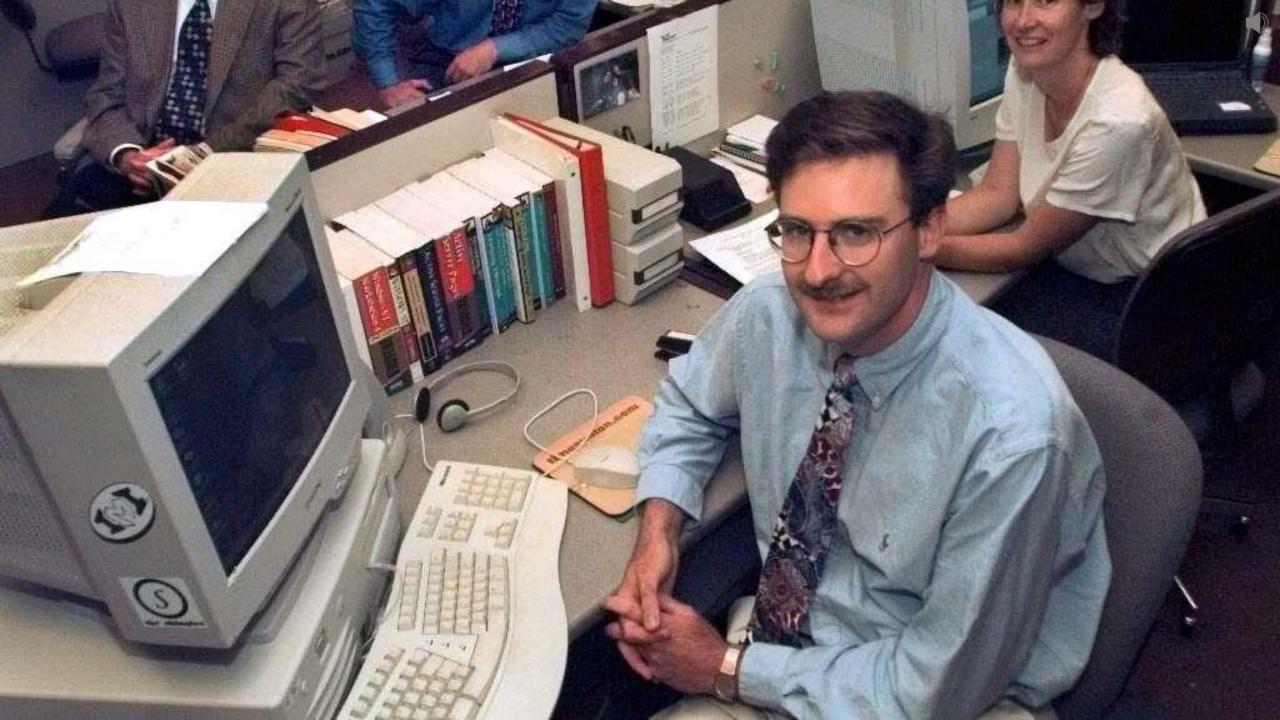
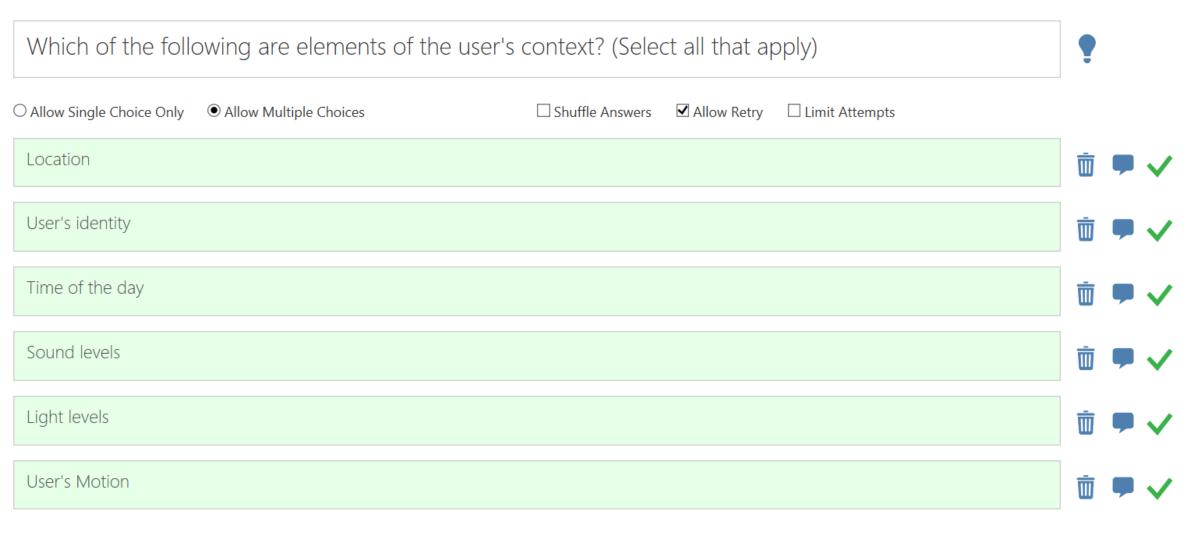
Context & Activity RECOGNITION







♣ Add another answer

What is GONEXTO Awareness





Contextual mediation

Context-triggered actions

Context Display

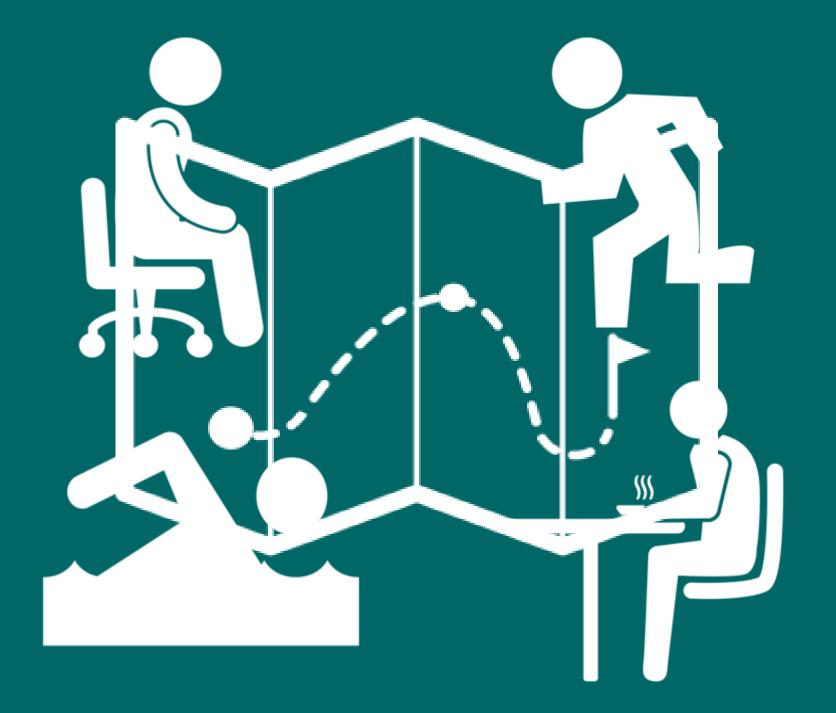
CONTEX

Contextual adaptation of the environment

Contextual Augmentation

Context-aware configuration





A TUTORIAL ON HUMAN ACTIVITY RECOGNITION USING BODY-WORN INERTIAL SENSORS



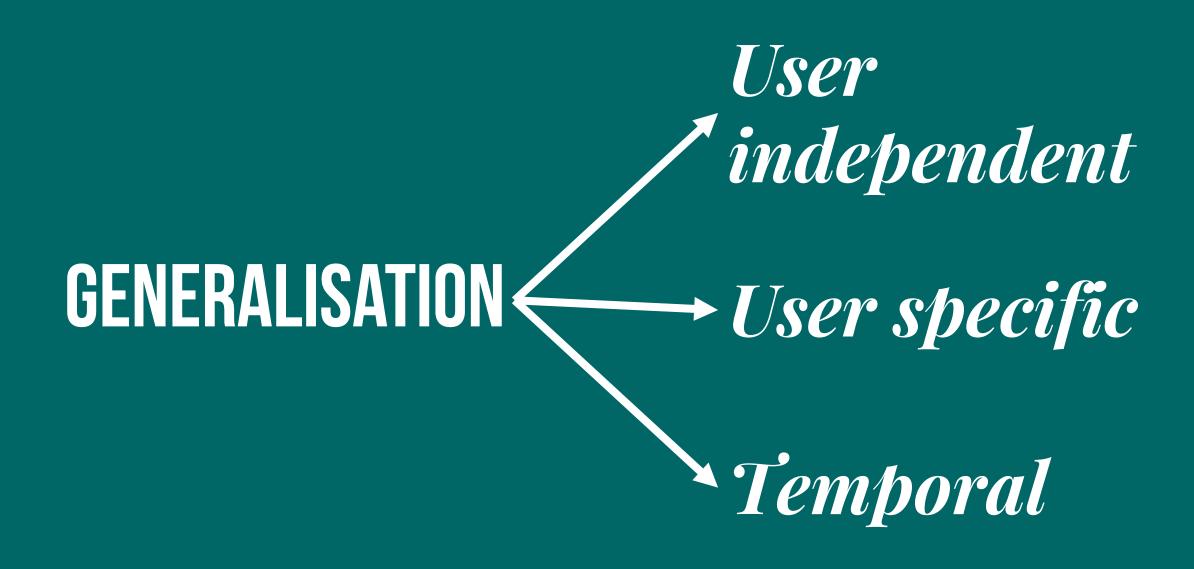




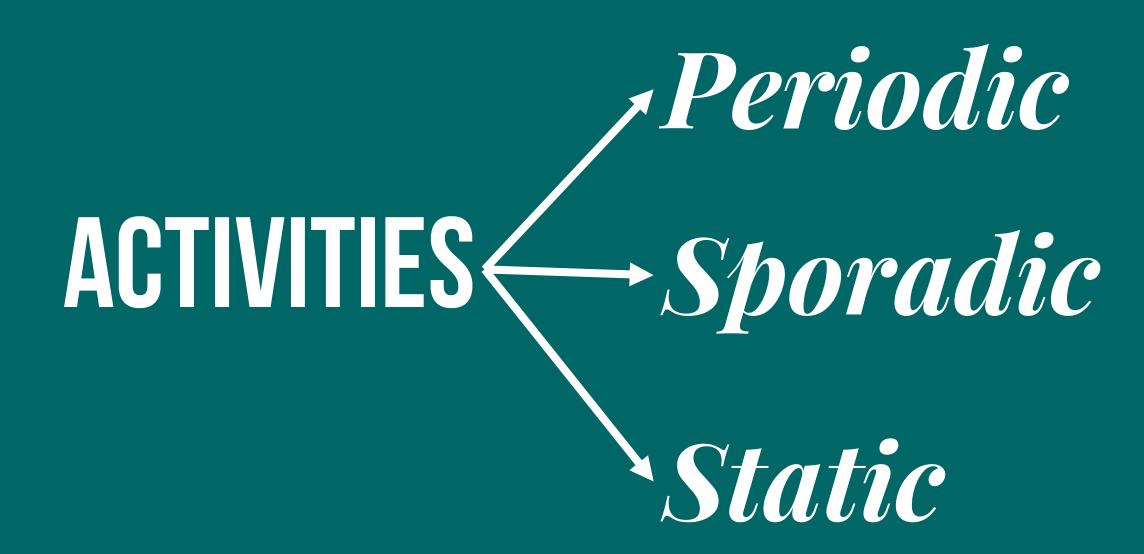
CHARACTERISTICS OF HAR SYSTEMS

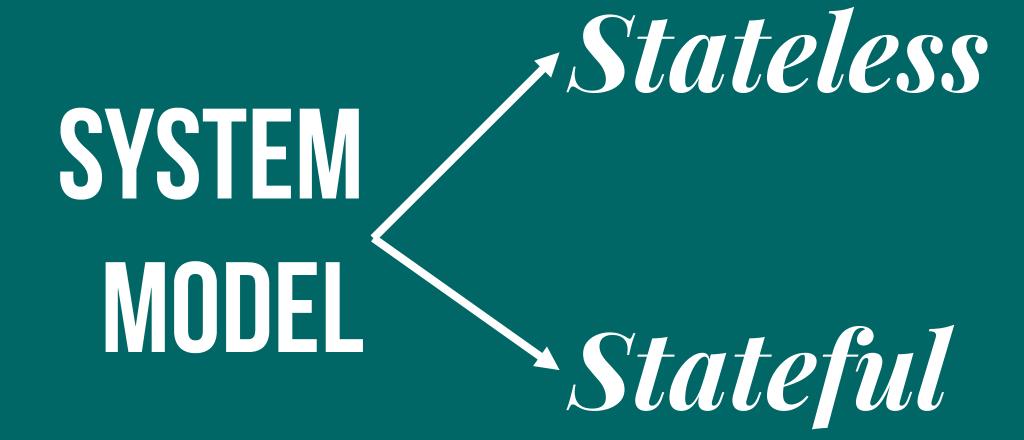


EXECUTION Conline Offline



RECOGNITION Continuous Segmented





Imagine an app that analyses your shopping lists and suggests at the end of the week recipes with a better nutriotional value based on the ingredients of that list. Check all characteristics tha apply to this app.

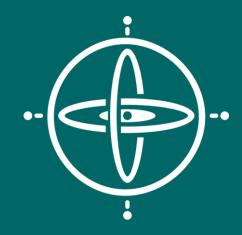


O Allow Single Choice Only	Allow Multiple Choices	☐ Shuffle Answers	✓ Allow Retry	☐ Limit Attempts			
Online					Ū	—	~
Offile					Ū	,	~
User-Independent					Ū	•	~
User-specific					Ū	•	~
Insert option here					Ū	•	~
Periodic					Ū	—	~
Sporadic					Ū	,	~
Preview		Terms Privacy & Cookies					











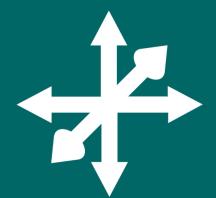






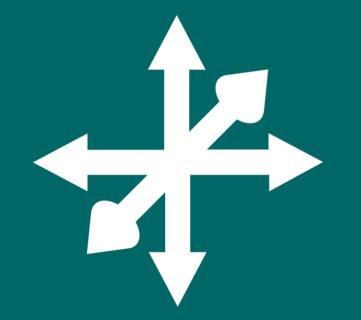








CHOOSING A SENSOR



What is it measuring?



CHOOSING A SENSOR



High Accuracy High Precision



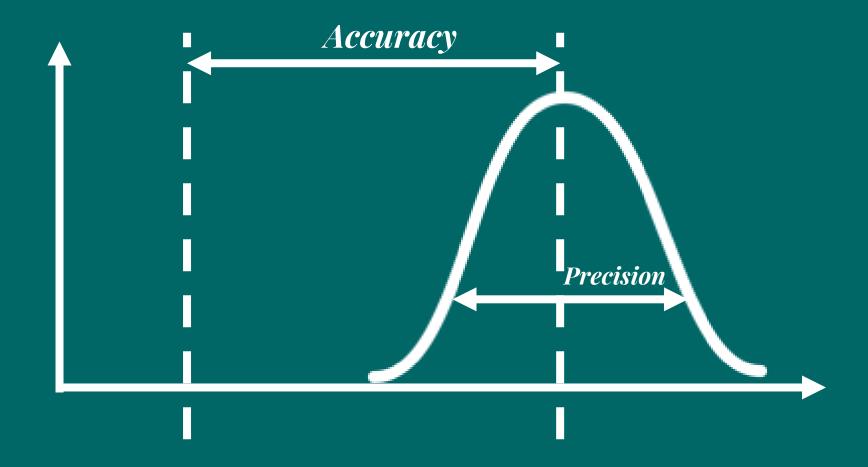
High Accuracy Low Precision



Low Accuracy High Precision



Low Accuracy Low Precision



True value

A certain broken thermometer always outputs 20 degrees regardless of the actual temperature of the environment. One could argue that this behaves like a sensor with...



O Allow Multiple Choices ✓ Shuffle Answers ✓ Allow Retry ☐ Limit Attempts Allow Single Choice Only Low accuracy, High precision Low accuracy, because the measurement mean is totally wrong, but high precision, because they are always the same. Low Accuracy, Low Precision High Accuracy, High Precision High Accuracy, Low Precision

♣ Add another answer

CHOOSING A SENSOR

Operating range



Force Sensitive Resistor 0.5"

SEN-09375 ROHS✓ D

Description: This is a force sensitive resistor with a round, 0.5" diameter, sensing area. This FSR will vary its resistance depending on how much pressure is being applied to the 女女女女女11 sensing area. The harder the force, the lower the resistance. When no pressure is being applied to the FSR its r distance will be a riger than 1M Ω . This FSR can sense applied force anywhere in the range of 100g-10kg.

Two pins extend from the hottom of the making it bread board friendly. There is a peel-and-stick rubber backing on the other side of the sensing area to mount the FSR.

CHOOSING A SENSOR

Resolution or Sensitivity

Infrared camera optris PI 400 / PI 450

The infrared cameras optris PI 400 / PI 450 are the smallest thermographic cameras in their class. Being equipped with a measurement speed of 80 Hz and an optical resolution of 382 x 288 pixels they provide real-time thermographic images in high speed.

The IR camera PI 450 is, due to its thermal sensitivity of 40 mK specifically suited for detection of slightest temp, rature differences, making it indispensable in quality control of products and in medical prevention.

The compact and high-performance infrared cameras offer a temperature range of -20°C up to 900°C, being optionally upgradeable up to 1500 °C. They can be delivered with exchangeable optics, industrial thermal imager equipment and they come with an extensive license-free thermography



Important Specifications

- Temperature range: -20 °C to 900 °C (optional up to 1500 °C)
- Spectral range: 7.5 to 13 μm
- Frame rate: 80 Hz

CHOOSING A SENSOR

Sampling Rate or Frame Rate

Infrared camera optris PI 400 / PI 450

The infrared cameras optris PI 400 / PI 450 are the smallest thermographic cameras in their class. Being equipped with a measurement speed of 80 Hz and an optical resolution of 382 x 288 pixels they provide real-time thermographic images in high speed.

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Important Specifications

- Temperature range: -20 °C to 900 °C (optional up to 1500 °C)
- Spectral range. 75 to 13 μm Frame rate: 80 Hz

CHOOSING A SENSOR



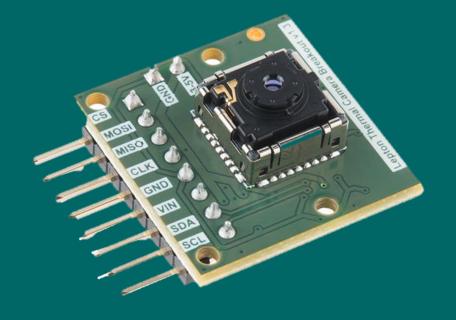
Cost

\$259.95

ADD TO CART

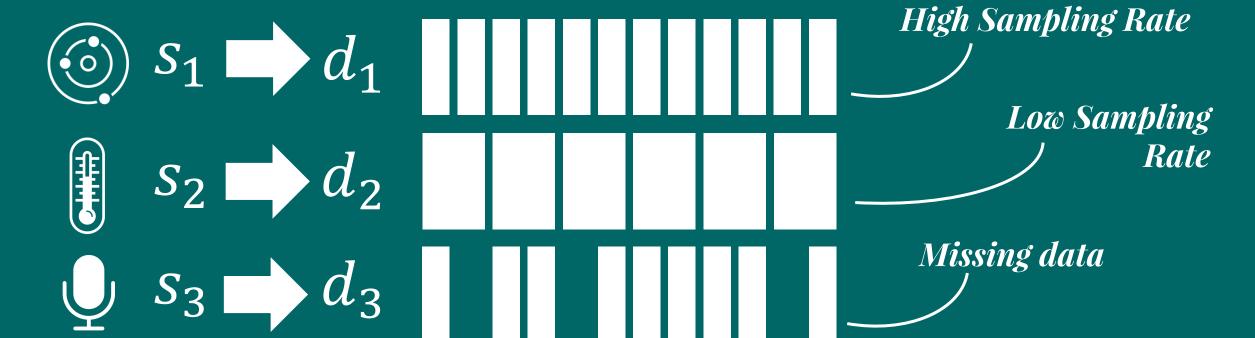
Shipping outside of the US?

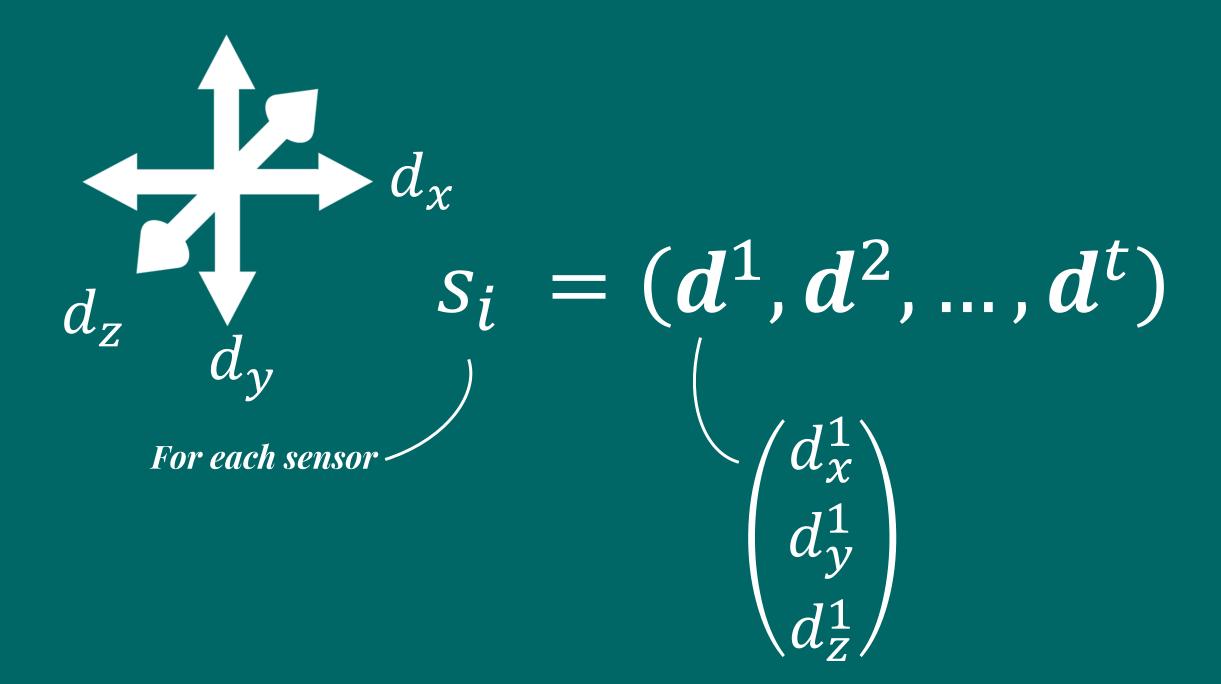
Click here for info



RAW DATA

$$D = (d_1 \dots d_n)^T$$





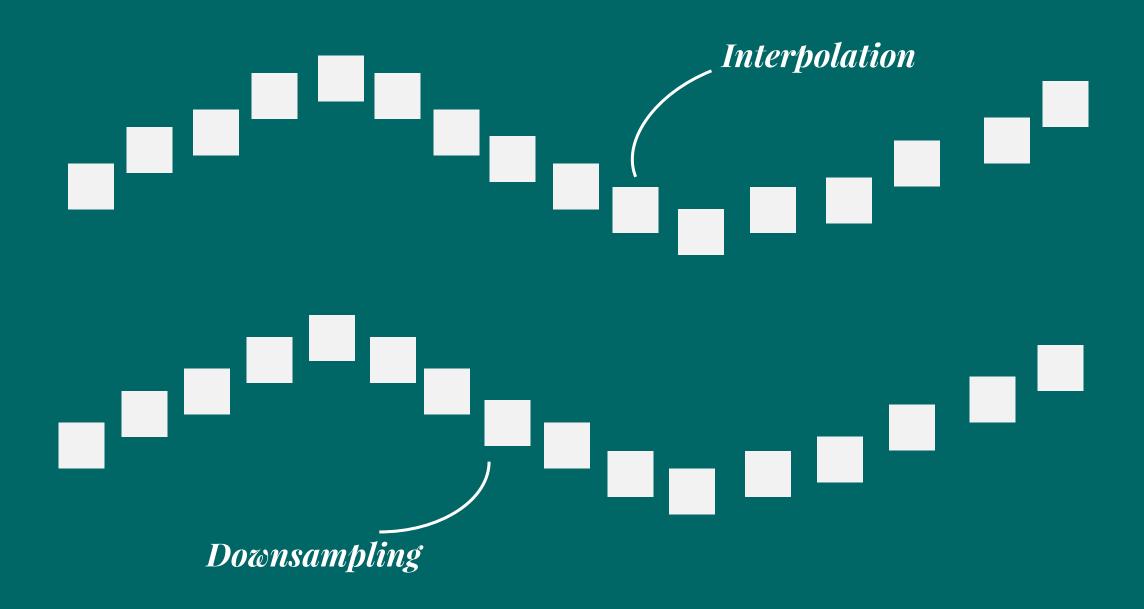
PREPROCESSING

$$D' = (d'_1 \dots d'_n)^T$$

$$S_1 \longrightarrow d'_1$$
 $S_2 \longrightarrow d'_2$
 $S_3 \longrightarrow d'_3$

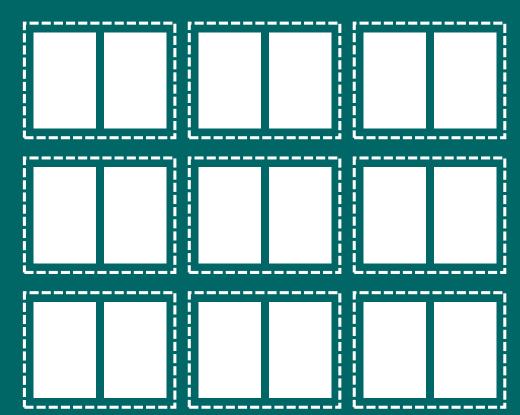
Time

$$D' = \begin{pmatrix} d'_1^1 & \cdots & d'_1^t \\ \vdots & \ddots & \vdots \\ d'_n^1 & \cdots & d'_n^t \end{pmatrix}$$



SEGMENTATION

$$W = \{w_1 \dots w_m\}$$



SEGMENTATION -

Sliding Window

Energy Based

Additional Context Sources

Non-Overlapping Sliding Window

A B C D E F G H I J K L

$$W_{1} = [ABC]$$

$$W_{2} = [DEF]$$

$$W_{3} = [GHI]$$

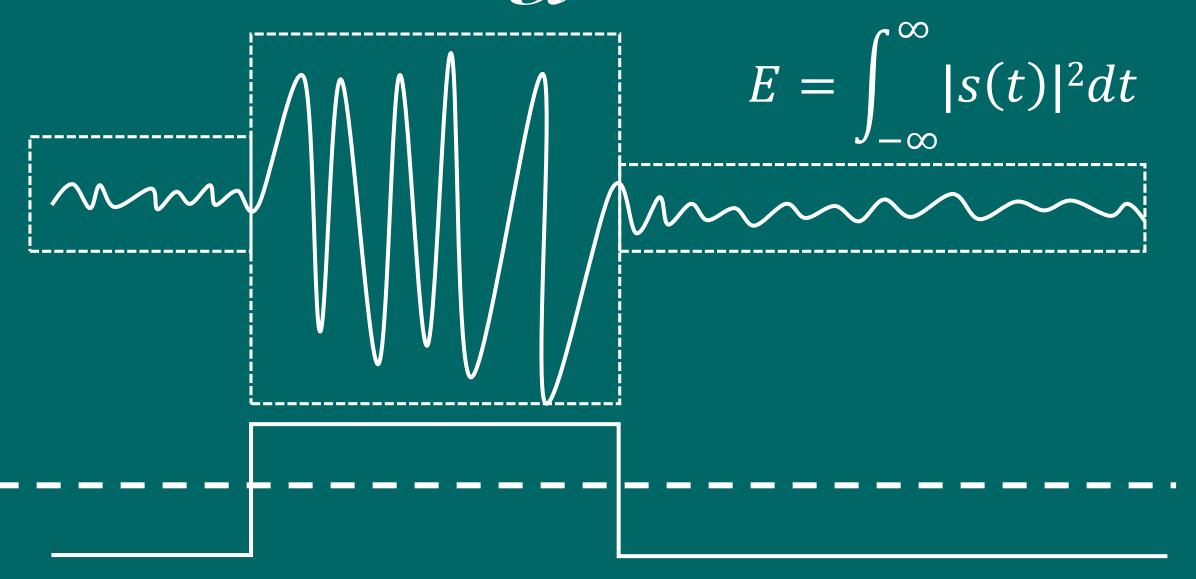
$$W_{4} = [FKL]$$

Overlapping Sliding Window

A B C D E F G H I J K L

$$W_1 = [ABC]$$
 $W_5 = [EFG]$ $W_9 = [IJK]$ $W_2 = [BCD]$ $W_6 = [FGH]$ $W_{10} = [JKL]$ $W_3 = [CDE]$ $W_7 = [GHI]$ $W_8 = [HIJ]$

Energy-Based

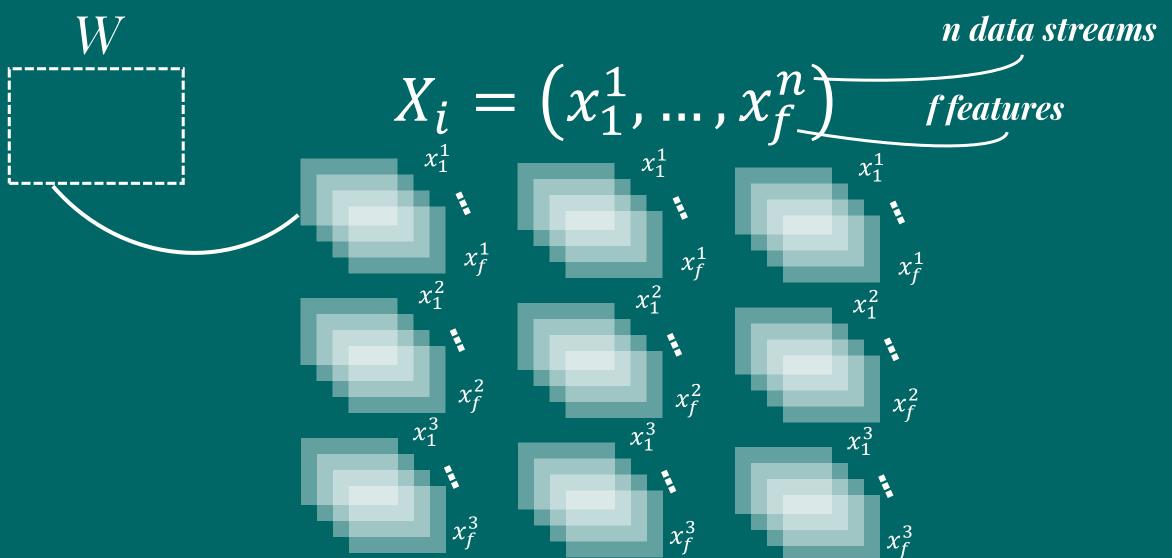


Additional Context Sources





FEATURE EXTRACTION



Min

Skewness

Mean

Range FEATURES

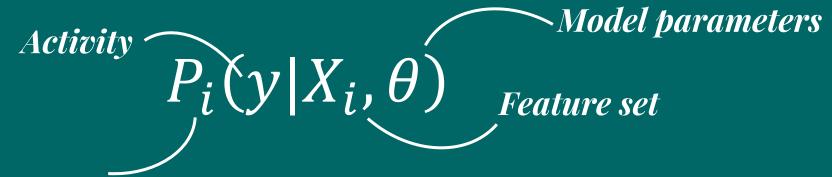
Energy

Kurtosis

Max

Variance

CLASSIFICATION



For each segment

 $P_1(swimming|X_1,\theta)$

 $P_1(sitting|X_1,\theta)$

 $P_1(running|X_1,\theta)$







Hidden Markov Models

Dynamic Time Warping

kNN

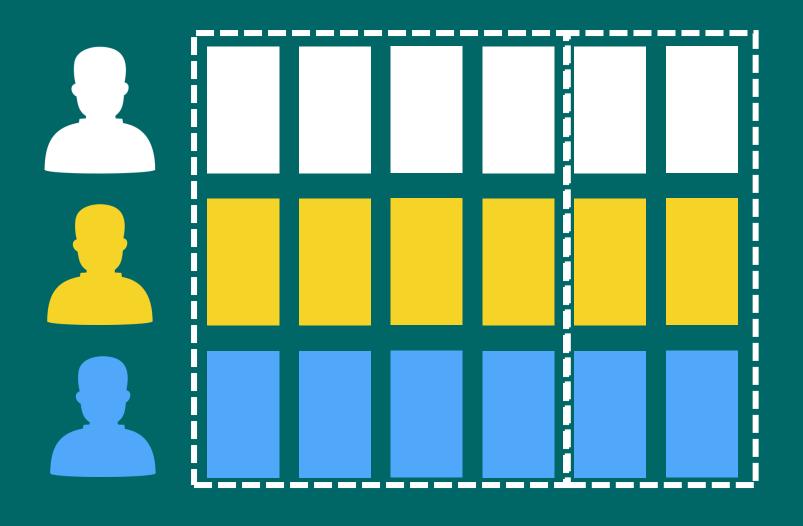
CLASSIFIERS

AdaBoost

Support Vector Machines



Random Forest



User-Dependent

Training

Testing

Training

Testing

User-Independent

Cross-Validation

Training

Testing

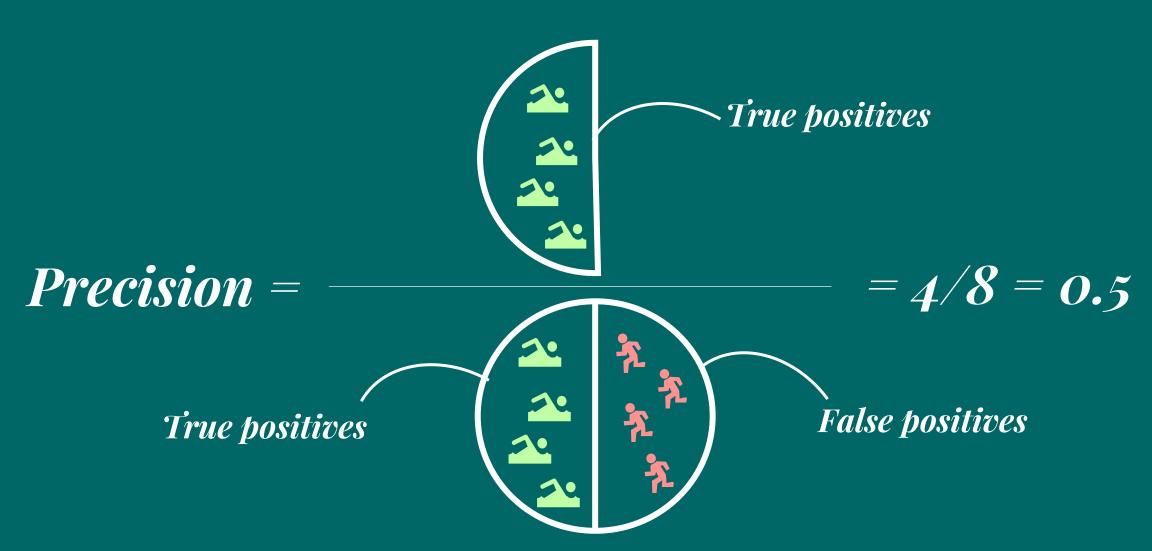
.85

.89 .72 .90 .99 .80 .83 .84 .91 .77 .80

REPORTING PERFORMANCE



What proportion of the labelled items were correct?



If the recognition of an activity has 100% precision and the system says that the activity is NOT happening, we can be sure that the activity is not happening.



✓ Allow Retry

True

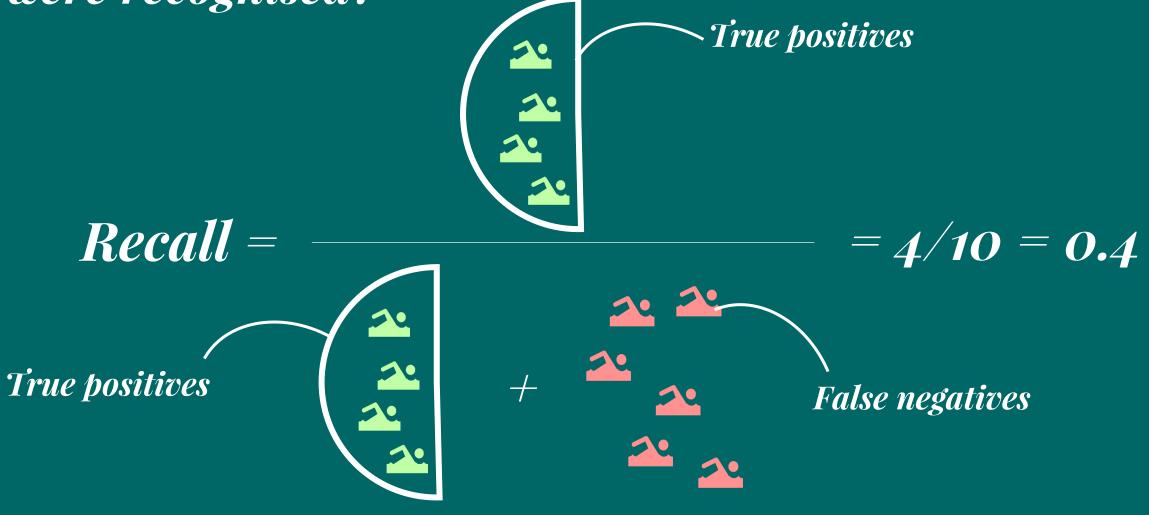


False



What proportion of the windows with that activity

were recognised?



Consider the case of the app for detecting when an elderly person has fallen down. Would you optimise this system for precision or recall? Justify your answer

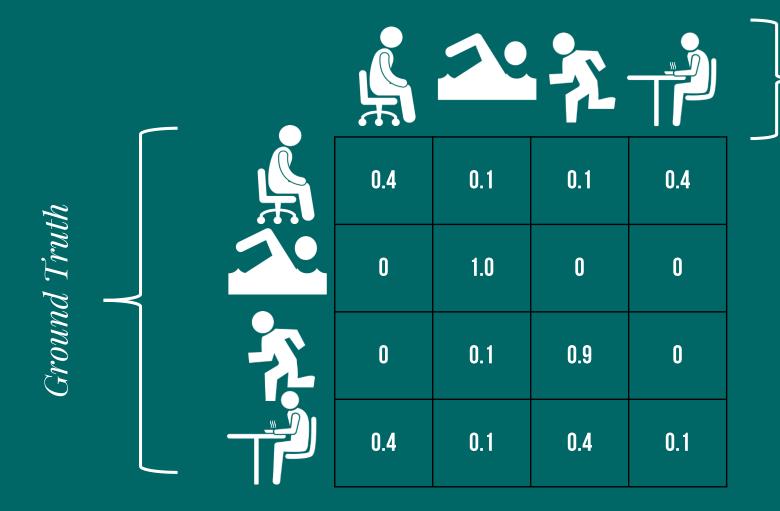


Combining both metrics...

$$F_{1}Score = \frac{2}{\frac{1}{Recall} + \frac{1}{Precision}}$$

$$= 2 \frac{Precision \times Recall}{Precision + Recall}$$

Confusion Matrix



System Output

A TUTORIAL ON HUMAN ACTIVITY RECOGNITION USING BODY-WORN INERTIAL SENSORS







CASE STUDY

Plotz et al. 2010



Select font size TTT

What classes were the authors trying to recognise?

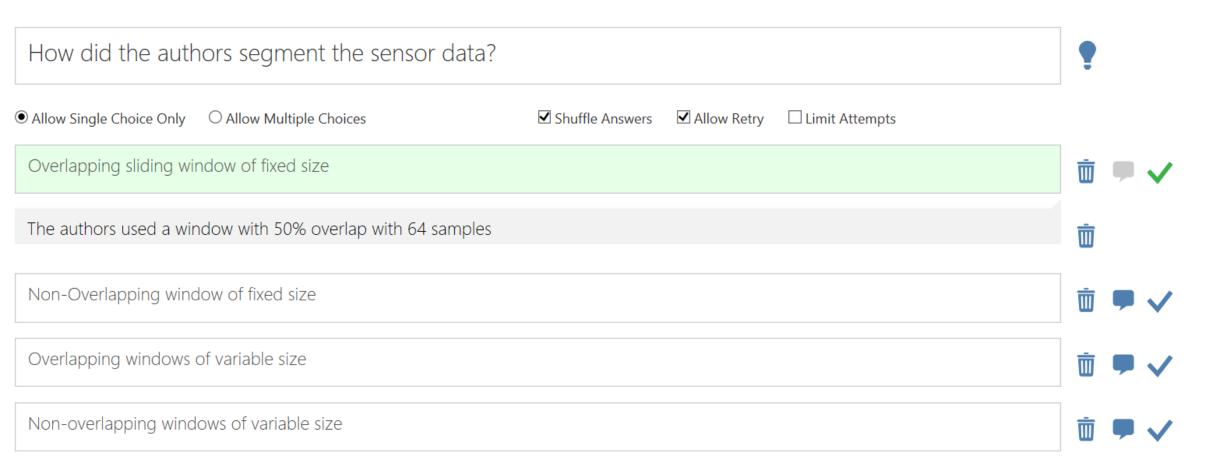


Check section 14.4.3



Describe the sensors used in terms of their form factor, their sampling rate, and the data they captured.



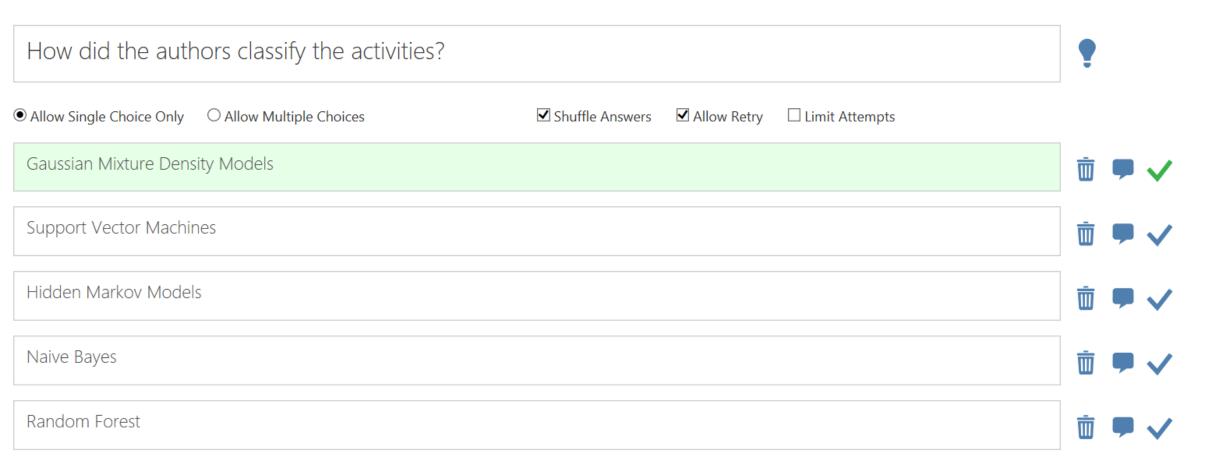


+ Add another answer

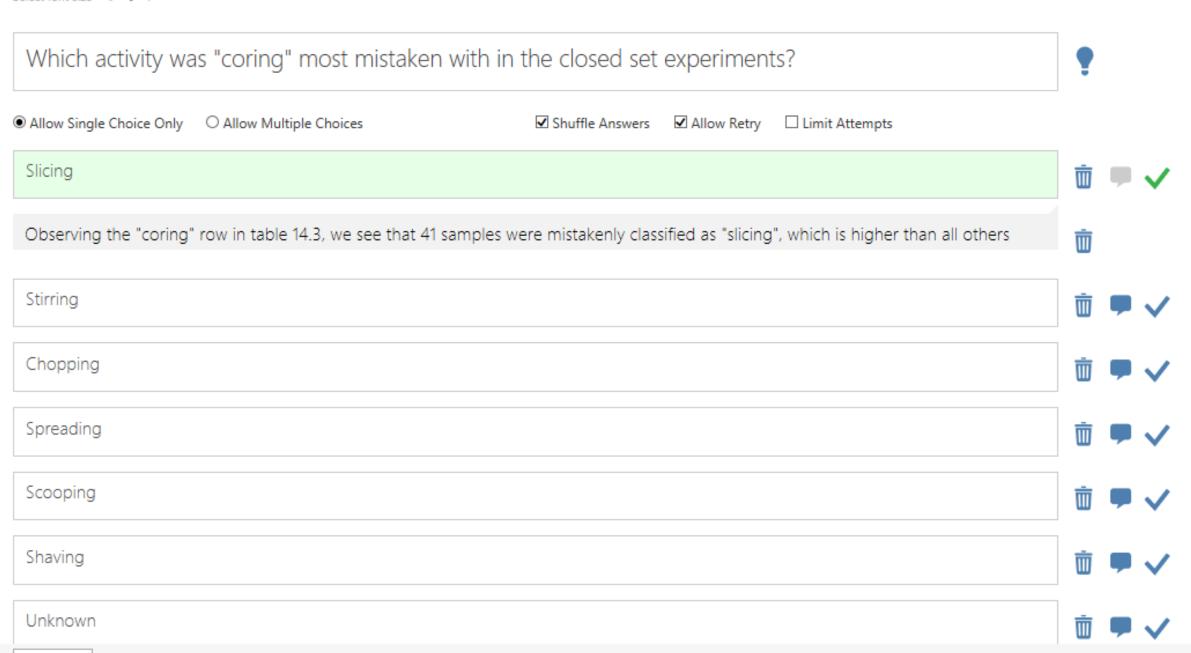
Select font size TTT

Which features the authors extracted from each window?





★ Add another answer



Use the data in table 14.2 to compute the precision, recall, and F1 score for the class "shaving"



Evaluation

Opportunities for context recognition

Segmentation

Characteristics of HAR Systems

Smart Utensils

Preprocessing

Choosing sensors

RECAP

What is context?

Classification

Feature Extraction

What to do with context?

How do you feel about this lecture?

Allow Single Choice Only
 Allow Multiple Choices

Loved it!	Ū
Liked it	Ī
Neither liked it, nor disliked it	Ī
Disliked it	ī

+ Add another answer

Hated it!

What did you like and dislike about this lecture? How can I improve it?