## No late homework!

1. I have k, for some k, water tanks,  $T_1, \dots, T_k$  (which are identical in size and shap), whose water levels are respectively denoted by nonnegative real variables  $x_1, \dots, x_k$ . Without loss of generality, we assume that  $x_i$  equals the amount of water that is currently in  $T_i$ . Initially, all the tanks are empty; i.e.,  $x_i = 0$ ;  $1 \le i \le k$ . I have m pumps  $p_1, \dots, p_m$ , that pump water into tanks. More precisely, a pump instruction, say,  $P_{A,c_1,c_2}$ , where  $A \subseteq \{T_1, \dots, T_k\}$ , is to pump the same amount of water to each of the tank  $T_i$  with  $i \in A$  (so water levels on other tanks not in A will not change), where the amount is anywhere between  $c_1$  and  $c_2$  (including  $c_1$  and  $c_2$ , of course we have assumed  $0 \le c_1 \le c_2$ ). For instance,  $P_{\{T_2,T_5\},1.5,2.4}$  means to pump simontaneously to  $T_2$  and  $T_5$  the same amount of water. However, the amount can be anywhere between 1.5 and 2.4. Suppose that we execute the instruction twice, say:

$$P_{\{T_2,T_5\},1.5,2.4};$$
  
 $P_{\{T_2,T_5\},1.5,2.4}.$ 

The first  $P_{\{T_2,T_5\},1.5,2.4}$  can result in 1.8 amount of water pumped into  $T_2$  and  $T_5$ , respectively, and the second  $P_{\{T_2,T_5\},1.5,2.4}$  can result in 2.15 amount of water pumped into  $T_2$  and  $T_5$ , respectively. That is, the amount of water can be arbitrary chosen inside the range specified in the instruction, while the choice is independent between instructions.

Now, let M be a finite state controller which is specified by a directed graph where each edge is labeled with a pump instruction. Different edges may be labell with the same pump instruction and may also be labeled with different pump instructions. There is an initial node and a final node in M. Consider the following condition  $Bad(x_1, \dots, x_k)$ :

$$x_1 = x_2 + 1 = x_3 + 2 \land x_3 > x_4 + 0.26.$$

A walk in M is a path from the initial to the final. I collect the sequence of pump instructions on the walk. If I carefully assign an amount (of water pumped) for each such pump instruction and, as a result, the water levels  $x_1, \dots, x_k$  at the end of the sequence of pump instruction satisfy  $Bad(x_1, \dots, x_k)$ , then I call the walk is a bad walk. Such a walk intuitively says that there is an undesired execution of M.

Design an algorithm that decides whether M has a bad walk. (Hint: first draw an example M where there is no loop and see what you can get. Then,

draw an M that is with a loop and see what you get. Then, draw an M that is with two nested loops and see what you get, and so on.)

2. The word bit comes from Shannon's work in measuring the randomness in a fair coin. However, such randomness measurement requires a probability distribution of the random variable in consideration. Suppose that a kid tosses a dice for 1000 times and hence he obtains a sequence of 1000 outcomes

$$a_1, a_2, \cdots, a_{1000}$$

where each  $a_i$  is one of the six possible outcomes. Notice that a dice may not be fair at all; i.e., the probability of each outcome is not necessarily  $\frac{1}{6}$ . Based on the sequence only, can you design an algorithm to decide how "unfair" the dice that the kid tosses is.

- 3. In below, a sequence is a sequence of event symbols where each symbol is drawn from a known finite alphabet. For a sequence  $\alpha = a_1 \cdots a_k$  that is drawn from a known finite set S of sequences, one may think it as a sequence of random variables  $x_1 \cdots x_k$  taking values  $x_i = a_i$ , for each i. We assume that the lengths of the sequences in the set S are the same, say n. In mathematics, the sequence of random variables is called a stochastic process and the process may not be i.i.d at all (independent and identical distribution). Design an algorithm that takes input S and outputs the likehood on the process being i.i.d.
- 4. Let  $G_1$  and  $G_2$  be two directed graphs and  $v_1, u_1$  be two nodes in  $G_1$  and  $v_2, u_2$  be two nodes in  $G_2$ . Suppose that from  $v_1$  to  $u_1$ , there are infinitely many paths in  $G_1$  and that from  $v_2$  to  $u_2$ , there are infinitely many paths in  $G_2$  as well. Design an algorithm deciding that the number of paths from  $v_1$  to  $u_1$  in  $G_1$  is "more than" the number of paths from  $v_2$  to  $u_2$  in  $G_2$ , even though both numbers are infinite (but countable).