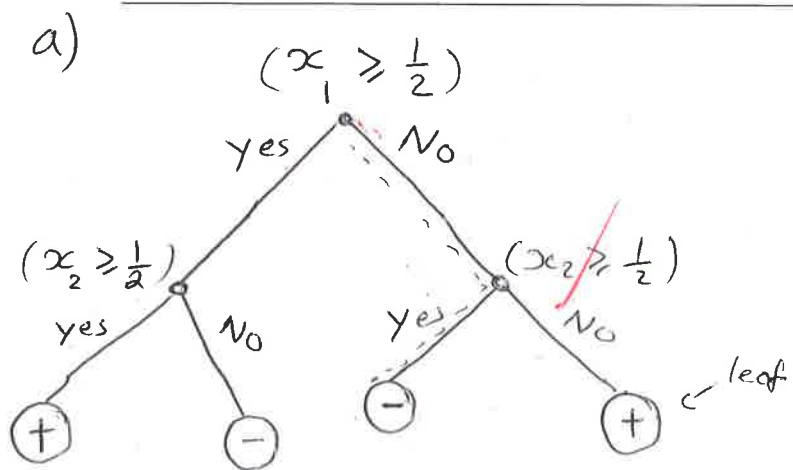


Figure 1. Two positive and two negative examples.

- Draw a decision tree that can perfectly classify the four examples in Figure 1.
- We observe the vector $[0,2]^T$. What is the decision using the decision tree?
- We observe the vector $[0,2]^T$. What is the decision according to the nearest-neighbor classifier?

(25) Marks



b) $v = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$, $x_1 = 0$, $x_2 = 2$

following the tree:

if $x_1 \geq \frac{1}{2}$: false $\Rightarrow x_2 \geq \frac{1}{2}$: True
 \Rightarrow branch (3) \Rightarrow class Negative

c) we need to find the distances between $v = [0,2]^T$ and each point (points are denoted above)

$$d_{v, Pt_1}^2 = \|[0,2]^T - [0,0]^T\|_2^2 = \|[0,2]\|_2^2 = \boxed{4}$$

$$d_{v, Pt_2}^2 = \|[0,2]^T - [1,0]^T\|_2^2 = \|[-1, 2]\|_2^2 = \boxed{5}$$

$$d_{v, Pt_3}^2 = \|[0,2]^T - [0,1]^T\|_2^2 = \|[0,1]\|_2^2 = \boxed{1}$$

$$d_{v, Pt_4}^2 = \|[0,2]^T - [1,1]^T\|_2^2 = \|[-1, 1]\|_2^2 = \boxed{2}$$

The nearest neighbor to v is point $(0,1)$ whose class is class Negative

\Rightarrow class of $[0,2]^T$ is class Negative (-)