

- A cluster is a collection of data objects
 - Similar to one another in the same cluster
 - · Disimilar to the objects in other cluster
- Cluster analysis (or clustering) is finding similarities between data objects according to the characteristics in the data and grouping similar data objects into clusters
- Cluster analysis is unsupervised, descriptive data mining
 - No predefined classes
- Typical applications
 - As a stand-alone tool to get insight into data distribution
 - As a pre-processing step (data cleaning and data reduction) for other data mining algorithms



Lecture outline

- What is cluster analysis?
- Applications and examples
- What is good clustering?
- Clustering requirements in data mining
- · Measurements of cluster quality
- Similarities between data objects
- Main clustering approaches
- · Partitioning algorithms
- K-means clustering approach



Applications of cluster analysis

- Pattern recognition
 - Image processing
- Spatial data analysis
 - Create thematic maps in geographical information systems (GIS) by clustering feature spaces
 - Detect spatial clusters for use in other spatial data mining tasks
- Economic science (especially market research)
 - · Groupings of similar customers
- Internet / WWW
 - Document / Web page categorisation
 - Cluster Web log data to discover groups of similar access patterns



Examples of cluster analysis

- Marketing: Help marketers to discover distinct groups in their customer bases, and then use this knowledge to develop targeted marketing programs
- Land use: Identification of areas of similar land use in an earth observation database (satellite images, etc.)
- *Insurance:* Identify groups of (for example, motor insurance) policy holders with a high average claim cost
- City planning: Identifying groups of houses according to their house type, value, and geographical location



Clustering requirements in data mining

- Scalability to very large databases
- Ability to deal with different attribute types
- · Ability to handle dynamic data
- Discovery of clusters of arbitrary shapes
- Minimal domain knowledge required to determine input parameters
- Able to deal with noise and outliers
- Insensitive to order of input records
- Handle high dimensionality
- Incorporation of user-specified constraints
- Interpretability and usability



What is good clustering?

- A good clustering will produce clusters with
- · High intra-class similarity
- · Low inter-class similarity
- The quality of a clustering result depends upon both the similarity measure and the algorithm used for searching
 - · Different algorithms deliver different clusterings
- The quality of a clustering is also measured by its ability to discover some or all of the hidden patterns in the data
- Clustering may not be the best way to discover interesting groups in data sets
 - · Visualisation often works well, allowing human experts to identify useful groups
 - This becomes problematic with very large data sets



Measurements of cluster quality

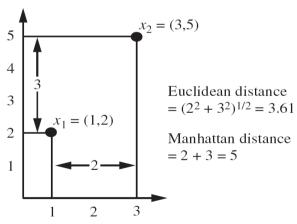
- Dissimilarity/similarity metric: Similarity is expressed in terms of a distance function, typically a metric: d(a, b), with s(a, b) = 1 d(a, b) (if dist normalised), or s(a, b) = 1/d(a, b)
- There is a separate "quality" function that measures the "goodness" of a cluster
- The definitions of distance functions are usually different for interval-scaled, boolean, categorical, ordinal, ratio-scaled, and vector variables
- Weights can be associated with different variables (attributes) based on applications and data semantics
- It is hard to define "similar enough" or "good enough"
 - The answer is typically highly subjective

Similarity and dissimilarity between objects

- Distances are normally used to measure similarity and dissimilarity between two data objects
 - Two objects: $a = (a_1, a_2, \dots a_n)$ and $b = (b_1, b_2, \dots b_n)$
- Properties of a distance measure d(i, j):
 - d(a, a) = 0
 - d(a, b) >= 0
 - d(a, b) = d(b, a)
 - d(a, c) <= d(a, b) + d(b, c) Triangular inequality
- The larger the distance, the smaller the similarity



Euclidean and Manhattan distance example



Source: Han and Kamber, DM Book, 2nd Ed. (Copyright © 2006 Elsevier Inc.)



Minkowski distance

• Popular distance measure includes *Minkowski* distance:

$$d(a,b) = \sqrt{(|a_1-b_1|^q + |a_2-b_2|^q + \dots + |a_n-b_n|^q)}$$

where $a = (a_1, a_2, ..., a_n)$ and $b = (b_1, b_2, ..., b_n)$ are two n-dimensional data objects, and q is a positive integer

• If q = 1, d is the *Manhattan* distance:

$$d(a,b)=|a_1-b_1|+|a_2-b_2|+...+|a_n-b_n|$$

• If q = 2, d is the Euclidean distance:

$$d(a,b) = \sqrt{(|a-b|^2 + |a-b|^2 + \dots + |a-b|^2)}$$



Similarities for other data types

- Many different ways to measure similarities between objects
 - Binary data: contingency tables
 - Nominal variables (e.g. colors): Count number of matches (of values in different attributes) divided by total number of possible matches (i.e. attributes considered)
 - Strings: Exact or approximate string similarities (edit-distance, q-gram based, longest common sub-string, etc.)
 - Vector objects (document words, micro array gene features): cosine measure based on term-frequency/inverse document frequency (TF-IDF) (more in the lecture on text mining later in the course)
- A database might contain different types of attributes
- One might use a weighted sum to calculate final similarity between objects
 - For example, $d(a, b) = 0.3 d_{name}(name_a, name_b) + 0.7 d_{salary}(salary_a, salary_b)$

Calculate the distance between clusters

- Single link: Smallest distance between a data object in one cluster and a data object in the other: $d(K_i, K_i) = min(t_i, t_i)$
- Complete link: Largest distance between a data object in one cluster and a data object in the other: $d(K_i, K_i) = max(t_{in}, t_{in})$
- Average: Average distance between a data object in one cluster and a data object in the other: $d(K_i, K_i) = avg(t_{in}, t_{in})$ (same as Centroid - Distance between the centroids of two clusters)
- Medoid: Distance between the medoids of two clusters: $d(K_{i}, K_{i}) = d(M_{i}, M_{i})$
 - A medoid is a data object centrally located in the cluster



Major clustering approaches (1)

Partitioning approaches

- · Construct various partitions and then evaluate them by some criterion, for example, minimising cluster radius or diameter, or the sum of square errors
- A fixed number, k, of clusters is generated
- Typical methods: k-means, k-medoids, CLARANS

Hierarchical approaches

- Create a hierarchical decomposition of the data objects using some criterion
- Typical methods: Diana, Agnes, BIRCH, ROCK, CAMELEON

Density based approaches

- · Based on connectivity and density functions
- Typical methods: DBSCAN, OPTICS, DenClue

Centroid, radius, and diameter of a cluster

• For numerical data objects $\mathbf{t}_{_{\mathbf{i}p}}$ in cluster i $C_{i} = \sum_{p=1}^{N} \left(t_{_{ip}}\right)$

$$C_{i} = \sum_{p=1}^{N} (t_{ip})$$

- · Centroid C: the "middle" of a cluster
- Radius: square root of average distance from any data object of the cluster to its centroid

 $R_i = \sqrt{\frac{\sum_{p=1}^{N} (t_{ip} - c_i)^2}{\sum_{p=1}^{N} (t_{ip} - c_i)^2}}$

• Diameter: square root of average mean squared distance between all pairs of data objects in the cluster



Major clustering approaches (2)

- Grid-based approaches
 - · Based on a multi-level granularity structure
 - Typical methods: STING, WaveCluster, CLIQUE

Model-based approaches

- A model is hypothesised for each of the clusters and the idea is to find the best fit of that model
- Typical methods: EM (Expectation-Maximisation), SOM (Self-organising maps), COBWEB
- Frequent-pattern based approaches
 - · Based on analysis of frequent patterns
 - · Typical method: pCluster
- User-guided or constrain-based approaches
 - Clustering by considering user- or application-specific constraints
 - · Typical method: COD (obstacles), constrained clustering



Partitioning algorithms: Basic concept

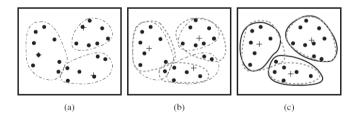
 Construct a partition of a database D of n objects into a set of k clusters, such that minimum sum of squared distance

$$\sum_{i=1}^k \sum_{t_{ip} \in Ki} (C_i - t_{ip})^2$$

- Given a *k*, find a partition of *k clusters* that optimises the chosen partitioning criterion
 - · Global optimal: exhaustively enumerate all partitions
 - Heuristic methods: *k-means* and *k-medoids* algorithms
 - k-means (MacQueen'67): Each cluster is represented by the center of the cluster
 - k-medoids or PAM (Partition Around Medoids) (Kaufman & Rousseeuw'87):
 Each cluster is represented by one of the objects in the cluster



The k-means clustering algorithm



+ = centroids

Source: Han and Kamber, DM Book, 2nd Ed. (Copyright © 2006 Elsevier Inc.)



The k-means clustering algorithm

Algorithm: k-means. The k-means algorithm for partitioning, where each cluster's center is represented by the mean value of the objects in the cluster.

Input:

- k: the number of clusters.
- D: a data set containing n objects.

Output: A set of k clusters.

Method:

- (1) arbitrarily choose k objects from D as the initial cluster centers;
- (2) repeat
- (3) (re)assign each object to the cluster to which the object is the most similar based on the mean value of the objects in the cluster;
- (4) update the cluster means, i.e., calculate the mean value of the objects for each cluster:
- (5) until no change;

Source: Han and Kamber, DM Book, 2nd Ed. (Copyright @ 2006 Elsevier Inc.)



Comments on the *k-means* algorithm

- *Strength:* Relatively efficient: O(t * k * n), where n is the number of data objects, k is the number of clusters, and t is the number of iterations. Normally, k and t << n
 - In comparison: PAM: $O(k(n-k)^2)$, CLARA: $O(ks^2 + k(n-k))$ (s = sample size)
- Comment: Often terminates at a local optimum!
 - K-means will always generate k clusters!
- The global optimum may be found using techniques such as deterministic annealing and genetic algorithms
- Basic idea: running k-means many times with different starting configurations
- Weaknesses
 - Applicable only when mean is defined, then what about categorical data?
 - Need to specify k, the number of clusters, in advance
 - · Unable to handle noisy data and outliers
 - Not suitable to discover clusters with non-convex shapes